

WD1691 FLOPPY SUPPORT LOGIC (F.S.L.)

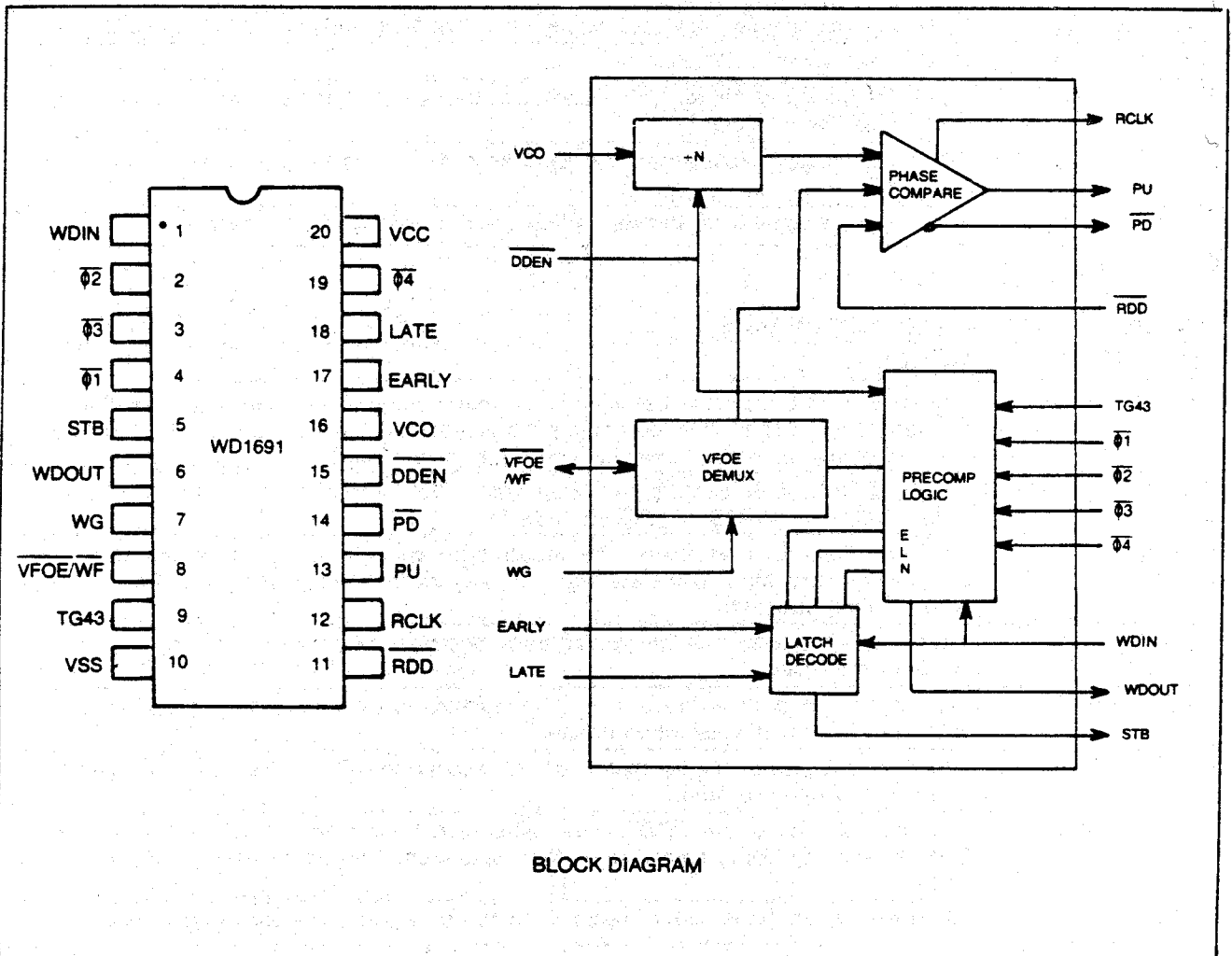
FEATURES

- Direct interface to the FD179X
- Eliminates external FDC Logic
- Data Separation/RCLK GENERATION
- Write Precompensation Signals
- VFOE/WF Demultiplexing
- Programmable Density
- 8" or 5.25" Drive Compatible
- All inputs and outputs TTL Compatible
- Single +5V Supply

GENERAL DESCRIPTION

The WD1691 F.S.L. has been designed to minimize the external logic required to interface the 179X Family of Floppy Disk Controllers to a drive. With the use of an external VCO, the WD 1691 will generate the RCLK signal for the WD179X, while providing an adjustment pulse (PUMP) to control the VCO frequency. VFOE/WF de-multiplexing is also accomplished and Write Precompensation signals have been included to interface directly with the WD2143 Clock Generator.

The WD1691 is implemented in N-MOS silicon gate technology and is available in a plastic or ceramic 20 pin dual-in-line package.



BLOCK DIAGRAM

PIN	NAME	SYMBOL	FUNCTION
1	WRITE DATA INPUT	WDIN	Ties directly to the FD179X WD pin.
2, 3, 4, 19	PHASE 2, 3, 1, 4	$\overline{02}$ $\overline{03}$ $\overline{01}$ $\overline{04}$	4 Phase inputs to generate a desired Write Precompensation delay. These signals tie directly to the WD2143 Clock Generator.
5	STROBE	STB	Strobe output from the 1691. Strobe will latch at a high level on the leading edge of WDIN and reset to a low level on the leading edge of 04.
6	WRITE DATA OUTPUT	WDOUT	Serial, pre-compensated Write data stream to be sent to the disk drive's WD line.
7	WRITE GATE	WG	Ties directly to the FD179X WG pin.
8	VFO ENABLE/ WRITE FAULT	$\overline{\text{VFOE/WF}}$	Ties directly to the FD179X $\overline{\text{VFOE/WF}}$ pin.
9	TRACK 43	TG43	Ties directly to the FD179X TG43 pin, if Write Precompensation is required on TRACKS 44-76.
10	V _{ss}	V _{ss}	Ground
11	READ DATA	$\overline{\text{RDD}}$	Composite clock and data stream input from the drive.
12	READ CLOCK	RCLK	RCLK signal generated by the WD1691, to be tied to the FD179X RCLK pin.
13	PUMP UP	PU	Tri-state output that will be forced high when the WD1691 requires an increase in VCO frequency.
14	PUMP DOWN	$\overline{\text{PD}}$	Tri-state output that will be forced low when the WD1691 required a decrease in VCO frequency.
15	Double Density Enable	$\overline{\text{DDEN}}$	Double Density Select input. When Inactive (High), the VCO frequency is internally divided by two.
16	Voltage Controlled Oscillator	VCO	A nominal 4.0MHz (8" drive) or 2.0MHz (5.25" drive) master clock input.
17, 18	EARLY LATE	EARLY LATE	EARLY and LATE signals from the FD179X, used to determine Write Precompensation.
20	V _{cc}	V _{cc}	+ 5V \pm 10% power supply

DEVICE DESCRIPTION

The WD1691 is divided into two sections:

- 1) Data Recovery Circuit
- 2) Write precompensation Circuit

The Data Separator or Recovery Circuit has four inputs: \overline{DDEN} , \overline{VCO} , \overline{RDD} , and $\overline{VFOE/WF}$; and three outputs: PU, PD and RCLK. The $\overline{VFOE/WF}$ input is used in conjunction with the Write Gate signal to enable the Data recovery circuit. When Write Gate is high, a write operation is taking place, and the data recovery circuits are disabled, regardless of the state on any other inputs.

When $\overline{VFOE/WF}$ and WRITE GATE are low, the data recovery circuit is enabled. When the \overline{RDD} line goes Active Low, the PU or PD signals will become active. If the \overline{RDD} line has made its transition in the beginning of the RCLK window, PU will go from a HI-Z state to a Logic 1, requesting an increase in VCO frequency. If the \overline{RDD} line has made its transition at the end of the RCLK window, PU will remain in a HI-Z state while PD will go to a logic zero, requesting a decrease in VCO frequency. When the leading edge of \overline{RDD} occurs in the center of the RCLK window, both PU and PD will remain tri-stated, indicating that no adjustment of the VCO frequency is needed. The RCLK signal is a divide-by-16 ($\overline{DDEN}=1$) or a divide-by-8 ($\overline{DDEN}=0$) of the VCO frequency.

WG	VFOE/WF	RDD	PU+PD
1	X	X	HI-Z
0	1	X	HI-Z
0	0	1	HI-Z
0	0	0	Enable

The Write Precompensation circuit has been designed to be used with the WD2143-01 clock generator. When the WD1691 is operated in a "single density only" mode, write precompensation as well as the WD2143-01 is not needed. In this case, $\overline{\phi 1}$, $\overline{\phi 2}$, $\overline{\phi 3}$, $\overline{\phi 4}$, and STB should be tied together, \overline{DDEN} left open, and TG43 tied to ground.

In the double-density mode ($\overline{DDEN}=0$), the signals Early and Late are used to select a phase input ($\overline{\phi 1} - \overline{\phi 4}$) on the leading edge of WDIN. The STB line is latched high when this occurs, causing the WD2143-01 to start its pulse generation. $\overline{\phi 2}$ is used as the write data pulse on nominal (Early=Late= $\overline{\phi}$), $\overline{\phi 2}$ is used for early, and $\overline{\phi 3}$ is used for late. The leading edge of $\overline{\phi 4}$ resets the STB line in anticipation of the next write data pulse. When TG43=0 or $\overline{DDEN}=1$, Precompensation is disabled and any transitions on the WDIN line will appear on the WDout line. If write precompensation is desired on all tracks, leave TG43 open (an internal pull-up will force a Logic 1) while $\overline{DDEN}=0$.

The signals, \overline{DDEN} , TG43, and \overline{RDD} have internal pull-up resistors and may be left open if a logic 1 is desired on any of these lines.

The minimum Voh level on PU is specified at 2.4V, sourcing 200ua. During PUMP UP time, this output will "drift" from a tri-state to .4V minimum. By tying PU and PD together, a PUMP signal is created that will be forced low for a decrease in VCO frequency and forced high for an increase in VCO frequency. To speed up rise times and stabilize the output voltage, a resistor divider can be used to set the tri-state level to approximately 1.4V. This yields a worst case swing of $\pm 1V$; acceptable for most VCO chips with a linear voltage-to-frequency characteristic.

Both PU and PD signals are affected by the width of the RAW READ (\overline{RDD}) pulse. The wider the RAW READ pulse, the longer the PU or PD signal (depending upon the phase relationship to RCLK) will remain active. If the RAW READ pulse exceeds 250ns. ($\overline{VCO} = 4\text{MHz}$, $\overline{DDEN} = 0$) or 500ns. ($\overline{VCO} = 4\text{MHz}$, $\overline{DDEN} = 1$), then both a PU and PD will occur in the same window. This is undesirable and reduces the accuracy of the external integrator or low-pass filter to convert the PUMP signals into a slow moving D.C. correction voltage.

Eventually, the PUMP signals will have corrected the VCO input to exactly the same frequency multiple as the RAW READ signal. The leading edge of the RAW READ pulse will then occur in the exact center of the RCLK window, and ideal condition for the FD179X internal recovery circuits.

FD179X Application Notes

JUNE, 1980

INTRODUCTION

Over the past several years, the Floppy Disk Drive has become the most popular on-line storage device for mini and microcomputer systems. Its fast access time, reliability and low cost-per-bit ratio enables the Floppy Disk Drive to be *the* solution in mass storage for microprocessor systems. The drive interface to the Host system is standardized, allowing the OEM to substitute one drive for another with minimum hardware/ software modifications.

Since Floppy Disk Data is stored and retrieved as a self-clocking serial data stream, some means of separating the clock from the data and assembling this data in parallel form must be accomplished. Data is stored on individual Tracks of the media, requiring control of a stepper motor to move the Read/Write head to a predetermined Track. Byte synchronization must also be accomplished to insure that the parallel data is properly assembled. After all the design considerations are met, the final controller can consist of 40 or more TTL packages.

To alleviate the burden of Floppy Disk Controller design, Western Digital has developed a Family of LSI Floppy Disk controller devices. Through its own set of macro commands, the FD179X Controller Family will perform all the functions necessary to read and write data to the drive. Both the 8" standard and 5¼" mini-floppy are supported with single or double density recording techniques. The FD179X is compatible with the IBM 3740 (FM) data format, or the System 34 (MFM) standards. Provisions for non-standard formats and variable sector lengths have been included to provide more storage capability per track. Requiring standard +5, +12 power supplies the FD179X is available in a standard 40 pin dual-in-line package.

The FD179X Family consists of 6 devices. The differences between these devices is summarized in Figure 1. The 1792 and 1794 are "single density only" devices, with the Double Density Enable pin (DDEN) left open by the user. Both True and inverted Data bus devices are available. Since the 179X can only drive one TTL Load, a true data bus system may use the 1791 with external inverting buffers to arrive at a true bus scheme. The 1795 and 1797 are identical to the 1791 and 1793, except a side select output has been added that is controlled through the Command Register.

SYSTEM DESIGN

The first consideration in Floppy Disk Design is to determine which type of drive to use. The choice ranges from single-density single sided mini-floppy to the 8" double-density double-sided drive. Figure 2 illustrates the various drive and data capacities associated with each type. Although the 8" double-density drive offers twice as much storage, a more complex data separator and the addition of Write Precompensation circuits are mandatory for reliable data transfers. Whether to go with 8" double-density or not is dependent upon PC board space and the additional circuitry needed to accurately recover data with extreme bit shifts. The byte transfer time defines the nominal time required to transfer one byte of data from the drive. If the CPU used cannot service a byte in this time, then a DMA scheme will probably be required. The 179X also needs a few microseconds for overhead, which is subtracted from the transfer time. Figure 3 shows the actual service times that the CPU must provide on a byte-by-byte basis. If these times are not met, bytes of data will be lost during a read or write operation. For each byte transferred, the 179X generates a DRQ (Data Request) signal on Pin 38. A bit is provided in the status register which is also set upon receipt of a byte from the Disk. The user has the option of reading the status register through program control or using the DRQ Line with DMA or interrupt schemes. When the data register is read, both the status register DRQ bit and the DRQ Line are automatically reset. The next full byte will again set the DRQ and the process continues until the sector(s) are read. The Write operation works exactly the same way, except a WRITE to the Data Register causes a reset of both DRQ's.

RECORDING FORMATS

The FD179X accepts data from the disk in a Frequency-Modulated (FM) or Modified-Frequency-Modulated (MFM) Format. Shown in Figures 4A and 4B are both these Formats when writing a Hexidecimal byte of 'D2'. In the FM mode, the 8 bits of data are broken up into "bit cells." Each bit cell begins with a clock pulse and the center of the bit cell defines the data. If the data bit = 0, no pulse is written; if the data = 1, a pulse is written in the center of the cell. For the 8" drive, each clock is written 4 microseconds apart.

FIGURE 1. DEVICE CHARACTERISTICS

DEVICE	SNGL DENSITY	DBLE DENSITY	INVERTED BUS	TRUE BUS	DOUBLE-SIDED
1791	X	X	X		
1792	X		X		
1793	X	X		X	
1794	X			X	
1795	X	X	X		X
1797	X	X		X	X

FIGURE 2. STORAGE CAPACITIES

SIZE	DENSITY	SIDES	UNFORMATTED CAPACITY (NOMINAL)		BYTE TRANSFER TIME	FORMATTED CAPACITY	
			PER TRACK	PER DISK		PER TRACK	PER DISK
5¼"	SINGLE	1	3125	109,375*	64µs	2304**	80,640
5¼"	DOUBLE	1	6250	218,750	32µs	4608***	161,280
5¼"	SINGLE	2	3125	218,750	64µs	2304	161,280
5¼"	DOUBLE	2	6250	437,500	32µs	4608	322,560
8"	SINGLE	1	5208	401,016	32µs	3328	256,256
8"	DOUBLE	1	10,416	802,032	16µs	6656	512,512
8"	SINGLE	2	5208	802,032	32µs	3328	512,512
8"	DOUBLE	2	10,416	1,604,064	16µs	6656	1,025,024

*Based on 35 Tracks/Side

**Based on 18 Sectors/Track (128 byte/sec)

***Based on 18 Sectors/Track (256 bytes/sec)

In the MFM mode, clocks are decoded into the data stream. The byte is again broken up into bit cells, with the data bit written in the center of the bit cell if data = 1. Clocks are only written if both surrounding data bits are zero. Figure 4B shows that this occurs only once between Bit cell 4 and 5. Using this encoding scheme, pulses can occur 2, 3 or 4 microseconds apart. The bit cell time is now 2 microseconds; twice as much data can be recorded without increasing the Frequency rate due to this encoding scheme.

The 179X was designed to be compatible with the IBM 3740 (FM) and System 34 (MFM) Formats. Although most users do not have a need for data exchange with IBM mainframes, taking advantage of these well studied formats will insure a high degree of system performance. The 179X will allow a change in gap fields and sector lengths to increase usable storage capacity, but variations away from these standards is not recommended. Both IBM standards are soft-sector format. Because of the wide variation in address marks, the 179X can only support soft-sectored media. Hard sectored diskettes have continued to lose popularity, mainly due to the unavailability of a standard and the limitation of sector lengths imposed by the physical sector holes in the diskette.

PROCESSOR INTERFACE

The interface of the 179X to the CPU consists of an 8-bit Bi-directional bus, read/write controls and optional interrupt lines. By selecting the device via the CHIP SELECT Line, each of the five internal registers can be accessed.

Shown below are the registers and their addresses:

PIN 3 CS	PIN 6 A ₁	PIN 5 A ₀	PIN 4 R \bar{E} = \bar{R}	PIN 2 W \bar{E} = \bar{W}
0	0	0	STATUS REG	COMMAND REG
0	0	1	TRACK REG	TRACK REG
0	1	0	SECTOR REG	SECTOR REG
0	1	1	DATA REG	DATA REG
1	X	X	H1-Z	H1-Z

Each time a command is issued to the 179X, the Busy bit is set and the INTRQ (Interrupt Request) Line is reset. The user has the option of checking the busy bit or use the INTRQ Line to denote command completion. The Busy bit will be reset whenever the 179X is idle and awaiting a new command. The INTRQ Line, once set, can only be reset by a READ of the status register or issuing a new command. The MR (Master Reset) Line does not affect INTRQ.

The A₀, A₁ Lines used for register selections can be configured at the CPU in a variety of ways. These lines may actually tie to CPU address lines, in which case the 179X will be memory-mapped and addressed like RAM. They may also be used under Program Control by tying to a port device such as the 8255, 6820, etc. As a diagnostic tool when checking out the CPU interface, the Track and Sector registers should respond like "RAM" when the 179X is idle (Busy = INTRQ = 0).

Because of internal synchronization cycles, certain time delays must be introduced when operating under Programmed I/O. The worst case delays are:

OPERATION	NEXT OPERATION	DELAY REQ'D
WRITE TO COMMAND REG	READ STATUS REGISTER	MFM = 14 μ s* FM = 28 μ s.
WRITE TO ANY REGISTER	READ FROM A DIFFERENT REG	NO DELAY

*NOTE: Times Double when CLK = 1MHz (5 $\frac{1}{4}$ " drive)

Other CPU interface lines are CLK, \bar{MR} and \bar{DDEN} . The CLK line should be 2MHz (8" drive) or 1MHz (5 $\frac{1}{4}$ " drive) with a 50% duty cycle. Accuracy should be $\pm 1\%$ (crystal source) since all internal timing, including stepping rates, are based upon this clock.

The \bar{MR} or Master Reset Line should be strobed a minimum of 50 microseconds upon each power-on condition. This line clears and initializes all internal registers and issues a restore command (Hex '03') on the rising edge. A quicker stepping rate can be written to the command register after a \bar{MR} , in which case the remaining steps will occur at the faster programmed rate. The 179X will issue a maximum of 255 stepping pulses in an attempt to expect the \bar{TROO} line to go active low. This line should be connected to the drive's \bar{TROO} sensor.

The \bar{DDEN} line causes selection of either single density (\bar{DDEN} = 1) or double density operation. \bar{DDEN} should not be switched during a read or write operation.

FLOPPY DISK INTERFACE

The Floppy Disk Interface can be divided into three sections: Motor Control, Write Signals and Read Signals. All of these lines are capable of driving one TTL load and not compatible for direct connection to the drive. Most drives require an open-collector TTL interface with high current drive capability. This must be done on all outputs from the 179X. Inputs to the 179X may be buffered or tied to the Drives outputs, providing the appropriate resistor termination networks are used. Undershoot should not exceed -0.3 volts, while integrity of V_{IH} and V_{OH} levels should be kept within spec.

MOTOR CONTROL

Motor Control is accomplished by the STEP and DIRC Lines. The STEP Line issues stepping pulses with a period defined by the rate field in all Type I commands. The DIRC Line defines the direction of steps (DIRC = 1 STEP IN/DIRC = 0 STEP OUT).

Other Control Lines include the \overline{IP} or Index Pulse. This Line is tied to the drives' Index L.E.D. sensor and makes an active transition for each revolution of the diskette. The TROO Line is another L.E.D. sensor that informs the 179X that the stepper motor is at its furthest position, over Track 00. The READY Line can be used for a number of functions, such as sensing "door open", Drive motor on, etc. Most drives provide a programmable READY Signal selected by option jumpers on the drive. The 179X will look at the ready signal prior to executing READ/WRITE commands. READY is *not* inspected during any Type I commands. All Type I commands will execute regardless of the Logic Level on this Line.

WRITE SIGNALS

Writing of data is accomplished by the use of the WD, WG, WF, TG43, EARLY and LATE Lines. The WG or Write Gate Line is used to enable write current at the drive's R/W head. It is made active prior to writing data on the disk. The WF or WRITE FAULT Line is used to inform the 179X of a failure in drive electronics. This signal is multiplexed with the VFOE Line and must be logically separated if required.

The TG43 or "TRACK GREATER than 43" Line is used to decrease the Write current on the inner tracks, where bit densities are the highest. If not required on the drive, TG43 may be left open.

WRITE PRECOMPENSATION

The 179X provides three signals for double density Write-Precompensation use. These signals are WRITE DATA, EARLY and LATE. When using single density drives (either 8" or 5 $\frac{1}{4}$ "), Write Precompensation is not necessary and the WRITE DATA line is generally TTL Buffered and sent directly to the drive. In this mode, EARLY and LATE are left open.

For double density use, Write Precompensation is a function of the drive. Some manufacturers recommend Precompensating the 5 $\frac{1}{4}$ " drive, while others do not. With the 8" drive, Precompensation may be specified from TRACK 43 on, or in most cases, all TRACKS. If the recommended Precompensation is not specified,

check with the manufacturer for the proper configuration required.

The amount of Precompensation time also varies. A typical value will usually be specified from 100-300ns. Regardless of the parameters used, Write Precompensation must be done external to the 179X. When DDEN is tied low, EARLY or LATE will be activated at least 125ns. before and after the Write Data pulse. An Algorithm internal the 179X decides whether to raise EARLY or LATE, depending upon the previous bit pattern sent. As an example, suppose the recommended Precomp value has been specified at 150ns. The following action should be taken:

EARLY	LATE	ACTION TAKEN
0	0	delay WD by 150ns (nominal)
0	1	delay WD by 300ns (2X value)
1	0	do not delay WD

DATA SEPARATION

The 179X has two inputs (RAW READ & RCLK) and one output (VFOE) for use by an external data separator. The RAW READ input must present clock and data pulses to the 179X, while the RCLK input provides a "window" or strobe signal to clock each RAW READ pulse into the device. An ideal Data Separator would have the leading edge of the RAW READ pulse occur in the exact center of the RCLK strobe.

Motor Speed Variation, Bit shifts and read amplifier recovery circuits all cause the RAW READ pulses to drift away from their nominal positions. As this occurs, the RAW READ pulses will shift left or right with respect to RCLK. Eventually, a pulse will make its transition outside of its RCLK window, causing either a CRC error or a Record-not-Found error at the 179X.

A Phase-Lock-Loop circuit is one method of achieving synchronization between the RCLK and RAW READ signals. As RAW READ pulses are fed to the PLL, minor adjustments of the free-running RCLK frequency can be made. If pulses are occurring too far apart, the RCLK frequency is *decreased* to keep synchronization. If pulses begin to occur closer together, RCLK is *increased* until this new higher frequency is achieved. In normal read operations, RCLK will be constantly adjusted in an attempt to match the incoming RAW READ frequency.

Another method of Data Separation is the Counter-Separator technique. The RCLK signal is again free-running at a nominal rate, until a RAW READ pulse occurs. The Separator then denotes the position of the pulse with respect to RCLK (by the counter value), and counts down to increase or decrease the current RCLK window. The next RCLK window will occur at a nominal rate and will continue to run at this frequency until another RAW READ pulse adjusts RCLK, but only the present window is adjusted.

Both PPL and Counter/Separator are acceptable methods of Data Separation. The PPL has the highest reliability because of its "tracking" capability and is recommended for 8" double density designs.

Figure 12 illustrates a Counter/Separator utilizing a PROM as the count generator. Depending upon the RAW READ phase relationship to RCLK, the PROM is addressed and its data output is used as the counter value. A 16MHz clock is required for 8" double density, while an 8MHz clock can be used for single density.

ADDRESS	DATA	ACTION TAKEN
00	01	NONE
01	01	RETARD BY 1 COUNT
02	02	
03	03	
04	03	RETARD BY 2 COUNTS
05	04	
06	05	
07	06	
08	08	ADVANCE BY 2 COUNTS
09	00	
0A	0C	
0B	0E	
0C	0F	ADVANCE BY 1 COUNT
0D	00	
0E	00	
0F	01	
10	01	FREE RUN
11	02	
12	03	
13	04	
14	05	
15	06	
16	07	
17	08	
18	09	
19	0A	
1A	0B	
1B	0C	
1C	0D	
1D	0E	
1E	0F	
1F	00	

74LS288 PROGRAMMING TABLE

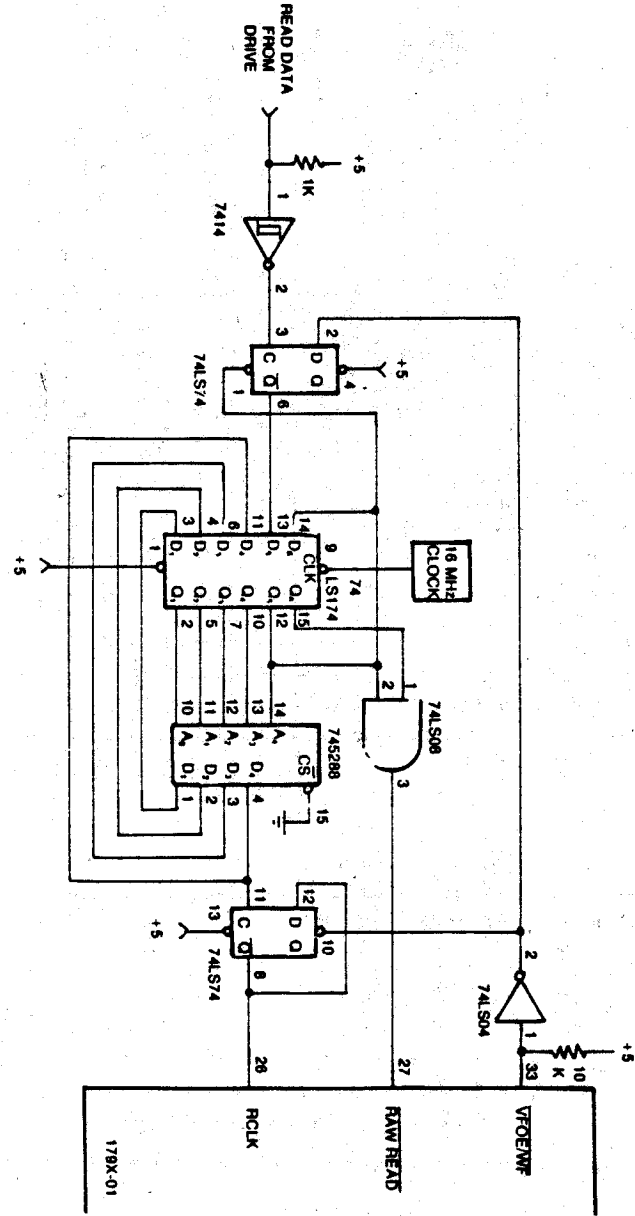
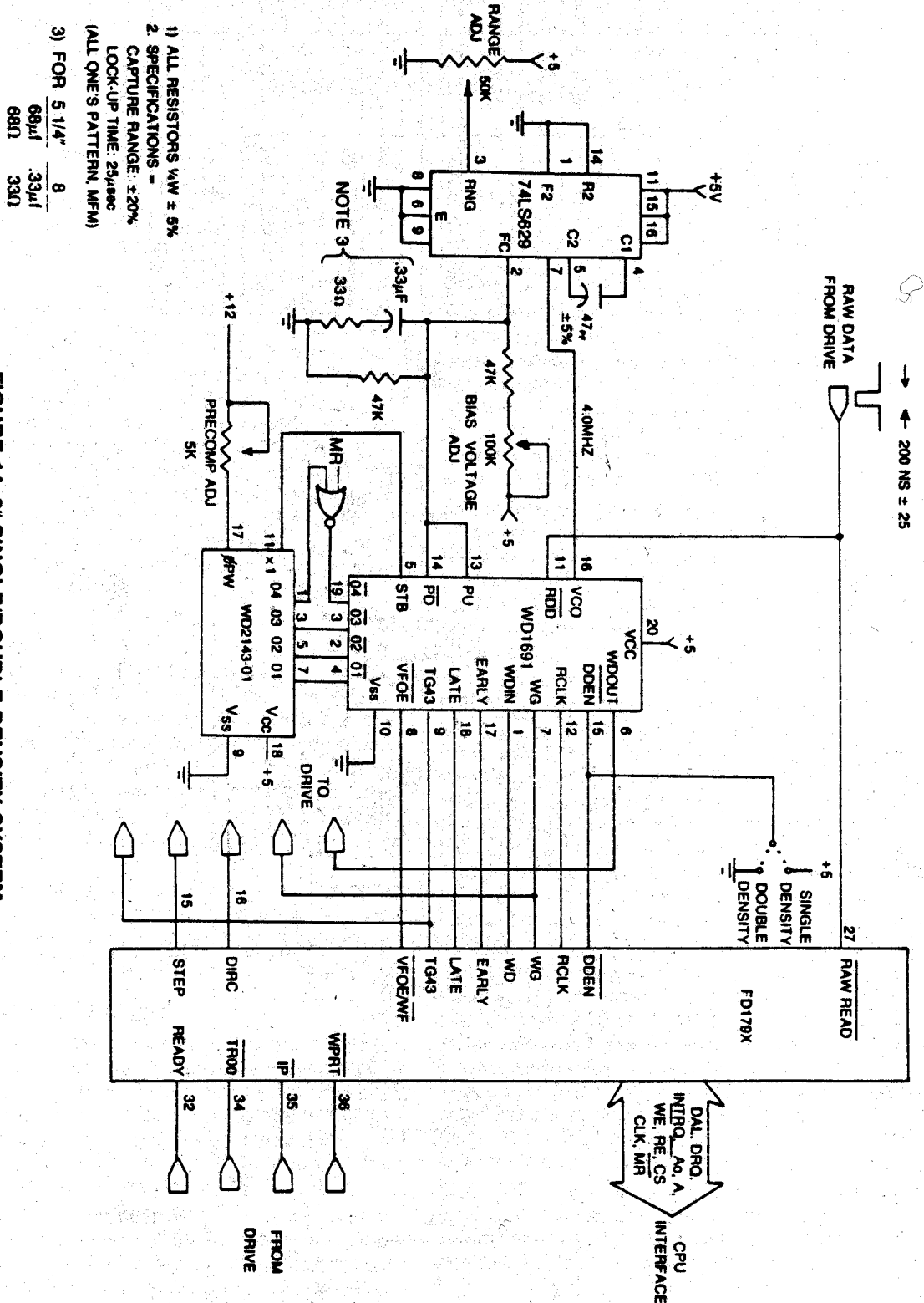


FIGURE 12. 179X DATA SEPARATOR

(PROVIDED COURTESY OF ANDROMEDA SYSTEMS, PANORAMA CITY, CA 91402)

Figure 14 illustrates a PPL data recovery circuit using the Western Digital 1691 Floppy Support device. Both data recovery and Write Precomp Logic is contained within the 1691, allowing low chip count and PLL reliability. The 74S124 supplies the free-running VCO output. The PUMP UP and PUMP DOWN signals from the 1691 are used to control the 74S124's frequency.



**ADVANCE
INFORMATION**

WESTERN DIGITAL CORPORATION

WD2143-01 Four Phase Clock Generator

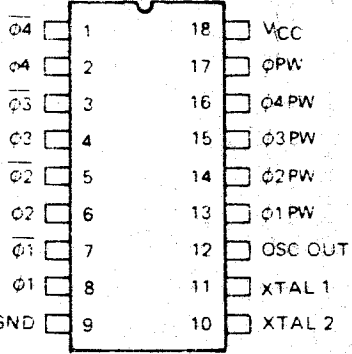
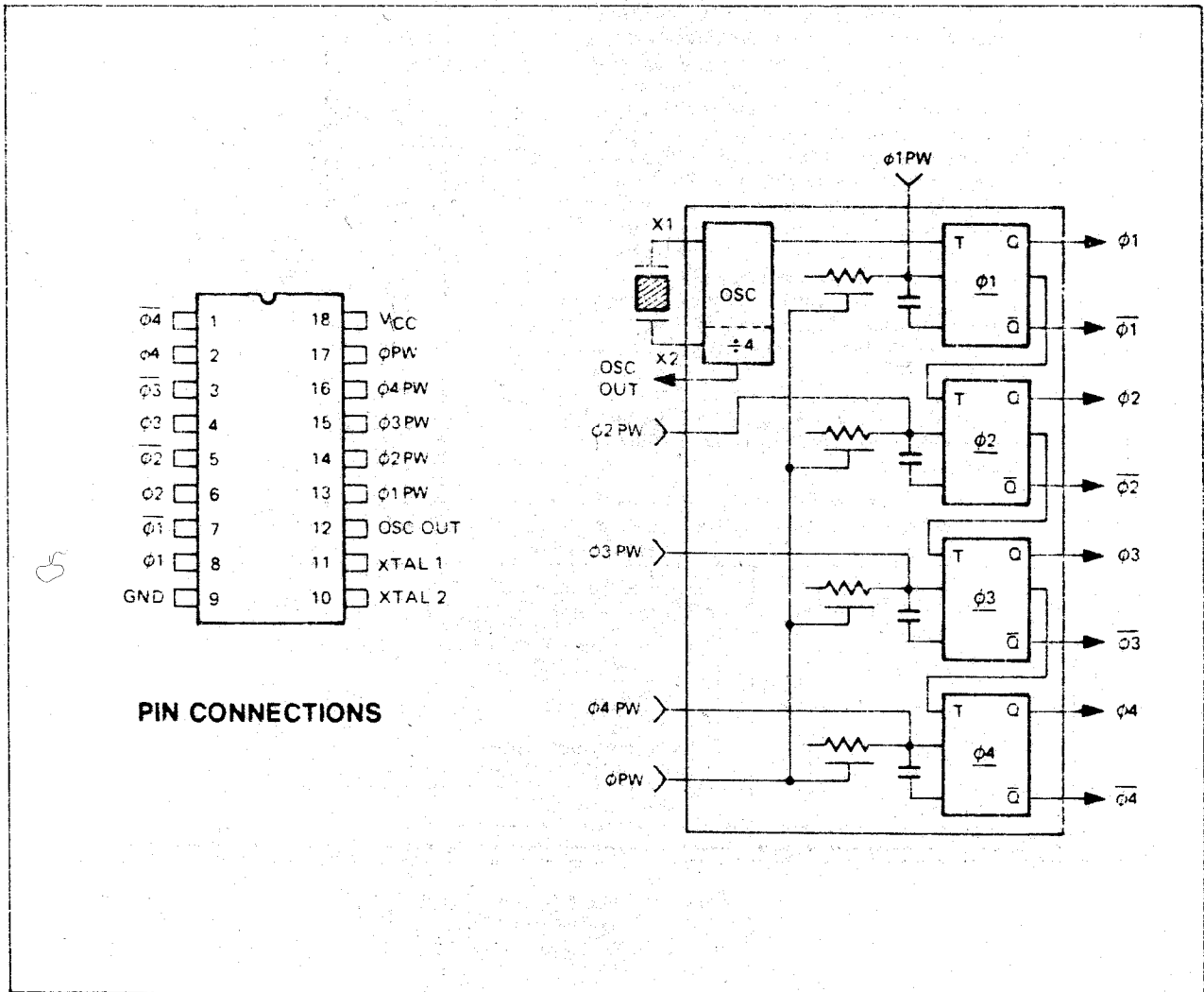
FEATURES

- TRUE AND INVERTED OUTPUTS
- SINGLE 5 VOLT SUPPLY
- TTL COMPATIBLE
- ON CHIP OSCILLATOR
- XTAL OR TTL CLOCK INPUTS
- 3 MHz OPERATION
- TTL CLOCK OUTPUT
- PROGRAMMABLE PULSE WIDTHS
- PROGRAMMABLE PHASE WIDTHS
- NO EXTERNAL CAPACITOR
- NON-OVERLAPPING OUTPUTS

GENERAL DESCRIPTION

The WD2143-01 Four-Phase Clock Generator is a MOS/LSI device capable of generating four non-overlapping clocks. The output pulse widths are controlled by tying an external resistor to the proper control inputs. All pulse widths may be set to the same width by tying the ϕPW line through an external resistor. Each pulse width can also be individually programmed by tying a resistor through the appropriate $\phi 1PW - \phi 4PW$ control inputs. In addition, the OSC OUT line provides a TTL square wave output at a divide-by-four of the crystal frequency.

September 1980



PIN CONNECTIONS

WD2143-01 BLOCK DIAGRAM