

CHAPTER 1 GENERAL

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As various number systems are in use, such as binary, decimal, hexadecimal, etc., the base or radix of a number system is placed as a subscript to the lower right of a number to identify whether the number is decimal, hexadecimal, octal, or binary as shown in Fig. 1-3.

1001 ₂	(Binary 1001)
10 ₈	(Octal 10)
10 ₁₀	(Decimal 10)
10 ₁₆	(Hexadecimal 10)

Fig. 1-3 Number Notation (with Base m)

Unless otherwise specified, the hexadecimal notation is used throughout this manual to express the contents of memory and registers which are represented by binary numbers. Characters represented by ASCII codes may be enclosed by single quotation marks (ex: 'ABCD'). Symbol Δ represents a space.

The MCU is provided with the internal registers shown in the following Table. The registers are abbreviated as follows.

Table 1-1 Internal Registers

Address	Register	Abbreviation
00	Port 1 Data direction register	DDR1
01	Port 2 Data direction register	DDR2
02	Port 1 Data register	PORT 1
03	Port 2 Data register	PORT 2
04	Port 3 Data direction register	DDR3
05	Port 4 Data direction register	DDR4
06	Port 3 Data register	PORT 3
07	Port 4 Data register	PORT 4
08	Timer control and status register	TCSR
09	Counter (high-order bytes)] FRC
0A	Counter (low-order bytes)	
0B	Output compare register (high-order bytes)] OCR
0C	Output compare register (low-order bytes)	
0D	Input capture register (high-order bytes)] ICR
0E	Input capture register (low-order bytes)	
0F	Port 3 control and status register	
10	Rate and mode control register	RMCR
11	Transmit/receive control and status register	TRCSR
12	Receive data register	RDR
13	Transmit data register	TDR
14	RAM control register	
15 to 1F	Reserved	

CHAPTER 1 GENERAL

1.1 Descriptive Expressions Used in This Manual

The HX-20 incorporates two HD6301 microprocessors. One of the microprocessors has a 64K-byte memory area to control the entire HX-20 components and is called the master MCU (Micro Computer Unit). The other plays an auxiliary role. Namely, it controls I/O devices such as the microprinter, cassettes, etc., and is called the slave MCU. Each MCU has a CPU, a ROM, a RAM, a serial I/O port, a parallel I/O port, and timer function. Fig. 1-1 shows the arrangement of the registers in the CPU.

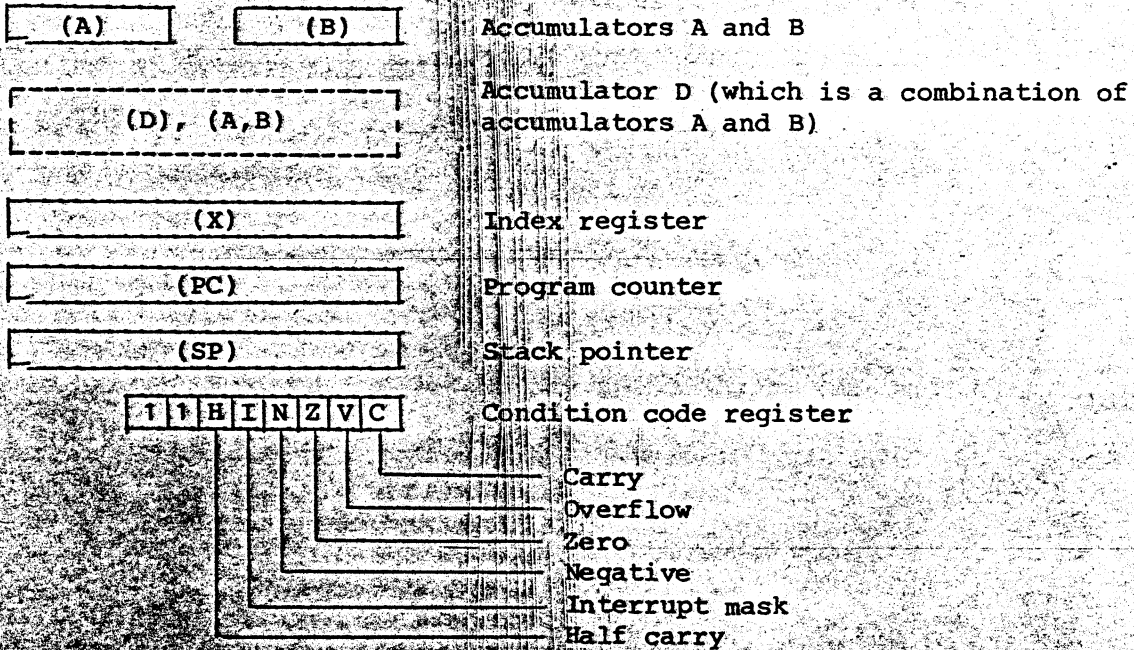


Fig. 1-1 Arrangement of CPU Registers

The registers are identified by symbols: (A) for accumulator A, (B) for accumulator B, (D) or (A,B) for accumulator D, (X) for the index register, (PC) for the program counter, and (SP) for the stack pointer. For the condition code register, (H), (I), (N), (Z), (V), and (C) are used to indicate the respective bits as shown in Fig. 1-1.

As shown in Fig. 1-2, bit positions are indicated from the bit lowest place with the lowest place value (or weighting) at the extreme right such as bit 0, bit 1 ... This bit with the lowest place value is called LSB (Least Significant Bit), while the bit with the highest place value (at the extreme left) is called MSB (Most Significant Bit).

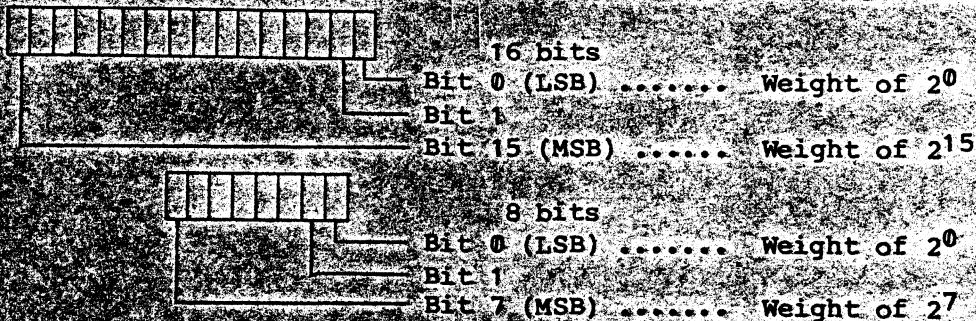


Fig. 1-2 Bit Positions

1.2 Sample Program Format

Table 1-3 shows the standard format of a sample program.

Table 1-3 Standard Format of Sample Program

Column number	Description	
1 to 5	Error message flag	
6 to 10	Source line number (decimal)	
11	Location counter section flag (see Note 1.)	
13 to 16	Location counter value (hexadecimal)	
18 to 19	Operation code (hexadecimal)	
21 to 28 Part which depends on instructions	Non-branch instructions	
	21 to 22	First byte of operand
	23 to 24	Second byte of operand
	26	Section flag of operand (See Note 2.)
	Branch instructions	
	21 to 22	Relative address of branch destination
	24 to 27	Location address of branch destination
	28	Branch error warning flag ("*" is displayed if relative address is in the range \$70 to \$90.)
	30 to 31	M1, M2, M3, M4: Macroexpansion statements (The digit following "M" indicates the nesting level.) IF: Statement skipped by the IF control instruction
35 to 40	Label field	
42 to 47	Operation field	
49 to 56	Operand field	
58 to last column	Comment field	

Table 2 lists the abbreviations for the respective bits of each internal register.

Table 2 Bits of Internal Registers and Their Abbreviations

Address register	Bit	Abbreviation
02 Port 1	0	P10
	1	P11
	2	P12
	3	P13
	4	P14
	5	P15
	6	P16
	7	P17
03 Port 2	0	P20
	1	P21
06 Port 3	0	P30
	1	P31
	2	P32
	3	P33
	4	P34
	5	P35
	6	P36
	7	P37
07 Port 4	0	P40
	1	P41
	2	P42
	3	P43
	4	P44
	5	P45
	6	P46
	7	P47
08 TCSR	0 (Output level)	OLVL
	1 (Input edge)	IEDG
	2 (Enable timer overflow interrupt)	ETOI
	3 (Enable output compare interrupt)	EOCI
	4 (Enable input capture interrupt)	EICI
	5 (Timer overflow flag)	TOF
	6 (Output compare flag)	OCF
	7 (Input capture flag)	ICF
11 TRCSR	0 (Wake up)	WU
	1 (Transmit enable)	TE
	2 (Transmit interrupt enable)	TIE
	3 (Receive enable)	RE
	4 (Receive interrupt enable)	RIE
	5 (Transmit data register empty)	TDRE
	6 (Overrun framing error)	ORFE
	7 (Receive data register full)	

1.3 How to Read Subroutine Lists

The subroutine lists in each chapter contain the subroutine names, entry points, descriptions of subroutines, and parameters. The parameters shown are divided into those to be output for subroutine call and those to be input for subroutine return. In describing the CPU registers, symbols are used: (A) for accumulator A, (B) for accumulator B, and (X) for the index register. For the condition code register, (C) stands for carry, (N) for a negative flag, and (Z) for a zero flag. Details of registers are listed under "Registers retained". "Subroutines referenced" lists the subroutines called in the course of execution. The I/O routines normally use addresses 0050 to 0077 as a work area. The actual locations used are represented as variables. (See Chapter 13.)

"(C): Abnormal I/O flag" appears quite often in the description of parameters at the time of subroutine return. This indicates that the I/O operation has not been performed correctly due to a drop in voltage, the power switch being turned OFF, or the BREAK key being pressed. (C)=1 indicates abnormal I/O operation and (C)=0 indicates normal I/O operation.

Line No.	Location	Operation code	Operand	Label field operation	Operend field	Comment field
00001						NAM MULT16
00002						TTL *** 16 BITS UNSIGNED MULTIPLY ***
00003						
00004						OPT PAGE=55
00005A	1000					ORG X1000
00006						
00007						* 16 BIT UNSIGNED MULTIPLY (16 BIT RESULT)
00008						* REENTRANT CODE (USES 6 BYTES ON STACK)
00009						* 4,0 TIMES X RESULT A,D
00010						
00011						MPY16 PSH B
00012A	1090 37					PSH A
00013A	1001 36					PSHX
00014A	1002 3C					TSX
00015A	1003 30					
00016						* STACK NOW LOOKS LIKE
00017						* +0 MS BYTE MULTIPLICATION * A * D
00018						* +1 LS BYTE * * C D
00019						* +2 MS BYTE MULTIPLIER * * * * * ---
00020						* +3 LS BYTE * * * * * BD
00021A	1004 A6 02	A				LDA A 2,X * A * D
00022A	1006 E6 01	A				LDA B 1,X * * AD
00023A	1008 30					MUL * * * * * RC
00024A	1009 37					PSH B * * * * * AC
00025A	100A A6 03	A				LDA A 3,X * * * * * X Y Z
00026A	100C E6 00	A				LDA B 0,X * * * * *
00027A	100E 30					MUL * * * * *
00028A	100F 37					PSH B * * * * *
00029A	1010 A6 03	A				LDA A 3,X * * * * * B * D
00030A	1012 E6 01	A				LDA B 1,X * * * * *
00031A	1014 3D					MUL * * * * *
00032A	1015 30					TSX * * * * *
00033A	1016 AB 00	A				ADD A 0,X * * * * *
00034A	1018 AB 01	A				ADD A 1,X * * * * *
00035A	101A 30					PULX * * * * *
00036A	101B 38					PULX * * * * *
00037A	101C 38					PULX * * * * *
00038A	101D 39					RYS * * * * *
00039						END * * * * *
00039						***** TOTAL ERRORS 0 *****

Fig. 4 Example of Program List Format

ERR SEQ LOC OBJECT PROGRAM MULT16 --- 16 BITS UNSIGNED MULTIPLY ---

```

00001          NAM      MULT16
00002          TTL      --- 16 BITS UNSIGNED MULTIPLY ---
00003          *
00004          * FILE NAME 'EXS3' BY K.A
00005          OPT      PAGE=55
00006          OPT      LOAD
00007          *
00008A 1000          ORG      $1000
00009          *
00010          * 16 BIT UNSIGNED MULTIPLY (16 BIT RESULT)
00011          * REENTRANT CODE (USES 6 BYTES ON STACK)
00012          *
00013          * A,B TIMES X RESULT A,B
00014          *
00015A 1000 37      MPY16  PSH B
00016A 1001 36          PSH A
00017A 1002 3C          PSHX
00018A 1003 3D          TSX
00019          *
00020          * STACK NOW LOOKS LIKE
00021          * +0 MS BYTE MULTIPLICATION          *      A B
00022          * +1 LS BYTE                          *      * C D
00023          * +2 MS BYTE MULTIPLIER              *      -----
00024          * +3 LS BYTE                          *      BD
00024A 1004 A6 02      LDA A  2,X          * A * D
00025A 1006 E6 01      LDA B  1,X          *      AD
00026A 1008 3D          MUL                      *      BC
00027A 1009 37          PSH B                      *      AC
00028A 100A A6 03      LDA A  3,X          *      -----
00029A 100C E6 00      LDA B  0,X          *      X Y Z
00030A 100E 3D          MUL                      *
00031A 100F 37          PSH B                      *
00032A 1010 A6 03      LDA A  3,X          * B * D
00033A 1012 E6 01      LDA B  1,X          *
00034A 1014 3D          MUL                      *
00035A 1015 3D          TSX                      *
00036A 1016 AB 00      ADD A  0,X          *
00037A 1018 AB 01      ADD A  1,X          *
00038A 101A 38          PULX          * CLEAN UP STACK
00039A 101B 38          PULX
00040A 101C 38          PULX
00041A 101D 39          RTS
00042          END

```

***** TOTAL ERRORS 0

3

4

5

6

CHAPTER 2 INPUT FROM KEYBOARD

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2.1 General

The keyboard, connected to the master MCU, has 8 lines each of which fetches 10 data. In other words, the keyboard is an 8 x 10 matrix structure. The pressed key can be found by inputting the data for each line. Interrupt IRQ1 occurs each time a key is pressed. The keyboard matrix incorporates the Printer ON/OFF and DIP switches in addition to the alphanumeric keys.

Key input is processed by interrupts and input data is stored in the 8-byte key stack. A power ON key stack, which stores data to be input automatically from the keyboard when the power is turned ON, is also provided. The contents of the power ON key stack are first fetched and the data in the key stack is input when the power ON key stack becomes empty. The contents of the power ON key stack can be restored by turning the power ON (reset).

2.2 I/O Ports for Keyboard Input

Table 2.1 shows the I/O ports related to the keyboard input.

Table 2.1 I/O Ports Related to Keyboard Input

Address	Bit position	Definition
20	0	Output. Specifies scanning of L0 line. 0: Scanning enabled. 1: Scanning is not performed.
	1	Output L1
	2	Output L2
	3	Output L3
	4	Output L4
	5	Output L5
	6	Output L6
	7	Output L7
22	0	Input. Scan result D0 0: ON 1: OFF
	1	Input. Scan result D1 0: ON 1: OFF
	2	Input. Scan result D2 0: ON 1: OFF
	3	Input. Scan result D3 0: ON 1: OFF
	4	Input. Scan result D4 0: ON 1: OFF
	5	Input. Scan result D5 0: ON 1: OFF
	6	Input. Scan result D6 0: ON 1: OFF
	7	Input. Scan result D7 0: ON 1: OFF
26	4	Output. Key input interrupt mask 0: Mask 1: Mask open
28	0	Input. Scan result D8
	1	Input. Scan result D9
P15		Input. Key input interrupt flag 0: A keyboard input interrupt has occurred. 1: No keyboard input interrupt has occurred.

2.3 Key Scan

As shown in Fig. 2-1, ten data can be input from each of the eight lines connected to the keyboard. Line L0 inputs data from keys 0, 1, 2, 3, 4, 5, 6, 7, the PF1 key and DIP switch 1. In the same way, data from keys @, A, B, C, D, E, F, G, the PF3 key and DIP switch 3 are input through line L2. This means that to input all of the data from the keyboard, lines L0 to L7 must be selected in turn and the data fetch operation repeated eight times.

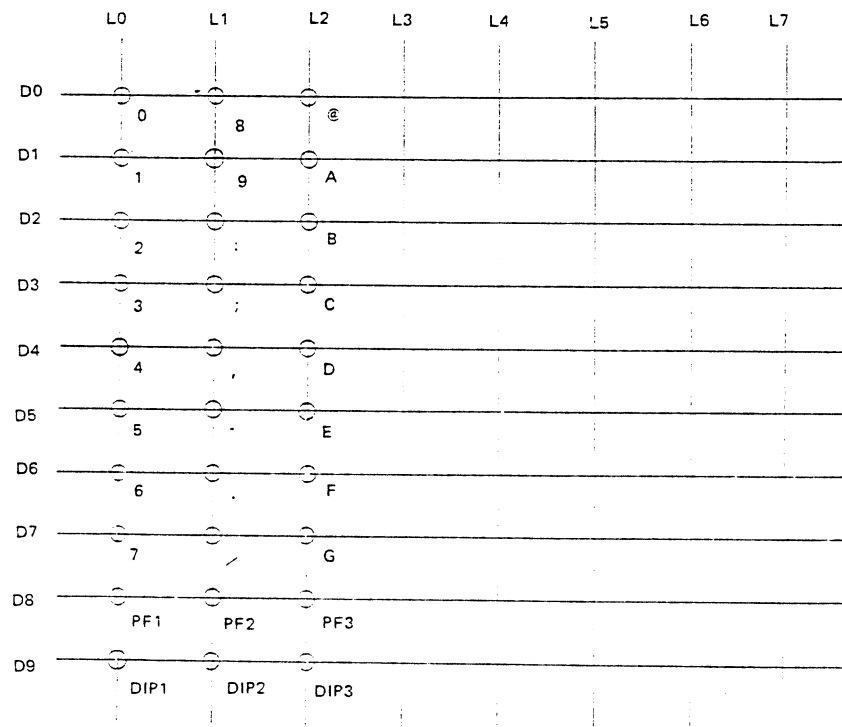


Fig. 2-1 Key Matrix

In some cases, data may not be input correctly from the keyboard due to this circuit configuration. For example, when keys 1, 8 and 9 are pressed, the circuit recognizes key 0 as having been pressed. That is, if key 9 is pressed while holding down keys 1 and 8, the input is recognized as 1, 8, 0. There are several such combinations which will cause incorrect data to be received. Key scan is performed by the following procedure.

(1) Close key input interrupt mask

P264 (bit 4 at address 26) is an IRQ1 key input interrupt mask. As an interrupt occurs if the key is pressed (i.e., the line to scan is specified and the key on the line is pressed) if this mask is open, the interrupt is disabled.

(2) Specify line to scan

There are 8 lines, L0 to L7, and any line can be specified for input. When line L0 is specified, the data on the line L0 can be input. If all lines L0 to L7 are specified, any key can be detected. The bit 0 at address 20 specifies line L0. When the

value of this bit is '0', scan is enabled and when '1', scan is not performed. The value FE (line L0 is scanned and the other lines are not scanned) is output first to address 20.

(3) Fetch data

When the contents of the address 22 are input, the data in D0 through D7 can be obtained. When the contents of address 28 are input, the data in D8 and D9 (bit 0, bit 1) can be obtained. (There is a wait of several tens of microseconds to obtain correct data after the line is specified.) Now, input from keys 0 to 7, PF1 and DIP switch 1 is enabled.

(4) Scan lines

Lines L1 through L7 are sequentially scanned and procedures 2 and 3 above are repeated. In this way all the data from the keyboard as well as the DIP switch values can be input. Table 2.2 shows the arrangement of the key matrix. Table 2.3 shows the arrangement of the keyboard matrix.

2.4 Keyboard input interrupt

An IRQ1 interrupt is enabled when the keyboard data is input. The following procedure is used to issue an IRQ1 interrupt.

(1) Specify the key line

The line where an interrupt occurs when a key is pressed is specified. Set '0' in address 20 to specify the key scan line. Once '0' is set, an interrupt occurs when any key is pressed. Note that the keys and switches on D9 such as DIP switches 1 to 4, shift key, control keys, and Printer ON/OFF switch are excluded from the keyboard input interrupt.

(2) Open the keyboard input interrupt mask

Write '1' to bit 5 of address 26 (P265) where the keyboard input interrupt mask is performed.

(3) Open the CPU interrupt mask

The CPU interrupt mask is opened by a CLI command.

(4) Confirm the keyboard interrupt

If the P15 is '0' when an IRQ1 interrupt occurs, it indicates the occurrence of the key input interrupt.

2.5 Timing of Key Input Process

An IRQ1 interrupt occurs when a key is input. Sampling (OCR interrupt) is performed using the MCU free running counter.

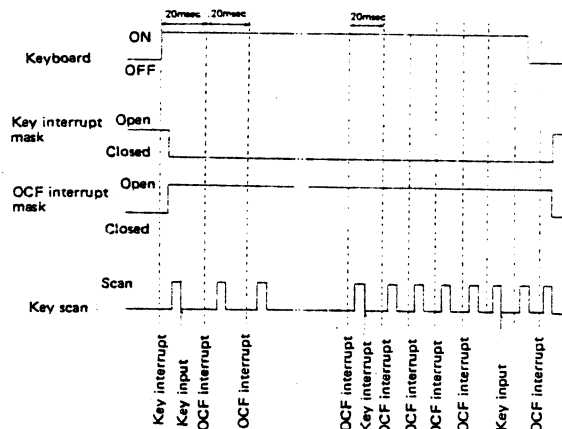


Fig. 2-2 Timing of Key Input

After a key is pressed as shown in Fig. 2-2, the Output Compare Register (OCR) issues interrupts at intervals of 20 msec (the key interrupt mask is closed) and auto repeat process is performed by key scan. If the same key is pressed continuously for a certain number of key scans after issuance of an OCF interrupt, it is assumed that the key has been newly pressed. The received data from the keyboard is stored in the First In, First Out (FIFO) key stack.

2.6 Automatic Key Input at Power ON

The 18-byte variable KYISTK contains key input data that can be specified by a monitor K command during reset (refer to Memory Map). When the value of the variable KYISFL is 0A, the KYISTK contains key input data. When the value is 0B, key input data is currently being fetched from the KYISTK. If the value of the KYISFL is 0B when the subroutine KEYIN (to fetch the key input data from the key stack) is called, the value obtained from the KYISTK is used as the key input data.

2.7 Key Input Subroutines

The following subroutines for key input are provided.

- (1) INITKY: Initializes the keyboard and sets the default value.
- (2) KEYSN: Performs the key scan operation and obtains input data from the pressed key.
- (3) KEYIN: Fetches one character from the key input buffer.
- (4) KEYSTS: Obtains the number of characters in the key input buffer.
- (5) KYSSTK: Specifies the automatic input key data.

2.8 Sleep Function

The MCU is provided with a sleep function to reduce power consumption when it is not functioning. The sleep mode is entered during execution of the KEYIN subroutine to wait for key input when the key input buffer is empty.

2.9 Special Keys

(1) BREAK key

When the BREAK key is pressed, the data is not taken into the key stack, but the I/O operation is cancelled. (Subroutine BREKIO is called.) Then, the break process is performed to the slave MCU and bit 7 of variables MIOSTS (address 007D) and SIOSTS (address 007C) become ON. The data input from the power ON key stack is cancelled. If bit 7 of the variable RUNMOD (address 007B) is '1', control returns from the key input interrupt. When bit 7 is '0', the subroutine is called starting at the address specified by address (0120, 0121). The default values of address (0120, 0121) is (FF, B2). The subroutine RSTRIO (re-start of I/O operation) is executed at the entry point of the address FFB2 and control jumps to the menu routine. In addition to the BREAK key, the specified subroutines are executed when the MENU, PAUSE, CTRL/PF3, CTRL/PF4 and CTRL/PF5 keys are pressed. Any addresses can be specified.

(2) MENU key

When the MENU key is pressed and bit 7 of the variable RUNMOD is '1', the code FC is input to the key stack and control returns from the interrupt. When bit 7 is '0', control returns from the interrupt after executing the subroutine starting at the address specified by address (0122, 0123).

(3) PAUSE key

When the PAUSE key is pressed, bit 6 of the variable MIOSTS becomes '1'. Then, control returns from the interrupt if bit 7 of the variable RUNMOD is '1'. If bit 7 is '0', control returns from the interrupt after executing the subroutine starting at the address specified by address (0124, 0125).

(4) CTRL/PF3, CTRL/PF4 and CTRL/PF5 keys

When the CTRL/PF3, CTRL/PF4 or CTRL/PF5 keys are pressed, control returns from the interrupt after executing the corresponding subroutine starting at the address specified by the address (0126, 0127), (0128, 0129) and (012A, 012B). If, for example, (FF, 10) (the entry point of Monitor) is written to the address (0126, 0127), the Monitor will be executed when the CTRL/PF3 keys are pressed.

2.10 Key Input Modes

The current key input mode (numeric and uppercase, shift, etc.) is indicated by the 1-byte variable KEYMOD. The address of this variable is (FFE4, FFE5). The current data in this address is 0169. Referring to the contents in the address, the current mode, (in this case, the keyboard mode) can be recognized. To force-set a certain mode, change the contents of the current address to those of the mode to be set. The following three modes are available.

Bit 1: Numeric mode

Bit 2: CAPS mode (lowercase letter mode is assumed when bit 2 is '1'.)

Bit 4: Graphic mode

Only one of these bits may be '1' or all of them may be '0'. The current mode is indicated by the bit which is '1'.

2.11 Changing Constants

The constants on the RAM are the following.

Key stack size, time interval until the second key input is accepted for auto repeat, time interval until the third or subsequent key input is accepted for auto repeat, sampling interval of key scan and power ON key stack. The default values for these constants are set when the keyboard is initialized. Values set after the default values have been set are used. (For details, refer to Memory Map).

Key scan

The keyboard value read by key scan is assigned to variable NEWKTB (10 bytes, starting address: FFD0, FFD1). Fig. 2-3 shows the format of the keyboard values read by key scan.

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
NEWKTB-0	D7(L0)	D8(L0)	D9(L0)	D0(L0)	D1(L0)	D2(L0)	D3(L0)	D4(L0)
NEWKTB-1	D7(L1)	D8(L1)						D0(L1)
NEWKTB-2	D7(L2)	D8(L2)						D0(L2)
NEWKTB-3	D7(L3)	D8(L3)						D0(L3)
NEWKTB-4	D7(L4)	D8(L4)						D0(L4)
NEWKTB-5	D7(L5)	D8(L5)						D0(L5)
NEWKTB-6	D7(L6)	D8(L6)						D0(L6)
NEWKTB-7	D7(L7)	D8(L7)						D0(L7)
NEWKTB-8	D8(L7)	D8(L6)	D8(L5)	D8(L4)	D8(L3)	D8(L2)	D8(L1)	D8(L0)
NEWKTB-9	D9(L7)	D9(L6)	D9(L5)	D9(L4)	D9(L3)	D9(L2)	D9(L1)	D9(L0)

Fig. 2-3 Key Scan Values

In this case, the DIP switches and the PRINTER ON/OFF switch are set according to the values at address 7F. (In other words, software specification takes precedence over the key scan specification.)

2.12 Tables

Table 2.2 Key Matrix

Line Return data	L 0	L 1	L 2	L 3	L 4	L 5	L 6	L 7
D 0	0 0 0	0 8 s	1 0 e	1 8 H	2 0 P	2 8 X	3 0 RET	3 8 CLR
D 1	0 1 1	0 9 9	1 1 A	1 9 I	2 1 Q	2 9 Y	3 1 SPACE	3 9 SCRN
D 2	0 2 2	0 A :	1 2 B	1 A J	2 2 R	2 A Z	3 2 TAB	3 A BREAK
D 3	0 3 3	0 B ;	1 3 C	1 B K	2 3 S	2 B [3 B PAUSE
D 4	0 4 4	0 C ,	1 4 D	1 C L	2 4 T	2 C]		3 C DEL
D 5	0 5 5	0 D -	1 5 E	1 D M	2 5 U	2 D Y	3 5 NUM	3 D MENU
D 6	0 6 a	0 E .	1 6 F	1 E N	2 6 V	2 E _		
D 7	0 7 -	0 F '	1 7 G	1 F O	2 7 W	2 F -	3 7 CAPS	
D 8	4 0 PF1	4 1 PF2	4 2 PF3	4 3 PF4	4 4 PF5	4 5 PAPER		
D 9	4 8 DIP1	4 9 DIP2	4 A DIP3	4 B DIP4		4 D SHIFT	4 E CTRL	4 F PRINT

Note: The hexadecimal values in the above Table indicate the positions of the key layout on the keyboard matrix table.

4F PR		45 WEFD											
2B PAUSE	3D MENU	3A BREAK	10 F1	11 F2	12 F3	13 F4	14 F5	35 NUM	38 CLR	39 SCRN	3C DEL		
01 1	02 2	03 3	04 4	05 5	06 6	07 7	08 8	09 9	00 0	0D -	2B 1	2C 2	3D 3
32 TAB	21 Q	27 W	15 E	22 R	24 T	29 Y	25 U	19 I	1F O	20 P	10 ;	2F -	2E -
4E CTRL	11 A	23 S	14 D	16 F	17 G	18 H	1A J	1B K	1C L	0B :	0A :	30 RETURN	
4D SHIFT	2A Z	28 X	13 C	26 V	12 B	1E N	1D M	0C ,	0E .	0F /	4D SHIFT		
37 CAPS			31					SPACE					

48 DIP SW1	49 DIP SW2	4A DIP SW3	4B DIP SW4
---------------	---------------	---------------	---------------

DIP switches

Fig. 2-4 Arrangement of the Keyboard Matrix

Note: The hexadecimal values in the above Table indicate the positions of the keys on the key table.

2.13 Keyboard Input Subroutines

Name of Subroutine	Entry Point	Description
INITKY	FFA0	<p>Initializes key input. Sets the initial values (including default values). Specifies the vectors jumped to when the BREAK, MENU, PAUSE, CTRL/PF3, CTRL/PF4, and CTRL/PF5 keys are pressed. Specifies default values for timing such as sampling time, etc. Specifies the number of key stack data, and the key stack used when the power is turned ON.</p> <p>°Parameters: At Entry None At Return None °Registers retained None °Subroutines referenced None °Variables used None</p>
KEYSTS	FF9D	<p>Inputs the number of key stack data (Excluding the key stack used when the power is turned ON.)</p> <p>°Parameters: At Entry None At Return (C): Abnormal I/O flag (A): Number of key stack data (in bytes) (Z): According to the value of (A) °Registers retained (B) and (X) °Subroutines referenced None °Variables used None Note: When a PF key is pressed, the number of stack data increases by 2.</p>
KEYIN	FF9A	<p>Inputs one character from the key stack. If no data exists in the key stack, this subroutine lets the MCU sleep and waits until data is input from the keyboard. If data exists in the key stack when the power is turned ON, this data is recognized as input data. If both key stack data and keyboard data are available, the key stack data take precedence over keyboard data.</p> <p>°Parameters: At Entry None At Return (C): Abnormal I/O flag (A,B): Character code. 1-byte codes are stored in (A) and 2-byte codes ((A)=FE) are stored in (A,B).</p>

Name of Subroutine	Entry Point	Description
		°Registers retained (X) °Subroutines referenced None °Variables used None
KEYSCN	FF6A	Scans the key matrix. The result of the key scan is stored in NEWKTB (10 bytes). Note that the DIP switches and Printer ON/OFF switch are set according to the value of the variable SDIPS2. The contents of NEWKTB are: <pre> Bit 7 Bit 6...Bit 0 NEWKTB+0: D7 D6 D0..... L0 NEWKTB+1: D7 D6 D0..... L1 NEWKTB+8: L7 L6 L1..... D8 NEWKTB+9: L7 L6 L1..... D9 </pre> °Parameters: At Entry None At Return None °Registers retained None °Subroutines referenced None °Variables used K0 and K1 (The values of these variables are retained.)
KYSSTK	FF22	Inputs data to the key stack when the power is turned ON. The size of the key stack is 18 bytes. If more than 18 bytes of data are input, the excess data is ignored. °Parameters: At Entry (X): Starting address of character strings (B): Number of characters (0 to 18: the key stack is cleared when the number is 0.) °Parameters: At Return None °Registers retained None °Subroutines referenced None °Variables used None

2.14 Keyboard Work Area

Address (from)(to)	Variable name	Bytes	Description
0140 0140	KSTKSZ	1	The size of the key stack. The default value is 8. May be specified in the range 1 to 15. If the value is '1', input of PF keys is not accepted.
0141 0141	KICNT1	1	Time until the first key input is accepted for auto repeat. The unit depends on sampling time. The default value for sampling time is 20 msec. The default value is 40 (800 msec).
0142 0142	KICNT2	1	Time until the second or subsequent key input is accepted for auto repeat. The unit are the same as those of KICNT1. The default value is 6 (120 msec).
0143 0144	KICNTM	2	Sampling time. The unit 1 equals approx. 1.6 μ sec. The default value is 12,288 (20 msec).
0145 014E	NEWKTB	10	Value of the key scan matrix. The status after the key scan is stored in this area. '1' denotes the ON condition. Bit 0 at the first address of the work area corresponds to 00 of the key matrix table and bit 7 corresponds to 07. In this manner, bit 7 of the last address corresponds to 4F.
014F 0158	OLDKTB	10	The value of the previous key scan. The previous value of NEWKTB is stored in this variable.
0159 0162	CHKKTB	10	Stores the data for the position of the newly pressed key after key scan.
0163 0164	KYISAD	2	Address of automatic key input when power is turned ON. Set to 016F at reset.
0165 0165	KYISFL	1	Flag indicating whether or not data exists in the key stack when power is turned ON. When this flag is 0A, data exists in the key stack but the fetch operation ends. When the flag is 0B, data is currently being fetched from the stack. If the flag is other than 0A and 0B, no data exists in the key stack.
0166 0166	KYISCN	1	The number of data in the automatic input key stack. Value is in the range 0 to 255.
0167 0167	KYISPN	1	The number of data input from the automatic key input. The number is in the range 0 to the value specified by KYISCN.
0168 0168	STKCNT	1	The number of data in the input key stack. The number is in the range 0 to the value specified by KSTKSZ.
0169 0169	KEYMOD	1	Input key modes. This address indicates the uppercase, numeric modes, etc.

Address (from)(to)	Variable name	Bytes	Description
			Bit 1: Numeric mode when this bit is '1'. Bit 2: Lowercase mode when this bit is '1'. Bit 3: Unused Bit 4: Graphic mode when this bit is '1'. Bit 5: SHIFT mode when this bit is '1'. Bit 6: The CTRL key has been pressed when this bit is '1'. Bit 7: Indicates that a special keys such as the BREAK, PAUSE, MENU or one of the PF keys has been pressed when this bit is '1'. One of bits 0 through 4 must be ON or all bits must be OFF.
016A 016A	ONKFLG	1	Indicates the key input status. 00: Inhibits key reception. Waits until the pressed key is released. FF: Key input enabled. 01: Auto repeat function
016B 016B	KPRFLG	1	For auto repeat, this variable indicates the number of times the same key input has been received. When this value equals that of KICNT1 or KICNT2, the pressed character is taken to be input once.
016C 016C	KEYRPT	1	Indicates the auto repeat key position on the matrix. Refer to the Matrix Table.
016D 016E	CKEYRD	2	Input key code A PF key is 2 bytes.
016F 0180	KYISTK	18	Work area for the power ON key stack
0181 0188	CHRSTK	8	Work area for the key stack
0189 018F		7	This area is secured for expansion of the key stack.

CHAPTER 3 LIQUID CRYSTAL DISPLAY (LCD)

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3.1 General

The Liquid Crystal Display (LCD) has a resolution of 120 horizontal dots and 32 vertical dots and LCD controllers which enable the specification of data for each dot.

6 LCD controllers together control the LCD, each of which controls an area 40 horizontal by 16 vertical dots.

Normally, a single character is displayed in a matrix of 6 horizontal by 8 vertical dots. Alphanumeric characters, however, are actually formed in a matrix 5 by 7 dots as spaces are left between characters on the screen.

3.2 Functions of LCD Controllers

As abovementioned, the 6 controllers together control the LCD.

The dot areas controlled by each controller are shown in Table 3-1.

Table 3-1 Dot Area Controlled by Each LCD Controller

	0	39 40	79 80	119
0	Controller 1	Controller 2	Controller 3	
7	(bank 0)	(bank 0)	(bank 0)	
8	Controller 1	Controller 2	Controller 3	
15	(bank 1)	(bank 1)	(bank 1)	
16	Controller 4	Controller 5	Controller 6	
23	(bank 1)	(bank 0)	(bank 0)	
24	Controller 4	Controller 5	Controller 6	
31	(bank 1)	(bank 1)	(bank 1)	

As shown in the table, each controller is responsible for an area of above of 40 by 16 dots.

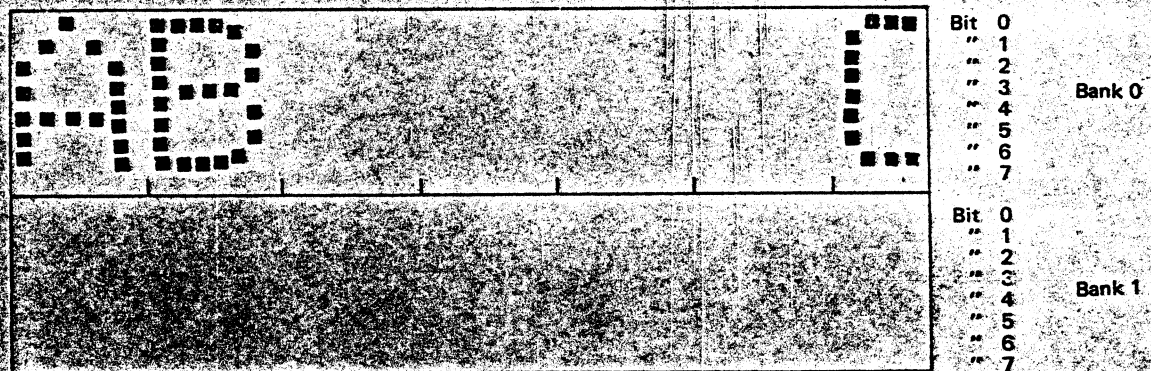


Fig. 3-1 Displayed Contents of Each LCD Controller

Each controller has data addresses 0 to 27₁₆ in the row direction. Data consists of 8 bits (Fig. 3-1).

3.3 I/O Ports for Display and Input

Table 3-2 I/O Ports Related to LCD Controllers

	Address	Bit position	Description	
Master MCU	26	0	Output Selection of LCD driver	
		1	1-6: Controllers 1 to 6 selected.	
		2	0: No controller is selected.	
			3	Output Selection of data or command for LCD driver
				0: Data
				1: Command
		28	7	Input BUSY signal of LCD controller
				0: Busy
		2A		Output Serial clock to LCD controller
		2B		Output Serial clock to LCD controller
		2A	0	Output Output data to LCD controller
			1	Output Output data to LCD controller
			2	Output Output data to LCD controller
	3		Output Output data to LCD controller	
	4		Output Output data to LCD controller	
	5		Output Output data to LCD controller	
	6		Output Output data to LCD controller	
	7		Output Output data to LCD controller	

3.4 Data Display Procedure

Data is displayed on the LCD by the following procedure.

(1) Selection of controller

One of the 6 controllers is selected by specifying an appropriate value in the bits 0 to 2 of address 26 using subroutine WRTP26. If 0 is specified, no controller is selected. System default is 0 for power conservation.

(2) Command setting

The bit 3 of address 26 is a bit used to select either data or command for the selected controller. When this bit is set to "1", a command is selected. This data/command selection may be performed simultaneously with the controller selection described in (1) above. Set a command in address 2A and confirm that the LCD controller is ready (when the bit 7 of address 28 is "1"). Then apply 8 serial clock pulses to the controller. (Address 2A is read 8 times. Since address 2B is also for serial clock input, 8 serial clock pulses are given to the controller upon execution of "LDD\$2A" 4 times.)

(3) Data

When the bit 3 of address 26 is set to "0", data is selected. The data setting procedure is the same as the command setting described above. Depending on the type of command, data must be continuously output for display.

3.5 Input of Display Data

The bit indicating that the controller is busy (i.e., bit 7 of address 28) becomes the input data for display.

3.6 Display Subroutines

The HX-20 has the following three subroutines for character display:

- (1) DSPLCN: Displays n characters of data (ASCII code) on the physical screen.
- (2) DSPLCH: Displays one character of data (ASCII code) on the physical screen.
- (3) DISPIT: Displays one character of data (ASCII code) on the physical screen.

3.7 Coordinates on the LCD

(x,y) indicates the coordinates on the LCD. x is the coordinate in the horizontal directions (columns) and y is the coordinate in the vertical direction (rows). (0,0) indicates that the positions of both the vertical and horizontal coordinates are the upper left edge of the LCD. The values of x,y coordinates on the text screen must be in the range shown below.

$$0 < x < 19 \quad \text{and} \quad 0 < y < 3$$

The values of x,y coordinates on the graphic screen must be in the range shown below.

$$0 < x < 119 \quad \text{and} \quad 0 < y < 31$$

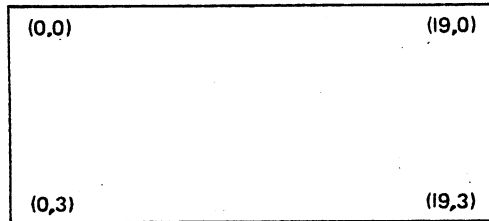


Fig. 3-2 Coordinates on the LCD (Text Screen)

3.8 LCD Subroutines

Subroutine name	Entry point	Description
DSPLCN	FF49	Displays or clears n characters on the physical screen.
		<p>Parameters:</p> <p>At Entry</p> <p>(B): Number of characters displayed The screen is cleared when (B) is 0.</p> <p>(x): Starting address of data packet This parameter need not be specified when (B) is 0.</p> <p>Data packet</p> <p>Byte 0: x coordinate (0 to 19₁₀) of the display position of the first character.</p> <p>Byte 1: y coordinate (0 to 3₁₀) of the display position of the first character.</p> <p>Byte 2: Character code (ASCII)</p> <p>Byte 3: Character code (ASCII)</p> <p>Byte n+1: Character code (ASCII)</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>None</p> <p>Subroutines referenced</p> <p>'DSPLCH'</p> <p>Variables used</p> <p>None</p>
DSPLCH	FF4C	Displays one character on the physical screen. The display data is first written into the screen buffer PSBUF.
		<p>Parameters:</p> <p>At Entry</p> <p>(A): ASCII character code</p> <p>(X): Display position on LCD (high, low)=x coordinate (0 to 19), y coordinate (0 to 3)</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>(A), (B), and (X)</p> <p>Subroutines referenced</p> <p>CHRGEN, LCDMOD and DATMOD</p> <p>Variables used</p> <p>None</p>
DISPIT	FF5B	<p>Displays one character on the physical screen. The display data is not written into the screen buffer (PSBUF).</p> <p>Parameters at entry and return, registers retained, subroutines referenced and variables used are the same as those for subroutine DSPLCH.</p>

Subroutine name	Entry point	Description																																																												
CHRGEN	FF67	<p>Generates the character pattern. A character pattern (6x8 dots) is provided for display of the character specified by the ASCII code on the LCD. Certain character patterns may change according to the value set by the DIP switch for different countries.</p> <p>Parameters: At entry (A): Character code (X): Starting address where 6-byte character display pattern is stored</p> <p>At Return Character display pattern (specified address)</p> <div style="text-align: center;"> <table border="1" style="margin: auto;"> <tr> <td></td> <td style="text-align: center;">Bit 7</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td style="text-align: center;">Bit 0</td> </tr> <tr> <td style="text-align: right;">Specified address</td> <td style="text-align: center;">0</td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;">0</td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td style="text-align: right;">Specified address 15</td> <td style="text-align: center;">0</td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;"> </td> <td style="text-align: center;">0</td> </tr> </table> </div> <p style="text-align: right;">Display pattern of character "A" Unspecified bits are logic 0.</p> <p>Registers retained None Subroutines referenced None Variables used None Others Re-entrant</p>		Bit 7								Bit 0	Specified address	0								0																															Specified address 15	0								0
	Bit 7								Bit 0																																																					
Specified address	0								0																																																					
Specified address 15	0								0																																																					

3.9 Screen Routine Work Area

Address	Variable name	No. of bytes	Description
220 26F	PSBUF	80	Positions of data (ASCII codes) displayed on the physical screen represented in (column, row) format as follows: (0,0), (1,0) ... (19 ₁₀ , 0) (0,1) ... (19 ₁₀ , 3)
270 271	SCRTOP	2	Starting address of the virtual screen buffer
272 273	SCRBOT	2	Ending address of the virtual screen buffer
274 275	DISTOP	2	Starting position of the physical screen on the virtual screen The address of position (0,0) of the physical screen in the physical screen buffer
276 276	VSCRX	1	Virtual screen width indicated as the maximum values of x coordinate.
277 277	VSCRY	1	Virtual screen length indicated as the maximum value of y coordinate.
278 278	CURX	1	x coordinate of the cursor position (on the physical screen)
279 279	CURY	1	y coordinate of the cursor position (on the physical screen)
27A 27A	LRMODE	1	Scroll step x (left and right)
27B 27B	UDMOD	1	Scroll step y (up and down)
27C 27C	CURMRG	1	Scroll margin (1 through 10)
27D 27D	SSPEED	1	Vertical scrolling speed (0 to 9) When the scrolling speed is set at 8, there is a 130-msec wait between each scroll. This wait is increased in 130-msec increments for each setting: 7,6,5 ... 0. When a scrolling speed of 9 is specified, there is no wait between vertical scrolls.
27E 27E	DISPX	1	x coordinate (0 to 19 ₁₀) of the character to be displayed on the physical screen by a virtual screen routine
27F 27F	DISPY	1	y coordinate (0 to 3) of the character to be displayed on the physical screen by a virtual screen routine
280 280	DISSTS	1	Indicates the display status. Bit 0: Indicates whether or not left and right scrolling is permitted. 1: Scrolling disabled 0: Scrolling enabled Bit 1: Not used Bit 2: Not used Bit 3: Not used Bit 4: Indicates whether or not there is a wait in vertical scrolling. 1: Wait executed

Address	Variable name	No. of bytes	Description
			<p>Bit 5: Cursor ON/OFF switch Determines whether the cursor ('_' below the character) will be displayed on the physical screen. 1: Cursor ON 0: Cursor OFF</p> <p>Bit 6: Indicates cursor ON/OFF status. 1: Cursor ON 0: Cursor OFF</p> <p>Bit 7: Flag to indicate whether or not the entire screen is to be rewritten 0: Display for only one character 1: Rewrites for entire screen.</p> <p>Note: All screen data must be checked and rewritten even if only one character is to be displayed. However, since doing this adversely affects operating speed, this switch is used to reduce the amount of screen data checked and rewritten. Bits 5 and 6 The following two operations are required to display a character at the cursor position and then move the cursor to the next position:</p> <ol style="list-style-type: none"> 1. Display of the character at the cursor position The cursor is turned OFF and the character is displayed at the cursor position. 2. Cursor movement A space character is displayed where the cursor is ON. Bit 5 is used to control cursor ON/OFF condition and bit 6 determines whether the cursor will be displayed on the screen.
281 285		5	Used as temporary work area.
286 28B	CHRPTN	6	Contains the character font (result of subroutine CHRGEN).

ERR SEQ LOC OBJECT PROGRAM LCD -----LCD DRIVER ROUTINE-----

```

00056          * REGISTER PRESERVE (X) <--- (A,B)
00057          *
00058          DPCHEK EQU      *
00059A 1000 72 017D A      OIM      #$1,MIOSTS * SET FLAG   LCD IS ON WRITING
00060A 1003 37          PSH B
00061A 1004 36          PSH A
00062A 1005 3C          PSHX
00063A 1006 CE 0286 A    LDX      #CHRPTL * SET CHARACTER PATTERN TO "CHRPTL"
00064A 1009 BD FF67 A    JSR      CHRGEN
00065A 100C 32          PUL A
00066A 100D 33          PUL B
00067A 100E 38          PULX
00068A 100F 81 13      A      CMP A   #19      * NOTE. (X) <---> (A,B)
00069A 1011 25 02 1015  BCS     NONOVX   * IS COLUMN LIMIT OUT OF RANGE ?
00070A 1013 86 13      A      LDA A   #19      * NO.
00071A 1015 C4 03      A      NONOVX AND B #3 * YES. LIMIT= 19
00072          *
00073A 1017 39          RTS
00074          *
00075          **
00076          * DISPLAY ONE CHARACTER TO REAL SCREEN WITHOUT WRITING TO SCREEN BUFFER
00077          * ON ENTRY
00078          * (A): CHARACTER (ASCII CODE)
00079          * (X): DISPLAY ADDRESS (HIGH:COLUMN, LOW:LINE)
00080          *
00081          * ENTRY POINT
00082          DISPIT EQU     *
00083A 1018 8D E6 1000  BSR     DPCHEK
00084A 101A 3C          PSHX      * SAVE VALUE OF (A,B)
00085A 101B 2D 15 1032  BRA     NONSET
00086          * ENTRY POINT
00087          DSPLCH EQU    *
00088A 101D 8D E1 1000  BSR     DPCHEK
00089          *
00090A 101F 3C          PSHX      * SAVE (A,B)
00091          *
00092A 1020 37          PSH B
00093A 1021 36          PSH A
00094A 1022 86 14      A      LDA A   #20
00095A 1024 3D          MUL
00096A 1025 30          TSX
00097A 1026 E5 00      A      ADD B   0,X      * ADDRESS OFFSET <--- (B)*WIDTH + (A)
00098A 102B A6 02      A      LDA A   2,X
00099A 102A CE 0220 A   LDX     #PSBUF   * (X) <--- PHYSICAL SCREEN BUFFER ADDRESS
00100A 102D 3A          ABX
00101A 102E A7 00      A      STA A   0,X
00102A 1030 32          PUL A
00103A 1031 33          PUL B
00104          *CALCULATE ADDRESS IN LCD DRIVER
00105          NONSET EQU    *
00106A 1032 37          PSH B      * SAVE LOCATION POINTER (X,Y)
00107A 1033 36          PSH A
00108          *
00109          * ALREADY SAVE FOUR BYTES
00110          * STACK+0: COLUMN,   STACK+1:LINE
          * STACK+2: (A)          STACK+3:(B)

```

ERR SEQ LOC OBJECT PROGRAM LCD -----LCD DRIVER ROUTINE-----

```

00001          NAM      LCD
00002          *
00003          * LCD DRIVER'S ROUTINE
00004          TTL      -----LCD DRIVER ROUTINE-----
00005          * FILE NAME 'EX$9' BY K.A
00006          OPT      LOAD
00007          OPT      PAGE=55
00008          *
00009          * I/O PORT
00010          * $28
00011          *       7:R LCD DRIVER BUSY (0:BUSY 1:READY)
00012          *
00013          * $26
00014          *       0:W LCD COMMAND/DATA 1
00015          *       1:W LCD COMMAND/DATA 2
00016          *       2:W LCD COMMAND/DATA 4
00017          *       3:W LCD COMMAND/DATA SELCTION (0:DATA 1:COMMAND)
00018          *       4:W KEY BOARD INTERRUPT MASK (0:CLOSE 1:OPEN)
00019          *       5:W PERIPHERAL CONTROL (TO SERIAL)
00020          *       6:W TO PLUG IN 1
00021          *       7:W TO PLUG IN 2 AND SLAVE P40
00022          *
00023          * SUBROUTINE ENTRY POINT
00024          FED4  A    WRTP26 EQU    $FED4
00025          FF67  A    CHRGEN EQU    $FF67
00026          * WORK AREA
00027          007D  A    MIOSTS EQU    $7D          * MAIN I/O STATUS
00028          *                                           * BIT 0: ON READ/WRITE TO LCD 1:READING/WRITING
00029          0286  A    CHRPTL EQU    $286        * WORK AREA TO STORE CHARACTER PATTERN
00030          0220  A    PSBUF  EQU    $220        * CHARACTER CODES ON PHISICAL SCREEN.
00031          0280  A    DISSTS EQU    $280        * DISPLAY STATUS
00032          *                                           * . BIT 5: CURSOR ON WITH CHARACTER PATTERN FLA
00033          *                                           * (1:ON)
00034          *
00035          *
00036A 1000          ORG      $1000
00037          *
00038          * DISPLAY ONE CHARACTER TO REAL LCD SCREEN
00039          * ROUTINE 'DISPIT': DISPLAY 1 CHARACTER TO LCD WITHOUT SUFFER
00040          * 'DISPCH': DISPLAY ONE CHARACTER TO LCD AND WRITE TO SUFFER
00041          * ON ENTRY
00042          * (A): ASCII CHARACTER CODE
00043          * (X): LCD POSITION (HIGH:COLUMN, LOW:LINE)
00044          * ON EXIT
00045          * (X): NEXT DATA POSITION (IF ILLEGAL ADDRESSING, CHANGE TO LEGAL)
00046          * REGISTER PRESERVE A,B
00047          *
00048          *
00049          *
00050          * CHECK DISPLAY POSITION AND GENERATE CHARACTER FONT
00051          * ON ENTRY
00052          * (X):DISPLAY ADDRESS (HIGH BYTE:COLUMN, LOW BYTE:LINE)
00053          * (A):DISPLAYED CHARACTER
00054          * ON EXIT
00055          * (A,B):MODEFIED POSITION

```

```

ERR  SEQ  LOC  OBJECT  PROGRAM  LCD  -----LCD DRIVER ROUTINE-----
00166A 1082 20 D3 1057          BRA  WRTLOP  *
00167          *
00168          *
00169A 1084 CC 0F08 A          ENDDIC LDD  #$0F08  * CHIP SELECT OFF. COMMAND MODE
00170A 1087 8D 53 10DC        BSR  DATMOD  *
00171A 1089 31                INS                * RECOVER STACK POINTER (+5)
00172A 108A 38                PULX
00173A 108B 38                PULX
00174A 108C 32                PUL A              * RESTORE POSITION ON LCD
00175A 108D 33                PUL B
00176A 108E 4C                INC A
00177A 108F 81 14 A          CMP A  #20         * NEXT POINTER.
00178A 1091 26 04 1097        BNE  DIC100
00179A 1093 4F                CLR A
00180A 1094 5C                INC B
00181A 1095 C4 03 A          AND B  #$03
00182          1097 A          DIC100 EQU  *
00183A 1097 71 FE7D A        AIM  #$FF-$1,MIOSTS * LCD FLAG LCD NOT BUSY
00184A 109A 38                PULX
00185A 109B 18                XGDX              *RETURN NEXT DISPLAY POINT.
00186A 109C 39                RTS
00187          *
00188          *
00189          *
00190          * SELECT LCD DRIVER AND CALCULATE BANK AND ADDRESS POINTER
00191          * NOTE. SET TO $26 DIRVER ADDRESS, BUT NOT SET TO LCD DRIVER, ONLY RETURN
00192          * LCD ADDRESS TO (A).
00193          * ON ENTRY
00194          * (A): DOT LINE COLUMN POSITION (00 - 119)
00195          * (B): LINE (0 - 3)
00196          * ON EXIT
00197          * (A): DOT POINTER IN THE LCD DRIVER
00198          * (B): CHIP NO. (BIT3=1)
00199          * REGISTER PRESERVE X
00200          *
00201          109D A          LCADDR EQU  *
00202A 109D 3C                PSHX              * SAVE (X)
00203A 109E 37                PSH B            * STACK VALUE OF (B)
00204A 109F 30                TSX
00205A 10A0 5F                CLR B
00206A 10A1 80 28 A          LCAD10 SUB A  #40       * (A) <--- ADDRESS AND BANK
00207A 10A3 5C                INC B            * (B) <--- CHIP NO.
00208A 10A4 24 FB 10A1        BCC  LCAD10
00209A 10A6 8B 28 A          ADD A  #40       * GET START ADDRESS. (B): 1-3
00210A 10A8 6B 010D A        TIM  #$1,0,X    * CHECK BANK (ODD LINE NO. = BANK 1)
00211A 10AB 27 02 10AF        BEQ  LCAD20
00212A 10AD 8A 40 A          ORA A  #$40
00213          10AF A          LCAD20 EQU  *
00214A 10AF 6B 0200 A        TIM  #$2,0,X    * CHECK DRIVER CHIP (LINE >=2, 4-6)
00215A 10B2 27 02 10B6        BEQ  LCAD30
00216A 10B4 CB 03 A          ADD B  #3       * CHIP IS 4 , 5 OR 6
00217A 10B6 31                LCAD30 INS
00218A 10B7 38                PULX
00219A 10B8 36                PSH A
00220A 10B9 CA 0B A          ORA B  #$08     * BIT3= DATA MODE BIT (1:COMMAND)
    
```

```

ERR  SEG  LOC  OBJECT      PROGRAM  LCD      -----LCD DRIVER ROUTINE-----
00111A 1034 37          PSH B
00112A 1035 48          ASL A          * (A) <--- (A) * 6 (DOT COLUMN)
00113A 1036 16          TAB
00114A 1037 48          ASL A
00115A 1038 18          ASB
00116A 1039 33          PUL B
00117
00118          *
00119          * WORK USE STACK
00120          * STACK 00: DOT COUNTER (1 CHARACTER = 6 DOT LINES)
00121          * 01,02: CHARACTER FONT ADDRESS
00122          * 03,04: DOT COLUMN, LINE
00123A 103A 37          PSH B
00124A 103B 36          PSH A
00125
00126          *
00127          * ***** LCD DRIVE RUOTINE ***** (X):CHARACTER PATTERN TOP ADDRESS
00128A 103C CE 0286 A    * SET CHARACTER TO DRIVER
00129A 103F 3C          LDX #CHRPTL
00130A 1040 5F          PSHX
00131A 1041 37          CLR B
00132A 1042 30          PSH B
00133          TSX
00134A 1043 EC 03 A     DISCHL EQU *          * SET COUNTER.
00135A 1045 8D 56 109D  LDD 3,X
00136A 1047 16          BSR LCADDR      * GET CHIP NO. & DATA ADDRESS.(DATAADD,CHIPNO)
00137A 1048 86 64 A     TAB             * SAVE LCD ADDRESS TO (B)
00138A 104A 8D 76 10C2* LDA A #$64      * SELECT WRITE MODE.
00139A 104C 17          BSR LCDMOD      * SET COMMAND
00140A 104D 8A 80 A     ORA A #$80      * SET DATA ADDR TO LCD DRIVER.(AUTO INCREMENT)
00141A 104F 8D 71 10C2* BSR LCDMOD
00142A 1051 CC 0800 A   LDD #$0800     * SET DATA MODE CODE FOR *WRTP26* ROUTINE
00143A 1054 BD 10DC A   JSR DATMOD     * LCD DRIVER: ENTER DATA MODE (NOT COMMAND)
00144A 1057 E6 0D A     WRTLOP LDA B 0,X    * GET 8 BITS PATTERN
00145A 1059 EE 01 A     LDX 1,X        * (B): DOT POSITION (0 - 5)
00146A 105B 3A          ASX
00147A 105C A6 0D A     LDA A 0,X
00148A 105E C1 05 A     CMP B #5        * LAST DOT (6 TH): WITHOUT CURSOR
00149A 1060 27 09 106B  BEQ DISC20
00150A 1062 F6 028D A   LDA B DISSTS   * CURSOR ON ?
00151A 1065 C5 20 A     BIT B #$20
00152A 1067 27 02 106B  BEQ DISC20
00153A 1069 8A 80 A     ORA A #$80
00154A 106B 8D 55 10C2  DISC20 BSR WIDAT * WRITE ONE BYTE BIT PATTERN
00155A 106D 30          TSX
00156A 106E 6C 0D A     INC 0,X        * COMPLETE TO WRITE 6 BYTES ?
00157A 1070 A6 0D A     LDA A 0,X
00158A 1072 81 06 A     CMP A #6
00159A 1074 27 0E 1084  BEQ ENDDIC     * YES . END
00160A 1076 6C 03 A     INC 3,X
00161A 1078 A6 03 A     LDA A 3,X      * INCREMENT DATA ADDRESS
00162A 107A 81 28 A     CMP A #40      * BOUNDARY OF DRIVER = 40.
00163A 107C 27 C5 1043  BEQ DISCHL
00164A 107E 81 50 A     CMP A #80
00165A 1080 27 C1 1043  BEQ DISCHL     * CHIP LAST ADD ?

```



```

ERR  SEQ  LOC  OBJECT  PROGRAM  LCD  -----LCD DRIVER ROUTINE-----

00276
00277A 10F3 8D 18 110D          BSR  LCDCLR  * CLEAR SCREEN .
00278
00279A 10F5 86 09  A          LDA  A  #$09  * DISPLAY ON COMMAND.
00280
00281
00282          ***** SET COMMAND ALL DRIVERS.
00283          * SET COMMAND TO LCD DRIVER
00284          * ON ENTRY
00285          * (A): COMMAND FOR LCD DRIVER
00286          * ON EXIT
00287          * REGISTER PRESERVE X
00288          * NOTE. THIS ROUTINE MUST BE CALL ONLY *INITLC.
00289          * BECAUSE .COMMAND WILL BE CHANGED.
00290
00291A 10F7 5F          STRALL CLR B          * (B): DRIVER NUMBER
00292A 10F8 5C          STRA10 INC B
00293A 10F9 37          PSH B
00294A 10FA CA 08  A          ORA  B  #$8
00295A 10FC 36          PSH A
00296A 10FD 86 0F  A          LDA  A  #$0F  * SELECT DRIVER AND COMMAND MODE
00297A 10FF BD FED4  A          JSR  W RTP26
00298A 1102 32          PUL  A
00299A 1103 8D BD 10C2        BSR  LCDMOD  * SET COMMAND TO DRIVER
00300A 1105 84 FD  A          AND  A  #$FF-$2  * TO CHANGE '1E' (SMM COMMAND) COMMAND TO '1C'
00301A 1107 33          PUL  B          * OTHER COMMANS ARE $10, $08, $09.(NOT EFFECT
00302A 1108 C1 06  A          CMP  B  #6
00303A 110A 26 EC 10F8        BNE  STRA10
00304A 110C 39          RTS
00305
00306
00307          * CLEAR LCD SCREEN
00308          * ON ENTRY
00309          * PARAMETER NONE
00310          * ON EXIT
00311          * (X):0
00312          * REGISTER PRESERVE NONE
00313
00314          LCDCLR EQU  *
00315A 110D CE 000D  A          LDX  #0  * POINTER SET.
00316A 1110 86 20  A          LCDC10 LDA A  #$20  * SET SPACE CODE.
00317A 1112 BD 101D  A          JSR  DSPLCH
00318A 1115 08          INX          * IX HAS DISPLAY POINTER.
00319A 1116 09          DEX
00320A 1117 26 F7 111D        BNE  LCDC10  * NOT END.
00321A 1119 39          RTS
00322
00323
00324          * DISPLAY CHARACTER STRING TO LCD
00325          * ON ENTRY
00326          * (B): MEMBER OF CHARCTER STRING (0 - 80)
00327          * (X): ADDRESS OF DATA PACKET
00328          * DATA PAKET:(ADDRESS X), (ADDRESS Y), DATA1,.....
00329          * ON EXIT
00330          * PARAMETER NONE

```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  LCD      -----LCD DRIVER ROUTINE-----
00221A 10B3 86 0F      A          LDA A    #30F      * SET CHIP NO.
00222A 10B0 BD FED4    A          JSR      WRTP26   * SELECTED DRIVER CHIP, AND ENTER COMMAND MODE
00223                                     *
00224A 10C0 32                                     PUL A      * SET DATA ADDRESS TO DRIVER
00225A 10C1 39          RTS
00226                                     *
00227                                     *
00228          10C2  A      WITDAT EQU    *
00229          10C2  A      LCDMOD EQU    *
00230A 10C2 37          PSH B
00231A 10C3 16          TAB
00232A 10C4 36          PSH A
00233A 10C5 07          TPA
00234A 10C6 0F          SEI
00235A 10C7 3C          PSHX
00236A 10C8 D7 2A      A      STA B    $2A      * SET ADD OR MODE.
00237A 10CA 7D 0028    A      LCDM10 TST    $28      * 7 BIT IS LCD BUSY FLAG.
00238A 10CD 2A FB 10CA BPL    LCDM10     * WAIT.
00239A 10CF DE 2A      A      LDX    $2A      * LDD SEND 2 PULSES ,SO 2 BIT SHIFT
00240A 10D1 DE 2A      A      LDX    $2A
00241A 10D3 DE 2A      A      LDX    $2A
00242A 10D5 DF 2A      A      LDX    $2A
00243A 10D7 38          PULX
00244A 10D8 06          TAP
00245A 10D9 32          PUL A
00246A 10DA 33          PUL B
00247A 10DB 39          RTS
00248                                     *
00249                                     *
00250                                     * AFTER CHECK LCD BUSY, CALL 'WRTP26'
00251                                     * ON ENTRY, (SAME AS 'WRTP26')
00252                                     * (A):TARGET BIT POSITION
00253                                     * (B): DATA
00254                                     *
00255          10DC  A      DATMOD EQU    *
00256A 10DC 7D 0028    A      TST    $28      * 7 BIT IS LCD BUSY FLAG.
00257A 10DF 2A FB 10DC BPL    DATMOD     * WAIT.
00258A 10E1 7F FED4    A      DTMD10 JMP    WRTP26   * SET INTERRUPT MASK.
00259                                     *
00260                                     *
00261                                     **
00262                                     *
00263                                     * INITIALIZE LCD ROUTINE
00264                                     * DRIVER INITIALIZE AND CLEAR CURSOR ON FLAG
00265                                     * ON ENTRY PARAMETER NONE
00266                                     *
00267A 10F4 86 10      A      INITLC LDA A    #310      * SFF (SET FRAME FREQUENCY) COMMAND
00268A 10E6 8D 0F 10F7 BSR    STRALL     * SET IT FOR EACH DRIVER.
00269A 10E8 86 1E      A      LDA A    #31E      * ACCA : SMM (SET MULTIPLEXING MODE) COMMAND
00270A 10EA 8D 03 10F7 BSR    STRALL     * NOTE. 1 ST DRIVER: SMM VALUE=#1E
00271                                     *          2ND - 6 TH DRIVER: SMM=#1C
00272A 10FC 86 03      A      LDA A    #308      * ACCA : DISP OFF COMMAND. ACCB : CHIP NO.
00273A 10FE 8D 07 10F7 BSR    STRALL
00274                                     *
00275A 10F0 7F 028D    A      CLR    DISSTS   * CLEAR DISPLAY STATUS FOR NON CURSOR CLEAR.
    
```

CHAPTER 4 SERIAL COMMUNICATION

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ERR SEQ LOC OBJECT PROGRAM LCD -----LCD DRIVER ROUTINE-----

```

00331      * REGISTER PRESERVE NONE
00332      * ENABLE REENTRANT
00333      * WORK USE : STACK      STACK + 0,1 :LOCATION OF CHARACTER ON LCD
00334      *                               2,3 :ADDRESS OF STORED CHARACTER
00335      *                               4   :DISPLAYED CHARACTER NUMBER
00336A 111A 5D      DSPLCN TST B      * IF (B)=0, CLEAR SCREEN.
00337A 111B 27 FO 110D      BEQ      LCDCLR
00338A 111D 37      PSH B
00339A 111E 3C      PSHX
00340A 111F EE 00      A      LD      0,X      * GET LOCATION OF DISPLAY
00341A 1121 3C      PSHX      *
00342A 1122 5F      CLR B      * COUNTER OF DISPLAYED CHARACTER
00343A 1123 30      TSX
00344A 1124 EE 02      A      DSPL10 LD      2,X
00345A 1126 3A      ABX      *
00346A 1127 A6 02      A      LDA A      2,X      * (A) <--- DISPLAYED CHARACTER
00347A 1129 38      PULX      * (X): LOCATION ON LCD
00348A 112A BD 101D      A      JSR      DSPLCH      * DISPLAY ONE CHARACTER TO SCREEN.
00349A 112D 3C      PSHX
00350A 112E 5C      INC B
00351A 112F 30      TSX
00352A 1130 E1 04      A      CMP B      4,X      * FINISHED ?
00353A 1132 26 FO 1124      BNE      DSPL10
00354A 1134 38      PULX
00355A 1135 38      PULX
00356A 1136 33      PUL B
00357A 1137 39      RTS
00358      *
00359      0000 A      END
***** TOTAL ERRORS      0
    
```

4.1 General

Serial communication is performed by the start-stop synchronous transmission system. In start-stop transmission, the signal is logic 1 while no data is being sent and becomes 0 to show the start of data. (See Fig. 4-1.) This first bit is called the start bit. Bits are then transmitted sequentially from the lowest order bit. A stop bit (logic 1) is always included to end transmission of the character. Stop bits may be 1 or 2 bits long. The word length (data bits) must be 5 to 8 bits. Bit time varies according to the bit rate. At 300 BPS (bits per second), the duration of a single bit is 3.3 msec.

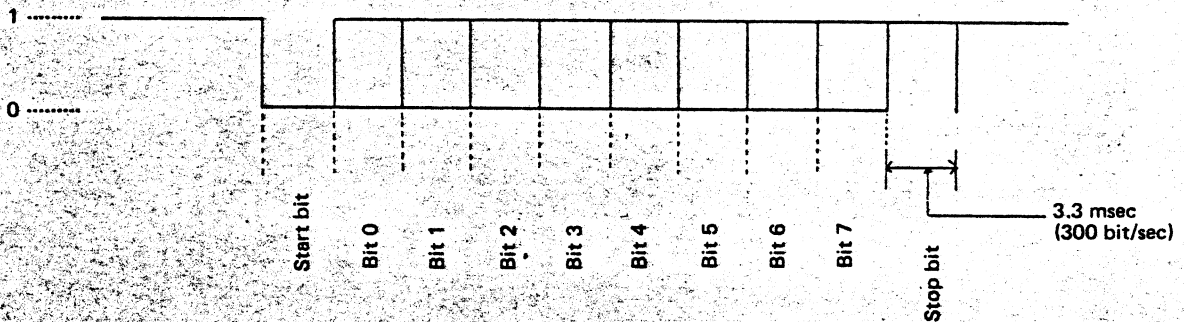


Fig. 4-1 Start-stop Data Transmission Format

The figure below shows an example of signal status when data 3A (00111010₂) is transmitted in start-stop format with a single stop bit.

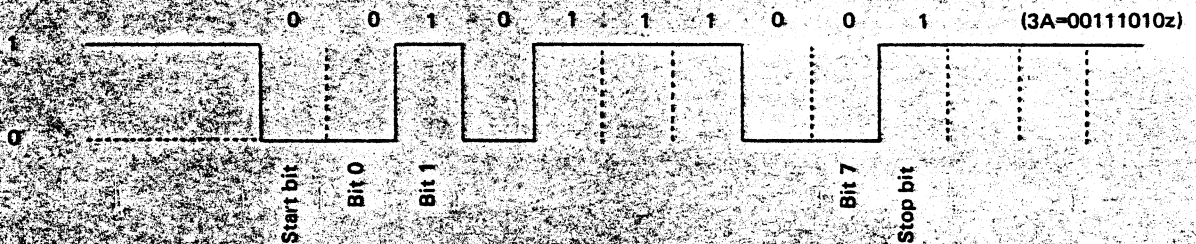


Fig. 4-2 Start-stop DATA 3A

Data 1 is represented by a low signal (-3 to -8V) and data 0 by a high signal (+3 to +8V) as shown in Fig 4-3 below.

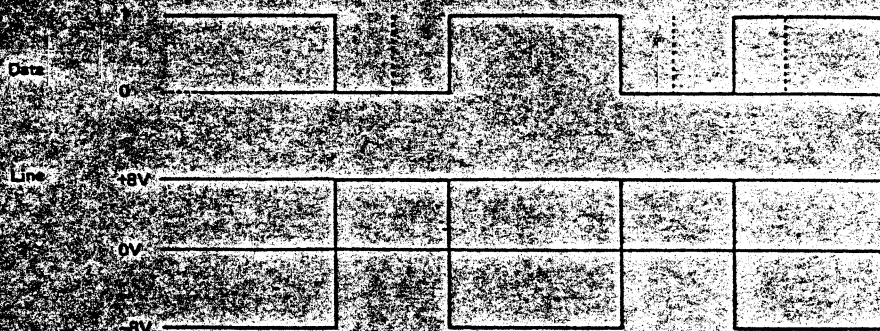


Fig. 4-3 Relationship Between Data and Signals States

The status signal lines are RTS (output), CTS (input), DTR (output), DSR (input), and CD (input). These signals are ON when high and OFF when low (Fig. 4-4).

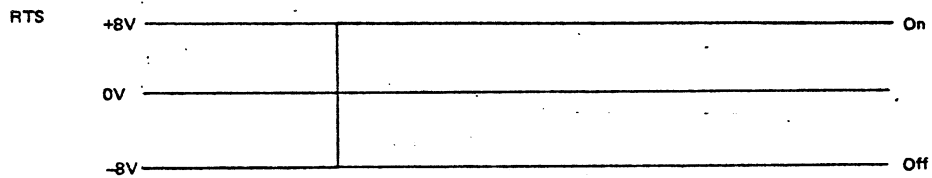


Fig. 4-4 Signal Line Output Status (RTS)

The HX-20 is provided with two types of interfaces. These are serial and RS-232C. The serial interface uses the serial port of the MCU and the bit rates and word length are fixed. The RS232C interface, however, performs handshaking by software. It can therefore support bit rates up to 4800 bps and both the bit rate and word length can be set by the user. Fig. 4-5 shows the respective range of functions for the serial and RS-232C interfaces.

	Transmission speed	Word length (bits)	Stop bit (bits)	Control lines (input)	Control lines (output)
Serial	38.4K BPS 4.8K BPS 600 BPS 150 BPS	8		1	1
RS232C	4.8K BPS max.	5, 6, 7 or 8	1 or 2	3 (CTS, DSR, and CD)	2 (RTS and DTR)

Fig. 4-5 Functions of Serial and RS-232C Interfaces

The serial interface is used for communication between the master and slave MCUs and for the floppy disk units.

4.2 I/O Ports

Table 4-1 I/O Ports for Serial Communication

MCU	Port (address)	Input/output	Signal name or function	Signal state	Port bit state
Master	P10	Input	DSR (RS-232C)	High	0
				Low	1
	P11	Input	CTS (RS-232C)	High	0
				Low	1
	P16	Input	PIN (serial control line)	High	0
				Low	1
	P21	Output	TXD (RS-232C)	High	0
Low				1	
P22	Output	Selection of slave or serial for CPU serial communication		0: Slave 1: Serial	
RMCR (0010)	Output	Serial bit rate control			

MCU	Port (address)	Input/output	Signal name or function	Signal state	Port bit state
	TRCSR (0011)	Input	Serial control and status		
	SRDR (0012)	Input	Serial receive data		
	STDR (0013)	Output	Serial transmit data		
	\$26 Bit 5	Output	POUT (serial control line)	High Low	0 1
Slave	P20	Input	RXD (RS-232C)	High	0
				Low	1
	P31	Output	RTS (RS-232C)	High	0
				Low	1
	P36	Output	Serial and RS-232C interface driver ON/OFF		0: On 1: OFF
	P45	Output	P20 signal selection		0: RS-232C 1: Micro-cassette
P47	Input	CD (RS-232C)	High	0	
			Low	1	

Note: DSR: Data set ready
CTS: Clear to send
TXD: Transmit data
RTS: Request to send
DTR: Data terminal ready
RXD: Receive data
CD: Carrier detect

4.3 Serial Communication Procedure

The SCI (serial communication interface) in the MCU performs serial communication in the following procedure.

(1) Driver ON

The communication driver is turned ON. The port for driver ON is connected to the slave MCU. Subroutine SERONF turns the drivers ON/OFF.

(2) Serial switching

The serial communication lines of the MCU can be used either for external data communication or for communication with the slave MCU. Normally, the slave MCU is selected. To select external communication, port P22 of the main MCU is set to 1.

(3) Bit rate setting

RMCR (address 10) sets the bit rate. The bit rate is normally set to 38.4K BPS. Table 4-2 shows selection of bit rates by RMCR.

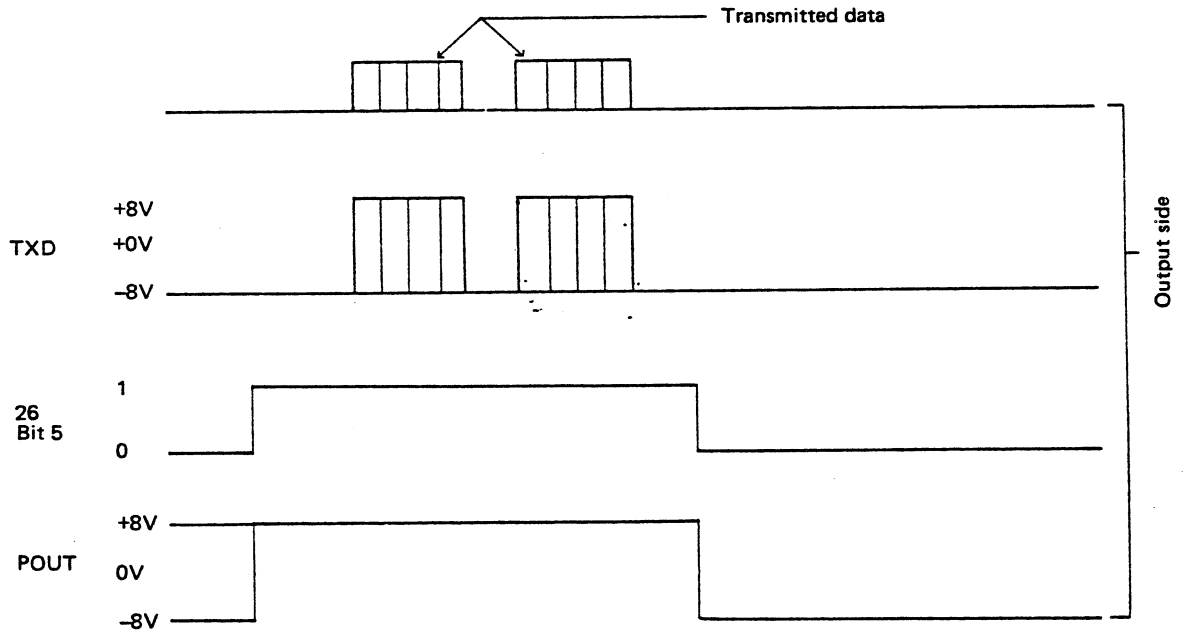
Table 4-2 SCI Bit Time and Bit Rates

Lower 4 bits	Hexadecimal	Bit time/bit rate
0100	4	26 μ sec/38.4 BPS
0101	5	208 μ sec/4.8K BPS
0110	6	1.67msec/600 BPS
0111	7	6.67msec/150 BPS

- (4) Data transmission (one byte)
TRCSR (address 0011) is input and when it is confirmed that TDRE (bit 5 of TRCSR) is 1, one byte of data is transmitted by writing it to TDR(address 0013).
- (5) Data reception (one byte)
TRCSR is input and if RDRF (bit 7 of TRCSR) is 1, serial data can be received by SRDR (address 12). One byte of Serial data is then received. Note that if the received data is not fetched before the next data is received, an overrun error occurs (ORFE is set at 1).
- (6) Termination procedure
The bit rate is set to 38.4K bps (procedure 3) and the driver is turned OFF. This procedure is followed because transmission of commands to the slave MCU is always performed at 38.4K PBS.

4.4 Control Lines

Two control lines are available: PIN (input) and POUT (output). PIN is connected to P16 (bit 6 of port 1) and POUT is connected to bit 5 of address 26. Both of these signals are set at 1 when the signal goes high and at 0 when the signal goes low. Subroutine WRTP26 is used to set data in address 26. Fig. 4-6 shows the relationship of the signals and ports.



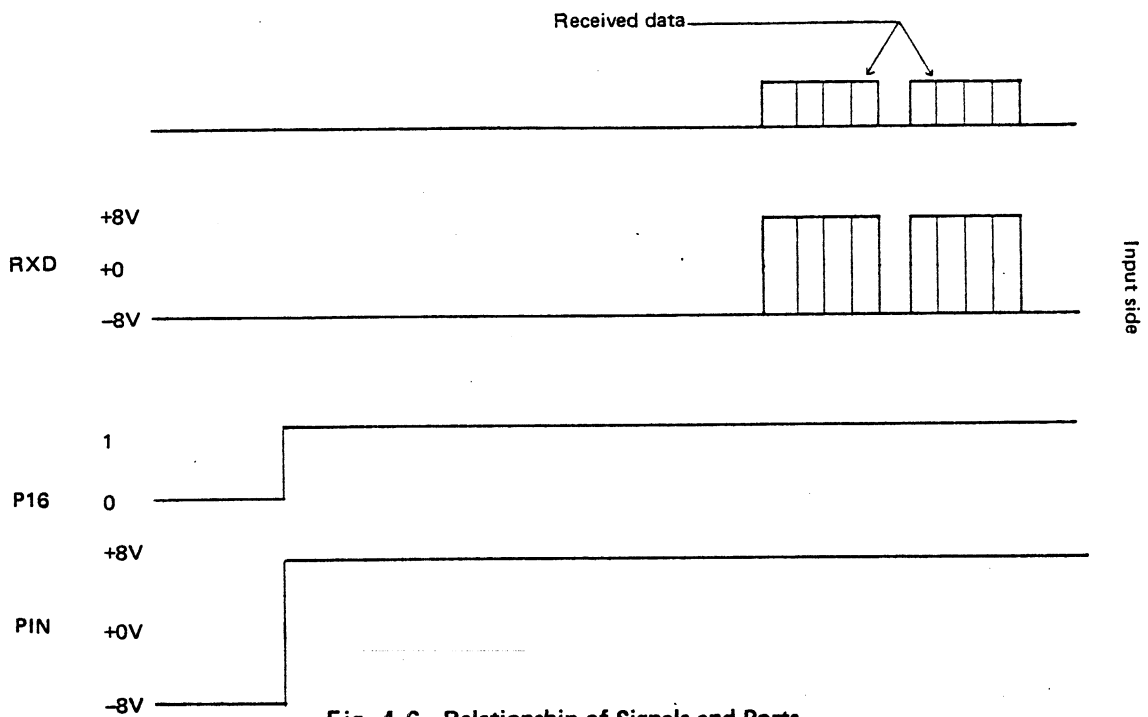


Fig. 4-6 Relationship of Signals and Ports

4.5 High-Speed Serial Communication

EPSP (EPSON Serial Communication Protocol) is provided to enable serial communication between the HX-20 and a floppy disk unit (TF-20) or between two HX-20s.

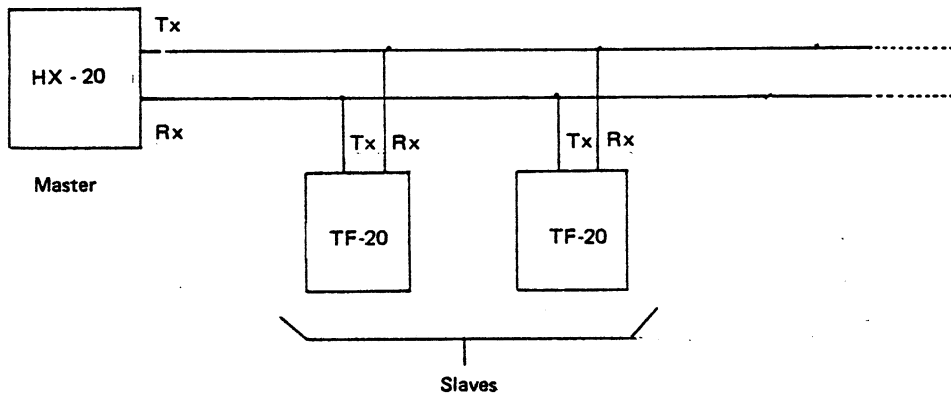


Fig. 4-7 Connection of Slave Devices to HX-20 for Serial Communication

Fig. 4-7 shows how slave devices can be connected by data lines to the HX-20. Up to two slave devices can be connected to a single master device. Each slave is assigned a device number by the master. The master then uses the device number to select which of the slaves to perform communication with. The master can only communicate with one slave at a time. Communication between slave devices cannot be performed.

Fig. 4-8 shows the format for messages sent from the HX-20 to a slave device.

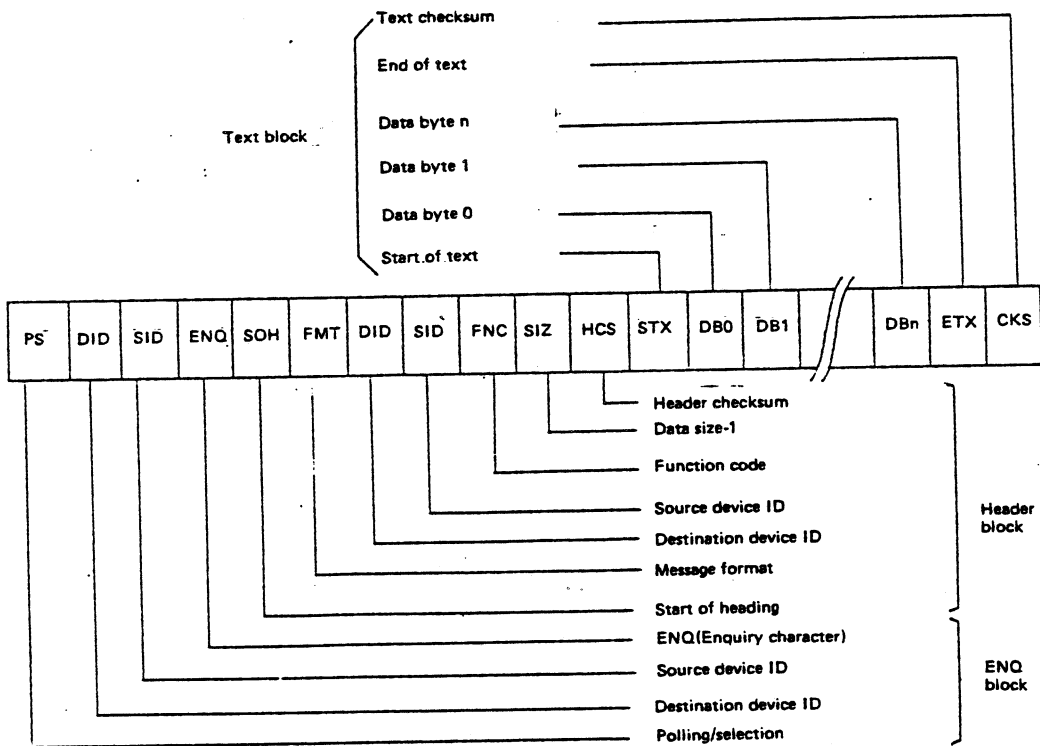


Fig. 4-8 Message Format

Messages sent from the master can be divided into three blocks described below.

- (1) ENQ block
PS to ENQ in Fig. 4-8. The master sends this block to request connection with a slave.
- (2) Header block
SOH to HCS in the above figure.
This block specifies the data format etc.
- (3) Text block
STX to CKS in the above figure. The text block contains the actual data transmitted.

Details of each block are as follows.

ENQ block

The contents of the ENQ block are shown below

PS	DID	SID	ENQ
----	-----	-----	-----

The master device selects one of the slave devices and issues a connection request to it, using this block. When connection with the slave has been established, the header and text blocks are sent. Once a slave device has been connected, this procedure is not repeated until a new slave device is selected for communication. The selected slave device issues an ACK signal in response to the connection request from the master (Fig. 4-9).

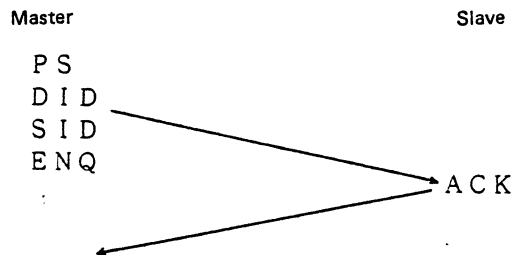


Fig. 4-9 ENQ Block Procedure

PS specifies polling/selection. At present, however, only selection is supported. The code for PS is $31_{16} = 1$.

DID indicates the destination device ID. The following destination device IDs are available.

- 31_{16} : Floppy disk drive A
- 32_{16} : Floppy disk drive B
- 33_{16} : Floppy disk drive C
- 34_{16} : Floppy disk drive D
- 20_{16} : Master HX-20

The code for NEQ is 05_{16} .

Header block

The master transmits the header block to specify the message format and the function codes as well as text size to be sent to the floppy disk unit in the text block that follows.

The contents of the header block are shown below.

SOH	FMT	DID	SID	FNC	SIZ	HCS
-----	-----	-----	-----	-----	-----	-----

SOH: Indicates the start of the header. The value is 01 .

FMT: Indicates the header block format.

00 indicates that the master device is transmitting a message to a slave device.

01 indicates that a slave device is transmitting a message to the master device.

DID: Indicates the destination device ID. The codes for DID are the same as in the ENQ block.

SID: Indicates the source device ID.

FNC: Specifies the function of the disk unit. Must be 00 to FF . For details of each function, refer to the descriptions in the corresponding sections.

SIZ: Indicates the text block size. This value is the number of bytes in the text block (excluding STX and CKS) minus 1. The value of SIZ must be in the range 0 to 255_{10} .

HCS: Indicates the checksum of the header block. The value is such that the lower 8 bits of the sum of the values of the header block (SOH to HCS) will all be 0 .

When the slave device receives a correct header block, it responds by sending 'ACK' to the corresponding source device. If the slave device receives an incorrect header block, it responds by sending 'NCK' to the source device.

Text block

The text block contains the actual data to be sent to the selected device. The text block follows the header block.

The contents of the text block are shown at right.

STX	DB ₀	DB ₁	~	DB _n	CKS
-----	-----------------	-----------------	---	-----------------	-----

STX: Indicates the start of text. The value is 02.

DB₀: Data 0

DB_n: Data n (n < 255)

EXT: Indicates the end of text.

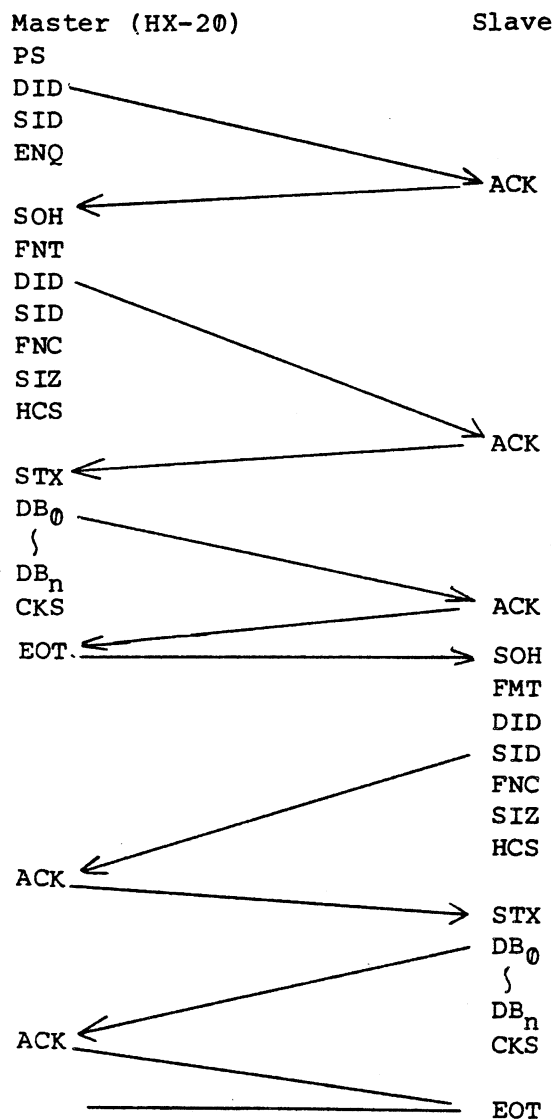
CKS: Indicates the checksum of the text block. The value is such that the lower bits of the sum of the values of the text block (STX to CKS) will be 0.

When the slave device receives a correct text block, it responds by sending ACK to the source device. If the slave device receives an incorrect text block, it responds by sending 'NCK' to the source device.

Switching Transmit State

There are cases when the master (HX-20) will request data transmission from a slave device (e.g., floppy disk unit). In this case, the sending and receiving sides (master and slave) are reversed. Switching over from master-to-slave to slave-to-master data transmission is accomplished by the following procedure.

The master sends EOT (code 04) to the slave after it has received an ACK from the slave indicating the slave has correctly received the text block. The slave device, after receiving EOT, sends the header and text blocks to the master device. It then sends EOT to the master and the transmit state returns to master-to-slave. (Fig. 4-11).



Details of protocol are shown in the EPSP standard at the end of this chapter.

4.6 Subroutines for Serial Communication

The following four subroutines support serial communication using EPSP procedures:

1. SERONF: Turns ON/OFF the serial communication drivers.
2. SEROUT: Transmits the ENQ, header, and text blocks.
3. SERIN: Receives the header and text blocks.
4. SRIWIT: Sets constants and performs initialization.

4.7 High-Speed Serial Subroutines

Subroutine name	Entry point	Description
SERONF	FF73	Turns ON/OFF the high-speed serial driver. This subroutine checks bit 4 of 'SRSTS' and turns ON the driver only when both are off.
		The contents of the SERONF parameters are the same as those of RSONOF.
SEROUT	FF70	High-speed serial data output (EPSP-based data transmission). This subroutine transmits the ENQ, header, and text blocks to the specified device according to the ENQ... SOH... STX procedure.
		<p>Parameters:</p> <p>At Entry</p> <p>(X): Head address of a data packet</p> <p>(A): Indicates whether to proceed to the receive procedure after completion of the transmit procedure.</p> <p>00: Transmit procedure only.</p> <p>01: (LSB=1) proceeds to the receive procedure after completion of the transmit procedure.</p> <p>Packets</p> <ol style="list-style-type: none"> 1. EMT (1 byte) 2. DID (1 byte) 3. SID (1 byte) 4. FNC (1 byte) 5. SIZ (1 byte) 6. (data string) (1 byte) <p>}</p> <p>n</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Return codes</p> <p>00: Normal end</p> <p>B0: Time out</p> <p>B1: Not linked (device error)</p> <p>B2: Communication error</p> <p>B3: Driver OFF.</p> <p>(Z): according to the value of (A)</p> <p>Registers retained</p> <p>None</p> <p>Subroutines referenced</p> <p>CHKRS</p> <p>Variables used</p> <p>R0, R1, R2, R3, R4, and R5H</p>
SERIN	FF6D	Receives the header and text blocks according to the SOH ... STX ... procedure (high-speed serial data block reception.)
		<p>Parameters:</p> <p>At Entry</p> <p>(X): Head address of receive data block.</p>

Subroutine name	Entry point	Description
		<p>Parameters:</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Return codes</p> <p> 00: Normal</p> <p> B0: Time out</p> <p> B2: Error during receive procedure</p> <p>(B): Indicates the receive block status when (A) is 00.</p> <p> 00: Data with a header string (SOH...) received.</p> <p> 01: Data without a header string received.</p> <p>(Z): According to the value of (A).</p> <p>Note: The format of a data block received is the same as that of the data block transmitted.</p> <ol style="list-style-type: none"> 1. FMT 2. DID 3. SID 4. FNC 5. SIZ 6. Data <p style="text-align: center;">}</p> <p style="text-align: center;">n</p> <p>Registers retained</p> <p>None</p> <p>Subroutines referenced</p> <p>CHKRS</p> <p>Variables used</p> <p>R0, R1, R2, R3, R4, and R5H</p>
SRINIT	FFIC	<p>Sets constants and performs high-speed serial initialization.</p> <p>Values of constants on initialization.</p> <p>SRTCN + 3</p> <p>SRTMO + 10₁₀</p> <p>SREMO + 100₁₀</p> <p>SRAMO + 10₁₀</p> <p>SRTDL + 1</p> <p>Others + 0</p> <hr/> <p>Parameters:</p> <p>At Entry</p> <p>(A): Value of SRMODE 00 or 01 (00: master)</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>None</p> <p>Subroutines referenced</p> <p>None</p> <p>Variables used</p> <p>None</p>

4.8 High-Speed Serial Communication Work Areas

Address	Variable name	Byte count	Description
1C4 1C4	SRFMT	1	FMT (format) data
1C5 1C5	SRDDEV	1	DID (Destination Device ID) data
1C6 1C6	SRSDEV	1	SID (Source Device ID) data
1C7 1C7	SRFNC	1	FNC (function) data
1C8 1C8	SRSIZ	1	SIZ (Size) data
1C9 1C9	SRACKC	1	ACK character (Sent from destination device on completion of block transmission)
1CA 1CA	SRTRCN	1	Number of time same block has been sent.
1CB 1CB	SRTIMO	1	Time out for received characters (unit: msec)
1CC 1CC	SRETMO	1	Time out for received block reception (unit: msec)
1CD 1CD	SRATMO	1	Time out for received ACK characters (unit: msec)
1CE 1CE	SRMODE	1	Relationship between devices (0: Master, any other value: Slave)
1CF 1CF	SRETDL	1	Idle time after EOT transmission (unit: msec)
1D0 1D0	SRBLCN	1	Number of received data (block reception)
1D1 1D1	SRERMD	1	Error (block reception)
1D2 1D2	SRRVFL	1	Not used
1D3 1D4	SREIX	2	Address where received data is stored (block reception)

APPENDIX SERIAL COMMUNICATION PROTOCOL (EPSP)

1. BASIC LINE SPECIFICATION

- 1.1 Transmission Speed
- 1.2 Synchronization
- 1.3 Communication
- 1.4 Transmission
- 1.5 Response System
- 1.6 Error Control
- 1.7 Transmission Codes
- 1.8 Bit Transmission Sequence bit 0, bit 1, bit 7

2. TRANSMISSION CHARACTERS AND SEQUENCE

PS]	Request receiving side to prepare to receive data
DID		
SID		
ENQ		
SOH		Indicates start of header block.
STX		Indicates start of text block.
ETX		Indicates end of text block.
ACK		Acknowledge
NAK		Negative acknowledge
DLE ;		Waits for WAK, acknowledge or transmission.
ENQ		Prompt for block response.
EOT		Releases data lines.

PS must be '1'₁₆. Control characters, DID and SID must be 8 bits (MSB=0).

3. MESSAGE FORMAT

3.1 Header Format

SOH	Start of header
FMT	Text format
	00: Indicates that the master is transmitting a block.
	01: Indicates that a slave is transmitting a block.
DID	Destination ID
SID	Source ID
FNC	Text function
SIZ	Text size (in bytes)
	This value is the length of the text block (excluding STX, ETX and CSK) minus 1.
HCS	Checksum of header block
	This is a value such that the lower 8 bits of the sum of SOH to ACS are 0.

3.2 Text Format

STX: Start of text

DB0: Data 0

DB1: Data 1

}

DBn: Data n

ETX: End of text

CKS Checksum of a text block

The value of CKS is such that the lower 8 bits of the sum of STX to CKS are 0.

Text length excluding STX, ETX and CKS must be within 256 bytes.

4. RESPONSE TO SLAVE SELECTION SEQUENCE

(a) ACK (Acknowledgement)

Indicates that that slave can receive a block. The master then initiates data transmission.

(b) NAK (Negative acknowledgement)

Indicates that the corresponding I/O device is not connected or that an error has occurred and the slave cannot receive data. The master then issues EOT and terminates the data link. The master will also send EOT to terminate the data link by transmitting if no response is received within a fixed period of time or an invalid response other than ACK and NAK is received after a selection sequence has been sent.

5. HEADER BLOCK TRANSMISSION

5.1 Response to a Header Block

(a) ACK (Acknowledge)

Indicates that the slave has received a correct header block. The master proceeds to the next phase.

(b) NAK (Negative acknowledge)

Indicates that the slave has received an incorrect header block. In this case, the master repeats transmission of the same block. If the master still receives NAK after the block has been transmitted a specified number of times, it assumes a line error and terminates the data link (by send EOT).

(c) WAK (Acknowledge and temporary wait)

Indicates that the slave has received a correct block but that it cannot yet receive the next block. The master will wait and then issue ENQ to prompt a response from the slave.

(d) No response or invalid response

If no response is made within a given time or a response other than ACK, NAK or WAK is received, the master will issue ENQ to prompt a response from the slave.

If no correct response is received even after ENQ has been transmitted a specified number of times, the master assumes an error and terminates the data link.

6. TERMINATION

(a) When, after sending EXT to the slave, the master receives ACK, it sends EOT to the slave and terminates the data link.

(b) When a transmission error occurs after the data link has been established, or during data transmission, the master will terminate the data link by transmitting EOT.

7. TIME SUPERVISION

(1) Number of selection sequences transmitted

The master will repeat the selection sequence after receiving a response other than ACK from the slave for the number of times listed in the table below.

	Mode 0	Mode 1
NAK	One time	One time
No response or invalid response	Three times (at 1-sec intervals)	Three times (at 3-sec intervals)

(2) Number of transmitted ENQs (response retransmit request)

	Mode 0	Mode 1
No response or invalid response	Three times (at 1-sec intervals)	Three times (at 3-sec intervals)

(3) Timers

	Mode 0	Mode 1
Response wait timer	1 sec	3 sec
Interblock supervision	32 sec	96 sec
Character supervision	1 sec	3 sec

8. TERMINAL NUMBERS

31₁₆ : Floppy disk drive A

32₁₆ : Floppy disk drive B

33₁₆ : Floppy disk drive C

34₁₆ : Floppy disk drive D

Terminal numbers (slave): 30₁₆ through 3F₁₆ for mode 0
 40₁₆ through 5F₁₆ for mode 1
Center number (master) : 20₁₆

9. OMISSION OF A HEADER BLOCK

If the terminal previously transmitted to is still selected and the header to be transmitted is the same as the last transmission, the header may be omitted. In this case, the master need only transmit the data block following STX. The slave treats this data block without header as if it included the header of the previously received data block.

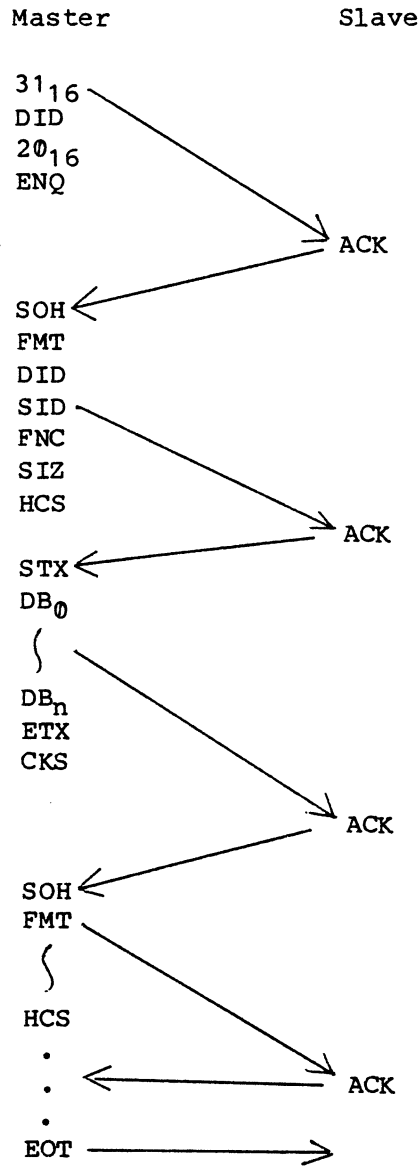
10. TRANSMISSION CONDITIONS SUPPORTED BY VER-1

Transmission speed is 38.4K BPS.
Mode 0 is used for a time supervision.
Header block cannot be omitted.

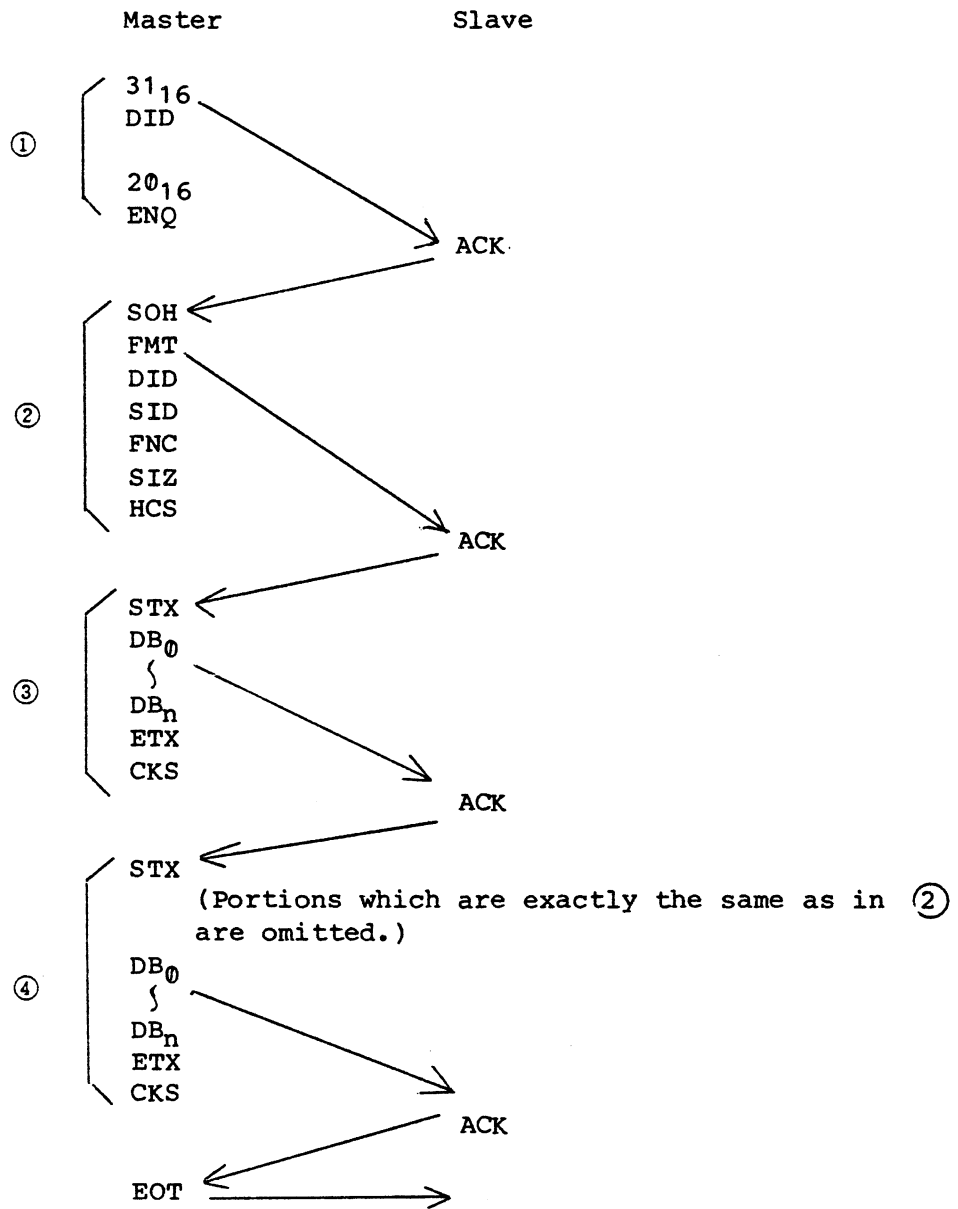
TRANSMISSION PROCEDURE DIAGRAMS

1. WITHOUT ERRORS

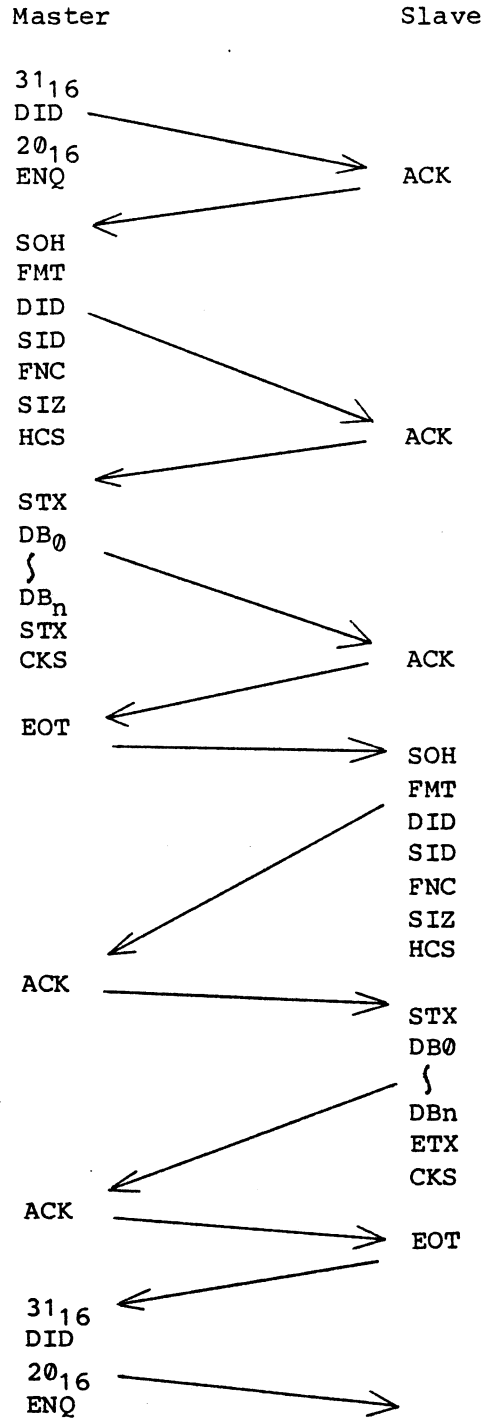
(1) When the slave does not send a data block to the master in response to the master's transmission and a header is not omitted.



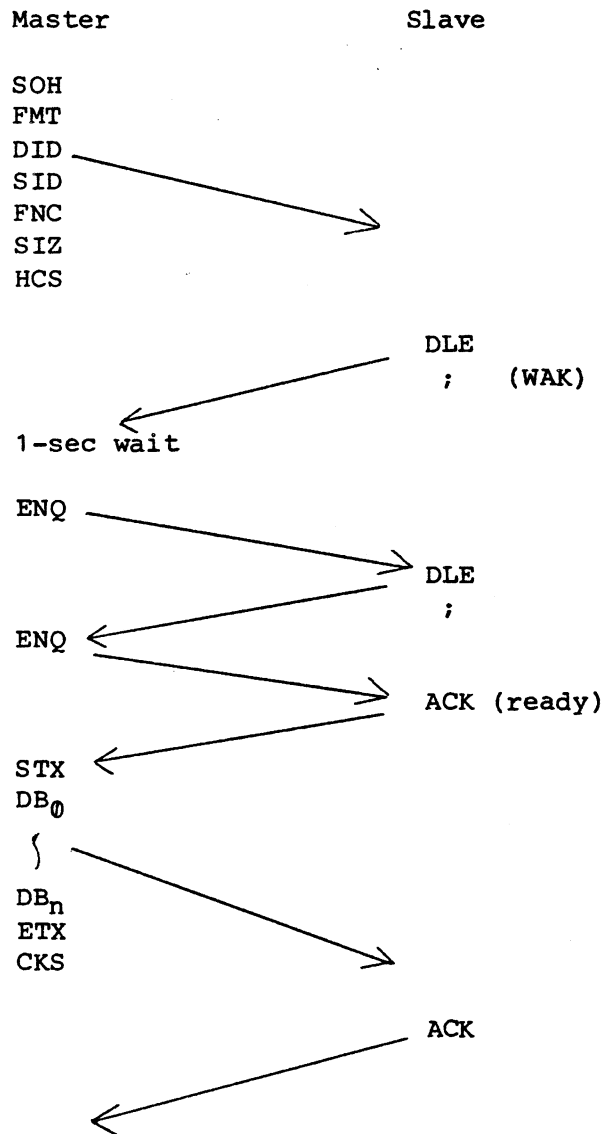
(2) When the terminal does not transmit a data block to the master in response to the master's transmission but the header is omitted.



(3) When the terminal transmits a data block to the master in response to EOT from the master and the header is not omitted.

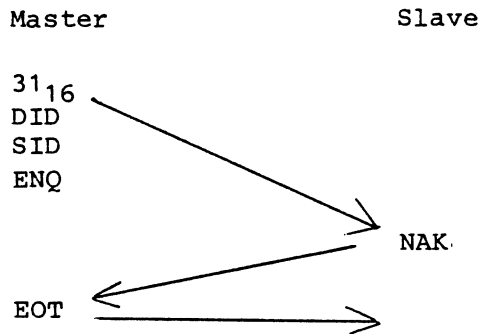


(4) When the slave responds with WAK to a block transmission with header from the master.

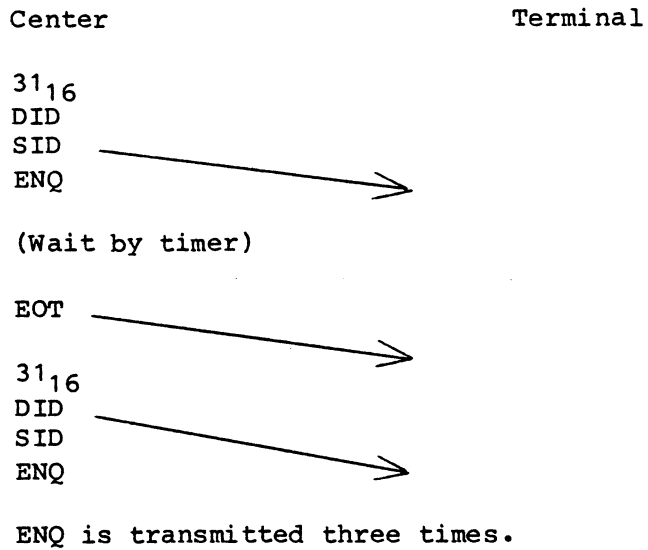


2. WITH ERRORS

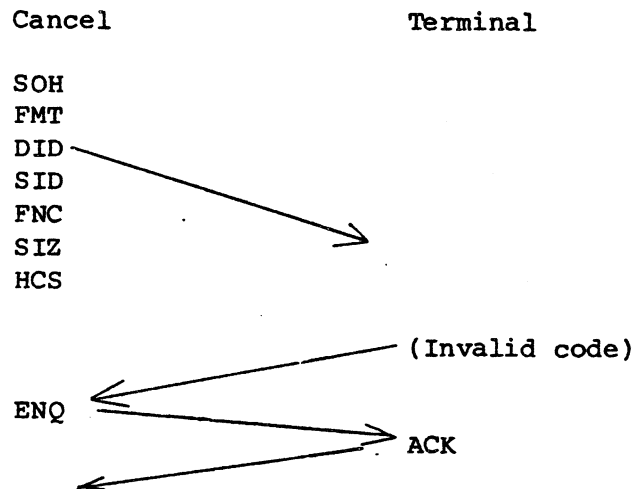
(1) When the slave responds by sending NAK in response to ENQ from the master.



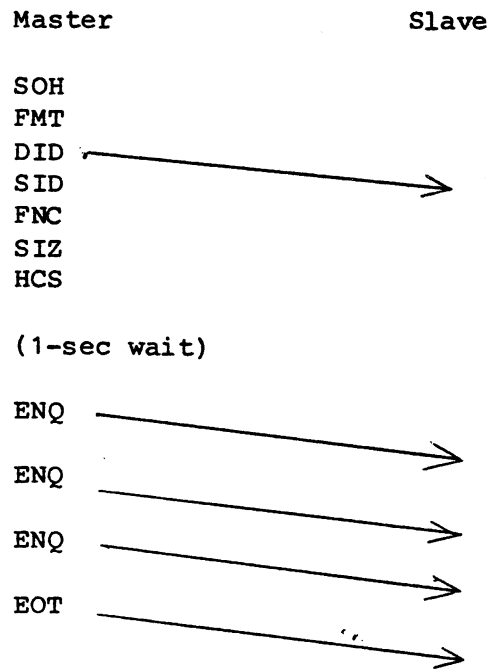
(2) When no response or an invalid response is received from the slave in response to ENQ from the master.



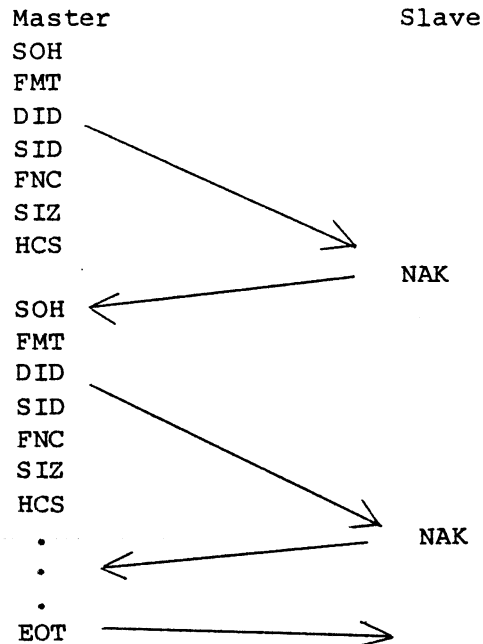
(3) When the master receives an invalid code from the slave in response to transmitting a header to the terminal.



(4) When no response is received from the slave in response transmission of a header from the master.



- (5) When NAK is sent from the slave in response to transmission of a header from the master.



If the master receives NAK three or more times, it terminates the data link by transmitting EOT.

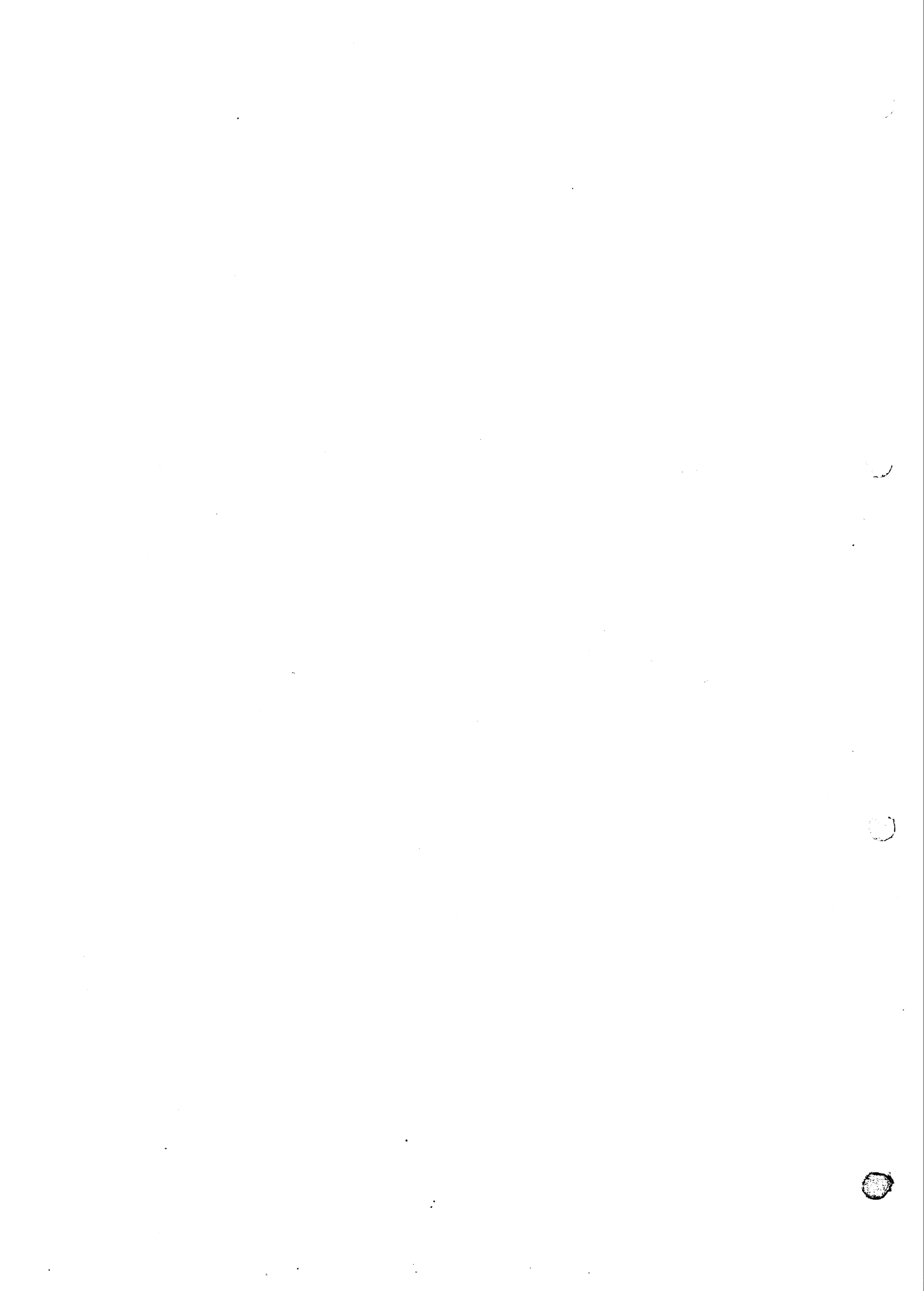
If the slave transmits NAK three times in succession, the master will not send the header but will send EOT to terminate the data link.

- (6) When the master receives an invalid response code from the slave in response to text transmission, the master handles this as in (3) above.
- (7) If no response is received from the slave, the master handles this as in (4) above.
- (8) If the slave responds with NAK when the master transmits text, the master handles this as in (5) above (text retransmission).
- (9) When the master does not receive a correct response after sending EOT to the slave.
 - a. If there is no response, the master waits for 1 second and terminates the data link by transmitting EOT.
 - b. If the master receives a code other than EOT from the slave, it terminates the data link by transmitting EOT.
- (10) When the slave has not correctly received and responded to EOT sent from the master (when response from the slave is necessary)

- a. If the slave has not received EOT and does not respond to the master, the master will wait (3 seconds in mode 0), terminate the data link and restart the link procedure from the beginning.
 - b. If the slave receives a code other than EOT, the master assumes that the terminal has made no response. If the slave does not receive EOT after the master has sent EOT the specified number of times (3 times), the center returns to the link start procedure.
- (11) If the slave does not transmit a header after the master transmits EOT, the master requests the slave to transmit the header by retransmitting EOT after waiting for a given time. If the slave does not transmit the header even after EOT has been transmitted the specified number of times, the master assumes that an error occurred and terminates the data link.

Function character code table

	0	1
0		DLE
1	SOH	
2	STX	
3	ETX	
4	EOT	
5	ENQ	NAK
6	ACK	
7		
8		
9		
A		
B		
C		
D		
E		
F		



ERR SEQ LOC OBJECT PROGRAM EPSP. --- SERIAL (EPSP) EXAMPLE ---

```

CC001          NAM      EPSP
CC002          *
CC003          * READ CHARACTER FROM KEYBOARD AND SEND CHARACTERS TO ANOTHER HC-20
CC004          * BY EPSP.
CC005          * AND AT ANOTHER HC-20.
CC006          * RECEIVED CHARACTER FROM EPSP, DISPLAY CHARACTERS ON THE VIRTUAL
CC007          * SCREEN.
CC008          *
CC009          * FILE NAME 'EXS1' BY K.A
CC010          TTL      --- SERIAL (EPSP) EXAMPLE ---
CC011          *
CC012          OPT      LOAD
CC013          OPT      PAGE=55
CC014          *
CC015          *
CC016          * SERIAL COMMUNICATION
CC017          *
CC018          * CONDITION SWITCH
CC019          0000  A    SRSL EQU 0 * SERIAL SELECT PROCEDURE
CC020          *
CC021          * COMMON DEFINITION
CC022          *
CC023          * MPU 6301 I/O PORT
CC024          0002  A    PORT1 EQU $02 * I/O PORT 1
CC025          0003  A    PORT2 EQU $03 * I/O PORT 2
CC026          0006  A    PORT3 EQU $06 * I/O PORT 3
CC027          *
CC028          * OTHER REGISTERS
CC029          0011  A    TRCSR EQU $11 * TRANSMIT/RECEIVE CONTROL & STATUS REGISTER
CC030          0010  A    RMCR EQU $10 * RATE & MODE CONTROL REGISTER (PMCR)
CC031          0013  A    STDR EQU $13 * SERIAL TRANSMIT DATA REGISTER
CC032          0012  A    SRDR EQU $12 * SERIAL DATA RECEIVE DATA REGISTER
CC033          *
CC034          * SUBROUTINE ENTRY POINT
CC035          FF4F  A    DSPSCR EQU $FF4F * DISPLAY ONE CHARACTER TO VIRTUAL SCREEN
CC036          FF5E  A    SCRFNC EQU $FF5E * VIRTUAL SCREEN FUNCTION
CC037          FF6D  A    SERIN EQU $FF6D * SERIAL PECEIVE
CC038          FF70  A    SEROUT EQU $FF70 * SERIAL TRANSMITTE
CC039          FF73  A    SERONF EQU $FF73 * SERIAL DRIVER ON/OFF
CC040          FF9A  A    KEYIN EQU $FF9A * GET ONE CHARACTER FROM KEYBOARD BUFFER
CC041          FF9D  A    KEYSTS EQU $FF9D * GET NUMBER OF CHARACTERS IN THE KEY BUFFER
CC042          *
CC043A 0050          ORG      $50
CC044          * GENERAL REGISTERS USED BY I/O ROUTINE
CC045          0050  A    R0 EQU * * 2 BYTES REGISTER (R0H,R0L)
CC046A 0050          0001  A    R0H RMB 1
CC047A 0051          0001  A    R0L RMB 1
CC048          0052  A    R1 EQU * * 2 BYTES REGISTER (R1H,R1L)
CC049A 0052          0001  A    R1H RMB 1
CC050A 0053          0001  A    R1L RMB 1
CC051          0054  A    R2 EQU * * 2 BYTES REGISTER (R2H,R2L)
CC052A 0054          0001  A    R2H RMB 1
CC053A 0055          0001  A    R2L RMB 1
CC054          0056  A    R3 EQU * * 2 BYTES REGISTER (R3H,R3L)
CC055A 0056          0001  A    R3H RMB 1
    
```

ERR	SEQ	LOC	OBJECT	PROGRAM	EPSP	---	SERIAL (EPSP) EXAMPLE	---
	00056A	0057	0001 A	R3L	RMB	1		
	00057		0058 A	R4	EQU	*	* 2 BYTES REGISTER (R4H,R4L)	
	00058A	0058	0001 A	R4H	RMB	1		
	00059A	0059	0001 A	R4L	RMB	1		
	00060		005A A	R5	EQU	*	* 2 BYTES REGISTER (R5H,R5L)	
	00061A	005A	0001 A	R5H	RMB	1		
	00062A	005B	0001 A	R5L	RMB	1		
	00063A	007A			ORG	\$7A		
	00064A	007A	0001 A	SRSTS	RMB	1	* SERIAL STATUS	
	00065			*			* BIT 0,1: RS232 MODE(00:STOP 01:INTERRUPT READ	
	00066			*			02:READ ONE CHARACTER)	
	00067			*			* BIT 2: EXECUTE/PAUSE (0:ON EXECUTE 1:PAUSE)	
	00068			*			* BIT 3: RS232 DRIVER (0:OFF 1:DRIVER ON	
	00069			*			* BIT 4: SERIAL DRIVER (0:OFF 1:DRIVER ON	
	00070			*			* BIT 5,6,7: CPU SERIAL RECEIVE INTERRUPT MODE	
	00071A	007B	0001 A	RUNMOD	RMB	1	* RUN MODE (\$80: BASIC \$00: SYSTEM)	
	00072A	007C	0001 A	SIOSTS	RMB	1	* SLAVE I/O STATUS (EACH BIT 0:OFF, 1:ON)	
	00073			*			* BIT 0: PRINTER	
	00074			*			* BIT 1: EXTERNAL CASSETTE	
	00075			*			* BIT 2: INTERNAL CASSETTE	
	00076			*			* BIT 3: RS232C ON (READ)	
	00077			*			* BIT 4: SPEAKER ON	
	00078			*			* BIT 5: PROM CASSETTE	
	00079			*			* BIT 6: BAR CODE READER	
	00080			*			* BIT 7: BREAK SLAVE CPU (0:ON EXECUTE	
	00081			*			1: BROKEN BY INTERRUPT	
	00082A	007D	0001 A	MIOSTS	RMB	1	* MAIN I/O STATUS EACH BIT (0:OFF 1:ON)	
	00083			*			* BIT 0: LCD ON READ/WRITE CHARACTERS	
	00084			*			* BIT 1: ON CONTINUE SEND COMMAND TO SLAVE CPU	
	00085			*			* BIT 2: ON CONTINUE TO SEND SERIAL LINE (1:ON)	
	00086			*			* BIT 3: ON CLOCK INTERRUPT (1:ON)	
	00087			*			* BIT 4: (POWER FAIL)	
	00088			*			* BIT 5: (OFF POWER SWITCH)	
	00089			*			* BIT 6: ON PAUSE KEY	
	00090			*			* BIT 7: ON BREAK KEY	
	00091			*				
	00092			*				
	00093			*			* RAM COMMON WORK AREA	
	00094A	01C4			ORG	\$1C4		
	00095			*				
	00096			*			* WORK FOR SERIAL COMMUNICATION	
	00097		01C4 A	SRWKTP	EQU	*	* SERIAL WORK TOP ADDRESS	
	00098A	01C4	0001 A	SRFMT	RMB	1	* FORMAT	(0)
	00099A	01C5	0001 A	SRDDEV	RMB	1	* DESTINATION DEVICE	(1)
	00100A	01C6	0001 A	SRSDEV	RMB	1	* SOURCE DEVICE	(2)
	00101A	01C7	0001 A	SRFNC	RMB	1	* FUNCTION	(3)
	00102A	01C8	0001 A	SRSIZ	RMB	1	* TEXT SIZE	(4)
	00103A	01C9	0001 A	SRACKC	RMB	1	* RECEIVED ACK CHARACTER	(5)
	00104A	01CA	0001 A	SRTRCN	RMB	1	* SEND TRY COUNT	(6)
	00105A	01CB	0001 A	SRTIMO	RMB	1	* FOR RECEIVE CHARACTER TIME OVER LIMIT	(7)
	00106A	01CC	0001 A	SRETMO	RMB	1	* FOR RECEIVE BLOCK TIME OVER LIMIT	(8)
	00107A	01CD	0001 A	SRATMO	RMB	1	* FOR RECEIVE ACK TIME OVER LIMIT	(9)
	00108A	01CE	0001 A	SRMODE	RMB	1	* SERIAL MASTER/SLAVE MODE (0:MASTER) (10)	
	00109			*			(NOT:SLAVE)	
	00110A	01CF	0001 A	SRETDL	RMB	1	* AFTER SEND 'EOT', IDLING TIME (1 = 1 MILI SEC	


```

ERR  SEQ  LOC  OBJECT      PROGRAM  EPSP      --- SERIAL (EPSP) EXAMPLE ---
00111A 01D0      0001  A      SRBLCN  RMB      1      * FOR RECEIVE BLOCK, BLOCK COUNTER
00112A 01D1      0001  A      SRERMD  RMB      1      * FOR RECEIVE BLOCK, ERROR MODE
00113A 01D2      0001  A      SRRVFL  RMB      1      * FOR RECEIVE BLOCK, RECEIVED CHARACTER FLAG
00114A 01D3      0002  A      SREIX   RMB      2      * FOR RECEIVE BLOCK, DATA STORED ADDRESS
00115      01D5  A      SRWKBT  EQU      *      * WORK BOTTOM
00116
00117
00118
00119
00120      0001  A      SOH     EQU      $01      * SOH
00121      0002  A      STX     EQU      $02      * STX
00122      0003  A      ETX     EQU      $03      * ETX
00123      0004  A      EOT     EQU      $04      * EOT
00124      0005  A      ENQ     EQU      $05      * ENQ
00125      0006  A      ACK     EQU      $06      * ACK
00126      0015  A      NAK     EQU      $15      * NAK
00127      0010  A      DLE     EQU      $10      * DLE
00128      0038  A      WAK     EQU      $3B      * WAK (;)
00129      0031  A      DEVCRT  EQU      $31      * DEVICE NO. (CRT)
00130
00131A 1000
00132
00133
00134
00135
00136
00137
00138
00139
00140
00141
00142
00143
00144
00145
00146
00147
00148
00149
00150
00151
00152
00153A 1000 36 01CB  A      SRVSGL  LDA  A      SRTIMO      * SET TIME OVER COUNTER
00154
00155A 1003 37
00156A 1004 16
00157A 1005 8D 0D 1014
00158A 1007 25 09 1012
00159A 1009 28 07 1012
00160A 100B 5D
00161A 100C 27 F7 1005
00162A 100E 5A
00163A 100F 26 F4 1005
00164A 1011 03
00165A 1012 33
          ORG      $1000
          *
          *
          * OUT TO SERIAL ROUTINE
          *
          * INITIALIZATION OF SERIAL
          * 1. CLEAR FMT, DID, SID, FNC, SIZ WORK
          * 2. SET "NAK" CODE TO ACK CHARACTER AREA
          * 3. SET RETRY COUNT (INITIAL 5)
          * 4. SET TIME OVER COUNT (INITIAL 0.5 SEC)
          * 5. SET START BLOCK TIME OVER COUNT (INITIAL 10 SEC)
          *
          *
          * RECEIVE ONE CHARACTER FROM SERIAL PORT
          * ON ENTRY
          * PARAMETER NONE
          * ON EXIT
          * (C): I/O ERROR FLAG 0:OK 1:ERROR
          * (V): TIME OVER FLAG 0:OK 1:TIME OVER (TIME OVER = 0.1 SEC)
          * (A): RECEIVED CHARACTER (IF (C)=0 AND (Z)=1)
          * REGISTER PRESERVE B,X
          *
          SRVSGL LDA A SRTIMO      * SET TIME OVER COUNTER
          * ENTRY POINT (PARAMETER (A):TIME OVER LIMIT)
          SRVSXX PSH B
          TAB
          SRVS40 BSR      SRVRYT      * RECEIVE ONE CHARACTER
          ECS      SRVS50      * I/O ERROR ?
          BVC      SRVS50      * OK ?
          TST B
          BEQ      SRVS40      * TIME OVER LIMIT CHECK
          DEC B
          BNE      SRVS40
          SEV
          * TIME OUT
          SRVS50 PUL B
    
```

ERR SEQ LOC OBJECT PROGRAM EPSP --- SERIAL (EPSP) EXAMPLE ---

```

00166A 1013 39          RTS
00167                  *
00168                  *
00169                  * RECEIVE ONE BYTE
00170                  * REGISTER PRESERVE B,X
00171                  *
00172A 1014 3C          SRVBYT PSHX
00173A 1015 CE 0988 A   LDX      #3000      * 21*1.6*3000 = 100,000
00174A 1018 4F          SRVS10 CLR A      * (C)----0, (V)---- 0      (1 C/S)
00175A 1019 09          DEX          * NOT RECEIVED, CHECK TIME OVER (1 C/S)
00176A 101A DB          SEV          * PRESET (V)      (1 C/S)
00177A 101B 27 12 102F BEQ      SRVS30    *      (2 C/S)
00178A 101D 0D          SEC          * PRESET I/O ERROR FLAG (1 C/S)
00179A 101E 78 B07D A   TIM      #$80,MIOSTS *      (3 C/S)
00180A 1021 26 0C 102F BNE      SRVS30    *      (2 C/S)
00181A 1023 78 0403 A   TIM      #$4,PORT2 * CONNECTED EXTERNAL SERIAL (3 C/S)
00182A 1026 26 07 102F BNE      SRVS30    *      (2 C/S)
00183A 1028 7D 0011 A   TST      TRCSR    * RECEIVED ?      (3 C/S)
00184A 102B 2A EB 1018 BPL      SRVS10    *      (2 C/S) 21 C/S
00185                  * RECEIVED      * (A) ---- RECEIVED CHARACTER
00186A 102D 96 12 A   LDA A  SRDR      * (C),(V) ---- 0 BY *TST* INSTRUCTION
00187A 102F 38          SRVS30 PULX
00188A 1030 39          RTS
00189                  *
00190                  * WAIT TO BE SELECTED
00191                  * RECEIVE SEQUENCE
00192                  * 1. WAIT SERIAL IDLING
00193                  * 2. CHECK *EOT*
00194                  * PARAMETER
00195                  * ON ENTRY
00196                  * (A):DESTINATION DEVICE (FOR SENDING SIDE)
00197                  * (B):SOURCE DEVICE (FOR SENDING SIDE)
00198                  * (X):TIME OVER LIMIT (1=0.1 SEC, 0:NO LIMIT)
00199                  * ON EXIT
00200                  * (C):I/O ERROR FLAG (0:NORMAL 1:ERROR)
00201                  * (A):RETURN CODE (0:NORMAL) ($B3:TIME OUT ERROR)
00202                  * (Z):DEPEND ON VALUE OF (A)
00203                  *
00204                  * WORK USE AS REGISTER
00205                  * ROH:31
00206                  * ROL:DIR
00207                  * R1H:SID
00208                  * R1L:ENQ
00209                  *
00210                  * ENTRY POINT: RECEIVED *EOT*, CHECK ENQ PATTERN.
00211A 1031 DD 51 A   SRSLET STD  ROL      * SET ENQ PATTERN
00212A 1033 86 05 A   LDA A  #ENQ
00213A 1035 97 53 A   STA A  R1L
00214A 1037 86 31 A   LDA A  #$31
00215A 1039 97 50 A   STA A  ROH      * SET P1
00216A 103B 20 2E 106B BRA      SRSL18
00217                  *
00218                  * ENTRY POINT: WAIT *EOT* *P1*, ... *ENQ* PATTERN
00219A 103D DD 51 A   SRSLET STD  ROL      * SET ENQ PATTERN
00220A 103F 86 05 A   LDA A  #ENQ

```

ERR	SEQ	LOC	OBJECT	PROGRAM	EPSP	---	SERIAL (EPSP) EXAMPLE	---
	00221A	1041	97 53	A		STA A	R1L	
	00222A	1043	86 31	A		LDA A	#\$31	
	00223A	1045	97 50	A		STA A	ROH	* SET P1
	00224							
	00225		1047	A		SRSL10	EQU	*
	00226A	1047	71 FB03	A		AIM	#\$FF-\$4,PORT2	* SELECT EXTERNAL SERIAL
	00227		104A	A		SRSL11	EQU	*
	00228A	104A	72 0111	A		OIM	#\$1,TRCSR	* SET WAKE UP FLAG
	00229		104D	A		SRSL13	EQU	*
	00230A	104D	7B 0111	A		TIM	#\$1,TRCSR	* IDLE ?
	00231A	1050	27 0E 1060			BEQ	SRSL15	
	00232A	1052	0D			SEC		
	00233A	1053	7B 0403	A		TIM	#\$4,PORT2	
	00234A	1056	26 30 1088			BNE	SRSL30	* BROKEN SERIAL ?
	00235A	1058	96 11	A		LDA A	TRCSR	* IGNORE RECEIVED CHARACTER
	00236A	105A	2A F1 104D			BPL	SRSL13	
	00237A	105C	96 12	A		LDA A	SRDR	
	00238A	105E	20 EA 104A			BRA	SRSL11	
	00239A	1060	BD 1014	A		SRSL15	JSR	SRVBYT
	00240A	1063	25 23 1088			BCS	SRSL30	* READ CHARACTER
	00241A	1065	29 22 1089			BVS	SRSL40	* I/O ERROR ?
	00242							
	00243A	1067	81 04	A		* RECIEVD	'EOT' ?	
	00244A	1069	26 1E 1089			CMP A	#EOT	
	00245A	106B	5F			BNE	SRSL40	
	00246A	106C	BD 1014	A		SRSL18	CLR B	* (B):RECEIVED COUNTER DID:0 SID:1
	00247A	106F	29 18 1089			SRSL20	JSR	SRVBYT
	00248A	1071	25 15 1088			BVS	SRSL40	* TIME OVER ?
	00249A	1073	3C			BCS	SRSL30	* I/O ERROR ?
	00250A	1074	CE 0050	A		PSHX		
	00251A	1077	3A			LDX	#R0	
	00252A	1078	A1 00	A		ABX		
	00253A	107A	38			CMP A	0,X	
	00254A	107B	26 0C 1089			PULX		
	00255A	107D	5C			BNE	SRSL40	
	00256A	107E	C1 04	A		INC B		
	00257A	1080	26 EA 106C			CMP B	#4	* RECEIVED 00 'DID' 'SID' 'ENQ' ?
	00258					BNE	SRSL20	
	00259A	1082	86 06	A		* RECEIVED	'ACK' SEQUENCE'	
	00260A	1084	BD 1098	A		LDA A	#ACK	
	00261A	1087	4F			JSR	SSRSGL	
	00262A	1088	39			CLR A		
	00263					SRSL30	RTS	
	00264A	1089	8C 0000	A		* TIME OUT ?		
	00265A	108C	27 B9 1047			SRSL40	CPX	#0
	00266A	108E	09			BEQ	SRSL10	* CHECK TIME OUT ?
	00267A	108F	26 B6 1047			DEX		
	00268A	1091	86 B3	A		BNE	SRSL10	
	00269A	1093	7F 01C5	A		LDA A	#\$B3	* TIME OUT ERROR RETURN
	00270A	1096	4D			CLR	SRDEV	
	00271A	1097	39			TST A		
	00272					RTS		
	00273							
	00274					* SEND ONE CHARACTER TO SERIAL PORT		
	00275					* ON ENTRY		
						* (A): SEND CHARACTER		

ERR SEQ LOC OBJECT PROGRAM EPSP --- SERIAL (EPSP) EXAMPLE ---

```

00276          * ON EXIT
00277          *          (C): I/O BREAK FLAG  0:OK  1:ERROR
00278          * REGISTER PRESERVE  ALL
00279          *
00280          *          SSRSGL EQU          *
00281A 1098 0D          1098  A          SSRS10 SEC          * PRESET I/O ERROR FLAG
00282A 1099 7B 307D  A          TIM          #$80,MIOSTS * BREAK ?
00283A 109C 26 0D 10AB          BNE          SSRS20
00284A 109E 7B 0403  A          TIM          #$4,PORT2 * CONNECT TO EXTERNAL SERIAL ?
00285A 10A1 26 08 10AB          BNE          SSRS20
00286A 10A3 7B 2011  A          TIM          #$20,TRCSR * SEND READY ?
00287A 10A6 27 F0 1098          BEQ          SSRS10
00288A 10A8 97 13   A          STA A      STDR
00289A 10AA 0C          CLC          * OK RETURN
00290A 10AB 39          SSRS20 RTS
00291          * SERIAL INITIALIZE
00292          * ON ENTRY
00293          * (A):MODE (MASTER:0 SLAVE:NONZERO)
00294          *
00295A 10AC 36          SRINIT PSH A
00296A 10AD CC 0011  A          LDD          #SRWKBT-SRWKTP * CLEAR WORK (A):PATTERN, (B):COUNT
00297A 10B0 CE 01C4  A          LDX          #SRWKTP
00298A 10B3 3C          PSHX
00299A 10B4 A7 00   A          CLRB      STA A  0,X
00300A 10B6 08          INX
00301A 10B7 5A          DEC B
00302A 10B8 26 FA 10B4          BNE          CLRB
00303          *
00304A 10BA 38          PULX
00305A 10BB 32          PUL A
00306A 10BC A7 0A   A          STA A      SRMODE-SRWKTP,X * SET MASTER/SLAVE MODE
00307A 10BE 62 0306  A          OIM          #3,SRTRCN-SRWKTP,X * SEND RETRY COUNT = 3
00308A 10C1 CC 0A64  A          LDD          #10*256+100
00309A 10C4 ED 07   A          STD          SRTIMO-SRWKTP,X * TIME OVER LIMIT = 1 SEC
00310          *          * RECEIVE BLOCK TIME OVER LIMIT=10
00311A 10C6 A7 09   A          STA A      SRATMO-SRWKTP,X * RECEIVE ACK TIME OVER = 1 SEC
00312A 10C8 6C 0B   A          INC          SRETDL-SRWKTP,X * AFTER 'EOT', IDLING TIME
00313          *
00314A 10CA 39          RTS
00315          *
00316          *
00317          * RECEIVE FROM SERIAL (FOR SLAVE DEVICE)
00318          * ON ENTRY
00319          * (X):RECEIVED DATA STORED ADDRESS
00320          * ON EXIT
00321          * (A):RETURN CODE  0:OK  $B0:TIME OVER  $B2:RECEIVE ERROR
00322          *          $B8: RECEIVED 'EOT'
00323          * (B): 0:RECEIVED WITH HEADER  1:RECEIVED WITHOUT HEADER
00324          *          (EFFECTIVE (A)=0)
00325          * (Z):DEPEND ON VALUE OF (A)
00326          *
00327          * WORK USE AS REGISTER
00328          * R0H:TOP CHARACTER OF BLOCK ($1 OR $2)
00329          * R1:ADDRESS OF STORED DATA
00330          * R2L:BLOCK LENGTH

```

ERP SEQ LOC OBJECT PROGRAM EPSP --- SERIAL (EPSP) EXAMPLE ---

```

00331      * R3H:RETRY COUNT
00332      * R3L:TIME OVER COUNTER
00333      * R4H:TOP CHARACTER OF BLOCK
00334      * R4L:OMITTED HEADER FLAG (0:NOT 1:OMITTED)
00335      *
00336      *
00337      *
00338      *
00339      * ERROR RETURN ROUTINE
00340      * SET ERROR CODE TO (A), CLEAR (C)
00341      *
00342A 10CB 86 B0 A SRERB0 LDA A #S80 * ERROR S80 (TIME OVER)
00343A 10CD 20 0A 10D9 BRA SRER10
00344      *
00345A 10CF 86 B1 A SRERB1 LDA A #S81 * ERROR S81 (
00346A 10D1 20 06 10D9 BRA SRER10
00347A 10D3 86 B8 A SRERB8 LDA A #S88 * ERROR S81 (RECEIVED 'EOT')
00348A 10D5 20 02 10D9 BRA SRER10
00349      *
00350A 10D7 86 B3 A SRERB3 LDA A #S83 * ERROR B3 (DRIVER OFF)
00351A 10D9 7F 01C5 A SRER10 CLR SRDDEV * CLEAR DID (FOR START FROM END PROCESS) (C)
00352      * EQU *
00353A 10DC 7E 117F A SRER20 EQU *
00354      * JMP SRR39D
00355      *
00356      * EPSP RECEIVE (SLAVE DEVICE) SUBROUTINE
00357      * RECEIVE FROM SERIAL
00358      * ON ENTRY
00359      * (X):RECEIVED DATA STORED ADDRESS
00360      *
00361A 10DF DF 52 A SERRCV STX R1
00362A 10E1 7B 107A A TIM #S10,SRSTS * DRIVER ON ?
00363A 10E4 27 F1 10D7 BEQ SRERB3
00364      *
00365      * SELECT SERIAL (DETATCH SLAVE)
00366A 10E6 96 11 A LDA A TRCSR * SAVE TRCSR FOR RECOVER RS232
00367A 10E8 97 5B A STA A R5L
00368      *
00369      * SERINS EQU *
00370A 10EA 0F SEI *
00371A 10EB 71 EF11 A AIM #FFF-S10,TRCSR * SERIAL INTERRUPT DISABLE
00372A 10EE 71 FB03 A AIM #FFF-S4,PORT2
00373      * INSR05 EQU *
00374A 10F1 4F CLR A
00375A 10F2 4C INC A
00376A 10F3 97 59 A SRRB10 STA A R4L * OMITTED HEADER BLOCK (INITIAL)
00377A 10F5 B6 01CA A SRRB20 LDA A SRTRCN * SET RETRY COUNT
00378A 10F8 97 56 A STA A R3H
00379      * RECEIVE FIRST CHARACTER
00380A 10FA DE 52 A SRRB30 LDX R1 * (X): STORED DATA ADDRESS
00381A 10FC B6 01CC A LDA A SRETMO * SET TIME OVER FOR WAITING BLOCK
00382A 10FF BD 10D3 A JSR SRVSXX
00383A 1102 25 D8 10DC BCS SRER20
00384A 1104 29 C5 10CB BVS SRERB0 * TIME OVER ERROR ?
00385A 1106 C6 04 A LDA B #4 * (B): BLOCK SIZE (PRESET FOR HEADER BLOCK)
    
```

ERR	SEQ	LOC	OBJECT	PROGRAM	EPSP	---	SERIAL (EPSP) EXAMPLE	---
	00386A	1108	81 01	A			CMP A #SOH	
	00387A	110A	27 2E 113A				BEQ SRRB50	
	00388A	110C	5C				INC B	* (B): 5
	00389A	110D	3A				ABX	* (X): DATA STORED ADDRESS
	00390A	110E	F6 01C8	A			LDA B SRSIZ	* (B): BLOCK SIZE (FOR DATA BLOCK)
	00391A	1111	81 02	A			CMP A #STX	
	00392A	1113	27 25 113A				BEQ SRRB50	
	00393A	1115	81 05	A			CMP A #ENQ	
	00394A	1117	27 19 1132				BEQ SRCE10	
	00395A	1119	81 04	A			CMP A #EOT	* EOT ?
	00396A	111B	27 86 10D3				BEQ SRERB8	
	00397							
	00398							
	00399A	111D	8D 1014	A			SRRB40 JSR SRVBYT	* OTHER CODES (SKIP CURRENT BLOCK AND SEND "NAK")
	00400A	1120	25 5D 117F				BCS SRRB90	* RECEIVED ONE CHARACTER ?
	00401A	1122	28 F9 111D				BVC SRRB40	
	00402							* TIME OVER (NOT RECEIVED DATA 0.1 SEC)
	00403							
	00404							* ERROR "NAK" SEND
	00405A	1124	86 15	A			SRCSER LDA A #NAK	
	00406A	1126	B7 01C9	A			STA A SRACKC	* SET NAK CHARACTER FOR "ENQ"
	00407A	1129	D6 56	A			LDA B R3H	* RETRY COUNT CHECK
	00408A	112B	27 A2 10CF				BEQ SRERB1	
	00409A	112D	7A 0056	A			DEC R3H	
	00410A	1130	27 9D 10CF				BEQ SRERB1	
	00411							* ENTRY FROM "ENQ"
	00412A	1132	86 01C9	A			SRCE10 LDA A SRACKC	
	00413A	1135	8D 1098	A			JSR SRSRGL	* SEND NAK
	00414A	1138	20 C0 10FA				BRA SRRB30	
	00415							
	00416							
	00417							* RECEIVE DATA BLOCK (SOH.... OR STX....)
	00418							
	00419A	113A	5C				SRRB50 INC B	
	00420A	113B	D7 55	A			STA B R2L	
	00421A	113D	97 58	A			STA A R4H	* R4H:RECEIVED FIRST CHARACTER
	00422A	113F	97 50	A			STA A R0H	* R0H:\$1 (SOH) OR \$2 (STX)
	00423A	1141	16				TAB	* (B):CHECKSUM
	00424							* RECEIVE DATA STRING LOOP
	00425A	1142	8D 1000	A			SRRB70 JSR SRVSGL	
	00426A	1145	25 38 117F				BCS SRRB90	
	00427A	1147	29 D8 1124				BVS SRCSER	* TIME OVER ?
	00428A	1149	A7 00	A			STA A 0,X	
	00429A	114B	08				INX	
	00430A	114C	1B				ABA	
	00431A	114D	16				TAB	
	00432A	114E	7A 0055	A			DEC R2L	
	00433A	1151	26 EF 1142				BNE SRRB70	
	00434							
	00435A	1153	8D 1000	A			SRRB75 JSR SRVSGL	* RECEIVE CHECKSUM
	00436A	1156	25 27 117F				BCS SRRB90	
	00437A	1158	29 CA 1124				BVS SRCSER	
	00438A	115A	1B				ABA	
	00439A	115B	16				TAB	
	00440A	115C	7A 0050	A			DEC R0H	* IF STX..., RECEIVE "ETX"

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ERR  SEQ  LOC  OBJECT  PROGRAM  EPSP  --- SERIAL (EPSP) EXAMPLE ---

00441A 115F 26 F2 1153      BNE  SRRB75
00442A 1161 5D              TST  B      * CHECKSUM OK ?
00443A 1162 26 CO 1124      BNE  SRCSER
00444
*
00445A 1164 86 06  A      LDA  A  #ACK
00446A 1166 87 01C9  A      STA  A  SRACKC  * SAVE SEND ACK CODE FOR 'ENQ'
00447A 1169 BD 1098  A      JSR  SRSGL
00448A 116C 25 11 117F      BCS  SRRB90
00449A 116E DC 58  A      LDD  R4      * R4H<--- FIRST CHARACTER OF BLOCK, (B):MODE
00450A 1170 88 01  A      EOR  A  #SOH
00451A 1172 26 DA 117E      BNE  SRRB80  * IF 'SOH', RECEIVED HEADER BLOCK (A=0)
00452
*
00453A 1174 DE 52  A      LDX  R1      * SET COUNTER
00454A 1176 E6 04  A      LDA  B  SRSIZ-SRFMT,X
00455A 1178 F7 01C8  A      STA  B  SRSIZ
00456A 117B 7E 10F3  A      JMP  SRRB10
* COMPLETED TO RECEIVE DATA BLOCK
00457
*
00458
SRRB80 CLR  A
SRRB90 CLI
LDX  R1
AIM  #5FF-54,MIOSTS * STATUS, STOP SERIAL COMMUNICATION
* RECOVER RS232 (NOT CHANGE C)
00464A 1185 7B B07D  A      TIM  #590,MIOSTS * BROKEN ?
00465A 1188 27 01 118B      BEQ  SRRB9A  * NOTE. AFTER 'CLI' INSTRUCTION, 'BREAK'
00466A 118A 0D              SEC      * MAY BE CAUSED.
00467
*
00468      118B  A      SRRB9A EQU  *
00469A 118B 7B 037A  A      TIM  #53,SRSTS * ON RS232 READ RUNNING ?
00470A 118E 27 0E 119E      BEQ  SRRB92
* WAIT 250 MICRO SEC (FOR SERIAL TERMINAL TO RECEIVE CHARACTER)
00471
00472A 1190 36              PSH  A
00473A 1191 86 32  A      LDA  A  #50
00474A 1193 4A              SRRB91 DEC  A
00475A 1194 26 FD 1193      BNE  SRRB91
00476A 1196 72 0403  A      OIM  #54,PORT2 * SELECT SERIAL SLAVE CPU
00477A 1199 96 5B  A      LDA  A  R5L  * RECOVER TRCSR
00478A 119B 97 11  A      STA  A  TRCSR
00479A 119D 32              PUL  A
*
00480
00481A 119E 8A 00  A      SRRB92 ORA  A  #50  * FOR RECOVER (Z) (UNCHANGE C)
00482A 11A0 39              RTS
*
00483
*
00484

*
00486
00487  * PROGRAM OF SENDING SIDE (MAIN DEVICE)
00488  * GET CHARACTERS FROM KEYBOARD AND SEND BY EPSP.
00489
*
00490
*
00491
00492A 11A1 86 01  A      OPNBIS LDA  A  #1  * DRIVER ON
00493A 11A3 BD FF73  A      JSR  SERONF
    
```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  EPSP      --- SERIAL (EPSP) EXAMPLE ---

00494A 11A6 CE 12B8 A          LDX      #SCRPSD * SET SCREEN PACKET X:DATA ADDRESS
00495A 11A9 C6 02 A          LDA B    #SCRPSE-SCRPSD * (B):NUBER OF DATA
00496A 11AB A6 00 A          INIT10  LDA A    0,X
00497A 11AD A7 08 A          STA A   SCRPK1-SCRPSD,X
00498A 11AF 08          INX
00499A 11B0 5A          DEC B
00500A 11B1 26 F8 11AB      BNE     INIT10
00501
*
00502A 11B3 CE 12C0 A          LDX      #SCRPK1 * INITIALIZE SCREEN
00503A 11B6 BD FF5E A          JSR      SCRFC * SELECT SCREEN DEVICE (DISPLAY CONTROLER)
00504
*
00505A 11B9 BD FF9A A          REPEAT  JSR      KEYIN
00506A 11BC 25 0C 11CA      BCS     BRKRTN
00507A 11BE B7 1231 A          STA A   BUF
00508A 11C1 4F          CLR A
00509A 11C2 CE 122C A          LDX      #SNDPKT * SERIAL TRANSMITTE
00510A 11C5 BD FF70 A          JSR      SEROUT
00511
*
00512A 11C8 20 EF 11B9      BRA     REPEAT
00513A 11CA 39          BRKRTN  RTS
00514
*
00515
*
00516

*
00518
*
00519
* PROGRAM OF RECEIVING SIDE (SLAVE DEVICE)
00520 * GET CHARACTERS FROM EPSP AND DISPLAY ON THE VIRTUAL SCREEN.
00521
*
00522
*
00523
*
00524
*
00525A 11CB 86 01 A          RECSID  LDA A   #1 * DRIVER ON
00526A 11CD BD FF73 A          JSR     SERONF
00527A 11D0 86 01 A          LDA A   #1 * SERIAL MASTER/SLAVE MODE = SLAVE
00528A 11D2 B7 01CE A          STA A   SRMODE
00529A 11D5 CE 132E A          LDX     #SCRPRD * SET SCREEN PACKET X:DATA ADDRESS
00530A 11D8 C6 0E A          LDA B   #SCRPRE-SCRPRD * (B):NUBER OF DATA
00531A 11DA A6 00 A          RECS10  LDA A   0,X
00532A 11DC A7 92 A          STA A   SCRPK1-SCRPRD,X
00533A 11DE 08          INX
00534A 11DF 5A          DEC B
00535A 11E0 26 F8 11DA      BNE     RECS10
00536
*
00537A 11E2 CE 12C0 A          LDX     #SCRPK1 * INITIALIZE SCREEN
00538A 11E5 BD FF5E A          JSR     SCRFC * SELECT SCREEN DEVICE
00539A 11E8 CE 12C8 A          LDX     #SCRPK2
00540A 11EB BD FF5E A          JSR     SCRFC * SET SCREEN SIZE AND BUFFER ADDRESS
00541A 11EE CE 12CD A          LDX     #SCRPK3 *
00542A 11F1 BD FF5E A          JSR     SCRFC * SET CURSOR MARGIN
00543A 11F4 CE 12CF A          LDX     #SCRPK4 *
00544A 11F7 BD FF5E A          JSR     SCRFC * SET SCROLL STEP
00545A 11FA CE 12D2 A          LDX     #SCRPK5 *
00546A 11FD BD FF5E A          JSR     SCRFC * SET SCROLL SPEED
    
```



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ERR  SEQ  LOC  OBJECT  PROGRAM  EPSP  --- SERIAL (EPSP) EXAMPLE ---

00547
00548A 1200 CC 3020 A          * DEVICE : TREAT AS DISPLAY CONTROLLER.
                                LDD  #$3020  * WAIT TO BE EPSP SELECTED
00549A 1203 CE 0000 A          LDX  #0
00550A 1206 BD 103D A          JSR  SRSLCT
00551A 1209 25 BF 11CA        RCVR10 BCS  BRKRTN
00552
                                *
00553A 120B CE 1233 A          RCVRPT LDX  #RCVPKT  * RECEIVE DATA
00554A 120E BD 10DF A          JSR  SERRCV
00555A 1211 25 B7 11CA        BCS  BRKRTN
00556A 1213 27 0F 1224        BEQ  RCVR20  * ERROR ?
00557A 1215 81 B8 A          CMP  A  #$B8  * RECEIVED 'EOT' ?
00558A 1217 26 F2 120B        BNE  RCVRPT
00559A 1219 CC 3020 A          LDD  #$3020  * WAIT TO BE EPSP SELECTED
00560A 121C CE 0000 A          LDX  #0
00561A 121F BD 1031 A          JSR  SRSLET
00562A 1222 20 E5 1209        BRA  RCVR10
00563
                                *
00564A 1224 B6 1238 A          RCVR20 LDA  A  RCVPKT+5 * DISPLAY RECEIVED CHARACTERS ON THE VIRTUAL
00565A 1227 BD FF4F A          JSR  DSPSCR  * SCREEN (LCD)
00566A 122A 20 DF 120B        BRA  RCVRPT
00567
                                *
00568
                                * PACKET OF SEND DATA STRING
00569
                                *
00570A 122C 00 A          SNDPKT FCB  $0  * FORMAT
00571A 122D 30 A          FCB  $30  * SID (DISPLAY CONTROLLER)
00572A 122E 20 A          FCB  $20  * DID (HC-20)
00573A 122F 92 A          FCB  $92  * FUNCTION
00574A 1230 00 A          FCB  0  * DATA LENGTH
00575A 1231 00 A          BUF  FCB  0  * DATA
00576A 1232 00 A          FCB  0
00577
                                *
00578
                                * PACKET OF RECEIVE DATA STRING
00579
                                *
00580A 1233 00 A          RCVPKT FCB  $0  * FORMAT
00581A 1234 30 A          FCB  $30  * SID (DISPLAY CONTROLLER)
00582A 1235 20 A          FCB  $20  * DID (HC-20)
00583A 1236 92 A          FCB  $92  * FUNCTION
00584A 1237 00 A          FCB  0  * DATA LENGTH
00585A 1238 0080 A        RMB  128  * DATA
00586
                                *
00587
                                * SCREEN PACKET FOR SENDING SIDE
00588A 1238 84 A          SCRPSD FCB  $84  * SCREEN DEVICE SELECT (DISPLAY CONTROLLER)
00589A 12B9 30 A          FCB  $30
00590
                                *
00591
                                *
00592
                                *
00593
                                *
00594
                                * WORK AREA
00595A 12BA 0006 A        RMB  6
00596A 12C0 84 A          SCRPK1 FCB  $84  * SELECT SCREEN DEVICE
00597A 12C1 22 A          FCB  $22
00598A 12C2 0006 A        RMB  6
00599A 12C8 87 A          SCRPK2 FCB  $87  * SET SCREEN SIZE AND BUFFER ADDRESS
00600A 12C9 13 A          FCB  19,3
                                A 12CA 03 A

```

ERR	SEQ	LOC	OBJECT	PROGRAM	EPSP	--- SERIAL (EPSP) EXAMPLE ---	
	00601A	12CB	12D4	A	FDB	SCRBUF	
	00602				*		
	00603A	12CD	C3	A	SCRPK3	FCB \$C3	* SET CURSOR MARGIN
	00604A	12CE	04	A	FCB	4	
	00605				*		
	00606A	12CF	C4	A	SCRPK4	FCB \$C4	* SET SCROLL STEP
	00607A	12D0	0A	A	FCB	10	* X
	00608A	12D1	03	A	FCB	3	* Y
	00609				*		
	00610A	12D2	CB	A	SCRPK5	FCB \$CB	* SET SCROLL SPEED
	00611A	12D3	09	A	FCB	9	
	00612				*		
	00613A	12D4	005A	A	SCRBUF	RMB 90	
	00614				*	SCREEN PACKET FOR RECEIVING SIDE	
	00615A	132E	84	A	SCRPRD	FCB \$84	* SCREEN DEVICE SELECT (LCD)
	00616A	132F	22	A	FCB	\$22	
	00617				*		
	00618A	1330	87	A	FCB	\$87	* SET SCREEN SIZE AND BUFFER ADDRESS
	00619A	1331	13	A	FCB	19,3	
	A	1332	03	A			
	00620A	1333	12D4	A	FDB	SCRBUF	
	00621				*		
	00622A	1335	C3	A	FCB	\$C3	* SET CURSOR MARGIN
	00623A	1336	04	A	FCB	4	
	00624				*		
	00625A	1337	C4	A	FCB	\$C4	* SET SCROLL STEP
	00626A	1338	0A	A	FCB	10	* X
	00627A	1339	03	A	FCB	3	* Y
	00628				*		
	00629A	133A	CB	A	FCB	\$CB	* SET SCROLL SPEED
	00630A	133B	09	A	FCB	9	
	00631				*		
	00632		133C	A	SCRPRE	EQU *	
	00633				*		
	00634				*		
	00635		0000	A	END		
*****	TOTAL ERRORS		0				

CHAPTER 5

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5.1 General

The RS-232C port performs communication by the start-stop synchronization method (refer to the description of serial communication in Chapter 4). Generation of the TXD binary signal and read of the RXD binary signal are performed by software. The master MCU transmits data (TXD) and the slave MCU receives data (RXD). The slave MCU receives 1 character of data which it sends to the master MCU via the SCI. The master MCU then uses an SCI interrupt to store this data in the receive buffer (Fig. 5-1).

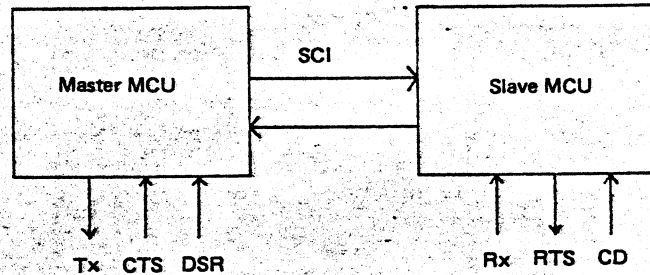


Fig. 5-1 Assignment of RS-232C Functions

5.2 Data Transmission Method

TXD is controlled by port P21 of the master MCU. When a value is set in the OCR and the OCF is set to 1, the value of the OLVL (bit 0 of TCSR) is output from P21 (Fig. 5-2).

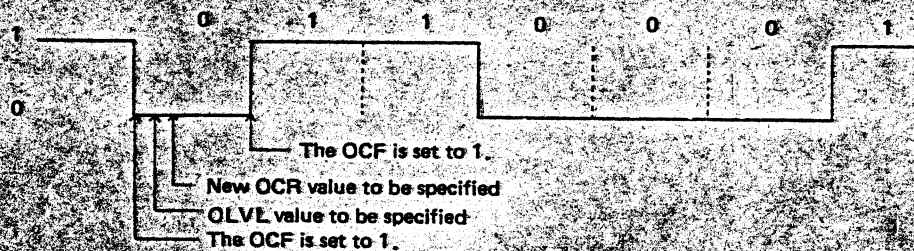


Fig. 5-2 Timing of TXD Transmission

5.3 Data Reception Method

Receive data is input to port P20 of the slave MCU. Input of a start bit in P20 is monitored.

The value of FRC when it takes the value specified by IEDG (bit 1 of TCSR) is set in ICR and this is used to measure the timing of the start bit. Based on this, the calculated center of each pulse is sampled to obtain one character of data (Fig. 5-3).

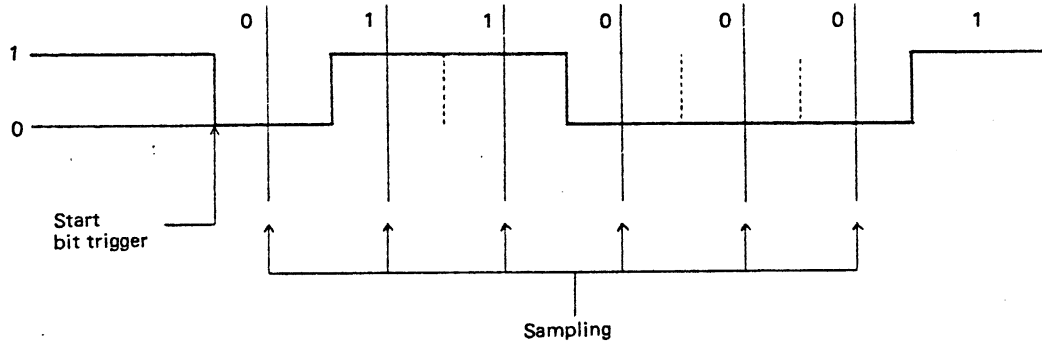


Fig. 5-3 Sampling of Receive Data

One character of data is then transmitted to the master MCU via the SCI (Fig. 5-4).

The master MCU enables receive interrupt by the SCI. The SCI receive interrupt routine stores the receive data in the receive buffer. When the buffer becomes full, an error flag is set and data received subsequent to this will be discarded. The slave MCU cancels input of data through the RS-232C port when a command is sent to it from the master MCU.

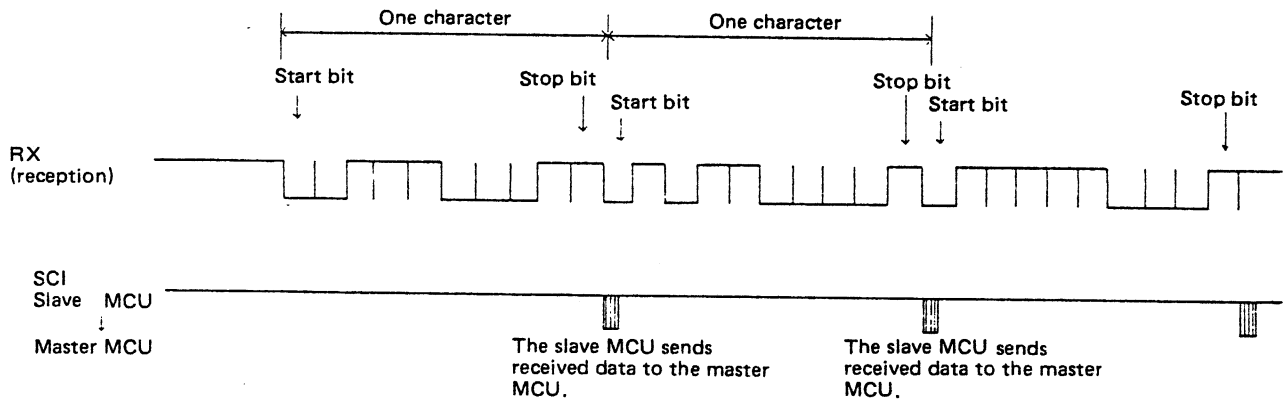


Fig. 5-4 Timing of Data Reception

5.4 Data Communication

Data communication via the RS-232C port is performed by the following procedures.

(1) Setting Parameters

Values for bit rate, word length, parity bit, stop bit length, CD, RTS, DSR detection, are specified by subroutine RSMST. This subroutine specifies the values for constants used in data communication in the I/O work area.

- (2) Driver ON
Subroutine RSONOF turns the RS-232C driver ON.
When the driver is turned ON, both RTS and TXD go low (RTS is turned OFF and TXD becomes logic 1).
A 10-bit preamble (logic 1) is then output. DTR is directly connected to the driver power and therefore goes high (ON) when the driver is turned ON.
- (3) Receive buffer open
The receive buffer in the master MCU is opened by subroutine RSOPEN. Once the receive buffer has been opened, the slave MCU begins sending data. The RTS value is set to the value specified procedure (1) above.
- (4) Input of one character
Data is fetched from the receive buffer using subroutine RSGET. The data received by the slave MCU is stored in the receive buffer during SCI interrupt processing.
- (5) Output of one character
Subroutine RSPUT outputs one character of data. Note that no buffer is used when outputting data.
- (6) Termination of data reception
Subroutine RSCLOS terminates RS-232C data reception.
- (7) Driver OFF
RSONOF is used to turn the RS-232C driver OFF.

5.5 Notes on I/O Open Condition

The main MCU enable SCI interrupt during RS-232C reception. When the SCI port is accessed directly, the SCI interrupt must be disabled. When the slave MCU receives new data from the SCI port, it cancels data reception from the RS-232C port. The master MCU uses subroutine SNSCOM to send a command to the slave MCU during RS-232C reception and calls subroutine CHKRS (resumption of the interrupted RS-232C data reception) upon completion of transmission of the command.

5.6 Bit Rate Setting

Subroutine RSMST is used to set bit rates for RS-232C transmission (110, 150, 300, 600, 1200, 2400, 4800 and 9600 BPS). To set a transmission speed other than one of those listed above, RSMST must be called and the desired bit rate set directly in variable RSBAUD (01AF, 01B0). This 2-byte variable indicates the number of MCU clock pulses and is set at 1000_{16} for a bit rate of 150 BPS. A bit rate of 75 BPS is therefore obtained by setting 2000_{16} in variable RSBAUD. Note that this value is used directly by the transmission subroutine so the bit rate will change as soon as the value of RSBAUD is altered.

5.7 RTS Operation and Carrier Detection

When using a half-duplex MODEM, the RTS output must be changed and the carrier ON/OFF must be detected. Both RTS and the carrier ports are connected to the slave MCU. RTS control and CD detection are performed by the procedures described below.

(1) RTS Control

Method 1: Subroutine RSOPEN

RTS is set when reception is opened by subroutine RSOPEN.

Reception is temporarily closed (subroutine RSCLOS) and the appropriate parameters are set by subroutine RSMST (the previously set parameters remain effective if this is not performed).

Reception is then reopened by subroutine RSOPEN. (Fig. 3-5).

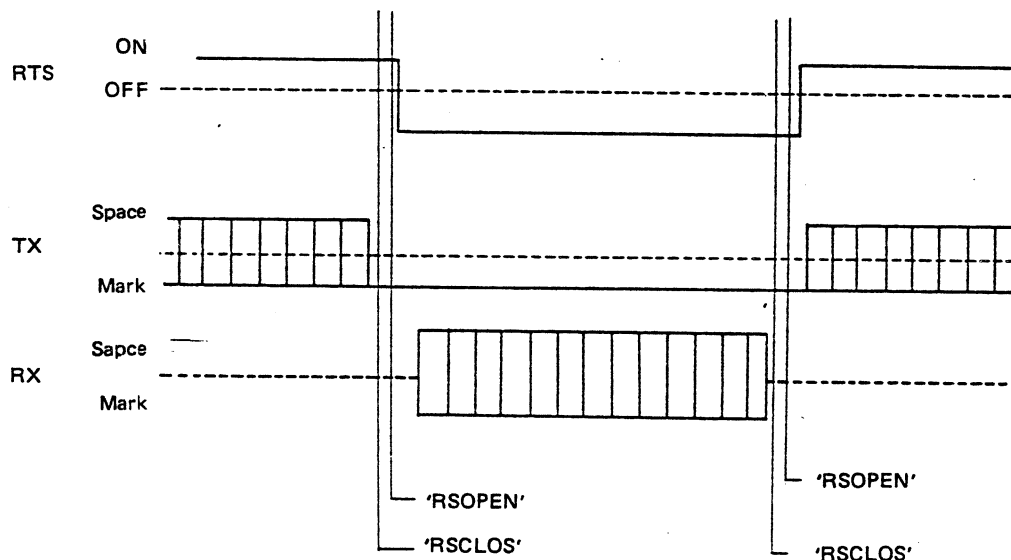


Fig. 5-5 RTS Control (1)

Method 2: Slave MCU command

When performing half-duplex communication, RTS is normally turned ON while data is being transmitted and turned OFF when data is being received. Command 4D, sent to the slave MCU, controls the RTS. This command should be used to turn RTS ON before the start of data transmission. RTS should be turned OFF to open reception (Fig. 5-5).

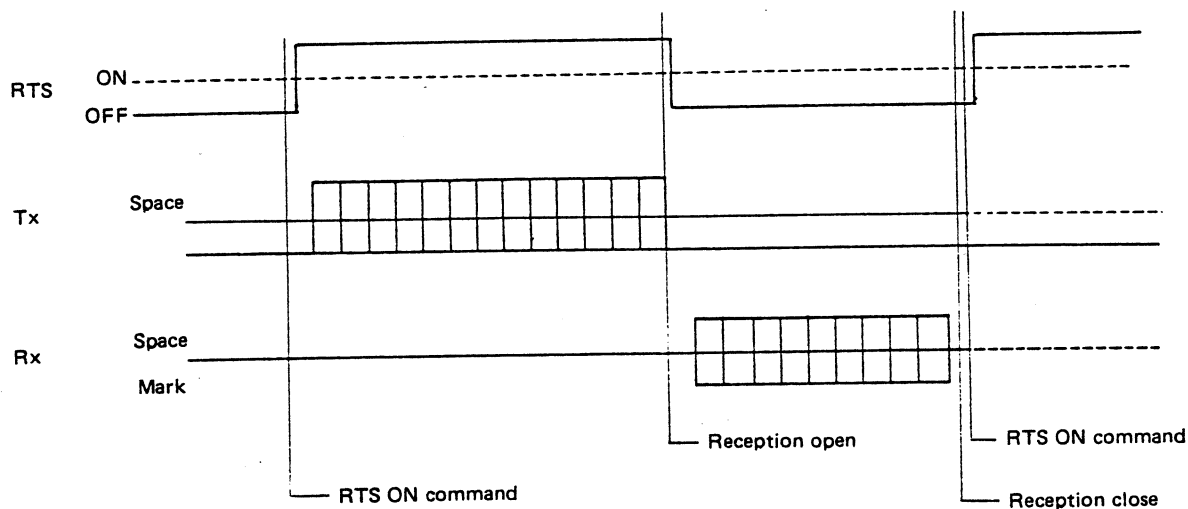


Fig. 5-6 RTS Control (2)

(2) Carrier detection

When the reception is opened, the carrier status is set in port P12 of the master MCU (port P47 of the slave MCU actually detects the carrier status but this data is set in port P12 of the master MCU by software). When the carrier is OFF, P12 of the master MCU is set to 1. When the carrier is ON, P12 is set to 0. Note that after reception has been opened, if carrier OFF status has been detected, carrier ON will cause data reception to start but P12 will not become 0.

The system waits for carrier ON by the following two methods.

Method 1: If P12 is 1 when the reception is opened, reception is closed and then reopened. This is repeated until carrier ON is detected.

Method 2: Command 80, which sets the value of the slave MCU port in port P12 of the master MCU, is executed for the slave MCU until the carrier is set ON (P12 is set to 0). Reception is then opened.

5.8 Communications Using a MODEM

When using a MODEM, in addition to the data lines for transmission and reception, the control lines must be operated. Fig. 7 shows the timing for a 1200-BPS, half-duplex MODEM.

When data communication is performed as shown in this figure, RTS control as well as CTS and CD detection must be confirmed.

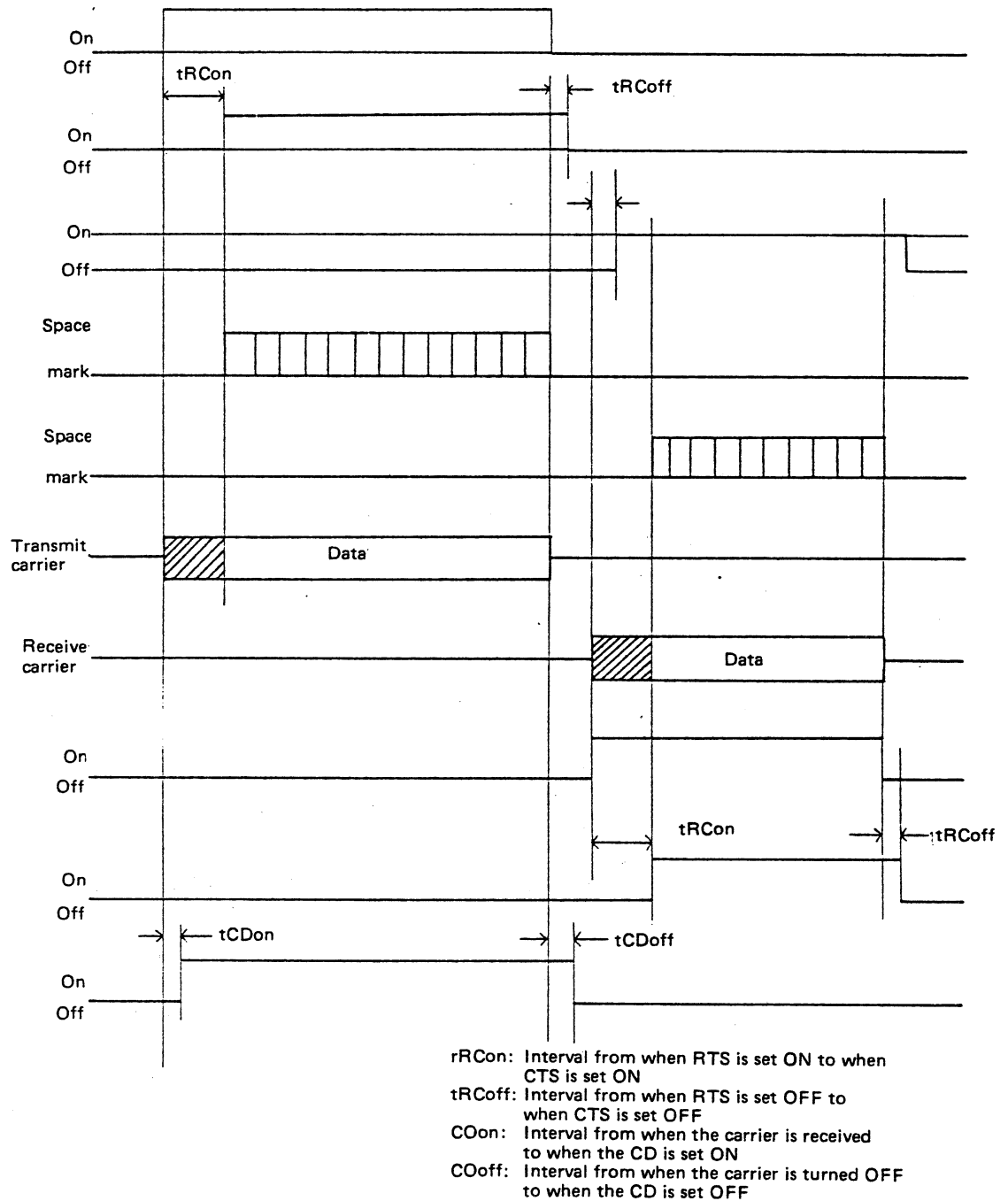


Fig. 5-7 Timing of 1200-BPS, Half-duplex MODEM

The reception routine provides a mode in which data can be received even if no carrier has been detected. If the carrier OFF state is not of great importance, the reception can be opened in this mode and the carrier ignored.

1200-BPS reverse channels

A 1200-BPS MODEM may use a 75-BPS reverse channel. This is performed by the following two procedures.

- (i) 1200-BPS transmission and 75-BPS reception. This is enabled by opening reception (RSOPEN) at 75 BPS and then setting the mode (RSMOD) at 1200 BPS.
- (ii) 1200-BPS reception and 75-BPS transmission
Reception is opened at 1200 BPS and the bit rate is set to 75 BPS (2000_{16} in variable RSBAUD).

Since master MCU interrupt is disabled during data transmission, data received at this time will be lost as shown in Fig. 5-8.

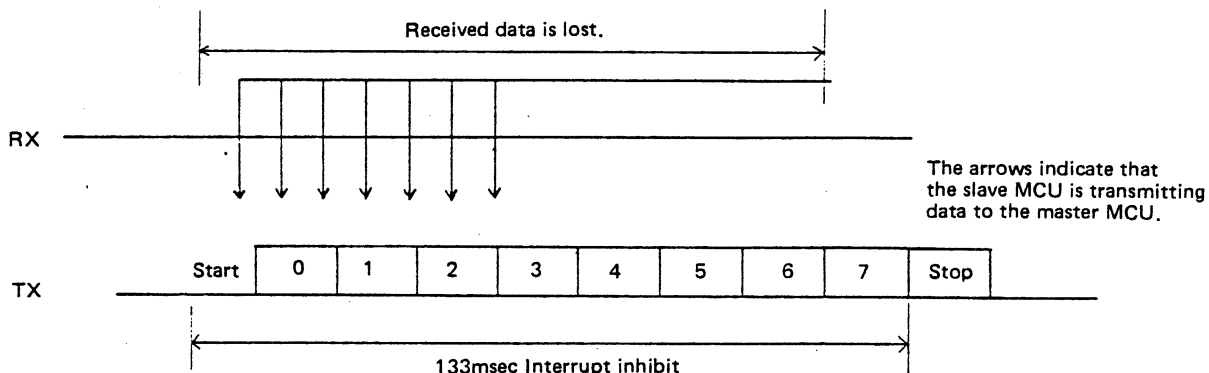


Fig. 5-8 Full-duplex Communication at 1200 and 75 BPS

To protect receive data, the data transmission routine in which interrupt inhibit instruction SEI is omitted must be used. (See end of this chapter.)

5.9 Cautions For Serial Driver ON/OFF

(1) When the Driver is Turned ON

Signal rise may be unstable when the driver is turned ON as shown in Fig. 5-9.

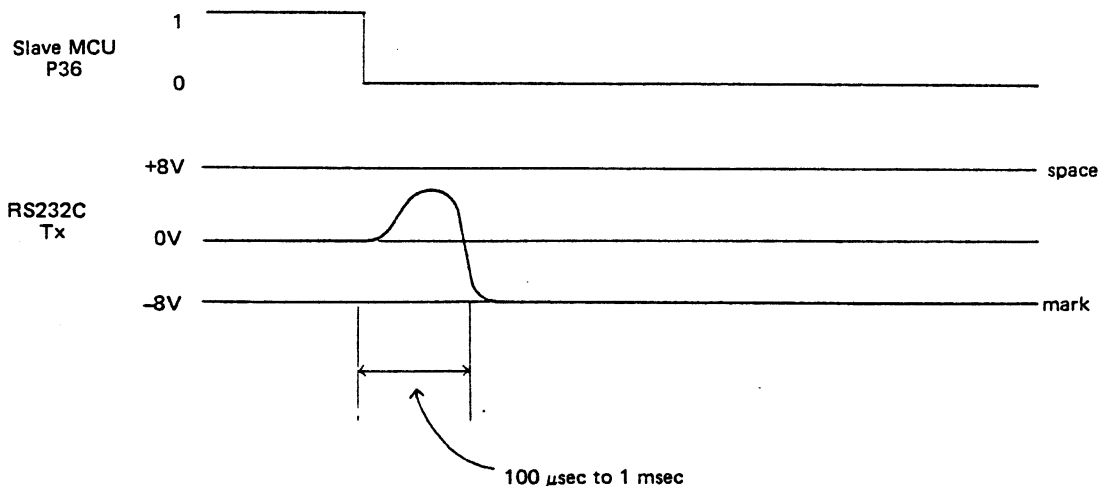


Fig. 5-9 Voltage Change when Driver is Turned ON

In this case, the receiving side may receive incorrect data because it interprets the space state when the driver is turned ON as the start bit.

(2) When the Driver is Turned OFF

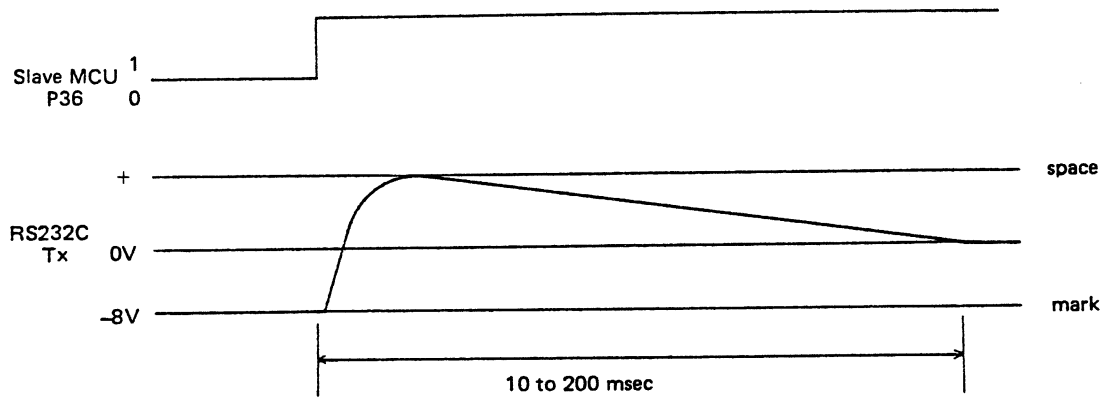


Fig. 5-10 Voltage Change when Driver is Turned OFF

The voltage may change as shown in Fig. 5-10 when the driver is turned OFF. Again, the receiving side may interpret the resulting several tens or hundreds of bits of space states as data, resulting in erroneous data reception.

The driver is turned OFF when the input through the RS-232C port is closed in BASIC. Turn the serial driver ON if you wish to leave the driver on after the RS-232C output is closed. (In terms of software, the serial and RS-232C driver are treated as separate elements. Therefore the driver will only be turned OFF when both drivers are set to OFF from software.)

Press the BREAK key and check the contents of bit 7 of address 7A. When bit 7 is 0, the driver is ON and when it is 1, the driver is OFF. The default value for bit 7 is 0.

5.10 Another Method of Managing Control Lines

Since the RTS and CD control lines are connected to the slave MCU, during RTS control and CD detection there is an idle time (time required for exchanging the master MCU commands) which may cause the user inconvenience.

To avoid this, serial POUT and PIN can be used instead of RTS and CTS as control lines (Fig. 5-11).

POUT corresponds to bit 5 of address 26, and is active low.

Subroutine WRTP26 is used to set data in address 26. PIN corresponds to bit 6 of port 1 and is also active low.

(Example)

Note:

As the floppy disk unit does not use PIN and POUT for serial communication, the RS-232C port can use them as control lines.

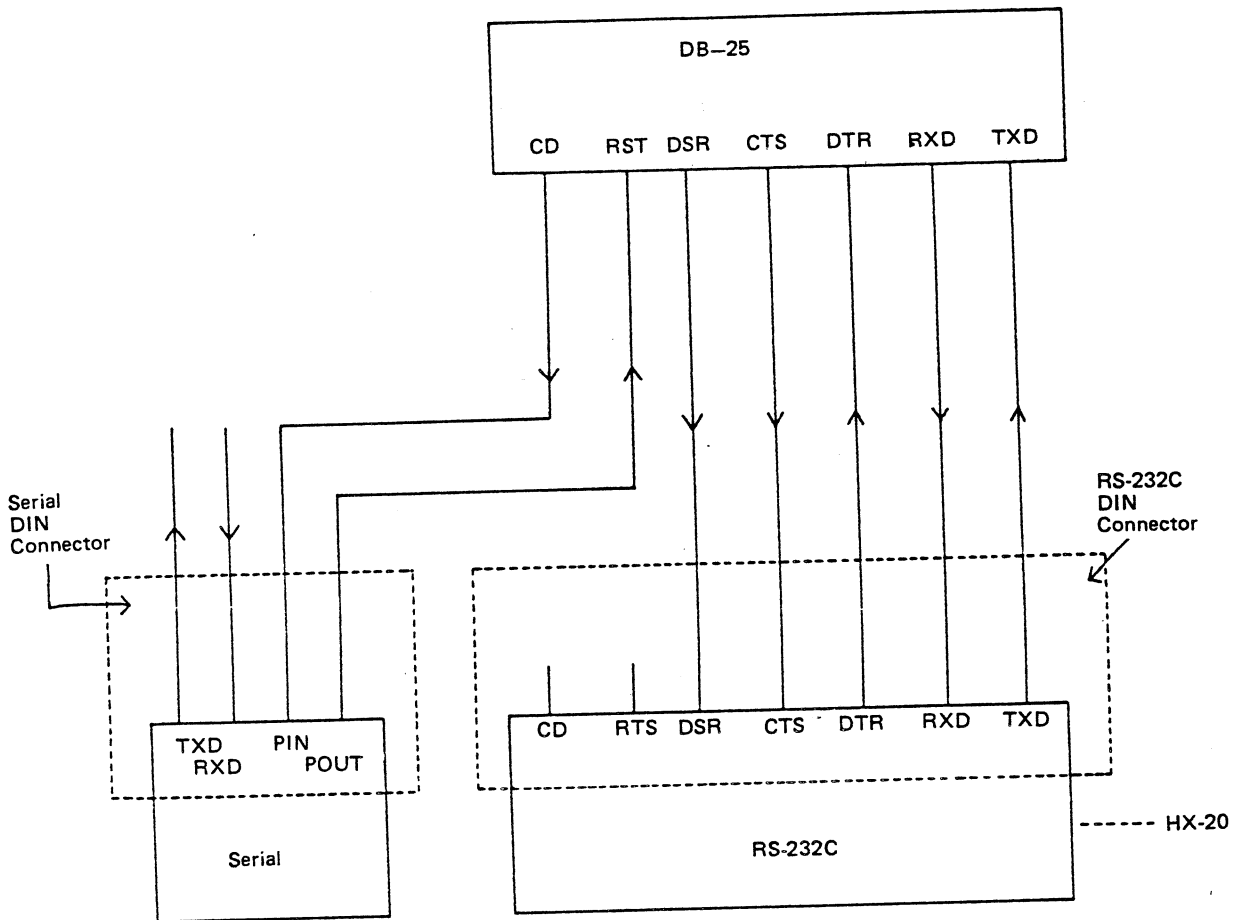


Fig. 5-11 Modification of RS-232C Control Lines

5.11 RS-232C Subroutines

Subroutine name	Entry point	Description
<p>RSMST</p> <p><i>A</i> 11110001</p> <p><i>B</i> 00000000</p>	<p>FF8A</p>	<p>Specifies the RS-232C mode. Sets values in variables RSBITL, RSMODS, and RSBAUD. Communications with the slave MCU are not performed.</p> <p>Parameters:</p> <p>At Entry</p> <p>(A): Mode</p> <p>Bit 0 and 1: Stop bit length (1, 2 or 3)</p> <p>Bit 2: Specifies whether or not carrier detection will be performed.</p> <p>0: Carrier detection</p> <p>1: No carrier detection</p> <p>Bit 3: RTS (0: OFF 1: ON)</p> <p>Bit 4: DRS</p> <p>0: Checks DSR</p> <p>1: Does not check DSR</p> <p>Bit 5: CTS</p> <p>0: Checks CTS</p> <p>1: Does not check CTS</p> <p>Bits 6 and 7: Parity</p> <p>0: Even</p> <p>1: Odd</p> <p>2 or 3: None</p> <p>(B): Bit rate and word length</p> <p>Bits 0 through 3: Word length (5, 6, 7, and 8)</p> <p>Bits 4 through 7: Bit rate</p> <p>0: 110 BPS</p> <p>1: 150 BPS</p> <p>2: 300 BPS</p> <p>3: 600 BPS</p> <p>4: 1200 BPS</p> <p>5: 2400 BPS</p> <p>6: 4800 BPS</p> <p>7: 9600 BPS (transmission only)</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>(A), (B), and (X)</p> <p>Subroutines referenced</p> <p>None</p> <p>Variables used</p> <p>None</p>
<p>RSONOF</p>	<p>FF85</p>	<p>Turns ON/OFF the RS-232C driver. When bits 3 and 4 of SRSTS are off, this subroutine turns the driver ON and transmits a 10-bit preamble (data logic 1).</p> <p>If the driver is already ON, the ON procedure will be ignored but no error will occur.</p>

Subroutine name	Entry point	Description
		<p>Parameters:</p> <p>At Entry (A) 0: Turns OFF the driver power. 1: Turns ON the driver power.</p> <p>At Return (A): Error code (C): Abnormal I/O flag (Z): According to the value of (A).</p> <p>Registers retained (B) and (X)</p> <p>Subroutines referenced SNSCOM</p> <p>Variables used None</p>
RSOPEN	FF82	<p>Opens the RS-232C input, initiates fetching data into a buffer, and exchanges commands between the master and slave MCUs. Receive data is stored in the receive buffer via the SCI (interrupt processing). When the RS-232C input is opened, RTS is set at the value specified in subroutine RSMST.</p> <p>Parameters:</p> <p>At Entry (A, B): Receive buffer size (X): Starting address of the receive buffer</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: RS-232C input has been correctly opened. 01: The driver is OFF.</p> <p>Registers retained None</p> <p>Subroutines referenced SNSCOM, SNSCOW and SNSDAT</p> <p>Variables used None</p> <p>(Example)</p> <p>In this example, a 260-byte monitor buffer is opened as the receive buffer.</p> <pre>LDA A #\$0D Even parity, CTS/DSR check, RTS high CD check, 1 stop bit LDA B #\$27 300 BPS 7-bit word length JSR RSMST LDA A #1 Driver ON JSR RSONOF LDD #260 Buffer size = 260 bytes LDX #CASBUF JSR RSOPEN</pre>
RSCLOS	FF7F	<p>Closes input to the RS-232C port and sends a command to the slave MCU to terminate reception. This subroutine does not turn the driver OFF.</p>

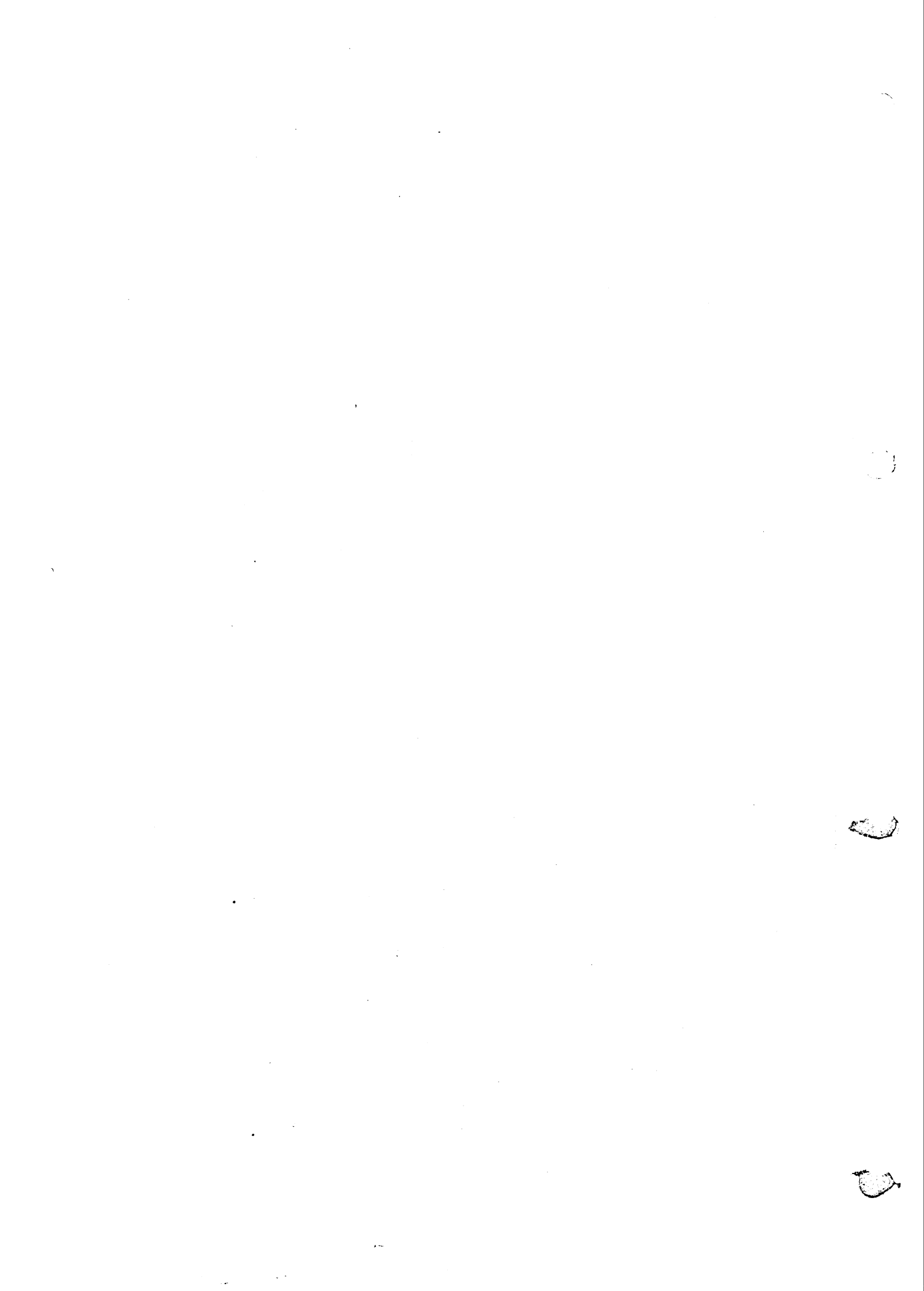
Subroutine name	Entry point	Description
		Parameters: At Entry None At Return (C): Abnormal I/O flag (A): Return codes 00: RS-232C has been correctly closed. (Only this code is currently available.) (Z): According to the value of (A) Registers retained (B) and (X) Variables used None Subroutines referenced None
RSGSTS	FF7C	Inputs the value of the status register. When a receive error occurs, this subroutine fetches the error status from the slave MCU and inputs this value to the master MCU. Then, the error status of the slave MCU is cleared. Logic 1 in any bit indicates an error. Parameters: At Entry None At Return (C): Abnormal I/O flag (A): Status managed by master MCU (RS-232 transmitting side) Bit 7: 1: Receive buffer overflow (B): Status managed by the slave MCU (RS-232C receiving side) Bit 0: Carrier disconnection (OFF) Bit 1: Parity error Bit 2: Overrun error Bit 5: Receive error Registers retained (X) Subroutines referenced SNSCOM and CHKRS Variables used None
RSGET	FF79	Fetches one character from the receive buffer. The data in the receive buffer is stored in word length + parity bit format. Once a character is fetched, the parity bit is set to 0. This parity bit is not stored in the receive buffer if the format is 8 bits + 1 parity bit. Parameters: At Entry None At Return (C): Abnormal I/O flag (A): Received character (B): Return codes

Subroutine name	Entry point	Description
		<p>00: Normal 01: Receive buffer full C0: Parity error C1: Carrier disconnection (OFF)</p> <p>Note: Carrier disconnection (OFF) error occurs not when the carrier falls but when the buffer becomes empty.</p> <p>(Z): According to the value of (B). Registers retained (X) Subroutines referenced None Variables used R0H</p>
RSPUT	FF76	<p>Transmits one character through the the RS-232C port. Note that no transmit buffer is provided.</p> <p>Parameters:</p> <p>At Entry (A): Output characters If the number of bits to be transmitted is less than 8 bits, data is right-justified. The remaining bits (including the parity bit) can be any value.</p> <p>At Return (C): Abnormal I/O flag (B): Return codes 00: Normal 01: No data transmitted when DSR is OFF. 02: No data transmitted when CTS is OFF. 03: No data transmitted when both DSR and CTS are OFF.</p> <p>(Z): According to the value of (B) Registers retained (A) and (X) Subroutines referenced None Variables used R0, R1, and R2H</p>
CHKRS	FF16	<p>Sends a command to the slave MCU to resume the interrupted RS-232C input.</p> <p>Parameters:</p> <p>At Entry None</p> <p>At Return None</p> <p>Registers retained (A), (B), (X), and condition code (CC) Subroutines referenced RSRST Variables used None</p>

5.12 RS-232C Work Areas

Address (from) (to)	Variable name	Byte count	Description
1AF 1B0	RSBAUD	2	RS-232C bit rates (clock cycles) 150 BPS : 1000_{16} 300 BPS : 800_{16}
1B1 1B2	RSCRC	2	Polynomial expressions generated for CRC Polynomial expression CRC-CCITT ($1+x^5+x^{12}+x^{16}$) equals 8408_{16} (default value) CRC-16 ($1+x^2+x^{15}+x^{16}$) equals $A00_{16}$ x^{16} is always 1, x^{15} is bit 0, and x^0 is bit 15.
1B3 1B4	RSBCC	2	BCC register for CRC check
1B5 1B5	RSBITL	1	RS-232C word length (stop bit excluded) Word length must be 5, 6, 7, or 8.
1B6 1B6	RSMODS	1	RS-232C mode Bits 0 and 1: Stop bit length (bit 1, bit 0): (0,1) = 1 (1,0) = 2 Bit 2: Carrier (CD) detection 0: Carrier detection 1: No carrier detection Bit 3: RTS 0: RTS OFF (low level) 1: RTS (high level) Bit 4: DSR check 0: Checks if DSR is OFF. 1: Does not check if DSR is OFF. Bit 5: CTS check 0: Checks if CTS is OFF. 1: Does not check if CTS is OFF. Bits 6 and 7: Parity (bit 7, bit 6) = (0,0) : Even parity (0,1) : Odd parity (1,x) : No parity x: don't care
1B7 1B7	RSSTSR	1	RS-232C error status register For all bits of this variable, logic 0 indicates normal operation and logic 1 indicates error. Bit 0: Carrier disconnection (OFF) Bit 1: Parity Bit 2: Overrun Bit 3: Undefined Bit 4: Undefined Bit 5: Receive error Bit 6: Transmit error Bit 7: Receive buffer overflow

Address (from) (to)	Variable name	Byte count	Description
1B8 1B9	RSBFAD	2	Starting address of RS-232C receive buffer
1BA 1BB	RSBFBT	2	Last address of RS-232C receive buffer plus 1
1BC 1BD	RSBFSZ	2	Size of RS-232C receive buffer (in bytes)
1BE 1BE	RSINP	2	Pointer indicating the last data stored in the RS-232C receive buffer (Indicates the next address the buffer in which received data will be stored.)
1C0 1C1	RSOUP	2	Pointer indicating the last data fetched from the RS-232C receive buffer (Indicates the next address to be fetched when data is fetched from the receive buffer.)
1C2 1C3	RSDCNT	2	Number of data in the RS-232C receive buffer (in bytes)



ERR SEQ LOC OBJECT PROGRAM RS232C -- RS232C SEND/RECEIVE DATA ROUTINE ---

```

00001          NAM      RS232C
00002          TTL      -- RS232C SEND/RECEIVE DATA ROUTINE ---
00003          *
00004          * RS232C SUBROUTINE.
00005          * 2 SUBROUTINES
00006          * 1. GET RECEIVED CHARACTER FROM RS232C RECEIVED DATA BUFFER (RSGET).
00007          * 2. TRANSMITTE ONE CHARACTER TO TXD LINE (RSPUT).
00008          *
00009          * FILE NAME 'EXSA'      BY K AKAHANE
00010          OPT      PAGE=55
00011          OPT      LOAD
00012          *
00013          * MCU 6301 I/O PORT
00014          0002  A    PORT1 EQU      $02      * I/O PORT 1
00015          0003  A    PORT2 EQU      $03      * I/O PORT 2
00016          0006  A    PORT3 EQU      $06      * I/O PORT 3
00017          * OTHER REGISTERS
00018          0009  A    FRC EQU      $09      * FREE RUNNING COUNTER
00019          0008  A    OCR EQU      $02      * OUTPUT COMPARE REGISTER
00020          0008  A    TCSR EQU     $08      * TIME CONTROL AND STATUS REGISTER
00021          * GENERAL REGISTERS USED BY I/O ROUTINE
00022A 0050          0050  A    ORG      $50
00023          0001  A    R0 EQU      *      * 2 BYTES REGISTER (R0H,R0L)
00024A 0050          0001  A    R0H RMB    1
00025A 0051          0001  A    R0L RMB    1
00026          0052  A    R1 EQU      *      * 2 BYTES REGISTER (R1H,R1L)
00027A 0052          0001  A    R1H RMB    1
00028A 0053          0001  A    R1L RMB    1
00029          0054  A    R2 EQU      *      * 2 BYTES REGISTER (R2H,R2L)
00030A 0054          0001  A    R2H RMB    1
00031A 0055          0001  A    R2L RMB    1
00032          0056  A    R3 EQU      *      * 2 BYTES REGISTER (R3H,R3L)
00033A 0056          0001  A    R3H RMB    1
00034A 0057          0001  A    R3L RMB    1
00035A 007A          0001  A    ORG     $7A
00036A 007A          0001  A    SRSTS RMB    1      * SERIAL STATUS
00037          *      * BIT 0,1: RS232 MODE(00:STOP 01:INTERRUPT AD
00038          *      *      *      *      *      *      *      *      *      *      *
00039          *      *      *      *      *      *      *      *      *      *      *
00040          *      *      *      *      *      *      *      *      *      *      *
00041          *      *      *      *      *      *      *      *      *      *      *
00042          *      *      *      *      *      *      *      *      *      *      *
00043          *      *      *      *      *      *      *      *      *      *      *
00044          *      *      *      *      *      *      *      *      *      *      *
00045          *      *      *      *      *      *      *      *      *      *      *
00046          *      *      *      *      *      *      *      *      *      *      *
00047          *      *      *      *      *      *      *      *      *      *      *
00048          *      *      *      *      *      *      *      *      *      *      *
00049          *      *      *      *      *      *      *      *      *      *      *
00050A 0073          0001  A    RUNMOD RMB    1      * RUN MODE ($80: BASIC $00: SYSTEM)
00051A 007C          0001  A    SIOSTS RMB    1      * SLAVE I/O STATUS (EACH BIT 0:OFF, 1:ON)
00052          *      *      *      *      *      *      *      *      *      *      *
00053          *      *      *      *      *      *      *      *      *      *      *
00054          *      *      *      *      *      *      *      *      *      *      *
00055          *      *      *      *      *      *      *      *      *      *      *

```

```

ERR  SEQ  LOC  OBJECT  PROGRAM  RS232C  -- RS232C SEND/RECEIVE DATA ROUTINE ---
00056
00057
00058
00059
00060
00061A 007D 0001 A  MIOSTS RMB 1
00062
00063
00064
00065
00066
00067
00068
00069
00070
00071A 01AF 0001 A  WORK AREA
                                ORG  $1AF
00072
00073
00074
00075 01AF A  RS232C WORK AREA
                                RSWKTP EQU *
00076A 01AF 0002 A  RSBAUD RMB 2
00077A 01B1 0002 A  RSCRC RMB 2
00078A 01B3 0002 A  RSBCC RMB 2
00079A 01B5 0001 A  RSBITL RMB 1
00080A 01B6 0001 A  RSMODS RMB 1
00081
00082
00083
00084
00085
00086
00087
00088A 01B7 0001 A  RS232C BUFFER POINTER
                                RSSTSR RMB 1
00089
00090
00091
00092
00093
00094
00095
00096A 01B8 0002 A  RSBFAD RMB 2
00097A 01BA 0002 A  RSBFBT RMB 2
00098A 01BC 0002 A  RSBFSZ RMB 2
00099A 01BE 0002 A  PSINP RMB 2
00100A 01C0 0002 A  RSOUNP RMB 2
00101A 01C2 0002 A  RSDCNT RMB 2
00102
00103
00104
00105
00106
00107
00108
00109
00110

* BIT 4: SPEAKER ON
* BIT 5: ROM CASSETTE
* BIT 6: BAR CODE READER
* BIT 7: BREAK SLAVE CPU (0:ON EXECUTE
                                1:BROKEN BY INTERRUPT)
* MAIN I/O STATUS EACH BIT (0:OFF 1:ON)
* BIT 0: LCD ON READ/WRITE CHARACTERS
* BIT 1: NOW SENDING COMMAND TO SLAVE CPU
* BIT 2: NOW SENDING DATA TO SERIAL LINE (1:ON)
* BIT 3: ON CLOCK INTERRUPT (1:ON)
* BIT 4: (POWER FAIL)
* BIT 5: (OFF POWER SWITCH)
* BIT 6: ON PAUSE KEY
* BIT 7: ON BREAK KEY

* WORK AREA
                                ORG  $1AF

* RS232C WORK AREA
                                RSWKTP EQU *
* RS232C WORK TOP ADDRESS
* RS232C BIT RATE (NUMBER OF CLOCK CYCLE)
* RS232C GENELATING POLYNOMIAL
* RS232C BCC REGISTER
* RS232C BIT LENGTH (5 6 7 8)
* RS232C MODE
* (0,1:NUMBER OF STOP BITS)
* (2: CARRIER DETECT MASK 0:CHECK 1:MASK)
* (3: CLEAR TO SEND 0:LOW 1:HIGH)
* (4: DSR 0:CHECK 1:NO CHECK)
* (5: CTS 0:CHECK 1:NO CHECK)
* (6,7:PARITY 00:EVEN 01:ODD 10,11:NONE PARITY)

* RS232C STATUS REGISTER
* (0: CARRIER DETECT 0:NORMAL 1:ERROR)
* (1: PARITY 0:NORMAL 1:ERROR)
* (2: OVERRUN 0:NORAML 1:ERROR)
* (5: READ ERROR 0:NORMAL 1:ERROR)
* (6: WRITE ERROR 0:NORMAL 1:ERROR)
* (7: BUFFER OVER 0:NORMAL 1:OVERFLOW)

* RS232C READ BUFFER ADDRESS
* RS232C READ BUFFER BOTTOM ADDRESS + 1
* RS232 READ BUFFER SIZE (0001 - FFFF)
* POINTER WHERE NEXT RECEIVED CHARACTER IS STOR
* POINTER WHERE NEXT CHARACTER IS LOADED
* NUMBER OF DATA IN THE BUFFER

* RS232C: GET ONE CHARACTER FROM RECEIVE BUFFER
* 1: GET ONE CHARACTER FROM RS232 RECEIVE BUFFER
* 2: IF BIT LENGTH < 8, AND 'PARITY CHECK' MODE, DO PARITY CHECK AND
                                SET RETURN CODE
* PARAMETER
* ON ENTRY
* NONE
* ON EXIT
    
```

ERR SEQ LOC OBJECT PROGRAM RS232C -- RS232C SEND/RECEIVE DATA ROUTINE ---

```

00111
00112
00113
00114
00115
00116
00117
00118
00119
00120
00121
00122
00123A 01C4 C6 01 A
00124A 01C6 0D
00125A 01C7 73 807D A
00126A 01CA 26 42 020E
00127A 01CC 3C
0C128
00129A 01CD FE 01C2 A
00130A 01D0 27 3D 020F
00131
00132A 01D2 FC 01B5 A
00133A 01D5 7F 0050 A
00134A 01D8 0D
00135A 01D9 79 0050 A
00136A 01DC 4A
00137A 01DD 26 F9 01D8
00138
00139A 01DF 0F
00140A 01E0 FE 01C0 A
00141A 01E3 A6 00 A
00142A 01E5 08
00143A 01E6 BC 018A A
00144A 01E9 26 03 01EE
00145A 01EB FE 0188 A
00146A 01EE FF 01C0 A
00147A 01F1 FE 01C2 A
00148A 01F4 09
00149A 01F5 FF 01C2 A
00150A 01F8 0E
00151
00152A 01F9 58
00153A 01FA 25 0F 020B
00154A 01FC 58
00155A 01FD 16
00156A 01FE 94 50 A
00157A 0200 24 02 0204
00158A 0202 C8 80 A
00159A 0204 58
00160A 0205 26 F9 0200
00161A 0207 56
00162A 0208 57
00163A 0209 20 01 020C
00164
00165A 020B 5F

* (A): CHARACTER (WITHOUT PARITY BIT)
* (B): STATUS $01:RECEIVED BUFFER IS EMPTY
* $00:NORMAL
* MSB= 1:ERROR 0:NORMAL
* $C0:PARITY ERROR $C1:CD ERROR (CARRIER DOWN)
* (C): SLAVE STATUS 0:NORMAL 1:ERROR
* SET Z N FLAG DEPEND ON VALUE OF (B) REGISTER
* REGISTER PRESERVE X
* WORK USE AS REGISTER
* ROH: EFFECTIVE BITS AS DATA (BIT LENGTH=7 THEN $7F,
* BIT LENGTH=8 THEN $FF)
RSGET EQU *
LDA B #$01 * PRESET 'BUFFER EMPTY' CODE
SEC * PRESET ERROR I/O FLAG
TIM #$80,MIOSTS * ERROR I/O ?
BNE RSIN23
PSHX
*
LDX RSDCNT * ARE THERE DATA IN THE BUFFER ?
BEQ RSIN25 * (B):1
* SET EFFECTIVE BITS TO ROH
LDD RSBITL * (B):RSMODS
CLR ROH * (A):BIT LENGTH
RSIN1A SEC
ROL ROH * ROH <-- ($7F IF B=7), <--- ($FF IF B=8)
DEC A
BNE RSIN1A
*
SEI * IF RS232C RECEIVED INTERRUPT IS CAUSED, THE
LDX RS0UP * POINTER MAY BE DESTROYED.
LDA A 0,X * (A): DATA
INX
CPX RSBFBT * IF THE POINTER SHOWS BOTTOM ADDRESS + 1 OF THE
BNE RSIN10 * BUFFER, POINTER MUST BE SET TO TOP ADDRESS.
LDX RSBFAD
RSIN10 STX RS0UP
LDX RSDCNT
DEX
STX RSDCNT * DATA COUNTER <--- CURRENT VALUE - 1
CLI
* PARITY ERROR CHECK
ASL B * PARITY CHECK MODE ?
BCS RSIN15 * MODE = 'CHECK PARITY' ?
ASL B
TAB * (B) <--- DATA, (C) <--- PARITY MODE (0:EVEN)
AND A ROH * TAKE DATA BITS (IGNORE PARITY BIT)
RSIN11 BCC RSIN12
EOR B #$80
RSIN12 ASL B
BNE RSIN11
ROR B * BIT7,BIT6 <--- (C)
ASR B
BRA RSIN20 * PARITY ERROR = $C0
*
RSIN15 CLR B * NORMAL RETURN
    
```


ERR SEQ LOC OBJECT PROGRAM RS232C -- RS232C SEND/RECEIVE DATA ROUTINE ---

```

00166          * BUFFER IS EMPTY
00167          020C A      RSIN20 EQU *
00168A 020C 5D          TST B          * CLEAR (C), SET (Z)
00169A 020D 38          PULX
00170A 020E 39          RSIN23 RTS
00171          * BUFFER IS EMPTY, IS CARRIER DOWN ?
00172          020F A      RSIN25 EQU *
00173A 020F 7B 047A A   TIM #54,SRSTS * ON PAUSE ?
00174A 0212 26 F8 020C BNE RSIN20
00175A 0214 7B 0402 A   TIM #54,PORT1 * SFLAG = ON ?
00176A 0217 27 F3 020C BEQ RSIN20
00177A 0219 C6 C1 A     LDA B #5C1 * CD ERROR
00178A 021B 2D EF 020C BRA RSIN20
00179          *
00180          *
00181          *
00182          *
00183          * SEND ONE TRANSMITTED CHARACTER SUBROUTINE
00184          * PARAMETER
00185          * ON ENTRY
00186          * TRANSMITTED CHARACTER
00187          * ON EXIT
00188          * (B): BIT 0 (1:DSR LOW) CHARACTER IS NOT SENT
00189          * BIT 1 (1:CTS LOW) CHARACTER IS NOT SENT
00190          * BIT 2 - 7 (ALWAYS 0)
00191          * (Z) DEPEND ON VALUE OF (B)
00192          * (C) 0:NORMAL 1:I/O ERROR
00193          * REGISTER PRESERVE A,X
00194          *
00195          * WORK USE AS REGISTER
00196          * R0H:PARITY BIT (LSB)
00197          * R0L:FLAG OF 'WITH PARITY BIT' (0:YES 1:NO)
00198          * R1H:SAVE DATA
00199          * R1L:BIT LENGTH
00200          *
00201          * NOTE. OCR IS USED. AND OCR IS USED BY KEY ROUTINE EITHER.
00202          *
00203          021D A      RSPUT EQU *
00204A 021D 0D          SEC * PRESET I/O ERROR FLAG
00205A 021E 7B B07D A   TIM #5B0,MIOSTS * I/O ERROR ?
00206A 0221 26 0F 0232 BNE SNDR04
00207          *
00208          * CHECK DSR, CTS
00209A 0223 F6 01B6 A   LDA B RSMODS * TAKE MODE (DSR CTS BITS)
00210A 0226 57          ASR B * RSMODS (DSR:BIT 4,CTS:BIT 5) MASK=1
00211A 0227 57          ASR B
00212A 0228 57          ASR B
00213A 0229 57          ASR B * PORT1 (DSR:BIT 0, CTS:BIT 1) NORMAL='LOW'
00214A 022A 53          COM B
00215A 022B D4 02 A    AND B PORT1 * CHECK DSR, CTS
00216A 022D C4 03 A    AND B #53
00217A 022F 27 02 0233 BEQ SNDR05
00218A 0231 0C          CLC * CTS, DSR LOW (ERROR)
00219A 0232 39          SNDR04 RTS
00220          *

```

ERR SEQ LOC OBJECT PROGRAM RS232C -- RS232C SEND/RECEIVE DATA ROUTINE ---

00221A	0233	36				SNDR05	PSH A		
00222A	0234	97	52	A			STA A R1H		
00223A	0236	3C					PSHX		
00224A	0237	CE	01AF	A			LDX #RSWKTP	* (X): TOP RAM ADDRESS OF WORK AREA FOR RS232C	
00225A	023A	0F					SEI	* DISABLE INTERRUPT	
00226A	023B	A6	06	A			LDA A RSBITL-RSWKTP,X		
00227A	023D	97	53	A			STA A R1L		
00228A	023F	4F					CLR A		
00229A	0240	E6	07	A			LDA B RSMODS-RSWKTP,X	* RSMODS (BIT7:WITH PARITY FLAG	
00230A	0242	05					ASLD	BIT6:EVEN OR ODD)	
00231A	0243	97	51	A			STA A ROL	* ROL:NUMBER OF PARITY BITS (ROL: 0 OR 1)	
00232A	0245	4F					CLR A		
00233A	0246	05					ASLD		
00234A	0247	97	50	A			STA A ROH	* LSB <--- PARITY	
00235									
00236			0249	A					
00237A	0249	7B	4008	A		SNDR20	EQU *		
00238A	024C	26	0B 0259				TIM #S40,TCSR	* OCR OVERFLOW ?	
00239							BNE SNDR30		
00240A	024E	DC	0B	A					
00241A	0250	93	09	A					
00242A	0252	83	0020	A					
00243A	0255	2B	F2 0249						
00244A	0257	20	07 0260						
00245									
00246A	0259	DC	09	A					
00247A	025B	C3	0020	A					
00248A	025E	DD	0B	A					
00249			0260	A					
00250A	0260	71	FE0B	A					
00251									
00252			0263	A					
00253A	0263	7B	4008	A					
00254A	0266	27	FB 0263						
00255									
00256A	0268	5F							
00257A	0269	77	0052	A					
00258A	026C	59							
00259A	026D	26	05 0274						
00260									
00261A	026F	71	FE0B	A					
00262A	0272	20	06 027A						
00263									
00264			0274	A					
00265A	0274	72	010B	A					
00266A	0277	75	0150	A					
00267									
00268A	027A	E8	05	A					
00269A	027C	A6	04	A					
00270A	027E	04							
00271A	027F	24	04 0285						
00272A	0281	A8	02	A					
00273A	0283	E8	03	A					
00274A	0285	ED	04	A					
00275									

ERR SEQ LOC OBJECT PROGRAM RS232C -- RS232C SEND/RECEIVE DATA ROUTINE ---

```

00276A 0287 DC 0B A LDD OCR
00277A 0289 E3 00 A ADDD RSBAUD-RSWKTP,X
00278A 028B DD 0B A STD OCR
00279A 028D 7A 0053 A DEC R1L * FINISHED ?
00280A 0290 26 D1 0263 BNE SNDR45
00281 * ADD PARITY ?
00282A 0292 96 51 A LDA A ROL
00283A 0294 26 DA 02A0 BNE SNDR60
00284A 0296 D6 50 A LDA B R0H * SET PARITY (R1H <--- R0H)
00285A 0298 4C INC A * 'ADD PARITY' FLAG <--- 'NONE' (ROL <--- 0)
00286A 0299 DD 51 A STD ROL
00287A 029B 7C 0053 A INC R1L * BIT COUNT <--- 1
00288A 029E 20 C3 0263 BRA SNDR45
00289 *
00290 * ADD STOP BITS
00291 SNDR60 EQU * * WAIT UNTIL START OF LAST BIT
00292A 02A0 7B 4008 A TIM #540,TCSR
00293A 02A3 27 FB 02A0 BEQ SNDR60
00294 *
00295A 02A5 DC 0B A LDD OCR
00296A 02A7 E3 00 A ADDD RSBAUD-RSWKTP,X
00297A 02A9 DD 0B A STD OCR
00298 *
00299A 02AB 72 0108 A OIM #51,TCSR * STOP BIT
00300 SNDR70 EQU *
00301A 02AE 7B 4008 A TIM #540,TCSR * WAIT UNTIL START TIME OF STOP BIT
00302A 02B1 27 FB 02AE BEQ SNDR70
00303 *
00304A 02B3 EE 06 A- LDX RSMODS-RSWKTP-1,X
00305A 02B5 18 XGDY * (X):OCR LAST TIME,
00306A 02B6 C4 03 A AND B #53 * (B):MSMODS (LS 3BITS:NUMBER OF STOP BITS)
00307A 02B8 26 D1 02BB BNE SNDR80
00308A 02BA 5C INC B * IF 0, 1 STOP BIT
00309A 02BB 4F SNDR80 CLR A * (X): NUMBER OF STOP BITS
00310A 02BC 18 XGDY
00311A 02BD F3 01AF A SNDR90 ADDD RSBAUD * (A,B):HIGH BIT TIME
00312A 02C0 09 DEX
00313A 02C1 26 FA 02BD BNE SNDR90
00314 *
00315A 02C3 DD 0B A STD OCR
00316 *
00317A 02C5 38 PULX
00318A 02C6 32 PUL A
00319A 02C7 0E CLI * IF RECEIVED KEY INTERRUPT, KEY SAMPLING TIME
00320 * * NOT PUNCTUAL.
00321A 02C8 5F CLR B
00322A 02C9 39 RTS
00323 *
00324 0000 A END
***** TOTAL ERRORS 0
    
```

ERR SEQ LOC OBJECT PROGRAM TERM --- TERMINAL MODE WITHOUT HARD COPY ---

```

C0001
C0002          *
C0003          NAM      TERM
C0004          * TSS  TERMINAL MODE
C0005          * 300 BPS, FULL DUPLEX, WITHOUT HARD COPY
C0006          * FILE NAME  'EX$5' BY K.A
C0007          TTL      --- TERMINAL MODE WITHOUT HARD COPY ---
C0008          OPT      LOAD
C0009          OPT      PAGE=55
0G010A 1000    *
                ORG      $1000
00011          *
00012          * EXEMPLE OF TERMINAL MODE
00013          *
C0014          FF4F  A    DSPSCR EQU    $FF4F
C0015          FF5E  A    SCRFNC EQU    $FF5E
C0016          FF85  A    RSONOF EQU    $FF85
C0017          FF88  A    RSMST  EQU    $FF88
C0018          FF82  A    RSOPEN EQU    $FF82
C0019          FF7F  A    RSCLOS EQU    $FF7F
C0020          FF79  A    RSGET  EQU    $FF79
C0021          FF76  A    RSPUT  EQU    $FF76
C0022          FF9A  A    KEYIN  EQU    $FF9A
C0023          FF9D  A    KEYSTS EQU    $FF9D
C0024          *
C0025          * INITIALIZE
00026A 1000 CC 8422 A    LDD      #8422    * CONSTRUCT SCREEN PACKET
00027A 1003 FD 105B A    STD      SCRPK1
00028A 1006 86 87  A    LDA  A    #87
00029A 1008 B7 105D A    STA  A    SCRPK2.
00030A 100B CC 1303 A    LDD      #1303
00031A 100E FD 105E A    STD      SCRPK2+1
00032A 1011 CC 1400 A    LDD      #1400
00033A 1014 FD 1060 A    STD      SCRPK2+3
00034A 1017 CE 105B A    LDX      #SCRPK1    * INITIALIZE SCREEN
00035A 101A BD FF5E A    JSR      SCRFNC
00036A 101D CE 105D A    LDX      #SCRPK2
00037A 1020 BD FF5E A    JSR      SCRFNC
00038A 1023 CC 3D27 A    LDD      #3D27    * SET MODE(STOP:1 CD:NO-CHECK, RTS:ON, PARITY:EV
00039          *
00040A 1026 BD FF88 A    JSR      RSMST    * 7 BITS LENGTH, 300 BPS
00041A 1029 86 01  A    LDA  A    #1
00042A 102B BD FF85 A    JSR      RSONOF    * RS232C DRIVER ON
00043A 102E FE FFDC A    LDX      $FFDC    * (X):BUFFER ADDRESS (SYSTEM BUFFER)
00044A 1031 CC 0104 A    LDD      #260     * (A,B): BUFFER SIZE
00045A 1034 BD FF82 A    JSR      RSOPEN    * RECEIVE OPEN
00046          *
00047A 1037 BD FF9D A    REDKEY JSR    KEYSTS    * ACCEPT FROM KEY BOARD ?
00048A 103A 25 1E 105A    ECS    BRKRTN    * IF BREAK KEY IS PRESSED, RETURN (IN BASIC MODE
00049A 103C 27 09 1047    BEQ    RCVRS
00050          * ACCEPTED CHARACTER FROM KB.
00051A 103E BD FF9A A    JSR      KEYIN
00052A 1041 BD FF76 A    JSR      RSPUT    * TRANSMIT ACCEPTED CHARACTER.
00053A 1044 BD FF4F A    JSR      DSPSCR    * DISPLAY ACCEPTES CHRACTER TO VIRTUAL SCREEN.
00054A 1047 FE FFD8 A    RCVRS  LDX    $FFD8    * ARE THERE RECEIVED CHARACTER IN THE BUFFER ?
00055A 104A EC 00  A    LDD      0,X
    
```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  TERM      --- TERMINAL MODE WITHOUT HARD COPY ---
00056A 104C 27 E9 1037      BEQ      REDKEY
00057A 104E BD FF79 A      JSR      RSGET
00058A 1051 81 7F A      CMP A    #57F
00059A 1053 24 E2 1037      BCC     REDKEY * IGNORE 7F - FF CHARACTERS
00060A 1055 BD FF4F A      JSR     DSPSCR * DISPLAY RECEIVED CHARACTER TO VIRTUAL SCREEN.
00061A 1058 20 DD 1037      BRA     REDKEY
00062
00063A 105A 39      *
00064      BRKRTN RTS
00065A 105B 84 A      * VIRTUAL SCREEN PACKET
00066A 105C 22 A      SCRPK1 FCB $84 * SELECT SCREEN DEVICE (LCD)
00067A 105D 87 A      FCB $22
00068A 105E 13 A      SCRPK2 FCB $87 * SET SCREEN SIZE AND BUFFER ADDRESS
00069A 105F 03 A      FCB 19,3
00069A 106D 1400 A      FDB $1400
00070      *
00071      *
00072      END
***** TOTAL ERRORS 0
    
```

ERR SEQ LOC OBJECT PROGRAM TERM --- TSS TERMINAL MODE WITH HARDCOPY ---

```

00001          NAM      TERM
00002          TTL      --- TSS TERMINAL MODE WITH HARDCOPY ---
00003          *
00004          * FILE NAME 'EX$2'          BY K.A
00005          OPT      LOAD
00006          OPT      PAGE=55
00007          *
00008          * EXAMPLE OF TERMINAL MODE
00009          * 300 BPS FULL DUPLEX TERMINAL MODE (1200 BPS)
00010          * VIRTUAL SCREEN SIZE = 20*4
00011          * RECEIVED AND TRANSMITTED CHARACTERS ARE ABLE TO PRINT TO SERIAL
00012          * PRINTER (MP-30, ...). THE CONNECTOR FOR HARD COPY IS 'SERIAL'.
00013          * HARD COPY ROUTINE IS INCLUDED IN INTERRUPT PROCEDURE.
00014          *
00015          * CABLE
00016          * 1. FOR CONNECT TO MODEM (CP-20)
00017          * OPTINAL CABLE
00018          * 2. FOR HARD COPY
00019          * HC-20 SERIAL (DIN 5 PINS)          MP-80 SERIAL (DB-25)
00020          * 1 (GROUND)          -----          7 (GROUND)
00021          * 2 (PTX)          -----          3 (RXD)
00022          * 3 (PRX)          -----          2 (TXD)
00023          * 4 (POUT)          -----          6 (DSR)
00024          * 5 (PIN)          -----          20 (DTR)
00025          * FG          -----          1 (PROTECTIVE GROUND)
00026          *
00027          *
00028          * OPERATION
00029          * PF1 KEY: START HARD COPY
00030          * PF2 KEY: STOP HARD COPY
00031          * PF3 KEY: 1200 BPS (DISPLAY MONITOR (RECEIVED CHARACTER) = OFF)
00032          * PF4 KEY: 300 BPS
00033          * PF5 KEY: QUIT
00034          * PF6 KEY: MONITOR DISPLAY ON
00035          * PF7 KEY: MONITOR DISPLAY OFF
00036          * PF8 KEY: ESC 'I'+$20 '0'
00037          *
00038          * 1200 BPS FULL DUPLEX TERMINAL PROCEDURE
00039          * 1: PF3 (1200 BPS)
00040          * 2: PF6 (MONITOR DISPLAY OFF, HARD COPY ON)
00041          * 3: (PF8 ?????)
00042          *
00043          * SUBROUTINE ENTRY POINT
00044          FF4F A      DSPSCR EQU      $FF4F          * DISPLAY ONE CHARACTER TO VIRTUAL SCREEN
00045          FF5E A      SCRFNC EQU      $FF5E          * VIRTUAL SCREEN FUNCTION
00046          FF85 A      RSONOF EQU      $FF85          * RS232C DRIVER ON/OFF
00047          FF88 A      RSMST EQU      $FF88          * SET RS232C PARAMETERS
00048          FF73 A      SERONF EQU      $FF73          * SERIAL DRIVER ON/OFF
00049          FF82 A      PSOPEN EQU      $FF82          * OPEN RS232C RECEIVE
00050          FF7F A      RSCLOS EQU      $FF7F          * CLOSE RS232C RECEIVE
00051          FF79 A      RSGET EQU      $FF79          * GET RS232C ONE CHARACTER
00052          FF76 A      RSPUT EQU      $FF76          * SEND RS232C ONE CHARACTER
00053          FF9A A      KEYIN EQU      $FF9A          * GET ONE CHARACTER FROM KEYBOARD BUFFER
00054          FF9D A      KEYSTS EQU      $FF9D          * GET NUMBER OF CHARACTERS IN THE KEY BUFFER
00055          FF25 A      MENU EQU      $FF25          * MENU
    
```

ERR SEQ LOC OBJECT PROGRAM TERM --- TSS TERMINAL MODE WITH HARDCOPY ---

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00056          * CONSTANTS OR REGISTERS
00057          0011 A   TRCSR EQU   $11   * TRANSMIT/RECEIVE CONTROL REGISTER
00058          0013 A   STDR  EQU   $13   * SERIAL TRANSMIT DATA REGISTER
00059          0012 A   SRDR  EQU   $12   * SERIAL RECEIVE DATA REGISTER
00060          0008 A   TCSR  EQU   $08   * TIMER CONTROL AND STATUS REGISTER
00061          0008 A   OCR   EQU   $03   * OUTPUT COMPARE REGISTER
00062          0009 A   FRC   EQU   $09   * FREE RUNNING COUNTER
00063          0010 A   RMCR  EQU   $10   * RATE AND MODE CONTROL REGISTER
00064          *
00065          0002 A   PORT1 EQU   $02   * 04:38.4 KBPS, 05:4.4 KRPS
00066          0003 A   PORT2 EQU   $03   * I/O PORT1
00067          1000 A   BUFSIZ EQU  4096  * I/O PORT2
00068          0008 A   SCBSIZ EQU   200  * BUFFER SIZE FOR PRINTER
00069          1000 A   RSBSIZ EQU  4096  * BUFFER SIZE FOR SCREEN
00070          0001 A   ECHODT EQU    1   * BUFFER SIZE FOR RS232C
00071          *
00072          0109 A   SERVCT EQU  $109  * TERMINAL MODE = 'ECHO CHARACTER' ?
00073          *
00074          1000          *
00075          *
00076          * INITIALIZE
00077A         1000 86 01   A   LDA A   #ECHODT
00078A         1002 B7 11E3 A   STA A   ECHO
00079A         1005 CE 11C7 A   LDX   #SCRPKD * SET SCREEN PACKET X:DATA ADDRESS
00080A         1008 C6 0E   A   LDA B   #SCRPK1-SCRPKD * (B):NUMBER OF DATA
00081A         100A A6 00   A   INIT10 LDA A   0,X
00082A         100C A7 0E   A   STA A   SCRPK1-SCRPKD,X
00083A         100E 08          INX
00084A         100F 5A          DEC B
00085A         1010 26 F8 100A BNE   INIT10
00086          *
00087A         1012 CE 11D5 A   LDX   #SCRPK1 * INITIALIZE SCREEN
00088A         1015 BD FF5E A   JSR   SCRFCN * SELECT SCREEN DEVICE
00089A         1018 CE 11D7 A   LDX   #SCRPK2
00090A         101B BD FF5E A   JSR   SCRFCN * SET SCREEN SIZE AND BUFFER ADDRESS
00091A         101E CE 11DC A   LDX   #SCRPK3
00092A         1021 BD FF5E A   JSR   SCRFCN * SET CURSOR MARGIN
00093A         1024 CE 11DE A   LDX   #SCRPK4
00094A         1027 BD FF5E A   JSR   SCRFCN * SET SCROLL STEP
00095A         102A CE 11E1 A   LDX   #SCRPK5
00096A         102D BD FF5E A   JSR   SCRFCN * SET SCROLL SPEED
00097          *
00098A         1030 86 01   A   LDA A   #1 * MCNITOR ON
00099A         1032 B7 11EA A   STA A   MONFLG
00100          *
00101A         1035 CC 11F1 A   LDD   #BUF * SET BUFFER POINTER FOR HARD COPY
00102A         1038 FD 11EB A   STD   BPIN
00103A         103B FD 11ED A   STD   BPOUT
00104A         103E CC 0000 A   LDD   #0 * CHARACTER COUNTER = 0
00105A         1041 FD 11EF A   STD   BUFcnt
00106A         1044 B7 11E4 A   STA A   PRtFLG * HARD COPY = 'NO'
00107          *
00108          * REWRITE SERIAL RECEIVE INTERRUPT VECTOR
00109          * NOTE. IF WE WANT TO SEND A CHARACTER TO THE PRINTER, WE MAY DETATCH
00110          * SLAVE MPU WHILE 20 MILI SECOND AFTER WE GOT THE CHARACTER FROM
          * SLAVE MCU.
    
```

ERR	SEQ	LOC	OBJECT	PROGRAM	TERM	---	TSS	---
							TERMINAL	MODE WITH HARDCOPY
	00111A	1047	FC 010A	A	LDD	SERVCT+1	*	SAVE VECTOR ADDRESS
	00112A	104A	FD 11E5	A	STD	SERADR		
	00113A	104D	CC 1146	A	LDD	#SERINT	*	WRITE NEW INTERRUPT ADDRESS
	00114A	1050	FD 010A	A	STD	SERVCT+1		
	00115							
	00116A	1053	CC 3D27	A	LDD	#S3D27	*	SET MODE(STOP:1 CD:NO-CHECK, RTS:ON, PARITY:EV
	00117							* 7 BITS LENGTH, 300 BPS)
	00118A	1056	FD 11E8	A	STD	RSPARM	*	SAVE PARAMETERS
	00119A	1059	BD FF88	A	JSR	RSMST		
	00120A	105C	86 01	A	LDA	A #1	*	RS232C DRIVER ON
	00121A	105E	BC FF85	A	JSR	RSONOF		
	00122A	1061	86 01	A	LDA	A #1	*	SERIAL DRIVER ON
	00123A	1063	BD FF73	A	JSR	SERONF		
	00124							
	00125A	1066	CE 22B9	A	INIT30	LDX #RSBUFF	*	(X):BUFFER ADDRESS (SYSTEM BUFFER)
	00126A	1069	CC 1000	A	LDD	#RSBSIZ	*	(A,B): BUFFER SIZE
	00127A	106C	BD FF82	A	JSR	RSOPEN	*	OPEN TO RECEIVE RS232C
	00128A	106F	BD FF9D	A	REDKEY	JSR KEYSTS	*	ACCEPT FROM KEY BOARD ?
	00129A	1072	25 7E 10F2*		BCS	BRKRTN	*	IF BREAK KEY IS PRESSED, RETURN (IN BASIC MODE
	00130A	1074	27 27 109D		BEQ	RCVRS		
	00131						*	ACCEPTED CHARACTER FROM KB.
	00132A	1076	BD FF9A	A	JSR	KEYIN		
	00133A	1079	81 FE	A	CMP	A #SFE	*	FUNCTION CODES ?
	00134A	107B	26 13 1090		BNE	GETKEY		
	00135							
	00136						*	FUNCTION KEYS
	00137A	107D	C0 F1	A	SUB	B #SF1	*	F1 - F10 ?
	00138A	107F	25 1C 109D		BCS	RCVRS	*	NO, IGNORE
	00139A	1081	C1 0A	A	CMP	B #SA		
	00140A	1083	24 18 109D		BCC	RCVRS		
	00141A	1085	58		ASL	B		
	00142A	1086	CE 10D6	A	LDX	#FNCTBL	*	GET FUCTION ADDRESS
	00143A	1089	3A		ASX			
	00144A	108A	EE 00	A	LDX	0,X	*	(X) <-- ENTRY POINT OF EACH SUBROUTINE
	00145A	108C	AD 00	A	JSR	0,X		
	00146A	108E	2D 0D 109D		BRA	RCVRS		
	00147A	1090	BD FF76	A	GETKEY	JSR RSPUT	*	TRANSMITTE CHARCTER TO RS232C.
	00148A	1093	F6 11E3	A	LDA	B ECHO	*	ECHO ?
	00149A	1096	27 02 109A		BEQ	GETK10		
	00150A	1098	8D 1C 1086		BSS	PSHCHR	*	PUSH RECEIVED CHARACTER TO STACK
	00151A	109A	BD FF4F	A	GETK10	JSR DSPSCR	*	DISPLAY CHARACTER TO VIRTUAL SCREEN.
	00152							
	00153A	109D	FE FFD8	A	RCVRS	LDX \$FFD8	*	ARE THERE CHARACTERS IN THE RS232C BUFFER ?
	00154A	10A0	EC 00	A	LDD	0,X		
	00155A	10A2	27 0F 10B3		BEQ	RCVR80		
	00156A	10A4	BD FF79	A	JSR	PSGET		
	00157A	10A7	81 7F	A	CMP	A #S7F		
	00158A	10A9	24 08 10B3		BCC	RCVR80	*	IGNORE 7F - FF CHARACTERS
	00159A	10AB	F6 11EA	A	LDA	B MONFLG	*	DISPLAY ON ?
	00160A	10AE	27 03 10B3		BEQ	RCVR80		
	00161							
	00162		10B0	A	RCVR10	EQU *		
	00163A	10B0	BD FF4F	A	JSR	DSPSCR	*	DISPLAY CHARACTER TO VIRTUAL SCREEN.
	00164							
	00165A	10B3	7E 106F	A	RCVR30	JMP REDKEY		

ERR SEQ LOC OBJECT PROGRAM TERM --- TSS TERMINAL MODE WITH HARDCOPY ---

```

00166
00167
00168
00169
00170
00171
00172
00173
00174
00175
00176A 10B6 7D 11E4 A
00177A 10B9 27 1A 10D5
00178A 10BB 0F
00179A 10BC FE 11EB A
00180A 10BF A7 00 A
00181A 10C1 08
00182A 10C2 8C 21F1 A
00183A 10C5 26 03 10CA
00184A 10C7 CE 11F1 A
00185A 10CA FF 11EB A
00186A 10CD FE 11EF A
00187A 10D0 08
00188A 10D1 FF 11EF A
00189A 10D4 0E
00190A 10D5 39
00191
00192
00193
00194
00195A 10D6 10EA A
00196A 10D8 10EE A
00197A 10DA 10F3 A
00198A 10DC 1108 A
00199A 10DE 1130 A
00200A 10E0 1115 A
00201A 10E2 1119 A
00202A 10F4 1123 A
00203A 10E6 1145 A
00204A 10E8 1145 A
00205
00206
00207A 10EA 86 01 A
00208A 10EC 20 01 10EF
00209
00210A 10EE 4F
00211A 10EF B7 11E4 A
00212 10F2 A
00213A 10F2 39
00214
00215
00216A 10F3 CC 3D47 A
00217
00218A 10F6 FD 11E8 A
00219A 10F9 BD FF7F A
00220A 10FC FC 11E8 A

```

```

*
*
*
* PSH RECEIVED CHARACTER TO PRINT STACK
* ON ENTRY
* (A): CHARACTER
* ON EXIT
* REGISTER PRESERVE
* (A), (B)
*
PSHCHR TST PRTFLG * HARD COPY = YES ?
        BEQ PSHC80
        SEI
        LDX BPIN * PSH A CHARACTER TO THE STACK
        STA A 0,X
        INX
        CPX #BUF+BUFSIZ
        BNE PSHC10
        LDX #BUF
PSHC10 STX BPIN
        LDX BUFCNT
        INX
        STX BUFCNT
        CLI
PSHC80 RTS
*
*
* FUNCTION KEY PROCEDURE TABLE
*
FNCTBL FDB PFKY10 * PF1 (HARD COPY ON)
        FDB PFKY20 * PF2 (HARD COPY OFF)
        FDB PFKY30 * PF3 (1200 BPS)
        FDB PFKY40 * PF4 (300 BPS)
        FDB PFKY50 * PF5 (QUIT)
        FDB PFKY60 * PF6 (MONITOR ON)
        FDB PFKY70 * PF7 (MONITOR OFF)
        FDB PFKY80 * PF8 (ESC 'I'+$20 '1')
        FDB INVLKY * PF9 (UNDEFINED)
        FDB INVLKY * PF10 (UNDEFINED)
*
* PF1 PRINT(HARD COPY) ON
PFKY10 LDA A #S1 * ON PRINT FLAG
        BRA PFKY25
* PF2 PRINT (HARD COPY) OFF
PFKY20 CLR A * OFF PRINT FLAG
PFKY25 STA A PRTFLG
BRKRTN EQU *
        RTS
*
* PF3 1200 BPS
PFKY30 LDD #S3D47 * SET MODE(STOP:1 CD:NO-CHECK, RTS:ON, PARITY:
* 7 BITS LENGTH, 1200 BPS)
*
        STD RSPARM * SAVE PARAMETERS
PFKY35 JSR RSCLOS * CLOSE RS232 FOR OPEN AGAIN.
        LDD RSPARM * CHANGE BIT RATE

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ERR  SEQ  LOC  OBJECT  PROGRAM  TERM  --- TSS TERMINAL MODE WITH HARDCOPY ---

00221A 10FF 3D FF88  A          JSR  RSMST
00222A 1102 38          PULX
00223A 1103 CE 1066  A          LDX  #INIT30  * REWRITE RETURN ADDRESS
00224A 1106 3C          PSHX
00225A 1107 39          RTS
00226          * PF4 300 BPS
00227A 1108 CC 3D27  A          PFKY40 LDD  #S3D27  * SET MODE(STOP:1 CD:NO-CHECK, RTS:ON, PARITY:EV
00228          *                               * 7 BITS LENGTH, 300 BPS)
00229A 110B FD 11E8  A          STD  RSPARM  * SAVE PARAMETERS
00230A 110E 36 01  A          LDA  A  #1    * DISPLAY MONITOR = ON
00231A 1110 87 11EA  A          STA  A  MONFLG
00232A 1113 20 E4 10F9  A          BRA  PFKY35
00233          * PF6 MONITOR ON
00234A 1115 86 01  A          PFKY60 LDA  A  #1
00235A 1117 20 06 111F  A          BRA  PFKY75
00236          * PF7 MONITOR OFF
00237A 1119 86 01  A          PFKY70 LDA  A  #1  * HARD COPY = ON
00238A 111B 37 11E4  A          STA  A  PRTFLG
00239A 111E 4F          CLR  A
00240A 111F 87 11EA  A          PFKY75 STA  A  MONFLG
00241A 1122 39          RTS
00242          * PF8 ESC 'I'+S20 '1'
00243A 1123 86 18  A          PFKY80 LDA  A  #S18  * ESC
00244A 1125 8D 3F 1086*  A          BSR  PSHCHR
00245A 1127 86 69  A          LDA  A  #'I'+S20 * 'I'+S20
00246A 1129 8D 38 1086*  A          BSR  PSHCHR
00247A 112B 86 31  A          LDA  A  #'1'    * '1'
00248A 112D 8D 37 1086*  A          BSR  PSHCHR
00249A 112F 39          RTS
00250          * PF5 QUIT
00251A 1130 3D FF7F  A          PFKY50 JSR  RSCLOS  * CLOSE RS232
00252A 1133 4F          CLR  A        * DRIVER OFF
00253A 1134 3D FF85  A          JSR  RSONOF
00254A 1137 4F          CLR  A
00255A 1138 3D FF73  A          JSR  SERONF
00256A 113B FC 11E5  A          LDD  SERADR  * RECOVER INTERRUPT VECTOR
00257A 113E FD 010A  A          STD  SERVCT+1
00258A 1141 38          PULX
00259A 1142 7E FF25  A          JMP  MENU
00260          *
00261          * INVLKY EQU  *
00262A 1145 39          RTS
00263          *
00264          *
00265          * SERIAL RECEIVE INTERRUPT (RECEIVE RS232C) ROUTINE
00266          * PUSH RECEIVED DATA TO PRINTER STACK AND SEND THE CHARACTER WHICH IS
00267          * IN THE PRINTER STACK
00268          *
00269          * SERINT EQU  *
00270A 1146 26 11E4  A          LDA  A  PRTFLG  * HARD COPY = 'YES' ?
00271A 1149 27 0F 115A  A          BEQ  SERI80  * NO, JUMP TO INTERRUPT ROUTINE
00272A 114B 96 11  A          LDA  A  TRCSR  * GET DATA
00273A 114D 96 12  A          LDA  A  SRDR
00274A 114F 84 7F  A          AND  A  #S7F  * SUPPRESS SIT 7
00275A 1151 81 7F  A          CMP  A  #S7F
    
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ERR SEQ LOC OBJECT PROGRAM TERM --- TSS TERMINAL MODE WITH HARDCOPY ---

```

00276A 1153 24 03 1158          BCC  SERI30  * IGNORE 7F - FF
00277A 1155 BD 10B6 A          JSR  PSHCHR
00278                                * HARD COPY ON
00279A 1158 8D 05 115F          SERI30 BSR  HRDCPY  * SEND 3 CHARACTERS (9 MILI SEC)
00280                                *
00281A 115A FE 11E5 A          SERI80 LDX  SERADR
00282A 115D 6E 00 A           JMP  0,X
00283                                *
00284                                * PRINT TO SERIAL PRINTER
00285                                * THIS ROUTINE CALLED ONLY IN INTERRUPT
00286                                * REGISTER PRESERVE
00287                                * (A)
00288                                *
00289A 115F 36                    HRDCPY PSH A
00290A 1160 B6 11E4 A          LDA  A  PRFLG  * HARD COPY = 'YES' ?
00291A 1163 27 60 11C5          BEQ  HARD80
00292                                * YES, PRINTING
00293A 1165 86 03 A           LDA  A  #3      * COPY COUNT = 3 (PRINT 3 CHARACTERS)
00294A 1167 B7 11E7 A          STA  A  CPYCNT
00295A 116A 7B 4002 A          TIM  #$40,PORT1 * PRINTER READY ?
00296A 116D 26 56 11C5          BNE  HARD80
00297                                * ARE THERE DATA IN THE BUFFER ?
00298A 116F FC 11EF A          LDD  BUFCNT
00299A 1172 27 51 11C5          BEQ  HARD80
00300                                *
00301A 1174 71 FB03 A          AIM  #$FF-4,PORT2 * DETACH SLAVE MCU, (SELECT SERIAL)
00302A 1177 96 11 A          LDA  A  TRCSR
00303A 1179 36                    PSH  A          * SAVE TRCSR
00304A 117A 86 05 A          LDA  A  #505    * 4800 BPS
00305A 117C 97 10 A          STA  A  RMCR
00306A 117E 86 0A A          LDA  A  #50A
00307A 1180 97 11 A          STA  A  TRCSR
00308                                *
00309A 1182 FE 11ED A          HARD10 LDX  BPOUT  * LOAD DATA FROM THE STACK
00310A 1185 A6 00 A          LDA  A  0,X
00311A 1187 08                    INX
00312A 1188 8C 21F1 A          CPX  #BUF+BUFSIZ
00313A 118B 26 03 1190          BNE  HARD20
00314A 118D CE 11F1 A          LDX  #BUF
00315A 1190 FF 11ED A          HARD20 STX  BPOUT  * INCREMENT DATA POINTER AT THE BUFFER
00316A 1193 FE 11EF A          LDX  BUFCNT
00317A 1196 09                    DEX
00318A 1197 FF 11EF A          STX  BUFCNT
00319                                *
00320A 119A 7B 2011 A          HARD30 TIM  #520,TRCSR * WAIT READY.
00321A 119D 27 FB 119A          BEQ  HARD30
00322A 119F 97 13 A          STA  A  STDR  * STORE DATA TO THE TRANSMIT REGISTER.
00323                                *
00324A 11A1 7A 11E7 A          DEC  CPYCNT  * WERE 3 CHARACTERS SENDEED ?
00325A 11A4 27 0A 11B0          BEQ  HARD40
00326A 11A6 7B 4002 A          TIM  #$40,PORT1 * PRINTER READY ?
00327A 11A9 26 05 11B0          ENE  HARD40
00328A 11AB FC 11EF A          LDD  BUFCNT  * IS BUFFER EMPTY ?
00329A 11AE 26 D2 1182          BNE  HARD10
00330                                *

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ERR SEQ LOC OBJECT PROGRAM TERM --- TSS TERMINAL MODE WITH HARDCOPY ---

```

00331          * WAIT 2 MILI SEC (TIME OF SENDING ONE CHARACTER)
00332A 1150 76 2011 A   HARD40 TIM   #$20,TRCSR
00333A 1153 27 FB 11B0   BEQ   HARD40
00334A 1165 CE 0190 A   LDX   #400
00335A 1128 09          HARD50 DEX
00336A 1189 26 FD 11B8   BNE   HARD50
00337          * RECOVER SERIAL COMMUNICATION
00338A 1133 86 04   A   LDA A   #$04   * SELECT SLAVE MCU
00339A 118D 97 10   A   STA A   RMCR
00340A 113F 32          PUL A          * RECOVER TRCSR
00341A 11C0 97 11   A   STA A   TRCSR
00342A 11C2 72 0403 A   JIM   #$4,PORT2
00343A 11C5 32          HARD80 PUL A
00344A 11C6 39          RTS
00345          *
00346          *
00347A 11C7      84   A   SCRPKD FCB   $84   * SCREEN DEVICE SELECT (LCD)
00348A 11C8      22   A          FCB   $22
00349          *
00350A 11C9      87   A          FCB   $87   * SET SCREEN SIZE AND BUFFER ADDRESS
00351A 11CA      13   A          FCB   19,3
          A 11CB      03   A
00352A 11CC      21F1 A          FDB   SCRBUF
00353          *
00354A 11CE      C3   A          FCB   $C3   * SET CURSOR MARGIN
00355A 11CF      04   A          FCB   4
00356          *
00357A 11D0      C4   A          FCB   $C4   * SET SCROLL STEP
00358A 11D1      0A   A          FCB   10   * X
00359A 11D2      03   A          FCB   3    * Y
00360          *
00361A 11D3      CB   A          FCB   $CB   * SET SCROLL SPEED
00362A 11D4      09   A          FCB   9
00363          *
00364          11D5 A   SCRPKE EQU   *
00365          *
00366          *
00367          * WORK AREA
00368A 11D5      84   A   SCRPK1 FCB   $84   * SCREEN DEVICE SELECT (LCD)
00369A 11D6      22   A          FCB   $22
00370A 11D7      87   A   SCRPK2 FCB   $87   * SET SCREEN SIZE AND BUFFER ADDRESS
00371A 11D8      13   A          FCB   19,3
          A 11D9      03   A
00372A 11DA      21F1 A          FDB   SCRBUF
00373          *
00374A 11DC      C3   A   SCRPK3 FCB   $C3   * SET CURSOR MARGIN
00375A 11DD      04   A          FCB   4
00376          *
00377A 11DE      C4   A   SCRPK4 FCB   $C4   * SET SCROLL STEP
00378A 11DF      0A   A          FCB   10   * X
00379A 11E0      03   A          FCB   3    * Y
00380          *
00381A 11E1      CB   A   SCRPK5 FCB   $CB   * SET SCROLL SPEED
00382A 11E2      09   A          FCB   9
00383          *

```

ERR	SEQ	LOC	OBJECT	PROGRAM	TERM	--- TSS TERMINAL MODE WITH HARDCOPY ---	
	00384A	11E3	01	A	ECHO	FCB	1 * TERMINAL MODE ECHO.
	00385				*		
	00386A	11E4	0001	A	PRTFLG	RMB	1 * HARD COPY (MP-80 PRINTER) ON/OFF FLAG
	00387				*		* 0:OFF 1:ON
	00388				*		
	00389A	11E5	0002	A	SERADR	RMB	2 * SAVE SERIAL RECEIVE INTERRUPT VECTOR.
	00390A	11E7	0001	A	CPYCNT	RMB	1 * WORK FOR HARD COPY
	00391A	11E8	0002	A	RSPARM	RMB	2 * RS232C OPEN PARAMETER
	00392A	11EA	0001	A	MONFLG	RMB	1 * DISPLAY RECEIVED CHARACTER = YES ?
	00393				*		* 1:DISPLAY 0:DISPLAY OFF
	00394				*		
	00395				*	SERIAL SEND	BUFFER
	00396A	11EB	0002	A	BPIN	RMB	2 * POINTER WHERE NEXT CHARACTER IS STORED
	00397A	11ED	0002	A	BPOUT	RMB	2 * POINTER WHERE NEXT CHARACTER IS LOADED
	00398A	11EF	0002	A	BUFCNT	RMB	2 * NUMBER OF CHARACTERS IN THE BUFFER
	00399A	11F1	1000	A	BUF	RMB	BUFSIZ * BUFFER
	00400				*		
	00401A	21F1	00C8	A	SCRBUF	RMB	SCBSIZ * SCREEN BUFFER
	00402A	22B9	1000	A	RSBUFF	RMB	RSBSIZ * RS232C RECEIVE BUFFER
	00403		32B9	A	WRKEND	EQU	*
	00404				*		
	00405				*		
	00406		0000	A			END
*****	TOTAL ERRORS		0				

```

ERR  SEQ  LOC  OBJECT      PROGRAM  MODEM      --- CONTROL HALF DUPLEX MODEM ---
00001
00002
00003
00004
00005
00006
00007
00008
00009
00010
00011
00012
00013      FF19  A      SNSCOM EQU      $FF19
00014      FF16  A      CHKRS EQU      $FF16
00015
00016
00017
00018      00FD  A      RSPRM1 EQU      $FD          * STOP BITS = 1, CARRIER DETECT:CHECK
00019
00020
00021      0048  A      RSPRM2 EQU      $48          * RTS:LOW, CTS:CHECK DSR:CHECK
00022
00023
00024A 1000
00025
00026
00027
00028
00029
00030
00031
00032
00033
00034
00035
00036      FF4F  A      DSPSCR EQU      $FF4F          * DISPLAY ONE CHARACTER TO VIRTUAL SCREEN
00037      FF5E  A      SCRFNC EQU      $FF5E          * VIRTUAL SCREEN FUNCTION
00038      FF85  A      RSONOF EQU      $FF85          * RS232C DRIVER ON/OFF
00039      FF88  A      RSMST EQU      $FF88          * SET RS232C PARAMETERS
00040      FF82  A      RSOPEN EQU      $FF82          * OPEN RS232C RECEIVE
00041      FF7F  A      RSCLOS EQU      $FF7F          * CLOSE RS232C RECEIVE
00042      FF79  A      RSGET EQU      $FF79          * GET RS232C ONE CHARACTER
00043      FF76  A      RSPUT EQU      $FF76          * SEND RS232C ONE CHARACTER
00044      FF9A  A      KEYIN EQU      $FF9A          * GET ONE CHARACTER FROM KEYBOARD BUFFER
00045      FF9D  A      KEYSTS EQU      $FF9D          * GET NUMBER OF CHARACTERS IN THE KEY BUFFER
00046
00047      0002  A      PORT1 EQU      $02          * CONSTANTS OR REGISTERS
00048      0003  A      PORT2 EQU      $03          * I/O PORT1
00049      1000  A      RSBSIZ EQU      4096          * I/O PORT2
00050      0055  A      SCBSIZ EQU      85          * BUFFER SIZE FOR RS232C RECEIVE
00051      0001  A      ECHODT EQU      1          * BUFFER SIZE FOR SCREEN
00052
00053
00054A 1000
00055

```

```

ERR   SEQ   LOC  OBJECT      PROGRAM  MODEM      --- CONTROL HALF DUPLEX MODEM ---

00056
00057A 1000 CE 10D2  A          * INITIALIZE
00058A 1003 C6 DE   A          LDX   #SCRPKD * SET SCREEN PACKET X:DATA ADDRESS
00059A 1005 A6 00   A          LDA B #SCRPK1-SCRPKD * (B):NUMBER OF DATA
00060A 1007 A7 DE   A          INIT10 LDA A 0,X
00061A 1009 08          STA A SCRPK1-SCRPKD,X
00062A 100A 5A          INX
00063A 100B 26 F8 1005 DEC B
00064          BNE   INIT10
00065A 100D CE 10E0  A          *
00066A 1010 BD FF5E  A          LDX   #SCRPK1 * INITIALIZE SCREEN
00067A 1013 CE 10E2  A          JSR   SCRFNC * SELECT SCREEN DEVICE
00068A 1016 BD FF5E  A          LDX   #SCRPK2
00069A 1019 CE 10E7  A          JSR   SCRFNC * SET SCREEN SIZE AND BUFFER ADDRESS
00070A 101C BD FF5E  A          LDX   #SCRPK3 *
00071A 101F CE 10E9  A          JSR   SCRFNC * SET CURSOR MARGIN
00072A 1022 BD FF5E  A          LDX   #SCRPK4 *
00073A 1025 CE 10EC  A          JSR   SCRFNC * SET SCROLL STEP
00074A 1028 BD FF5E  A          LDX   #SCRPK5 *
00075          JSR   SCRFNC * SET SCROLL SPEED
00076A 102B CC 3547  A          *
00077          LDD   #$3547 * SET MODE(STOP:1 CD:NO-CHECK, RTS:OFF, PARITY:
00078A 102E BD FF88  A          *          JSR   RSMST * 7 BITS LENGTH, 1200 BPS)
00079A 1031 86 01   A          LDA A #1 * RS232C DRIVER ON
00080A 1033 BD FF85  A          JSR   RSONOF
00081A 1036 CE 1151  A          LDX   #RSBUF * (X):BUFFER ADDRESS
00082A 1039 CC 1000  A          LDD   #RSBSIZ * (A,B): BUFFER SIZE
00083A 103C BD FF82  A          JSR   RSOPEN * OPEN RS232C RECEIVE
00084          *
00085A 103F BD FF9D  A          REDKEY JSR   KEYSTS * ACCEPT FROM KEY BOARD ?
00086A 1042 25 29 106D BCS   BRKPTN * IF BREAK KEY IS PRESSED, RETURN (IN BASIC MOD
00087A 1044 27 14 105A BEQ   RCVRS
00088          * ACCEPTED CHARACTER FROM KB.
00089A 1046 BD FF9A  A          JSR   KEYIN
00090          1049 A          GETKEY EQU *
00091A 1049 36          PSH A
00092A 104A BD FF4F  A          JSR   DSPSCR * DISPLAY CHARACTER TO VIRTUAL SCREEN.
00093A 104D 32          PUL A
00094A 104E 81 0D   A          CMP A #$0D * CR (SEND DATA) CODE ?
00095A 1050 26 08 105A BNE   RCVRS
00096A 1052 BD 106E  A          JSR   TXD * TRANSMITTE DATA STRING TO RS232C
00097A 1055 86 0A   A          LDA A #$0A * DISPLAY 'LF'
00098A 1057 BD FF4F  A          JSR   DSPSCR
00099          *
00100A 105A FE FFD8  A          RCVRS LDX   $FFD8 * RECEIVED CHARACTER FROM RS232C ?
00101A 105D EC 00   A          LDD   0,X
00102A 105F 27 DE 103F BEQ   REDKEY
00103A 1061 BD FF79  A          JSR   RSGET
00104A 1064 81 7F   A          CMP A #$7F
00105A 1066 24 D7 103F BCC   REDKEY * IGNORE 7F - FF CHARACTERS
00106A 1068 BD FF4F  A          JSR   DSPSCR
00107A 106B 20 D2 103F BRA   REDKEY
00108          *
00109A 106D 39          BRKRTN RTS
00110          *

```

ERR SEQ LOC OBJECT PROGRAM MODEM --- CONTROL HALF DUPLEX MODEM ---

```

00111
00112
00113
00114
00115
00116
00117
00118
00119
00120
00121
00122
00123
00124A 106E CE 10EE A
00125A 1071 86 91 A
00126A 1073 A7 00 A
00127A 1075 3D FF5E A
00128
00129A 1078 86 4D A
00130A 107A 8D FF19 A
00131A 107D 86 01 A
00132A 107F 8D FF19 A
00133
00134
00135A 1082 73 0202 A
00136A 1085 26 FB 1082
00137
00138
00139A 1037 B6 10F2 A
00140A 108A 80 10F0 A
00141A 108D 4C
00142A 108E F6 10F1 A
00143A 1091 3D
00144A 1092 C1 50 A
00145A 1094 25 01 1097
00146A 1096 5A
00147A 1097 F7 10F6 A
00148A 109A F7 1150 A
00149A 109D 36 10F0 A
00150A 10A0 B7 10F5 A
00151A 10A3 7F 10F4 A
00152A 10A6 CF 10F3 A
00153A 10A9 3D FF5E A
00154
00155A 10AC CE 10F4 A
00156A 10AF A6 00 A
00157A 10B1 08
00158A 10E2 3D FF76 A
00159A 10B5 7A 1150 A
00160A 10B8 26 F5 10AF
00161
00162A 10BA 86 0D A
00163A 105C 8D FF76 A
00164A 10BF 86 0A A
00165A 10C1 8D FF76 A

```

```

*
* SEND DATA ON THE SCREEN
* PROCEDURE
* 1: RTS ON. WAIT UNTIL CTS ON.
* 2: SEND DATA WHICH ARE DISPLAYED ON THE SCREEN.
* 3: RTS LOW.
* PARAMETERS
* ON ENTRY NONE
* ON EXIT NONE
* REGISTER PRESERVE NONE
*
*
TXD EQU *
LDX #SCRPK7
LDA A #$91 * GET EXTENT OF VIRTUAL SCREEN
STA A 0,X
JSR SCRFNC
*
RETRY LDA A #$4D * RTS HIGH
JSR SNSCOM
LDA A #$1
JSR SNSCOM
*
* WAIT 'CTS:ON'
CTSON TIM #$2,PORT1
BNE CTSON
*
* SEND DATA BLOCK
LDA A SCRPK7+4 * CALCULATE 'NUMBER OF CHARACTERS IN THE
SUB A SCRPK7+2 * CURRENT LINE.
INC A * (A):LINE DEPTH
LDA B SCRPK7+3 * (B):LINE WIDTH
MUL
CMP B #80 * IF OVER 79, COUNT = 79
BCS SND05
DEC B
SND05 STA B SCRPK8+3 * SET NUMBER OF CHARACTERS
STA B TXCNT
LDA A SCRPK7+2 *
STA A SCRPK8+2 * COORDINATE OF (Y) OF START POINT
CLR SCRPK8+1 * COORDINATE OF (X) OF START POINT
LDX #SCRPK8 * GET CHARACTERS ON THE SCREEN.
JSR SCRFNC
*
LDX #SCRPK8+1
SND10 LDA A 0,X
INX
JSR RSPUT
DEC TXCNT
BNE SND10
*
SND30 LDA A #$0D * SEND 'CR' 'LF'
JSR RSPUT
LDA A #$0A
JSR RSPUT

```



```

ERR  SEQ  LOC  OBJECT      PROGRAM  MODEM      --- CONTROL HALF DUPLEX MODEM ---
00166
00167A 10C4 86 4D  A      *          LDA A  #54D      * RTS:LOW
00168A 10C6 BD FF19 A          JSR      SNSCOM
00169A 10C9 86 00  A          LDA A  #500
00170A 10CB BD FF19 A          JSR      SNSCOM
00171
00172A 10CE BD FF16 A      *          JSR      CHKRS      * RESTART RECEIVING
00173
00174A 10D1 39          *          RTS
00175
00176
00177
00178A 10D2 84  A      * SCRPKD FCB  $84      * SCREEN DEVICE SELECT (LCD)
00179A 10D3 22  A          FCB  $22
00180
00181A 10D4 87  A      *          FCB  $87      * SET SCREEN SIZE AND BUFFER ADDRESS
00182A 10D5 13  A          FCB  19,3
A 10D6 03  A
00183A 10D7 2151 A          FDB  SCRBUF
00184
00185A 10D9 C3  A      *          FCB  $C3      * SET CURSOR MARGIN
00186A 10DA 04  A          FCB  4
00187
00188A 10DB C4  A      *          FCB  $C4      * SET SCROLL STEP
00189A 10DC 0A  A          FCB  10      * X
00190A 10DD 03  A          FCB  3      * Y
00191
00192A 10DE CB  A      *          FCB  $CB      * SET SCROLL SPEED
00193A 10DF 09  A          FCB  9
00194
00195      10E0 A      * SCRPKE EQU  *
00196
00197
00198
00199A 10E0 84  A      * WORK AREA
00200A 10E1 22  A      * SCRPK1 FCB  $84      * SCREEN DEVICE SELECT (LCD)
00201A 10E2 87  A          FCB  $22
00202A 10E3 13  A      * SCRPK2 FCB  $87      * SET SCREEN SIZE AND BUFFER ADDRESS
A 10E4 03  A          FCB  19,3
00203A 10E5 2151 A          FDB  SCRBUF
00204
00205A 10E7 C3  A      * SCRPK3 FCB  $C3      * SET CURSOR MARGIN
00206A 10E8 04  A          FCB  4
00207
00208A 10E9 C4  A      * SCRPK4 FCB  $C4      * SET SCROLL STEP
00209A 10EA 0A  A          FCB  10      * X
00210A 10EB 03  A          FCB  3      * Y
00211
00212A 10EC CB  A      * SCRPK5 FCB  $CB      * SET SCROLL SPEED
00213A 10ED 09  A          FCB  9
00214
00215A 10EE 91  A      * SCRPK7 FCB  $91      * GET EXTENT OF VIRTUAL SCREEN.
00216A 10EF 0004 A          RMB  4
00217
00218A 10F3 97  A      * SCRPK8 FCB  $97
    
```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  MODEM      --- CONTROL HALF DUPLEX MODEM ---
00219A 10F4   005A  A          RMB      90
00220
00221A 114E   01    A          ECHO    FCB      1          * TERMINAL MODE ECHO.
00222
00223A 114F   0001  A          PRNFLG  RMB      1          * HARD COPY (MP-80 PRINTER) ON/OFF FLAG
00224
00225A 1150   0001  A          TXCNT   RMB      1          * 0:OFF 1:ON
00226
00227
00228A 1151   1000  A          RSBUF   RMB      RSBSIZ    * RS232C RECEIVE BUFFER
00229
00230A 2151   0055  A          SCRBUF  RMB      SCBSIZ    * SCREEN BUFFER
00231
00232
00233
***** TOTAL ERRORS      0000  A          END
0

```

CHAPTER 6

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6.1 General

Two types of cassettes may be used as external data storages: an external audio cassette and the built-in microcassette (plug-in option). Data sent to cassettes is recorded sequentially. The average speed of data communication with cassettes is 1300 BPS. The format of data stored in the external audio cassette and that of the built-in microcassette are the same so the two types of cassettes are compatible. The only control line used for the external audio cassette is the remote ON/OFF line (REM). The built-in microcassette, however, is controlled by software and performs fast forward, rewind, write, and playback operations in response to commands in BASIC. The tape counter value is also recorded and displayed by software.

6.2 Data storage (SAVE)

(1) Format of one bit

In the recording format of the cassette, one bit is represented by one pulse (Fig. 6-1).

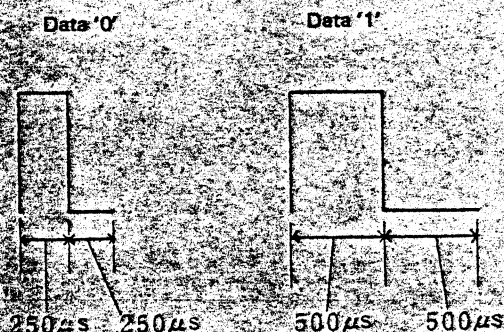


Fig. 6-1 Recording Format for One Bit

Each byte, consisting of 8 data bits and one stop bit, is sent from bit 0. The last bit of a byte is the stop bit (data '1'). (Fig. 6-2.)

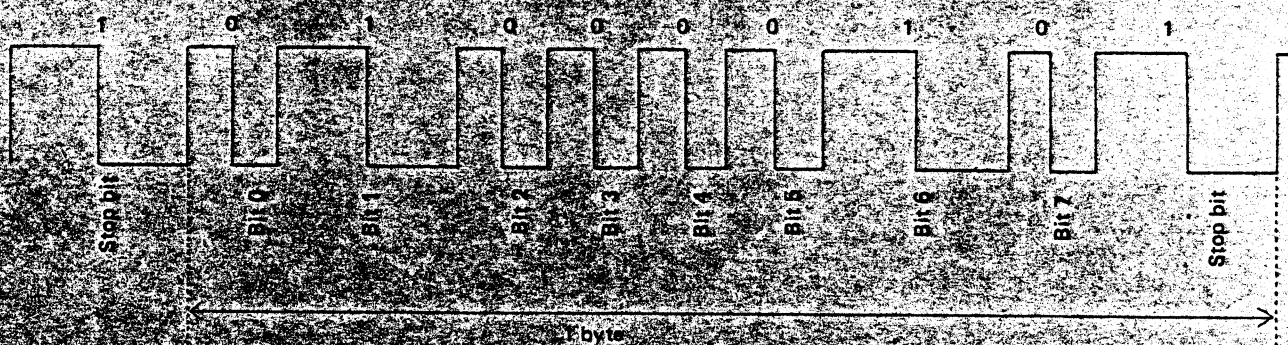


Fig. 6-2 Format of One Byte

(2) Synchronization

The first bit with data '1' which appears after 40 or more bits of data '0' is taken as the first bit (bit 0) of the synchronization character. Synchronization is performed when the data of this first byte is FF and that of the next byte sent is AA (Fig. 6-3).

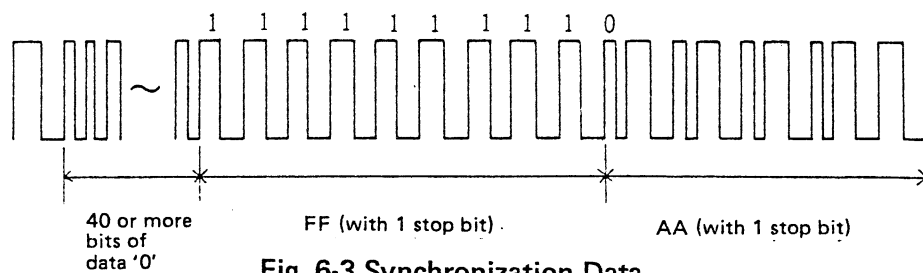


Fig. 6-3 Synchronization Data

The next data sent following the synchronization data will be used as actual data.

(3) Reverse waveform

The normal recording format for data bits is as shown in Fig. 6-1. However, depending on the cassette used, when the signal passes through the playback circuit of the HX-20, the high/low levels of the waveform may be reversed. (Fig. 6-4).

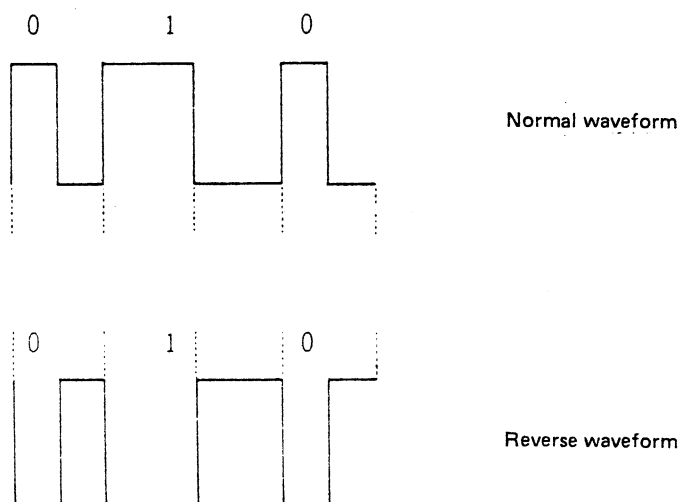


Fig. 6-4 Reverse Waveform

The type of a waveform is determined when synchronization is performed and then data read is performed. The waveform of the built-in microcassette is inverted.

(4) Bit judgement

To judge whether a bit is '0' or '1', the interval between the rise of the first pulse and that of the second is measured. If the measured value is above a specified value (approx. 750 μ sec), the bit is judged to be logic '1' (Fig. 6-5)

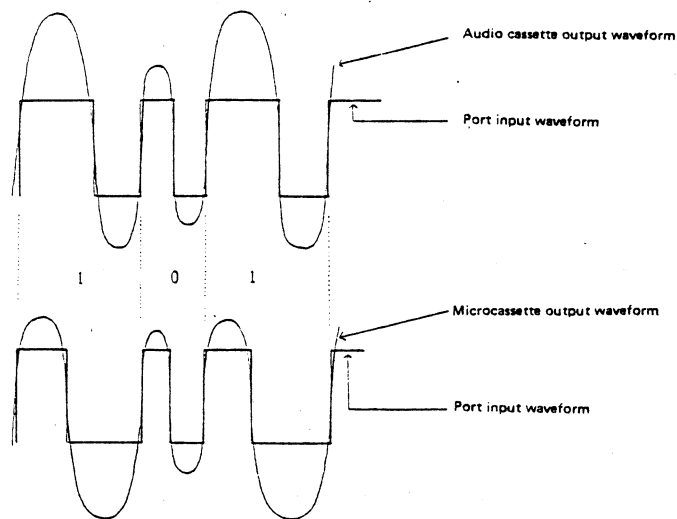


Fig. 6-5 Output Waveforms

6.3 I/O Ports

Table 6-1 lists the I/O ports related to the external cassette.

Table 6-2 lists the I/O ports related to the microcassette.

Table 6-1 I/O Ports Related to the External Cassette

	Port	Description
Master MCU	P12	Input. Connected to port P34 of the slave MCU, this port informs the master MCU of the slave MCU's error status.
Slave MCU	P30	Output. This port is used for the cassette REM output. 1: Off 0: On
	P32	Input. This port is used to input data from the external cassette. 1: High 0: Low
	P33	Output. This port is used to output data to the external cassette. 1: High 0: Low
	P34	Output. This port is connected to port P12 of the master MCU.

Table 6-2 I/O Ports Related to the Microcassette

	Port	Description
Master MCU	P12	Input. This port is connected to port P34 of the slave MCU and informs the master MCU of the slave MCU's error status.
	P17	Input. This port is used to input the counter status or to judge the plug-in option.
Slave MCU	P20	Input. This port is used to input data (1: High, 0: Low) or to judge the the write protection. The handling of the input contents of this port depends on the value of P45.
	P21	Output. This port is used to output data to the microcassette. 1: High 0: Low
	P42	Output. This port is used to turn the microcassette power ON/OFF. 1: ON 0: OFF
	P43	Output. This port is used to set microcassette commands.
	P44	Output. This port supplies a serial clock for timing the microcassette commands. 1: High 0: Low
	P45	Output. This port is used to select the P20 input. 0: RS-232C 1: Microcassette
	P46	Input. This port is used to input the counter status when port P44 is 0 and the head switch status when it is 1.

6.4 Block format

Cassette data is recorded in blocks. Each block consists of the items listed in Table 6-3.

Table 6-3 Block Configuration.

Field	Description
Synchronization field	Contains 80 bits of data '0'.
Preamble	Contains data FF, AA (2 bytes).
Block identification field	This field consists of 4 bytes. The function of each byte is as follows. Byte 0: Block identifier field indicating the type of the block. H: Header D: Data E: End of file (EOD) Bytes 1 and 2: Indicate the 2-byte block number and must be 0000 to FFFF. Byte 3: Block identification number. This is used to identify blocks which are written twice to improve a reliability. Values 00 through FF can be assigned to a block but the values actually used are 00 and 01.
Data field	Stores data. An 80-byte data field is assigned for header (the block identifier field begins with H) and EOF blocks (block identifier field begins with E). In all other cases, the data field size is defined by the header block.
BCC (Block Check Character) field	Performs CRC (Cyclic Redundancy Check) for the range from the beginning of the block to the BCC field. The two BCC bytes and CRC-CCITT are used for this check.
Postamble	Contains values AA, 00 (2 bytes).

6.5 File structure

Only sequential files are supported. Sequential file data is fixed-length and blocked. Each sequential file consists of an 80-byte header block (the length of the data field excluding the preamble, block identification field, BCC, and postamble), one or more data blocks (256 bytes each), and an EOF block. The block numbers assigned for each file begin with header block 00, followed by 01, 02 ... ending with the EOF block. Each block is written twice to improve reliability.

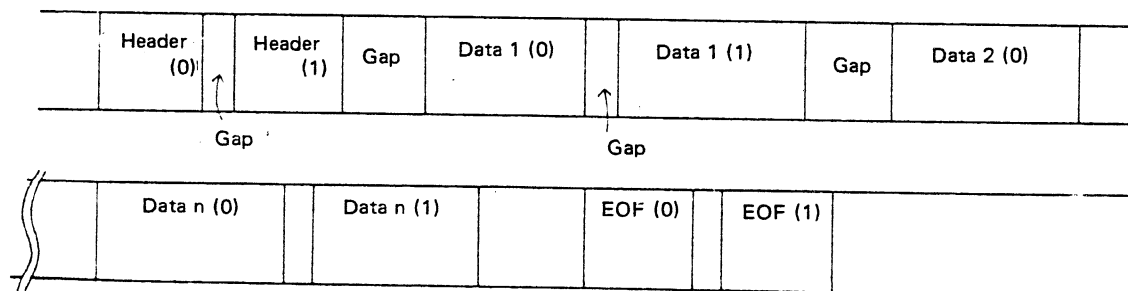


Fig. 6-6 Configuration of Sequential Files

A 5-sec tape feed (data FF) is provided at the beginning and end of each file as a gap to separate files.

6.6 Format of header and EOF blocks

The data format of the header block is shown in Table 6-4 and that of the EOF block is shown in Table 6-5.

Table 6-4 Format of Header Block

Column from to	Byte size	Item	Description
0 3	4	ID field	Data HDR1. Indicates, in ASCII code, that the block is a header
4 11	8	Filename	Stores the filename.
12 19	8	File type	Stores the file type.
20	1	Record type	This byte specifies the record type. The following record types can be specified. F : Fixed length V : Variable length 2 : Each fixed-length block is written twice. HX-20 currently supports only record type 2.
21	1	Interblock gap length	This byte specifies the interblock gap length "Δ": Interblock gap long enough for the tape to stop (long gap) "S": Interblock gap length not long enough for the tape to stop (short gap)
22 26	5	Block length	Indicates the data length of the block. Must be 00000 to 65535 (ASCII code).
27 31	4		Empty
32 37	6	Creation date	Indicates the date of file creation in "Month, Day, Year" format (ASCII code). Month, day, and year are represented by 2 bytes of data each.
38 43	6	Creation time	Indicates the time of file creation in "Hour, Minutes, Seconds" format (ASCII code). Hour, minute, and second are represented by 2 bytes of data each. Hour is the indicated by the 24-hour system (0 to 23).
44 49			Empty
50 51		Volume serial number	Indicates the tape volume number in ASCII code. (01 ~).
52 59	8	System name	Indicates the name of the system that created the file (ASCII code). "HX-20ΔΔΔ"
60 79	20		Empty

Table 6-5 Format of EOF Block

Column from to	Byte size	Item	Description
0 3	4	ID field	"EOFΔ".
4 79	66		Empty

6.7 Interblock Gaps

There are two types of interblock gaps: long and short. The length of an interblock gap depends on whether the tape will stop at the gap. An interblock gap of approx. 10 bytes (the length of tape required to write a single block twice) is secured between blocks where the tape will not stop. This is a short gap. An interblock gap of approx. 100 bytes is required when the tape stops between blocks. This type of gap (long gap) enables the motor of the tape drive to reach a constant rotation speed from a halt state. The length of the interblock gap is specified by the header.

6.8 Writing Blocks

Data is written to cassettes by the slave MCU in units of one block. Commands for block write are exchanged between the master and the slave MCUs as shown in Fig. 6-7. The master MCU must send the write data within 4 msec after receiving ACK from the slave. The tape drive must already be running when data is sent to the slave MCU. The data sent consists of the block ID ("H") and the contents of the data block (84 bytes for the header). CRC calculations are performed solely by the slave MCU.

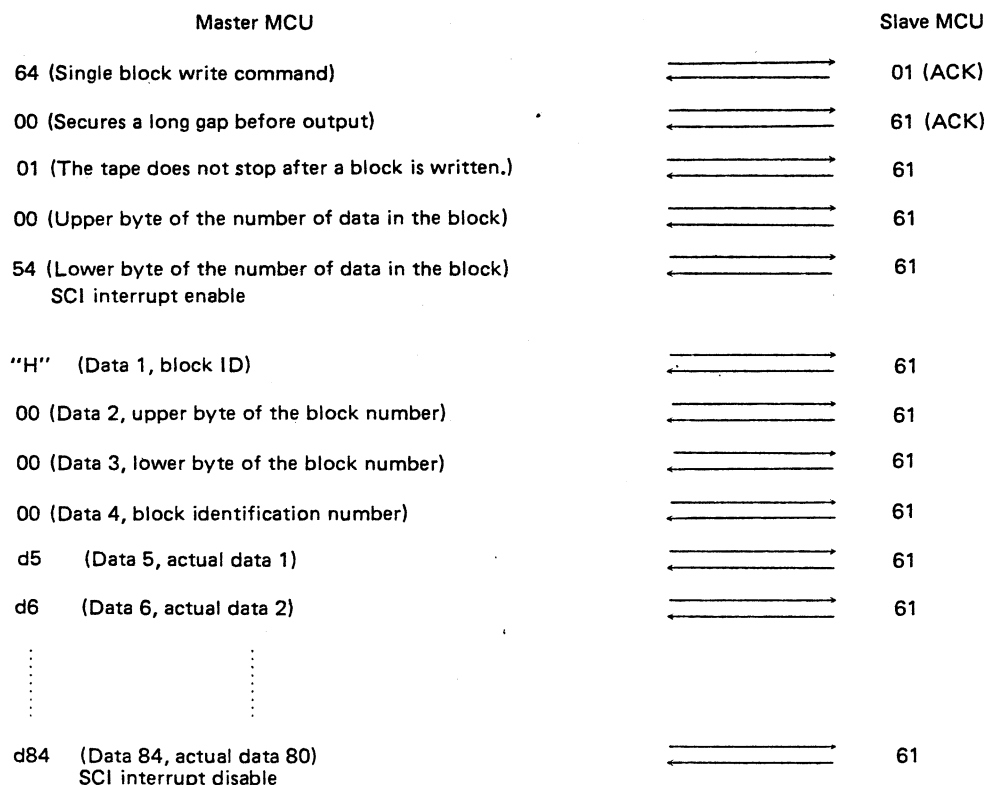


Fig. 6-7 Exchange of Commands for Write Operation for a Single Block (Header)

When the RIE (Receive Interrupt Enable) mask of the SCI (Serial Communication Interface) is opened, the main MCU uses the interrupt routine to transmit the data from "H" to d84 in Fig. 6-7 to the slave MCU. When master MCU receives data 61 from the slave MCU, an SCI interrupt is generated and the master MCU sends next data to the slave MCU.

The RIE mask is closed after one block has been transmitted. The master MCU can transmit data to the slave MCU without generating an SCI interrupt but the current transmission procedure uses the SCI interrupt.

6.9 Reading blocks

Command 28 (26, 27) is used to read a block from the external cassette. Command 68 (66, 67) is used to read a block from the microcassette. The slave MCU transmits to the master MCU the contents of the block, from the beginning of the block identification field to the beginning of the BCC. Redundant bytes used for the CRC check are not sent to the main MCU. When one block has been sent, the slave MCU sends a completion code (22 for the external cassette and 62 for the built-in microcassette) to the master MCU. When the master MCU receives the completion code, it inputs a BCC value to the slave MCU and evaluates the results of the CRC check. CRC check is performed for the range from the block identification field to the CRC redundant byte. If the result of the CRC check is 0, this indicates that the data write operation has been correctly performed. Next, the block number is checked. If block 4 is input when block 5 should be input, the next block must be input. If 6 is input, this means that the desired block has already passed. When a single block has been correctly input, this is taken as the completion of input processing. Otherwise, input processing is aborted or the input procedure for the next block is begun. The master MCU receives the data sent from the slave MCU via the SCI using SCI receive interrupt processing and stores this data in the specified buffer.

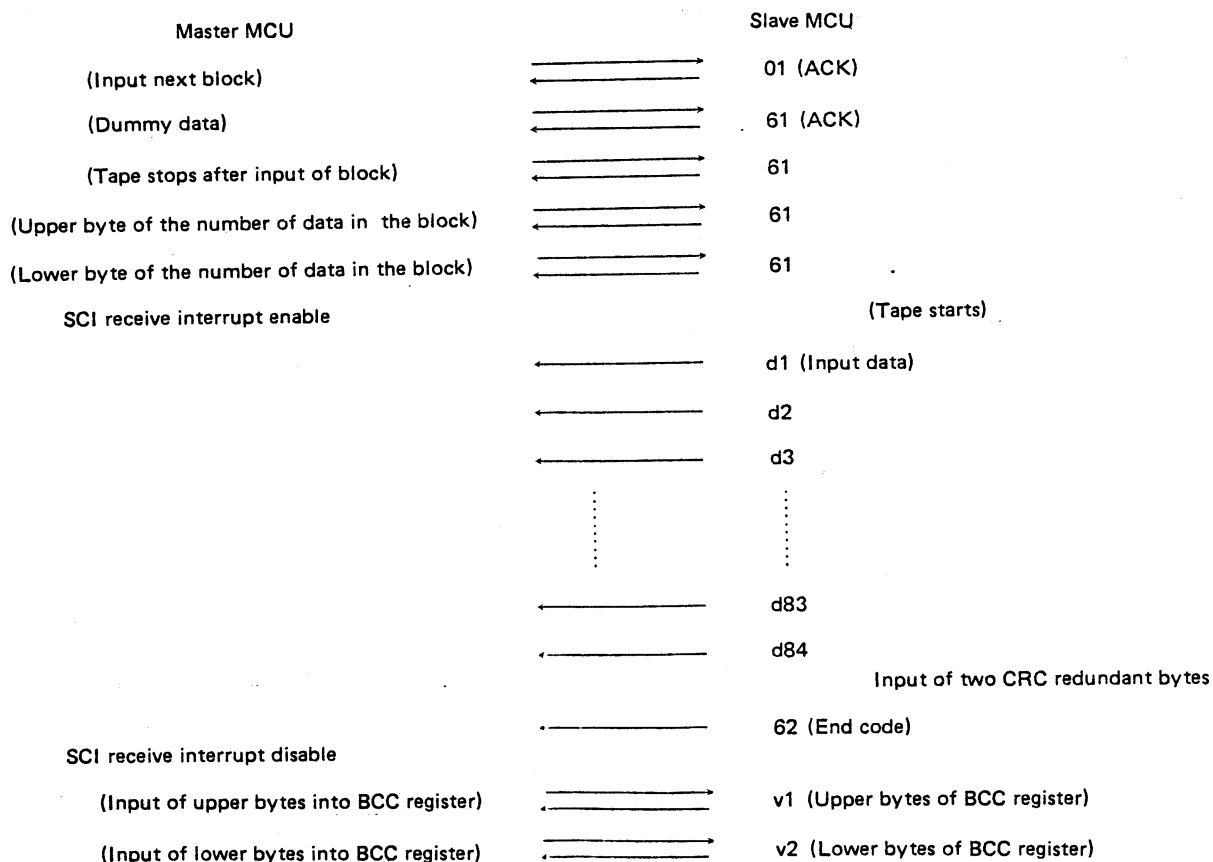


Fig. 6-8 Exchange of Commands for Read Operation for a Single Block (Header)

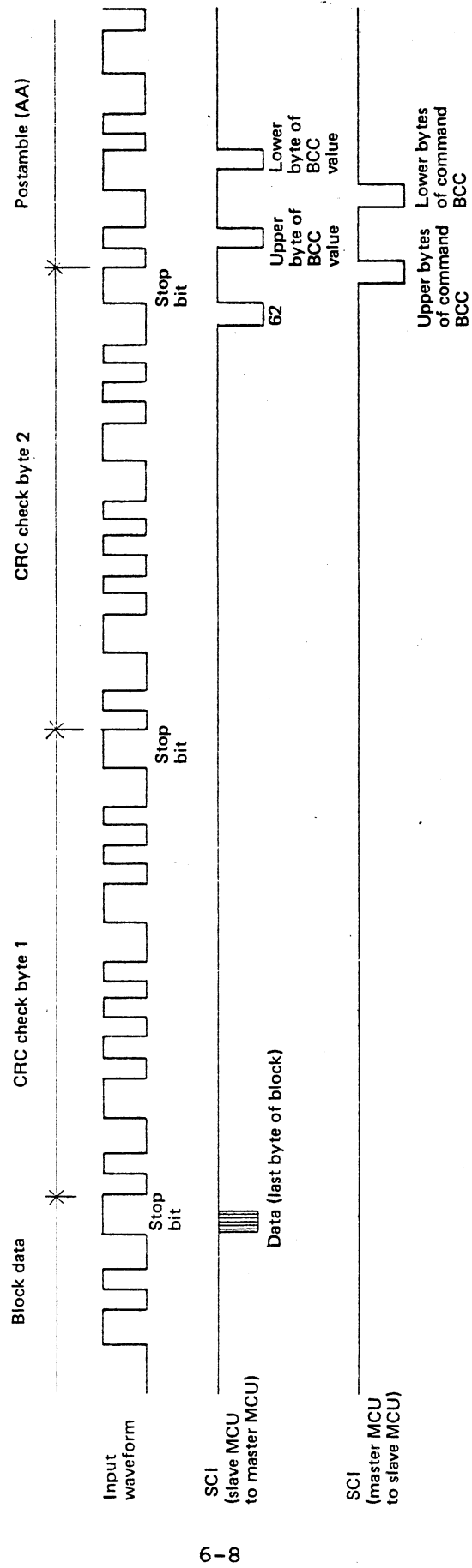


Fig. 6-9 Input Timing for Block Data

6.10 File output

Files are output to cassettes using the following three procedures.

(1) File open

Subroutine OPNWMS is used to open files for output to the built-in microcassette and subroutine OPNWCS performs the same function for the external cassette. When a file is opened for output, the header is output and internal preparations are made for data block output. Specification for the tape to stop after the head block has been output is included.

(2) Output of one byte to a tape file

Subroutine WRITMS outputs data to the built-in microcassette and subroutine WRITCS to the external cassette. Data is written to a buffer (256 bytes of data + block identification data). Actual output to the microcassette or external cassette is performed when the buffer becomes full.

(3) File close

Subroutine CLSMS closes the built-in microcassette file and subroutine CLSCS closes the external cassette file. If any data remains in the buffer when the file is closed, it is output as a data block. An EOF block is then output and the tape stops.

Double write

As a measure to improve reliability, the contents of the buffer are output twice (each block is written twice). This procedure is followed for all blocks (header, data and EOF).

6.11 File open

Files are input from cassettes using the following three procedures.

(1) File open

Subroutines SRCRCS and OPNRCS are used to open files for input from an the external cassette and subroutines SRCRMS and OPNRMS perform the same function for the built-in microcassette. These subroutines search a specified file by inputting a header from the tape and comparing this with the specified file. After the header of the specified file has been input the tape stops and data input is internally prepared.

(2) Input of one byte from a tape file

Subroutine READMS inputs one byte of data from the microcassette and subroutine READCS from the external cassette. Data is fetched one byte at a time from the 256-byte buffer. When the buffer is empty, the next block is written to it from the tape and data fetch continues.

(3) File close

Subroutine CLSMS closes the microcassette file and subroutine CLSCS closes the external microcassette file. The tape stops when one of these subroutines is called. When a file is closed, the corresponding input device is released.

6.12 Functions unique to the built-in microcassette

Fast forward and rewind of the microcassette are performed by the slave MCU in response to commands sent from the master MCU. The slave MCU also starts and stops the motor and reads the tape counter value. The following 4 subroutines are provided.

1. MCSMAN: Performs the operations of the manual operation mode.
2. REWMCS: Rewinds the tape to the beginning.
3. SEKMCS: Winds the tape to the specified tape counter value.
4. CNTMCS: Sets or reads the microcassette tape counter value.

Counter read

The main MCU controls the counter during data input or output. The slave MCU controls the counter at all other times. If there is no change in the counter signal for a specified length of time, it is judged that either no tape is set in the drive or that the tape has been wound to the BOT or EOT position. The tape then stops. Port P17 of the main MCU is used to input the tape counter status. This port value indicates whether the tape counter signal is high or low. The tape counter value is indicated by number of changes in the tape counter signal. When data is being input or output, the main MCU inputs the tape counter signal and performs sampling using a TOF interrupt (0.1-sec interval). The slave MCU controls the counter when fast forward or rewind is being performed.

6.13 Notes on I/O

(1) Polynomials generated for CRC check

The default value ($X^{16} + X^{12} + X^5 + 1$) for polynomial expressions generated for CRC check is set by the slave MCU after reset. This value can be modified by using slave MCU command 48. If the polynomial expression generated at the time of input is different from that generated at the time of output, the system assumes that a CRC error has occurred and no data can be input.

(2) Interblock gaps

When the REM terminal is used for data output to an external cassette, data write will not be correctly performed if the tape drive takes too much time to reach constant running speed from a fully stopped state. When using a tape recorder where such a condition occurs, the interblock gap must be lengthened (slave MCU command 21).

(3) Number of input data in a block

When one of slave MCU commands 28 or 68 (input one block) is input, if the first data input is H or E (header or EOF block), 84 bytes is assumed as the length of the data field of the block and the number of data specified by the command is ignored.

6.14 External cassette subroutines

Subroutine name	Entry point	Description
PONFCS	FF46	<p>Turns ON/OFF the remote (REM) terminal.</p> <p>Parameters:</p> <p>At Entry</p> <p>(A): 0: Turns the REM terminal OFF 1: Turns the REM terminal ON. (Bit 0 is used.)</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Return codes 00: Normal (00 is always set in the current version.)</p> <p>Registers retained (B) and (X)</p> <p>Subroutines referenced SNSCOM and CHKRS</p> <p>Variables used None</p>
OPNRCS	FF43	<p>Opens the cassette file for input and searches the specified file until it is found.</p> <p>Parameters:</p> <p>At Entry</p> <p>(X): Starting address of a data packet</p> <p>Data packet</p> <ol style="list-style-type: none"> Interblock stop mode (1 byte) 00: Tape stops at the interblock gap. 01: Tape does not stop at the interblock gap. FF: According to the header specification. Starting address of input buffer (two bytes, high- to low-byte order) Input buffer size is 260 bytes. 8-byte filename (ASCII code) 8-byte file type (ASCII code) <p>NOTE: If "*" is specified in the character string of a data packet filename, matching terminates at this asterisk position. "*" can also be used in a file type. A file whose filename and type match the specified filename and type is assumed to be the specified file. For example, if the filename is "FILE" and any file type is acceptable, the filename should be specified as "FILEΔΔΔΔ" and the file type as "*ΔΔ". To specify the first file in the tape, both filename and type should be "*ΔΔΔΔΔΔΔΔ".</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Return codes 00: Normal 85: File error</p> <p>(Z): According to the value of (A).</p>

		<p>Registers retained None</p> <p>Subroutines referenced SNSCOM, CRDBHD, and CRDBEF</p> <p>Variables used R1, R2, R3, R4 and R5</p>
SRCRCS	FF40	<p>Opens the cassette file when the first file found is the specified file. Returns the found filename.</p>
		<p>Parameters:</p> <p>At Entry (X): Top address of data packet Data packet</p> <ol style="list-style-type: none"> Interblock stop mode Same as for subroutine OPNRCS. Starting address of the input buffer Same as for subroutine OPNRCS. Filename Same as for subroutine OPNRCS. File type Same as for subroutine OPNRCS. Found filename (8 bytes) Found file type (8 bytes) <p>Note: The function of "*" in the specification of filename and type is the same as for subroutine OPNRCS.</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: Normal 85: File error 8B: The file found is not the specified file. (Z): According to the value of (A).</p> <p>Registers retained None</p> <p>Subroutines referenced SNSCOM, CRDBHD and CRDBEF</p> <p>Variables used R0, R1, R2, R3, R4 and R5</p>
READCS	FF3D	<p>Inputs one byte of data from the external cassette. Input data is fetched from the 256-byte buffer one byte at a time. When the buffer becomes empty, the next block is automatically written to the buffer.</p>
		<p>Parameters:</p> <p>At Entry None</p> <p>At Return (C): Abnormal I/O flag (A): 1-byte input data (B): Return codes 00: Normal 01: End of file (EOF) 84: The input file is not open. 81: Read error (Z): According to the value of (B).</p>

		<p>Registers retained (X)</p> <p>Subroutines referenced CRDBLK</p> <p>Variables used R0, R1, R2, R3, R4 and R5</p>
OPNWCS	FF3A	<p>Opens the external cassette file for output.</p> <p>Parameters:</p> <p>At Entry (X): Top address of a data packet</p> <p>Data packet</p> <ol style="list-style-type: none"> Interblock stop mode (1 byte) <ul style="list-style-type: none"> 00: Tape stops at the interblock gap. 01: Tape does not stop at the interblock gap. Starting address of output buffer (buffer size is 260 bytes) 8-byte filename (ASCII code) 8-byte file type (ASCII code) <p>At Return (C): Abnormal I/O flag (A): Return codes <ul style="list-style-type: none"> 00: Normal 88: File is already open. 91: Output error (Z): According to the value of (A).</p> <p>Registers retained None</p> <p>Subroutines referenced CWRHED</p> <p>Variables used R0, R1, R2, R3, R4 and R5</p>
WRITCS	FF37	<p>Outputs one byte of data to the external cassette. Output data is written to the 260-byte buffer. When the buffer becomes full, data is automatically written to the file.</p> <p>Parameters:</p> <p>At Entry (A): 1-byte output data</p> <p>At Return (C): Abnormal I/O flag (B): Return codes <ul style="list-style-type: none"> 00: Normal 94: File is not open. 91: Output error (Z): According to the value of (B).</p> <p>Registers retained (A) and (X)</p> <p>Subroutines referenced CWRBLK</p>

		<p>Variables used R0, R1, R2, R3, R4 and R5</p>
CLSCS	FF34	<p>Closes the external cassette file. When an output file is closed, any data remaining in the buffer is output to the cassette followed by an EOF block. When an input file is closed, input operation simply terminates.</p> <p>Parameters:</p> <p>At Entry None</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: Normal 87: File is not open. 91: Output error (Z) According to the value of (A).</p> <p>Registers retained None</p> <p>Subroutines referenced WRITCCS, CWRHED and SNSCOM</p> <p>Variables used R0, R1, R2, R3, R4 and R5</p>

6.15 Built-in microcassette subroutines

Subroutine name	Entry point	Description
MCSMAN	FF0D	<p>Performs FF (fast forward) and REW (rewind), etc., according to the keyboard input and displays the tape counter value on the LCD. The keys used for the manual operation mode are as follows.</p> <p>PF1: FF PF2: Slow forward PF3: Stop PF4: REW PF5: Quit. returns from the subroutine PF6: Counter reset</p> <p>This subroutine preserves the contents of the virtual screen while the HX-20 is in the manual operation mode.</p>
		<p>Parameters:</p> <p>At Entry None</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: Normal 80: Microcassette is not mounted. (Z): According to the value of (A).</p> <p>Registers retained None</p> <p>Subroutines referenced SNSCOM, KEYIN, KEYSTS, DSPLCN, BINDEC and LRECV</p> <p>Variables used None</p>
OPNRMS	FF0A	<p>Opens the microcassette file for input and searches the specified file until it is found. (see subroutine OPNRCS.)</p>
		<p>Parameters:</p> <p>At Entry and Return Same as subroutine OPNRCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine OPNRCS</p> <p>Variables used Same as subroutine OPNRCS</p> <p>Subroutines referenced MWRHED</p>
SRCRMS	FF07	<p>Opens the microcassette file. The function of this subroutine is the same as that of subroutine SRCRCS.</p>
		<p>Parameters:</p> <p>At Entry and Return Same as subroutine SRCRCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine SNSCOS</p> <p>Variables used Same as subroutine SNSCOS</p> <p>Subroutines referenced SNSOOM, MRDBHD and MRDBEF</p>
READMS	FF04	<p>Inputs one byte of data from the microcassette. The function of this subroutine is the same as that of subroutine READCS.</p>

		<p>Parameters:</p> <p>At Entry and Return Same as subroutine READCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine READCS</p> <p>Variables used Same as subroutine READCS</p> <p>Subroutines referenced WRTMCS, MWRHED and SNSCOM</p>
OPNWMS	FF01	<p>Opens the microcassette file.</p> <p>Parameters:</p> <p>At Entry and Return Same as subroutine OPNWCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine OPNWCS</p> <p>Variables used Same as subroutine OPNWCS</p> <p>Subroutines referenced MWRHED</p>
WRITMS	FEFE	<p>Outputs one byte of data to the microcassette. The function of this subroutine is the same as that of subroutine WRITCS.</p> <p>Parameters:</p> <p>At Entry and Return Same as subroutine WRITCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine WRITCS</p> <p>Variables used Same as subroutine WRITCS</p> <p>Subroutines referenced MWRBLK</p>
CLSMS	FEFB	<p>Closes the microcassette file. The function of this subroutine is the same as that of subroutine CLSCS.</p> <p>Parameters:</p> <p>At Entry and Return Same as subroutine CLSCS except that return code 80 is also used.</p> <p>Registers retained Same as subroutine CLSCS</p> <p>Variables used Same as subroutine CLSCS</p> <p>Subroutines referenced WRTMCS, MWRHED and SNSCOM</p>
REWMCS	FEF5	<p>Rewinds the microcassette tape to the beginning.</p> <p>Parameters:</p> <p>At Entry None</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: Normal 80: Microcassette not mounted. (X): Tape counter value after rewind (-32768 to 32767) (Z): According to the value of (A)</p> <p>Registers retained None</p> <p>Subroutines referenced</p>

		CHKMCS and SNSCOM Variables used R0
SEKMCS	FEF2	<p>Winds the microcassette tape to the specified tape counter value.</p> <p>Parameters:</p> <p>At Entry (X): Specified value of the binary counter. (-32768 through 32767)</p> <p>At Return (C): Abnormal I/O flag (A): Return codes 00: Normal 80: Microcassette not mounted. (Z): According to the value of (A). (X): Counter value after wind</p> <p>Registers retained None</p> <p>Subroutines referenced CHKMCS and SNSCOM</p> <p>Variables used R0</p>
CNTMCS	FEEF	<p>Sets or reads the microcassette tape counter value.</p> <p>Parameters:</p> <p>At Entry (A): Specifies setting or reading of the tape counter value. 00: Reads the tape counter value. 01: Sets the tape counter value. (Any value other than 00 is taken as 01.) (X): Counter value (A≠00)</p> <p>Return parameters (C): Abnormal I/O flag (0 is always set on return.) (X): Counter value (A=00 at entry)</p> <p>Registers retained (B)</p> <p>Subroutines referenced None</p> <p>Variables used None</p>

6.16 Work areas for external cassette

Address	Variable name	Byte count	Description
15D 1D5	CSMOD	1	Current mode Bits 0 and 1: Format (Bits 1 and 0) = (0, 0): EPSON format Other than (0, 0): Format other than EPSON format Bits 2 and 3: File open status (bit 3, bit 2) = (0, 0): File not open (0, 1): Open for input (1, 0): Open for output (1, 1): Undefined Bits 4 to 7: Undefined
1D6 1D7	CSBLNO	2	Block number
1D8 1D9	CSBCC	2	BCC register value (CRC check for a single block)
1DA 1DB	CSBLSZ	2	Unused
1DC 1DC	CSBSTP	1	Interblock gap tape stop mode 0: Tape stops at the interblock gap. 1: Tape does not stop at the interblock gap.
1DD 1DD	CSSTS	1	Error status (Logic '1' in any bit indicates an error.) Bit 0: EOF (EOF detected during input.) Bits 1 to 3: Underfined Bit 4: Underfined Bit 5: Write error Bit 6: Read error Bit 7: Buffer overflow
1DE 1DF	CSBFAD	2	Starting address of cassette buffer
1E0 1E1	CSBFBT	2	Ending address of cassette buffer plus 1
1E2 1E3	CSBFSZ	2	Cassette buffer size (in bytes)
1E4 1E5	CSBFIP	2	Pointer indicating the next address to be stored in the cassette buffer
1E6 1E7	CSBFOP	2	Pointer indicating the next address to be fetched from the cassette buffer
1E8 1E9	CSBFCM	2	Number of data in buffer
1EA 1EA	CSRDRTR	1	Upper limit for the number of block input trials
1EB 1EB	CSRDCN	1	Number of block input trials

6.17 Work areas for built-in microcassette

Address	Variable name	Byte count	Description
1EC 1EC	MSMOD	1	Current mode Bits 0 and 1: Format (Bits 1 and 0) = (0, 0): EPSON format Other than (0, 0): Format other than EPSON format Bits 2 and 3: File open status (0, 0): File not open (0, 1): Open for input (1, 0): Open for output (1, 1): Undefined Bits 4 to 7: Undefined
1ED 1EE	MSGLNO	2	Block number
1EE 1FO	MSBCC	2	BCC register value (CRC check for a single block)
1F1 1F2	MSBLSZ	2	Unused
1F3 1F3	MSBSTP	1	Interblock gap tape stop mode 0: The tape stops at the interblock gap. 1: The tape does not stop at the interblock gap.
1F4 1F4	MSSTS	1	Error status (Logic '1' in any bit indicates an error.) Bit 0: EOF (EOF detected during input.) Bits 1 through 3: Underfined Bit 4: Counter not updated Bit 5: Write error Bit 6: Read error Bit 7: Buffer overflow
1F5 1F6	MSBFAD	2	Starting address of microcassette buffer
1F7 1F8	MSBFBT	2	Ending address of microcassette buffer +1
1F9 1FA	MSBFSZ	2	Microcassette buffer size (in bytes)
1F9 1FC	MSBFIP	2	Pointer indicating the next address to be stored in the buffer
1FD 1FE	MSBFOP	2	Pointer indicating the next address to be fetched from the buffer
1FF 200	MSBFCM	2	Number of data in buffer
201 201	MSRDIR	1	Upper limit for the number of block input trials
202 202	MSRDCN	1	Number of block input trials
203 204	MSCNTR	2	Counter value
205 205	MSMNCM	1	Manual command currently being executed
206 206	MTOFCN	1	Sampling timeout counter for data I/O
207 207	MSPLMD	1	Counter pulse status (low or high)

6.18 Work areas for external cassette headers

Address	Variable name	Byte count	Description
2D0 2D0	CHBLID	1	'H'
2D1 2D2	CHBLNO	2	Block number (binary, 0 ...)
2D3 2D3	CHBLBU	1	Same block, block number (0, 1 ...)
2D4 2D7	CID	4	HDR
2D8 2DF	CFNAME	8	Filename
2E0 2E7	CFTYPE	8	File type
2E8 2E8	CRTYPE	1	Record type (2: Double write)
2E9 2E9	CBMODE	1	Block mode S: Short gap Δ : Interblock gap stop
2EA 2EE	CBLNG	5	Block length ($\Delta\Delta 256$: 256)
2EF 2F3		5	
2F4 2F9	CDATE	6	Data (MMDDYY)
2FA 2FF	CTIME	6	Time (HHMMSS)
300 305		6	
306 307	CVOLN	2	Volume number
308 30F	CSYSN	8	System name (HX-20 $\Delta\Delta\Delta$)
310 323		20	

6.19 Work areas for built-in microcassette headers

Address	Variable name	Byte count	Description
324 324	MHBLID	1	'H'
325 326	MHBLNO	2	Block number
327 327	MHBLBU	1	Same block, block number
328 32B	MID	4	HDR1
32C 333	MFNAME	8	Filename
334 33B	MFTYPE	8	File type
33C 33C	MRTYPE	1	Record type (2: Double write)
33D 33D	MBMODE	1	Block mode S: Short gap Δ : Interblock gap stop
33E 342	MBLNG	5	Block length ($\Delta\Delta\Delta 256$: 256)
343 347		5	
348 34D	MDATE	6	Date (MMDDYY)
34E 353	MTIME	6	Time (HHMMSS)
354 359		6	
35A 35B	MVOLN	2	Volume number
35C 363	CSYSN	8	System name (HX-20 $\Delta\Delta\Delta$)
364 377		20	
378 47B	CASBUF	260	Buffer used by the microcassette

CHAPTER 7 MICROPRINTER

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7.1 General

The built-in microprinter is a dot matrix printer with a print width of 144 dots. Printing is performed by a single print head driven by four solenoids. Print mode is unidirectional and paper feed is performed each time the print head is returned. The I/O ports related to printing are connected to the slave MCU which controls printing. The bit patterns for printing, however, are supplied by the master MCU.

7.2 Print Head and Solenoids

The microprinter has one print head and four solenoids: A, B, C and D. Each solenoid prints 36 dots during a single pass of the print head. (Fig. 7.1). Only unidirectional printing is performed and line feed of one dot-line is performed when the head is returned (Fig. 7-2).

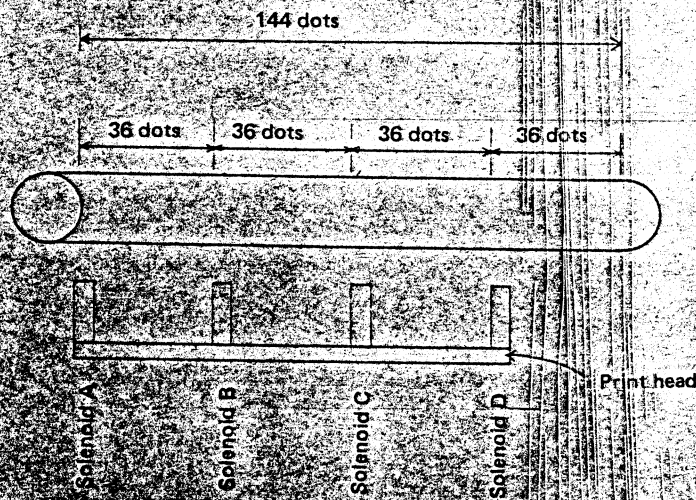


Fig. 7-1 Print Area of Each Solenoid

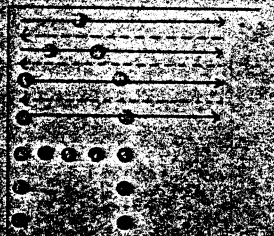


Fig. 7-2 Print Head Operation

Thus, to print a single 6 x 8-dot character pattern, the print head MUST make 8 passes in each direction.

When printing "ABCDEFGH IJKLMNOPQRST UVWX", characters "ABCDEF" are printed by solenoid A, "GHIJKL" are printed by solenoid B, "MNOPQR" by solenoid C, and "STUVWX" by solenoid D.

The printer is controlled by the slave MCU, but actual printing is performed in response to commands sent from the master MCU.

7.3 Ports

The I/O ports related to the printer are as follows.

	Port	Input/ Output	Function		
Slave MCU	P10	Output	Print solenoid 1	1: ON	0: OFF
	P11	Output	Print solenoid 2	1: ON	0: OFF
	P12	Output	Print solenoid 3	1: ON	0: OFF
	P13	Output	Print solenoid 4	1: ON	0: OFF
	P14	Output	Motor output	1: ON	0: OFF
	P15	Input	Reset signal input	1: High	0: Low
	P16	Input	Timing pulse	1: High	0: Low
	P17	Output	Motor break	1: Break ON	0: Break OFF

NOTE:

Commands must not be sent from the master MCU which will operate the above ports to supply current to the print solenoids for more than a few seconds or to supply a BREAK signal while motor output is specified (P14 is 1).

7.4 Slave MCU Commands

The slave MCU is provided with a command for printing 6 dots of print data. This command is sent from the master MCU 24 times to print one dot-line. Therefore, sending this command 48 times will print 2 dot-lines and sending it 192 (24 x 8) times will print one line of 6 x 8-dot character patterns.

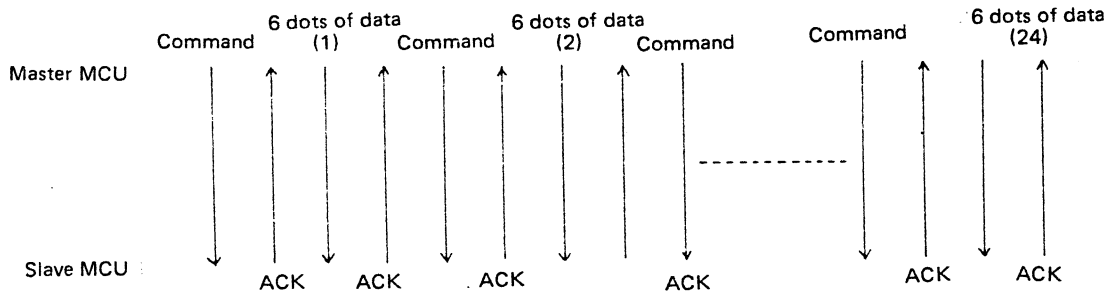
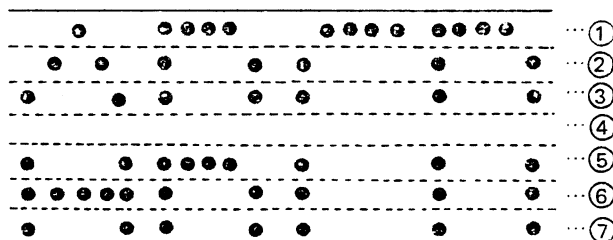


Fig. 7-3 Transmission of Slave MCU Command

If printing is resumed after being interrupted (the print head stops), a blank of one dot-line will occur. This is due to the automatic paper feed (one pitch) when the print head is returned and to the fact that the head stop and restart operation has not finished within the duration of the head's return pass across the page.



Lines ①, ② and ③ are printed normally. If printing is stopped after line ③, one dot line will be left blank by automatic line feed when the printing lines.

Fig. 7-4 One Blank Dot-line when Print Head Stops

After the slave MCU restarts printing on the printer and a new line is to be printed, if there are less than 24 bytes of data in the data buffer, printing is stopped automatically. When continuously printing a given print pattern, if an interrupt in command transmission from the master to the slave MCU of approx. 300msec occurs, data may be lost (Fig. 7-5).

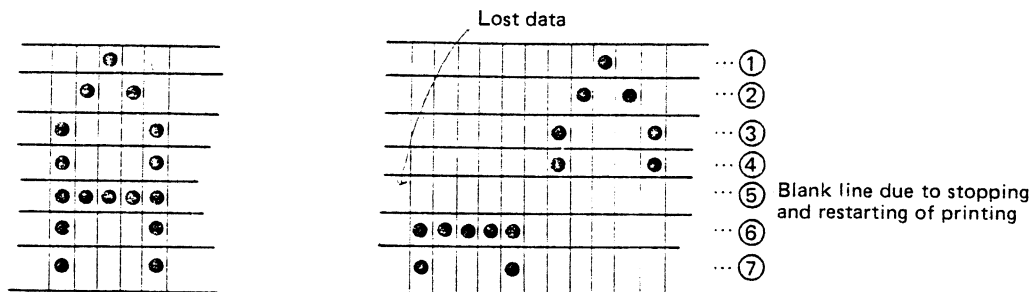


Fig. 7-5 Loss of Print Data

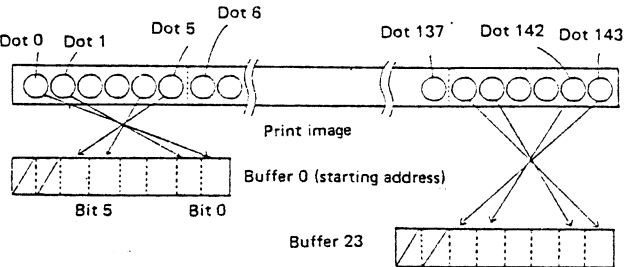
In Fig. 7-5, printing of an A pattern has been attempted. After the data on line 4 has been sent to the slave MCU and blank time has passed, data transmission is performed. Since there is only one byte of data in the slave MCU, printing is stopped. The data in the buffer at this time will be lost.

Printing is resumed when the contents of the buffer exceed 24 bytes. This results in lost print data, as shown in Fig. 7-5.

When printing a line of characters (subroutine "LNPRNT"), after 8 dot-lines of data have been sent, a 2-dot line feed command is sent from the master MCU. In this way, data loss due to timing is prevented (since the feed command processed by the slave MCU stops fetching of the dot pattern data to the buffer).

7.5 List of Printer Subroutines

Subroutine Name	Entry Point	Contents
CHPRNT	FF97	<p>Outputs one character to the microprinter. All control codes (00-1F) except CR(0D) and LF (0A) are ignored. For CR, the buffer column position is set to 0 (first position) and the contents of the buffer are cleared. For LF control codes, the contents of the buffer are printed. After printing, the buffer is cleared and the column position is set to 0.</p> <p>Parameters: At Entry (A): Character code (ASCII) At Return (C) Abnormal I/O flag Registers retained (A), (B), (X) Subroutines referenced LNPRNT, CLRB Variables used None</p>
LNPRNT	FF94	<p>Outputs 1 line of characters on the microprinter. Checks for printer switch ON or OFF. If OFF, the output procedure is ignored. Prints 24 characters of the printer buffer contents (ASCII). After printing, the contents of the buffer remain unchanged.</p> <p>Parameters: At Entry (X): Starting address of buffer Buffer size: 24 bytes Data is in ASCII code. At Return (C) Abnormal I/O flag Registers retained (A), (B), (X) Subroutines referenced SNSCO, NDFEED, CHKSWT, CHKRS Variables used R0, R1</p>
PRTDOT	FF91	<p>Prints one dot-line of bit-image data. One dot-line of bit-image print consists of 144 dots and is specified by the 24 bytes in the buffer. Data is entered into the buffer as follows.</p>

Subroutine Name	Entry Point	Contents
		 <p data-bbox="589 592 1274 654">Bit 6 and bit 7 of each byte of the buffer have no meaning.</p> <p data-bbox="589 659 675 687">NOTE:</p> <p data-bbox="589 692 1295 787">If during the printing of an image an empty interval occurs until this subroutine is called, a 1-dot blank line will result.</p> <hr/> <p data-bbox="589 820 769 849">Parameters:</p> <p data-bbox="589 853 724 882">At Entry</p> <p data-bbox="589 887 1096 915">(X): Starting address of buffer</p> <p data-bbox="589 920 738 948">At Return</p> <p data-bbox="589 953 934 982">(C) Abnormal I/O flag</p> <p data-bbox="589 986 884 1015">Registers retained</p> <p data-bbox="589 1019 801 1048">(A), (B), (X)</p> <p data-bbox="589 1052 950 1081">Subroutines referenced</p> <p data-bbox="589 1086 934 1114">SNSCOW, CHKSWT, CHKRS</p> <p data-bbox="589 1119 821 1148">Variables used</p> <p data-bbox="589 1152 644 1181">R0H</p> <p data-bbox="589 1185 735 1214">[Example]</p> <p data-bbox="589 1218 1075 1247">When the following is printed.</p> <p data-bbox="649 1251 1091 1280">○●●○○●●○○○</p> <pre data-bbox="667 1311 918 1369">LDX BUFF JSR PRTDOT</pre> <p data-bbox="589 1409 1012 1437">BUFF FCB \$06, \$03,</p> <hr/> <p data-bbox="589 1475 1177 1504">Performs paper feed for n dot-lines.</p> <hr/> <p data-bbox="589 1541 769 1570">Parameters:</p> <p data-bbox="589 1574 724 1603">At Entry</p> <p data-bbox="589 1608 1193 1667">(A): Number of dot-lines of line feed performed</p> <p data-bbox="589 1672 738 1701">At Return</p> <p data-bbox="589 1705 950 1734">(C): Abnormal I/O flag</p> <p data-bbox="589 1738 884 1767">Registers retained</p> <p data-bbox="589 1771 801 1800">(A), (B), (X)</p> <p data-bbox="589 1804 950 1833">Subroutines referenced</p> <p data-bbox="589 1838 801 1866">SNSCOW, CHKRS</p> <p data-bbox="589 1871 821 1900">Variables used</p> <p data-bbox="589 1904 644 1933">None</p>
NDFEED	FF8F	

Subroutine Name	Entry Point	Contents
SCRCPY	FF8B	<p>Copies the data displayed on the LCD on the microprinter. The width of the LCD is 120 dots and that of the printer, 144 dots. The data is left-justified and the remaining 24 dots remain blank.</p> <hr/> <p>Parameters: At Entry None At Return (C): Abnormal I/O flag Registers protect (A), (B), (X) Subroutine referenced SNSCOW, SNSCOM, WRTP26, CHKSWT, LCDMOD Variables used None</p>

7.6 Microprinter Work Areas

Addresses (From)	Addresses (To)	Variable Name	Byte Count	Contents
190	195	CHRPTN	6	Work Area for character font (for 1 character).
196	196	COLCNT	1	Data count in buffer (0~24 bytes)
197	1AE	CHRDAT	24	Buffer data for 1 line of characters.

ERP SEG LOC OBJECT PROGRAM PRINT --- PRINT FULL GRAPHIC PATTERN ---

```

00001
00002
00003
00004
00005
00006
00007
00008
00009
00010A 1000
00011
00012
00013      FF91  A
00014
00015
00016
00017
00018
00019
00020
00021
00022
00023
00024
00025A 1000 86 08  A
00026A 1002 C6 03  A
00027
00028A 1004 CE 101F  A
00029A 1007 C1 03  A
00030A 1009 27 0A 1015
00031A 100B CE 1037  A
00032A 100E C1 02  A
00033A 1010 27 03 1015
00034A 1012 CE 104F  A
00035A 1015 2D FF91  A
00036A 1018 5A
00037A 1019 26 E9 1004
00038A 101B 4A
00039A 101C 26 E4 1002
00040
00041A 101E 39
00042
00043A 101F 09  A
      A 1020 09  A
      A 1021 09  A
      A 1022 09  A
      A 1023 09  A
      A 1024 09  A
00044A 1025 09  A
      A 1026 09  A
      A 1027 09  A
      A 1028 09  A
      A 1029 09  A
      A 102A 09  A
00045A 102B 09  A

```

```

*
*      NAM      PRINT
*      TTL      --- PRINT FULL GRAPHIC PATTERN ---
*      OPT      LOAD
*      OPT      PAGE=55
*
* PRINT FULL GRAPHIC PATTERN TO INTERNAL MICRO PRINTER.
* FILE NAME    'EX34'    BY K.A
*
*      ORG      $1000
*
*
*      PRTDOT EQU    $FF91
*
* PRINT PATTERN OF OBLIQUE LINES.
*
*      . . . . .
*      . . . . .
*      . . . . .
*      . . . . .
*      . . . . .
*
*
*      LDA A #8      * (A): REPAETING TIMES
PRTR10 LDA B #3      * (B): PATTERN NUMBER (3 2 1)
*
PRTRPT LDX #PATN1    * SET ADDRESS OF PRINT PATTERN
      CMP B #3      * IF (B)=3, PATTERN 1
      BEQ PRTR30
      LDX #PATN2    * IF (B)=2, PATTERN 2
      CMP B #2
      BEQ PRTR30
      LDX #PATN3    * IF (B)=1, PATTERN 3
PRTR30 JSR PRTDOT   * PRINT BY GRAPHIC IMAGE.
      DEC B
      BNE PRTRPT
      DEC A      * FINISHED ?
      BNE PRTR10
*
*      RTS
*
PATN1 FCB $09,$09,$09,$09,$09,$09
*
FCB $09,$09,$09,$09,$09,$09
*
FCB $09,$09,$09,$09,$09,$09

```


ERR SEQ LOC OBJECT PROGRAM PRINT --- PRINT FULL GRAPHIC PATTERN ---

ERR	SEQ	LOC	OBJECT	PROGRAM	PRINT
		A 102C	09	A	
		A 102D	09	A	
		A 102E	09	A	
		A 102F	09	A	
		A 1030	09	A	
00046A		A 1031	09	A	FCB \$09,\$09,\$09,\$09,\$09,\$09
		A 1032	09	A	
		A 1033	09	A	
		A 1034	09	A	
		A 1035	09	A	
		A 1036	09	A	
00047A		A 1037	12	A	PATN2 FCB \$12,\$12,\$12,\$12,\$12,\$12
		A 1038	12	A	
		A 1039	12	A	
		A 103A	12	A	
		A 103B	12	A	
		A 103C	12	A	
00048A		A 103D	12	A	FCB \$12,\$12,\$12,\$12,\$12,\$12
		A 103E	12	A	
		A 103F	12	A	
		A 1040	12	A	
		A 1041	12	A	
		A 1042	12	A	
00049A		A 1043	12	A	FCB \$12,\$12,\$12,\$12,\$12,\$12
		A 1044	12	A	
		A 1045	12	A	
		A 1046	12	A	
		A 1047	12	A	
		A 1048	12	A	
00050A		A 1049	12	A	FCB \$12,\$12,\$12,\$12,\$12,\$12
		A 104A	12	A	
		A 104B	12	A	
		A 104C	12	A	
		A 104D	12	A	
		A 104E	12	A	
00051A		A 104F	24	A	PATN3 FCB \$24,\$24,\$24,\$24,\$24,\$24
		A 1050	24	A	
		A 1051	24	A	
		A 1052	24	A	
		A 1053	24	A	
		A 1054	24	A	
00052A		A 1055	24	A	FCB \$24,\$24,\$24,\$24,\$24,\$24
		A 1056	24	A	
		A 1057	24	A	
		A 1058	24	A	
		A 1059	24	A	
		A 105A	24	A	
00053A		A 105B	24	A	FCB \$24,\$24,\$24,\$24,\$24,\$24
		A 105C	24	A	
		A 105D	24	A	
		A 105E	24	A	
		A 105F	24	A	
		A 1060	24	A	
00054A		A 1061	24	A	FCB \$24,\$24,\$24,\$24,\$24,\$24
		A 1062	24	A	

*** 5301 CROSS MACROASSEMBLER VER1.0 ***

10/21/82 09:41:28

ERR SEQ LOC OBJECT PROGRAM PRINT --- PRINT FULL GRAPHIC PATTERN ---

A 1063 24 A
A 1064 24 A
A 1065 24 A
A 1066 24 A

00055 *
00056 *
00057 *

00058 0000 A END

***** TOTAL ERRORS 0

CHAPTER 8 ROM CARTRIDGE

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3.1 General

The ROM cartridge, which is provided as a plug-in option of the HK-20, can read 2K to 16K bytes of data from an external ROM memory via the I/O ports using its addressing counter and shift register. The addressing counter is incremental and its value can also be reset to 0.

The ROM cartridge is designed for an output-only file as a ROM file to allow data output in this file format.

3.2 Configuration

Table 8.1 shows the I/O ports related to the ROM cartridge.

	Port	I/O	Description
Master MCU	P17	Input	ROM data (1 bit)
	P266	Output	Shift/load select (0: Load; 1: Shift)
	P267	Output	Clock
Slave MCU	P20	Input	ROM cartridge interface judgment
	P46	Input	ROM cartridge interface judgment
	P42	Output	Shift register clear (0: OFF (Clear) 1: ON (Don't clear))
	P43	Output	Power supply (0: OFF 1: ON)
	P44	Output	Addressing counter clear (0: OFF (Clear); 1: ON (Don't clear))

The ROM cartridge is configured as shown in Fig. 8-1. One byte of ROM data at the address indicated by the addressing counter is input to the shift register, which in turn transfers the ROM data to the master MCU.

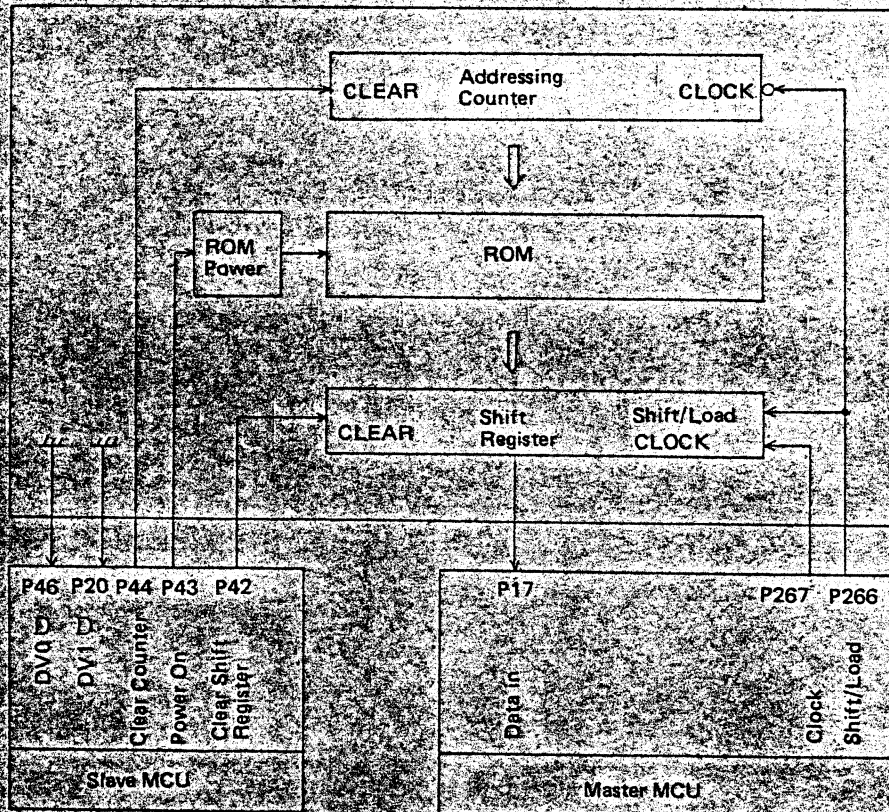


Fig. 8-1 Block Diagram of ROM Cartridge

8.3 Data Input Procedure

Only two types of instructions are applicable to the addressing counter: Clear (by setting the P44 of the slave MCU to "0") and Count-up. Data is fetched by the master MCU from the shift register by inputting one bit of data to the port P17 of the master MCU each time the data bits in the shift register are moved. Data input from the ROM cartridge is performed by the procedure as detailed below.

- (1) The power supply of the ROM cartridge is turned ON.
The port P43 of the slave MCU is the power supply port to turn on or off the ROM cartridge. The master MCU instructs the slave MCU to issue a ROM Power ON command to turn on the power supply of the ROM cartridge.
- (2) The addressing counter is cleared.
The addressing counter is automatically reset to 0 when the ROM Power ON command is issued to the ROM cartridge from the slave MCU.
- (3) The addressing counter is incremented to the address from which data is to be read.
The counter counts up when the voltage level at the port P266 (bit 6 at address 26) of the master MCU changes from High to Low.
- (4) When port P266 is at Low level, one byte of data at the address indicated by the addressing counter is loaded into the shift register at the leading edge of a CLOCK signal appearing at the P267 (bit 7 at address 26) of the master MCU. In this case, bit 7 is first loaded into the master MCU through port P17 (Data in).
- (5) When port P266 is at High level, the contents of the shift register are shifted by one bit at the trailing edge of the CLOCK signal (P267). By repeating this operation 7 times, one byte of data can be fetched by the master MCU.
- (6) If data input from the ROM cartridge is no longer required, the power supply of the ROM cartridge must be turned off by sending a command from the master MCU to the slave MCU to turn off the ROM power supply.

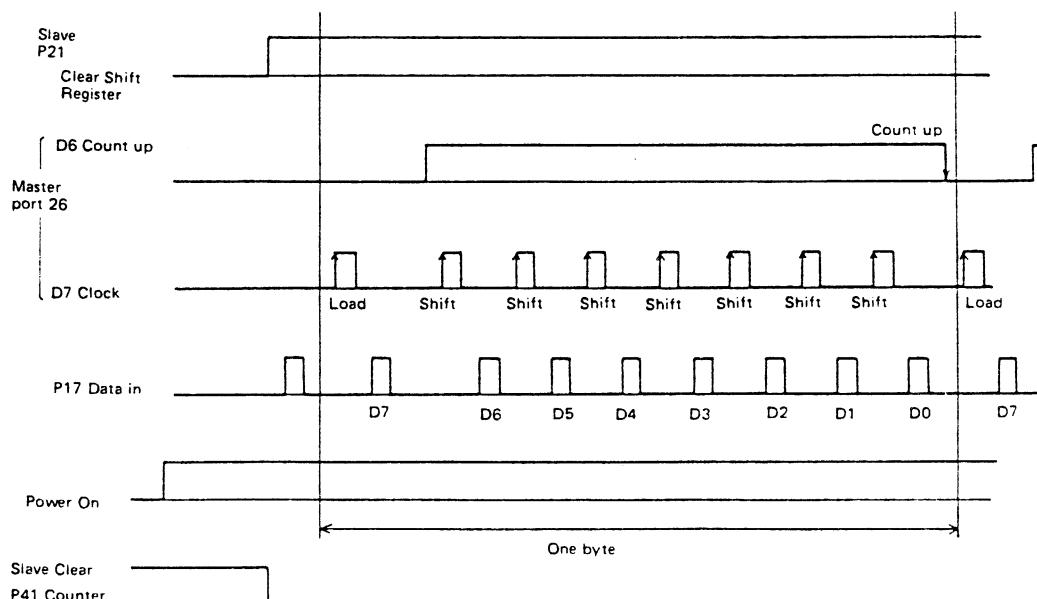


Fig. 8-2 Timing Chart of Data Input from ROM Cartridge

Note: If data is input after clearing the shift register, the data that is input to the master MCU is binary 0. If this Shift Register Clear operation is performed when the optional microcassette drive is connected to the HX-20, binary 1 is input.

8.4 ROM File

Data input from the optional ROM cartridge is supported in the form of data input from a ROM file. The ROM file consists of 32 headers and a data area. Each header may contain a maximum of 32 bytes of data as header information. The ROM file may only be accessed sequentially but not randomly.

Fig. 8-3 shows the structure of the ROM file.

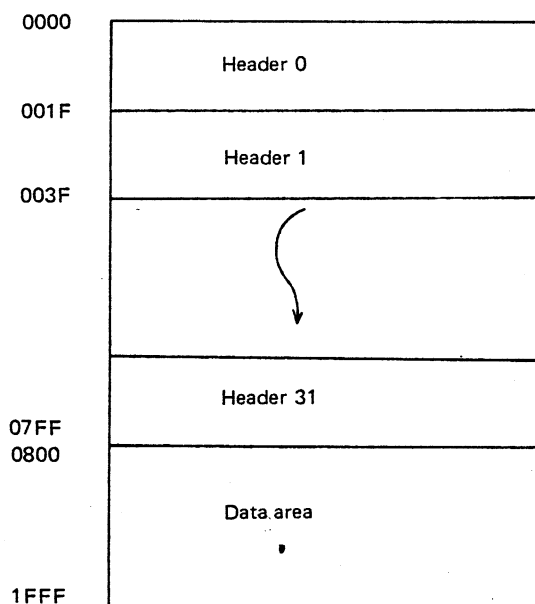


Fig. 8-3 Structure of ROM File

Headers are allocated as fixed areas from address 0000 in units of 32 bytes. Header 0 is from address 0000 to address 001F. A maximum of 32 headers can be set. The first one byte of each header represents the first letter of the filename as well as header information. If the first one byte of a header is "00", it indicates that the file with that header has been deleted. If "FF", it indicates that no subsequent header exists.

If the first one byte of header 2 is "FF", headers 0 and 1 are valid as headers. The contents of the header information are shown in Section 8.7 below.

8.5 Subroutines for ROM Cartridge

The following 4 subroutines are provided for the ROM cartridge:

- (1) OPNPRM: Opens the ROM file.
- (2) REDPRM: Inputs data from the ROM file in units of one byte.
- (3) CLSPRM: Closes the ROM file.
- (4) DIRPRM: Inputs the ROM file directory.

3.6 File Input Procedure

A ROM file is processed for data input as follows:

- (1) Opening the ROM file
Subroutine "OPNPRM" is used to start the input of data from the ROM file.
- (2) Data input
Data is read from the ROM file in units of one byte by subroutine "REDPRM."
- (3) Closing the ROM file
Data input from the ROM file is terminated by subroutine "CLSPRM".

Note: Upon opening the ROM file, the ROM cartridge is energized. The ROM file must be closed soon after the data input has been completed particularly when an NMOS type PROM with high power consumption is used.

3.7 Header Format of ROM File

Columns	Bytes	Item	Description
0 to 7	8	Filename	Filename (in ASCII codes.) Column 0 represents ID in addition to the filename. 00: File has been deleted. FF: No subsequent header exists.
8 to 15	8	File type	File type (in ASCII codes)
16 to 19	4	Starting address	The starting address of the ROM area secured as a file. The binary address value is expressed in 4-digit hexadecimal numbers (ASCII codes).
20 to 23	4	Ending address +1	The address next to the ending address of the ROM area secured as a file. The binary address value is expressed in 4-digit hexadecimal numbers (ASCII code).
24 to 29	6	Date	Month, day, and year each expressed in 2-digit ASCII codes.
30 to 31	2		Unused.

8.8 ROM Cartridge Subroutine Table

Subroutine name	Entry point	Description
OPNPRM	FEEC	<p>ROM file input open</p> <p>°Parameters:</p> <p>At Entry</p> <p>(A): This parameter specifies whether or not the filename is to be returned.</p> <p>01: Return the filename opened in the packet.</p> <p>00: Do not return the filename opened in the packet.</p> <p>(X): Starting address of packet</p> <p>°Packet</p> <ol style="list-style-type: none"> 1. Filename (8 bytes) 2. File type (8 bytes) 3. Filename (8 bytes) (Enter the filename opened when the filename is to be returned.) 4. File type (8 bytes) (Enter the file type opened when the filename is to be returned.) <p>Note:</p> <p>In the filename specification for the packet, if the string specifying a filename contains an asterisk (*), the filename matching terminates at the point of the asterisk and the system assumes that both the filenames have matched.</p> <p>In BASIC Version 1.0, when the matching of the filename with an asterisk (*) terminates, the system assumes that both the file types have also matched. (Note that the ROM file open procedure differs from the cassette file open procedure.)</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Return codes</p> <p>00: Normal</p> <p>A0: ROM cartridge not mounted</p> <p>A1: File not found</p> <p>A2: File already open</p> <p>A4: Invalid header data format</p> <p>A5: Invalid header address format</p> <p>(Z): This parameter depends on the value of parameter (A).</p> <p>°Packet (filename, file type)</p> <p>°Registers retained:</p> <p>None</p> <p>°Subroutines referenced:</p> <p>"PRMPON", "PREDBY", "HEXBIN" and "CLSPRM"</p> <p>°Temporary variables used:</p> <p>R0, R1, and R2</p>

Subroutine name	Entry point	Description
REDPRM	FEE9	<p>Input of one byte from ROM file.</p> <p>°Parameters:</p> <p>At Entry None</p> <p>At Return (C) Abnormal I/O flag (Always 00) (A): Input data (B): Return codes 00: Normal 01: End of file A3: File not opened (Z): This parameter depends on the value of parameter (B).</p> <p>°Registers retained: (X) °Subroutines referenced: "ADSTEP" °Temporary variables used: None</p>
CLSPRM	FEE6	<p>ROM file close.</p> <p>°Parameters:</p> <p>At Entry None</p> <p>At Return (C): Abnormal I/O flag</p> <p>°Registers retained: (B) and (X) °Subroutines referenced: "CHKRS" and "SNSCOM"</p> <p>Note: An attempt to close an unopened ROM file is not regarded by the system as an error.</p>
DIRPRM	FEE3	<p>ROM file directory read. This subroutine specifies record number of the directory and inputs the record.</p> <p>°Parameters:</p> <p>At Entry (A): Directory record number from 0 through 63 (D) (X): Starting address of memory locations here the directory record is stored. The size of each record must be 32 bytes.</p> <p>At Return: (C): Abnormal I/O flag (A): Return codes 00: Normal A0: ROM cartridge not connected A3: Invalid specification of the directory record number (Z): This parameter depends on the value of parameter (A).</p> <p>°Registers retained: None °Subroutines referenced: "PRMPON", "ADSTEP", "PREDBY" and "CLSPRM" °Temporary variables used: None</p>

8.9 ROM Cartridge Work Areas

Address (from)(to)	Variable name	Bytes	Description
208 208	PRMSTS	1	Status of the ROM file Bit 0: File open status flag 0: File not opened 1: File opened Bits 1 ~ 6: Undefined Bit 7: Power supply for ROM 0: OFF, 1: ON
209 20A	STAPRS	2	ROM addressing counter
20B 20C	FTADRS	2	Starting address of file
20D 20E	EDADRS	2	Ending address of file + 1

ERR SEQ LOC OBJECT PROGRAM ROMOPT --- ROM CARTRIDGE INTERFACE ROUTINE ---

```

00001          NAM      ROMOPT
00002          TTL      --- ROM CARTRIDGE INTERFACE ROUTINE ---
00003          * FILE   'EX57' BY K.A
00004          OPT      PAGE=55
00005          OPT      LOAD
00006          *
00007          *
00008          * COMMON DEFINITION
00009          *
00010          * MPU 6301 I/O PORT
00011          0002 A    PORT1 EQU    $02      * I/O PORT 1 (ADDRESS)
00012          0003 A    PORT2 EQU    $03      * I/O PORT 2 (ADDRESS)
00013          *
00014          * OTHER REGISTERS
00015          * REGISTER MEANINGS
00016          *
00017          * PORT1 $02
00018          *      0:R DATA SET READY (0:HIGH 1:LOW)
00019          *      1:R CLEAR TO SEND (0:HIGH 1:LOW)
00020          *      2:R PORT TO SLAVE P34 (SFLAG)
00021          *      3:R INTERRUPT FROM EXTERNAL PORT (0:INTERRUPT)
00022          *      4:R POWER FAIL (0:ABNORMAL)
00023          *      5:R KEY BOARD INTERRUPT FLAG (0:INTERRUPT)
00024          *      6:R PERIPHERAL STATUS (0:HIGH 1:LOW) (FROM SERIAL)
00025          *      7:R MICRO CASSETTE COUNTER / MICRO CASSETTE EXIST
00026          *
00027          *      $26
00028          *      0:W LCD COMAND/DATA 1
00029          *      1:W LCD COMAND/DATA 2
00030          *      2:W LCD COMAND/DATA 4
00031          *      3:W LCD CMMAND/DATA SELCTION (0:DATA 1:COMMAND)
00032          *      4:W KEY BOARD INTERRUPT MASK (0:CLOSE 1:OPEN)
00033          *      5:W PERIPHERAL CONTROL (TO SERIAL)
00034          *      6:W TO PLUG IN 1
00035          *      7:W TO PLUG IN 2 AND SLAVE P40
00036          *

```

```

ERR  SEQ  LOC  OBJECT  PROGRAM  ROMOPT  --- ROM CARTRIDGE INTERFACE ROUTINE ---

00038          * COMMON DEFINITION
00039          *
00040          * ZERO PAGE RAM
00041A 004E          *   ORG      $4E
00042A 004E    0001  A    PWRFLG RMB    1      * BIT 0-3: CLOCK POWER ON MODE
00043          *   * $01:POWER ON BY CLOCK IN BASIC MODE
00044          *   * $02:POWER ON BY CLOCK IN APPLICATION MODE
00045          *   * BIT 4-7: BEFOR POWER OFF, CALL PROCEDURE MODE
00046          *   * $01:BEFOR POWER OFF, CALL PROCEDURE IN
00047          *   *   BASIC MODE.
00048          *   * $02:BEFOR POWER OFF, CALL PROCEDURE IN
00049          *   *   APPLICATION MODE.
00050          *
00051A 004F    0001  A    P26      RMB    1      * VALUE OF ADDRESS $26
00052          * GENERAL REGISTERS USED BY I/O ROUTINE
00053          *   0050  A    R0      EQU    *      * 2 BYTES REGISTER (R0H,R0L)
00054A 0050    0001  A    R0H     RMB    1
00055A 0051    0001  A    R0L     RMB    1
00056          *   0052  A    R1      EQU    *      * 2 BYTES REGISTER (R1H,R1L)
00057A 0052    0001  A    R1H     RMB    1
00058A 0053    0001  A    R1L     RMB    1
00059          *   0054  A    R2      EQU    *      * 2 BYTES REGISTER (R2H,R2L)
00060A 0054    0001  A    R2H     RMB    1
00061A 0055    0001  A    R2L     RMB    1
00062          *   0056  A    R3      EQU    *      * 2 BYTES REGISTER (R3H,R3L)
00063A 0056    0001  A    R3H     RMB    1
00064A 0057    0001  A    R3L     RMB    1
00065          *
00066A 007C          *   ORG      $7C
00067A 007C    0001  A    SI0STS RMB    1      * SLAVE I/O STATUS (EACH BIT 0:OFF, 1:ON)
00068          *   * BIT 0: PRINTER
00069          *   * BIT 1: EXTERNAL CASSETTE
00070          *   * BIT 2: INTERNAL CASSETTE
00071          *   * BIT 3: RS232C ON (READ)
00072          *   * BIT 4: SPEAKER ON
00073          *   * BIT 5: PROM CASSETTE
00074          *   * BIT 6: BAR CODE READER
00075          *   * BIT 7: BREAK SLAVE CPU (0:ON EXECUTE
00076          *   *   1:BROKEN BY INTERRUPT)
00077A 007D    0001  A    MI0STS RMB    1      * MAIN I/O STATUS EACH BIT (0:OFF 1:ON)
00078          *   * BIT 0: LCD ON READ/WRITE CHARACTERS
00079          *   * BIT 1: NOW SENDING COMMAND TO SLAVE CPU
00080          *   * BIT 2: NOW TRANSMITTING DATA TO SERIAL (1:ON)
00081          *   * BIT 3: ON CLOCK INTERRUPT (1:ON)
00082          *   * BIT 4: (POWER FAIL)
00083          *   * BIT 5: (OFF POWER SWITCH)
00084          *   * BIT 6: ON PAUSE KEY
00085          *   * BIT 7: ON BREAK KEY
    
```

EPD SEQ LOC OBJECT PROGRAM ROMOPT --- ROM CARTRIDGE INTERFACE ROUTINE ---

00087						* ROM CASSETTE WORK AREA		
00088A	0208					ORG	\$208	
00089		0208	A			PRWKT	EQU	*
00090A	0208	0001	A			PRMSTS	RMB	1
00091						*		
00092A	0209	0002	A			STADRS	RMB	2
00093A	020B	0002	A			FTADRS	RMB	2
00094A	020D	0002	A			EDADRS	RMB	2

* ROM WORK TOP
 * ROM STATUS (BIT7:POWER ON 1:ON 0:OFF
 * (BIT0:OPEN FLAG 1:OPEN 0:CLOSE
 * ROM ADDRESS COUNTER
 * ADDRESS OF TOP OF FILE
 * ADDRESS OF LAST OF FILE +1

```

ERR  SEQ  LOC  OBJECT  PROGRAM  ROMOPT  --- ROM CARTRIDGE INTERFACE ROUTINE ---
00097A 1000          ORG      $1000
00098          *
00099          FF2E  A      CHKPLG EQU  $FF2E
00100          FF19  A      SNSCOM EQU  $FF19
00101          FF16  A      CHKRS  EQU  $FF16
00102          FED4  A      WRTP26 EQU  $FED4
00103          FF23  A      HEXBIN EQU  $FF2B
00104          *
00105          0051  A      CMPRON EQU  $51      * ROM POWER ON COMMAND TO SLAVE MCU
00106          0052  A      CMPROF EQU  $52      * ROM POWER OFF COMMAND TO SLAVE MCU
00107          *
00108          012E  A      FILBYT EQU  $12E      * REST BYTES IN THE FILE (2 BYTES SIZE)
00109          *
00110          *
00111          *
00112          *  HEADER FORMAT OF PROM
00113          *  00 - 07 (DEC) : FILE NAME      (00: $00:DELETED   $FF:END OF HEADER)
00114          *  08 - 15      : FILE TYPE
00115          *  16 - 19      : TOP ADDRESS OF THE FILE
00116          *  20 - 23      : BOTTOM ADDRESS + 1
00117          *  24 - 29      : DATE
00118          *  30 - 31      : NOT USED
00119          *
00120          *
00121          *  FUNCTION : OPEN TO READ
00122          *  ON ENTRY
00123          *  (A)=READ MODE(0:NOT ANSWER FILE NAME
00124          *  1:ANSWER FILE NAME )
00125          *  (X)=PACKET ADDRESS
00126          *  PACKET 0-7: FILE NAME
00127          *  8-15: FILE TYPE
00128          *  ON EXIT
00129          *  (A)=RETURN CODE
00130          *
00131          *  $00:NORMAL
00132          *  $A0:WITHOUT ROM CASSETTE
00133          *  $A1:FILE IS NOT FOUND
00134          *  $A2:ALREADY OPEN
00135          *  $A3:DIRECTRY NUMBER ERROR
00136          *  $A4:ROM FORMAT ERROR
00137          *  $A5:ADDRESSING ERROR
00138          *  (C)=0
00139          *  (Z) DEPEND ON VALUE OF (A)
00140          *  PACKET
00141          *  16-23: FOUND FILE NAME(WHEN 'ANSWER FILE NAME' MODE)
00142          *  24-31: FOUND FILE TYPE( ..)
00143          *  REGISTER PRESERVE
00144          *  NONE
00145          *
00146          *  WORK AREA AS REGISTER
00147          *  R0: SAVE PACKET ADDRESS
00148          *  R1H: SAVE MODE WHEN OPEN PROCEDURE WAS CALLED (VALUE OF (A))
00149          *  R1L: THE FLAG WHETHER FOUND FILE NAME IS MATCHED
00150          *  (BIT 7:STOP TO COMPARE      0:CONTINUE TO COMPARE 1:STOP)
00151          *  (BIT 0-4:FLAG FILE NAME IS MATCHED (0:MATCHED, OTHERS:NO)
          *  R2H: READ CHARACTER (READ BYTE ROUTINE)

```

```

ERR   SEQ   LOC   OBJECT   PROGRAM   ROMOPT   --- ROM CARTRIDGE INTERFACE ROUTINE ---

00152
00153      *   R2L: HEADER NUMBER
00154A 1000 97 52   A   OPNPRM STA A   R1H   *   SAVE MODE 'ANSWER FILE NAME OR NOT'
00155A 1002 DF 50   A           STX   R0   *   SAVE PACKET ADDRESS
00156
00157A 1004 BD 10EC A           JSR   PRMPON *   WITH ROM CARTRIDGE ? (RESET ADDRESS COUNTER)
00158A 1007 26 7B 1084* BNE   OPNP67 *   IF NONEZERO, ERROR DETECT.
00159A 1009 97 55   A           STA A   R2L   *   HEADER NUMBER = 0
00160A 1005 86 81   A           LDA A   #581 *   SET OPEN AND POWER ON FLAG
00161A 100D B7 0208 A           STA A   PRMSTS
00162
00163      *
00164A 1010 5F           *   READ HEADER AND SEARCH FILE NAME
00165A 1011 D7 53   A   OPNP20 CLR B           *   (B): DATA COUNTER (0 - $0F)
00166A 1013 DE 50   A           STA B   R1L   *   FLAG (NAME IS MATCHED)
00167A 1015 3A           OPNP25 LDX   R0   *   (X): PACKET ADDRESS
00168A 1016 BD 10C2 A           ABX
00169A 1019 25 72 108D* JSR   PREDBY *   READ ONE CHARACTER FROM THE ROM
00170A 1018 5D           BCS   OPNP80
00171A 101C 26 07 1025 TST B           *   ADDRESS = FIRST COLUMN OF FILE NAME ?
00172A 101E 81 FF   A           BNE   OPNP26
00173A 1020 27 6C 108E BEQ A   #3FF *   NOT FOUND ? (LAST DIRECTRY MARK= 3FF)
00174A 1022 4D           CMO   OPNP90
00175A 1023 27 2A 104F TST A           *   DELETED ? (DELETED FILE MARK = $00)
00176A 1025 7D 0052 A           BEQ   OPNP35
00177A 1028 27 02 102C OPNP26 TST   R1H *   'ANSWER FILE NAME' MODE ?
00178A 102A A7 10   A           BEQ   OPNP27
00179A 102C 7D 0053 A           STA A   16,X *   YES, STORE FILE NAME TO DATA PACKET.
00180A 102F 25 14 1045 OPNP27 TST   R1L *   STOP TO COMPARE (FILE NAME IS MATCHED) ?
00181A 1031 36           BMI   OPNP29
00182A 1032 86 2A   A           PSH A *   '*': MARK TO STOP TO COMPARE.
00183A 1034 A1 00   A           LDA A   #'*
00184A 1036 32           CMP A   0,X
00185A 1037 26 05 103E PUL A
00186A 1039 72 8053 A           BNE   OPNP28
00187A 103C 20 07 1045 OIM   #580,R1L *   '* MARK. SET 'STOP COMPARE' BIT
00188      BRA   OPNP29
00189A 103E A1 00   A           *
00190A 1040 27 03 1045 OPNP28 CMP A   0,X *   COPARE FILE NAME.
00191A 1042 7C 0053 A           BEQ   OPNP29
00192      INC   R1L *   SET 'FILE NOT MATCHED' FLAG
00193A 1045 5C           *
00194A 1046 C1 10   A   OPNP29 INC B *   FINISH TO COMPARE ?
00195A 1048 26 C9 1013 CMP B   #16 *   FILE NAME AND FILE TYPE HAVE 16 BYTES LENGTH
00196      SNE   OPNP25
00197A 104A 78 0F53 A           *   FILE NAME AND FILE TYPE ARE COPLETED TO COMPARE.
00198A 104D 27 12 1061 TIM   #3F,R1L *   OK ?
00199      BEQ   OPNP50 *
00200A 104F 7C 0055 A           *   NO, COMPARE NEXT HEADER
00201A 1052 D6 55   A   OPNP35 INC   R2L *   R2L: HEADER NUMBER (NEXT)
00202A 1054 C1 40   A           LDA B   R2L *   ADDRESS OF HEADER = '32' * 'HEADER NUMBER'
00203A 1056 2A 36 108E CMP B   #64 *
00204A 1058 86 20   A           BPL   OPNP90 *   LIMIT OF THE HEADER ($000 - $3FF)
00205A 105A 3D           LDA A   #32
00206A 105B 18           MUL
                                XGDX *   (X) : NEXT ADDRESSING POINTER

```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  ROMOPT      --- ROM CARTRIDGE INTERFACE ROUTINE ---

00207
00208A 105C BD 1155 A      JSR      ADSTEP      * SET ADDRESSING COUNTER TO FIRST COLUMN OF
00209A 105F 20 AF 1010     BRA      OPNP20      * THE HEADER.
00210
00211
00212
00213A 1061 CE 0204 A      * TOP ADDRESS AND LAST ADDRESS WHICH ARE SHOWN BY ASCII CODE ARE
00214A 1064 8D 5C 10C2     * CONVERTED TO BINARY VALUE.
00215A 1066 36
00216A 1067 8D 59 10C2     OPNP50 LDX      #PRWKTP-4
00217A 1069 16             OPNP65 BSR      PREDBY      * (A,B) <--- ASCII CODED HEXADECIMAL VALUE.
00218A 106A 32             PSH A
00219A 106B 8D FF2B A      BSR      PREDBY
00220A 106E 26 15 1085     TAB
00221A 1070 A7 07 A       PUL A
00222A 1072 08             JSR      HEX3IN      * CONVERT HEX TO BINARY.
00223A 1073 8C 0208 A      BNE      OPNP70      * ERROR ?
00224A 1076 26 EC 1064     STA A FTADRS-PRWKTP+4,X
00225
00226A 1078 EC 05 A       INX
00227A 107A A3 03 A       CPX      #PRWKTP
00228A 107C FD 012E A      BNE      OPNP65
00229
00230A 107F 86 81 A       *
00231A 1081 A7 00 A       LDA A EDADRS-PRWKTP,X * 'EDADRS' <--- LAST ADDRESS
00232A 1083 4F             SUBD FTADRS-PRWKTP,X * 'FTADRS' <--- TOP ADDRESS
00233A 1084 39             STD FILBYT * 'FILBYT' <---- DATA NUMBER IN THE FILE.
00234
00235A 1085 86 A4 A       *
00236A 1087 36             LDA A #S81 * SET 'OPENED FILE' FLAG.
00237A 1088 BD 113D A      STA A PRMSTS-PRWKTP,X
00238A 108B 32             CLR A
00239A 108C 16             OPNP67 RTS
00240A 108D 39
00241
00242A 108E 86 A1 A       *
00243A 1090 20 F5 1087     OPNP70 LDA A #SA4 * FORMAT ERROR
00244
00245
00246
00247
00248
00249
00250
00251
00252
00253
00254
00255
00256
00257
00258A 1092 3C             OPNP75 PSH A
00259
00260A 1093 C6 A3 A       JSR CLSPRM * ERROR CLOSE
00261A 1095 B6 0203 A      PUL A
                                TAB
                                * SET (Z), (N)
                                OPNP80 RTS
                                *
                                OPNP90 LDA A #SA1 * RETURN CODE (FILE WAS NOT FOUND)
                                BRA OPNP75
                                *
                                *
                                * FUNCTION : READ ONE CHARACTER FROM ROM FILE
                                * ON ENTRY
                                * NONE PARAMETER
                                * ON EXIT
                                * (A)=READ DATA
                                * (B)=STATUS $00:NORMAL $01:END OF FILE
                                * $A3:FILE NOT OPEN
                                * (C)=0
                                * (Z)=DEPEND ON VALUE OF (B)
                                * REGISTER PRESERVE
                                * (X)
                                *
                                REDPRM PSHX * SAVE (X)
                                *
                                LDA B #SA3 * PRESET ERROR CODE (FILE IS NOT OPEN)
                                LDA A PRMSTS * IS POWER ON ? (BIT0, BIT7 BOTH ON)

```



```

ERR  SEQ  LOC  OBJECT  PROGRAM  ROMOPT  --- ROM CARTRIDGE INTERFACE ROUTINE ---
00262A 1098 2A 0D 10A7          BPL      REDP08
00263A 109A 47                    ASR A
00264A 109B 24 0A 10A7          BCC      REDP08
00265
00266A 109D FC 020D A          *
REDP05 LDD      EDADRS      * IS CURRENT ADDRESS BOTTOM IN THE FILE ?
00267A 10A0 B3 020B A          SUBD     FTADRS
00268A 10A3 26 06 10A8          BNE      REDP10
00269
00270A 10A5 C6 01 A          *
00271A 10A7 4F          REDP08 LDA B #1      * EOF RETURN
00272A 10A8 5D          REDP08 CLR A
00273A 10A9 38          TST B      * SET (Z), (N), CLEAR (C).
00274A 10AA 39          PULX
00275          RTS
00276          * READ ON BYTES FROM FILE
10A8 A          REDP10 EQU *
00277A 10AB 18          XGDX
00278A 10AC 09          DEX
00279A 10AD FF 012E A          STX      FILBYT      * SET 'REST DATA NUMBER IN THE FILE'
00280A 10B0 C6 A5 A          LDA B #3A5          * PRESET 'ADDRESSING ERROR' FLAG
00281A 10B2 25 F3 10A7          BCS      REDP08
00282A 10B4 FE 020B A          LDX      FTADRS      * NON ERROR,
00283A 10B7 3C          PSHX
00284A 10B8 BD 1155 A          JSR      ADSTEP      * ROM ADDRESSING <---- +1 INCREMENT
00285A 10B8 38          PULX
00286A 10B8 08          INX
00287A 10BD FF 020B A          STX      FTADRS      * ADDRESSING COUNTER <--- +1 INCREMENT
00288A 10C0 5F          CLR B      * RETURN CODE = NORMAL
00289A 10C1 38          PULX
00290
00291
00292
00293
00294
00295
00296
00297
00298
00299
00300
00301
00302
00303
00304
00305
00306
00307
00308
00309
00310
00311
00312
00313
00314
00315
00316A 10C2 37          PREDSY PSH B

```

* ENTRY POINT 'READ NEXT ONE BYTE'
 * ON ENTRY
 * PARAMETER : NONE
 * READ ONE BYTE AND INCREMENT ADDRESSING COUNTER
 * ON EXIT
 * (A) READ CHARACTER
 * REGISTER PRESERVE
 * (B), (X)
 * WORK AS REGISTER
 * R2H: COUNTER FOR 8 TIMES AND WORKAREA FOR READ DATA

R2H	C	BIT7	BIT0
0	0	0	0
		I	
		I	
		V	
0	0	0	0
			1
			X
			X:READ BIT
		I	
		I	
		V	
0	0	0	0
			1
			X
			X
			X:READ BIT

```

ERR  SEQ  LOC  OBJECT      PROGRAM  ROMCPT      --- ROM CARTRIDGE INTERFACE ROUTINE ---
00317A 10C3 86 01    A          LDA A    #$1      * 1: MARK FOR 3 TH TIME.
00318A 10C5 97 54    A          STA A    R2H
00319A 10C7 5F          CLR B
00320A 10C8 C4 7F    A          REDP20 AND B    #$FF-$80 * BIT 7 LOW (D7)
00321A 10CA 86 C0    A          LDA A    #$C0      * BIT6,7 EFFECTIVE
00322A 10CC BD FED4  A          JSR     WRTP26      * CLOCK LOW (FIRST TIME: D6 LOW)
00323A 10CF CA 80    A          ORA B    #$80      * CLOCK HIGH (FIRST TIME :READ DATA
00324A 10D1 BD FED4  A          JSR     WRTP26      * SECOND TIME:SHIFT DATA)
00325
00326A 10D4 96 02    A          LDA A    PORT1     * INPUT DATA (BIT7, BIT6 ,...)
00327A 10D6 48          ASL A
00328A 10D7 79 0054  A          ROL     R2H        * R2L:SHIFT ONE BIT WHICH WAS GET.
00329A 10DA CA 40    A          ORA B    #$40      * FOR D6:HIGH
00330A 10DC 24 EA 10C8  A          BCC     ,REDP20    * COMPLETE TO READ 8 BITS ?
00331
00332A 10DE FC 0209  A          LDD     STADRS     * ADDRESSING POINTER <--- +1 INCREMENT
00333A 10E1 C3 0001  A          ADDD   #1
00334A 10E4 FD 0209  A          STD     STADRS
00335
00336A 10E7 96 54    A          LDA A    R2H        * (A) <--- READ DATA
00337A 10E9 33          PUL B
00338A 10EA 5D          TST B
00339A 10EB 39          RTS                * CLEAR (C), SET (Z) FOR 'REDPRM' ROUTINE
00340
00341
00342
00343
00344
00345
00346
00347
00348
00349
00350
00351
00352
00353
00354
00355
00356A 10EC 8D FF2E  A          PRMPON JSR     CHKPLG * CHECK PLUG-IN OPTION
00357A 10EF 25 26 1117  A          BCS     PRMP80
00358A 10F1 16          TAB
00359A 10F2 26 23 1117  A          BNE     PRMP80
00360A 10F4 72 207C  A          OIM    #$20,SIOSTS * SLAVE ROM CASSETTE ON
00361A 10F7 FD 0209  A          STD     STADRS     * ROM ADDRESS = 0 (A,B)=0
00362A 10FA 86 C0    A          LDA A    #$C0
00363A 10FC 8D FED4  A          JSR     WRTP26      * SET D6,D7 LOW (COUNT, CLOCK)
00364A 10FF 86 51    A          LDA A    #$51
00365A 1101 8D FF19  A          JSR     SNSCOM      * SEND 'PROM ON COMMAND' TO SLAVE MCU.
00366A 1104 25 11 1117  A          BCS     PRMP80
00367A 1106 3C          PSHX
00368A 1107 CE 019D  A          LDX     #400        * WAIT 2 M SEC
00369A 110A 09          PRMP20 DEX
00370A 110B 26 FD 110A  A          BNE     PRMP20
00371A 110D FE 0208  A          LDX     PRMSTS     * SET POWER ON FLAG (ON BIT7)
    
```

ERR SEQ LOC OBJECT PROGRAM ROMOPT --- ROM CARTRIDGE INTERFACE ROUTINE ---

```

00372A 1110 62 8000 A          OIM    #580,D,X
00373A 1113 38                PULX
00374A 1114 4F                CLR A
00375A 1115 20 33 114A       BRA    CLSP10    * (JMP  CHKRS)
00376                          *
00377A 1117 86 A0    A       PRMPBD LDA A    #5A0    * WITHOUT ROM CASSETTE (ERROR)
00378A 1119 39                RTS
00379                          *
00380                          *
00381                          * FUNCTION : READ DIRECTORY
00382                          * ON ENTRY
00383                          * (A):DIRECTORY NUMBER (FROM 0 TO 63)
00384                          * (X):ADDRESS WHERE HEADER ARE STORED
00385                          * ON EXIT
00386                          * (A):RETURN CODE $D0: NORMAL
00387                          *                               $A0: WITHOUT ROM CASSETTE
00388                          *                               $A3: DIRECTRY NUMBER ERROR
00389                          *
00390                          * (C)=0
00391                          * (Z)=DEPEND ON VALUE OF (A)
00392                          * REGISTER PRESERVE
00393                          * NONE
00394A 111A 16                DIRPRM TAB
00395A 111B 86 A3    A       LDA A    #5A3    * SAVE DIRECTORY NUMBER
00396A 111D C1 40    A       CMP B    #64    * (A) <--DIRECTORY ERROR FLAG (PRESET)
00397A 111F 24 29 114A       BCC    CLSP10  * IS DIRECTRY NO. LIMIT (00 - 63) OK ?
00398                          *
00399A 1121 DF 50    A       STX    R0    * SAVE ADDRESS OF DIRECTORY
00400                          *
00401A 1123 37                PSH B
00402A 1124 8D C6 10EC       BSR    PRMPON  * POWER ON (CHECK PROM)
00403A 1126 33                PUL B
00404A 1127 26 21 114A       BNE    CLSP10
00405                          *
00406A 1129 86 20    A       LDA A    #32    * CALCULATE HEADER ADDRESS (32 * *NUMBER*)
00407A 112B 3D                MUL
00408A 112C 18                XGDX
00409A 112D 8D 26 1155       BSR    ADSTEP  * SET ROM ADDRESS
00410A 112F C6 20    A       LDA B    #32
00411A 1131 DE 50    A       LDX    R0
00412A 1133 37                DIRP10 PSH B
00413A 1134 8D 8C 10C2*       BSR    PREDSY  * READ ONE CHARACTER
00414A 1136 A7 00    A       STA A    0,X
00415A 1138 08                INX
00416A 1139 33                PUL B
00417A 113A 5A                DEC B
00418A 113B 26 F6 1133       BNE    DIRP10
00419                          *
00420                          *
00421                          * FUNCTION : CLOSE ROM CASSETTE
00422                          * ON ENTRY
00423                          * PARAMETER NONE
00424                          * ON EXIT
00425                          * (C): I/O ERROR FLAG
00426                          * REGISTER PRESERVE

```

ERR SEQ LOC OBJECT PROGRAM ROMOPT --- ROM CARTRIDGE INTERFACE ROUTINE ---

```

00427          *      (B),(X)
00428          *
00429A 113D 7F 0208 A  CLSPRM CLR  PRMSTS  * SET ROM STATUS 'POWER OFF', 'CLOSED FILE'
00430A 1140 86 52  A   LDA  A  #CMPROF * SEND 'POWER OFF COMMAND' TO SLAVE MCU.
00431A 1142 8D FF19 A   JSR  SNSCOM
00432A 1145 71 DF7C A   AIM  #$FF-$20,SIOSTS * SET FLAG ('ROM CASSETTE IS OFF')
00433A 1148 86 00  A   LDA  A  #0      * (DO NOT CHANGE (C) BIT)
00434A 114A 7E FF16 A  CLSP10 JMP  CHKRS  * RECOVER RS232 (OPEN TO READ RS232)
00435          *
00436          *
00437          * FUNCTION : SET PROM ADDRESS TO DESTINATED VALUE
00438          * ON ENTRY
00439          * (X)= TARGET ADDRESS
00440          * ON EXIT
00441          * (C): I/O ERROR FLAG
00442          * REGISTER PRESERVE
00443          * NONE
00444          *
00445          *
00446A 114D 8D 9D 10EC A  ADST00 EQU  *      * CASE OF (NEW ADDRESS < CURRENT ADDRESS)
00447A 114F 26 20 1171 A   ESR  PRMPON  * WITHOUT ROM ? (CLEAR ADDRESSING COUNTER)
00448A 1151 5F          A   BNE  ADST80  * WITHOUT ?
00449A 1152 FD 0209 A   CLR  B      * IF ROM (A):0
00450          *      * ROM ADDRESSING COUNTER <--- 0
00451          *
00452A 1155 3C          A  * ENTRY POINT OF 'ADSTEP' ROUTINE
00453A 1156 32          A  ADSTEP PSHX  * (A,B)<---(X)
00454A 1157 33          A   PUL  A
00455A 1158 B3 0209 A   PUL  B
00456A 115B 27 14 1171 A   SUBD STADRS * NEW ADDRESS >= CURRENT ADDRESS ?
00457A 115D 25 EE 114D A   BEQ  ADST80 * = ?
00458          *
00459A 115F FF 0209 A   BCS  ADST00 * CASE OF 'TARGET ADDRESS > CUPRENT ADDRESS'
00460A 1162 18          A   STX  STADRS * SET NEW ADDRESS TO 'STADRS'
00461          *      * (X)<--- STEP COUNT
00462A 1163 5F          A  ADST30 CLR  B      * COUNT UP ADDRESSING COUNTER
00463A 1164 86 C0  A   LDA  A  #SC0
00464A 1166 8D FED4 A   JSR  WRTP26
00465A 1169 C6 40  A   LDA  B  #S40
00466A 116B 8D FED4 A   JSR  WRTP26
00467A 116E 09          A   DEX
00468A 116F 26 F2 1163 A   BNE  ADST30
00469A 1171 39          A  ADST80 RTS
00470          *
00471          *      END
00000 0000 0000 A
***** TOTAL ERRORS 0
    
```

CHAPTER 9 LOAD MODULE

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9.1 General

The module format for output of data by the SAVEM command in BASIC or the W command in the Monitor is a special format called a "Binary Load Module format". One file is divided into a number of records each containing memory addresses and data (Fig. 9-1).

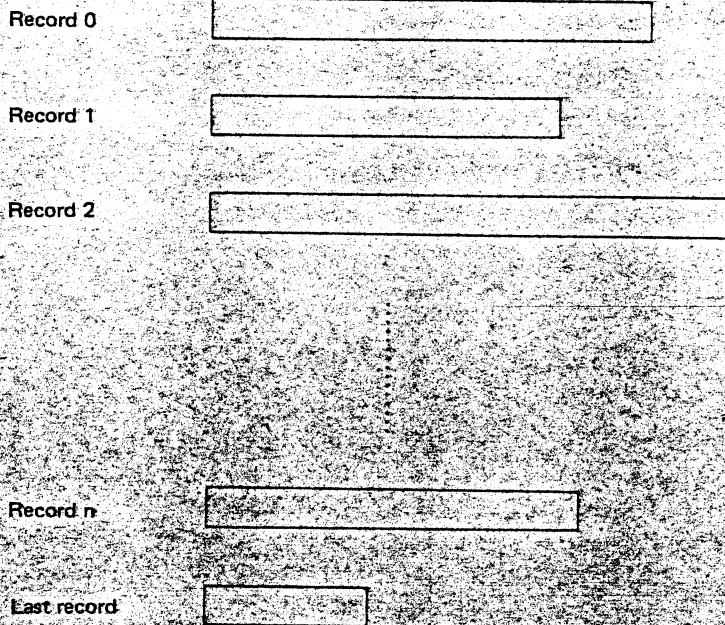


Fig. 9-1 Division of File into Records

Each record has a maximum length of 259 bytes and each data contained in the record is represented in binary numbers in units of one byte. The format of each record is shown below.

9.2 Load Module (Machine Language) Format

(1) Intermediate record

Column	Size (bytes)	Item	Description
0	1	Record length	Indicates the length of the data contained in the record in binary numbers (00 through FF).
1 ~ 2	2	Address	Indicates the address of the first data in the record in binary numbers 0000 through FFFF (in order of the upper and lower digits).
3	1	Data	Data 1. Namely, first data (00 through FF).
4	1	Data	Data 2
5			
n	1	Data	Data n (n must be a value in the range of 0 to 255.)
n + 1	1	Checksum	This value must be such that the low-order 8 bits of the sum of the data values in columns 0 through n + 1 become 0.

(2) Last record

Column	Size (bytes)	Item	Description
0	1	Record length	This value must always be 0.
1 ~ 2	2	Address	Indicates the entry point of a program in binary numbers (0000 through FFFF in order of the upper and lower digits).
3	1	Checksum	This value must be such that the low-order 8 bits of the sum of the data values in columns 0 through 3 become 0.

9.3 Dump/Load Procedures

9.3.1 I/O devices

The basic I/O routines support the following devices:

- (1) Input
 - (a) External audio cassette
 - (b) Built-in microcassette
 - (c) ROM cartridge
- (2) Output
 - (a) External audio cassette
 - (b) Built-in microcassette

9.3.2 Dump/load procedures

The memory contents in the binary load module format are transferred to and from an external storage as follows:

- (1) Output to the external storage
 - (a) File opening
Subroutine "OPNDMP" is provided to open the specified file (device) for output. Subroutine "OPNWCS" is called if the specified file is an external audio cassette.
 - (b) Output of the memory contents
Subroutine "BIDUMP" is provided to output the memory contents in the binary load module format to the opened file and closes it upon completion of the dumping.
- (2) Input from the external storage
 - (a) File opening
Subroutine "OPNLOD" is provided to open the specified file (device) for input. Subroutine "OPNPRM" is called if the specified file is a ROM cartridge.
 - (b) Loading into memory
Subroutine "BILOAD" is provided to store the input data in the binary load module format in the main memory and closes the file upon completion of the loading.

9.4 Binary Dump/Load Subroutine Table

Subroutine name	Entry point	Description
OPNDMP	FEEO	<p>Binary memory dump open. This subroutine opens the file to be dumped in a binary absolute format and supports an external cassette and the built-in microcassette drive.</p> <p>Parameters:</p> <p>At Entry</p> <p>(X): Top address of a data packet (B): Device name 'M': Microcassette drive 'C': External audio cassette</p> <p>Packet</p> <ol style="list-style-type: none"> 1. Interblock tape stop mode (1 byte) for external audio cassette or microcassette 00: Stop the tape between blocks. 01: Do not stop the tape between blocks. 2. Top address of buffer (2 bytes). The buffer size is 260 bytes. 3. Filename (8 bytes) 4. File type (8 bytes) 5. Dump start address (2 bytes) 6. Dump end address (2 bytes) 7. Offset value (2 bytes) 8. Program entry point (2 bytes) <p>Note:</p> <p>The offset value is added to the dump start address, dump end address, or the program entry point as an unsigned binary number.</p> <p>Parameters:</p> <p>At Return</p> <p>(C): Abnormal I/O flag (A): Return code (This parameter is dependent on subroutines OPNNCS and OPNWMS.)</p> <p>Registers retained None</p> <p>Subroutines referenced OPNWMS, OPNWCS</p> <p>Variables to be used: R0, R1, R2, R3, R4, R5, R6, and R7</p>
BIDUMP	FEED	<p>Binary memory dump. This subroutine dumps the memory contents in a binary absolute format to the file opened by subroutine OPNDMP and closes the file upon completion of the dumping.</p> <p>Parameters:</p> <p>At Entry None</p>

		<p>At Return Depend on subroutines WRTCS, WRTMS. Registers retained None Subroutines referenced WRTCS, WRTMS Variables used R0, R1, R2, R3, R4, R5, R6 and R7</p>
OPNLOD	FEDA	<p>Binary memory load. This subroutine opens the file to be loaded and loads the contents of the file dumped in binary absolute format, into memory.</p> <p>Parameters: At Entry (X): Top address of a data packet (B): Device name 'M': Microcassette 'C': External audio cassette 'P': ROM cartridge (A): Specifies whether or not the filename is to be returned. 00: Return the filename. 01: Do not return the filename.</p> <p>Packet</p> <ol style="list-style-type: none"> 1. Interblock tape stop mode (1 byte) for external audio cassette or microcassette. 00: Stop the tape between blocks. 01: Do not stop the tape between blocks. FF: Depends on the header. 2. Top address of buffer (2 bytes) The buffer size is 260 bytes. 3. Filename (8 bytes) 4. File type (8 bytes) 5. Lower limit of the memory address to be loaded (2 bytes) 6. Upper limit of the memory address to be loaded (2 bytes) 7. Offset value (2 bytes) <p>Note: The offset value is added to the address information of a file (load start address, load end address, or program entry point) as an unsigned binary number. The interblock tape stop mode is effective only for 'M' or 'C' but not for 'P'. If the return of a filename is specified by register (A), the filename is returned after the 19th byte of the packet. (In this case, the packet contents after the lower limit of the memory address are destroyed.) Since subroutines OPNRCS, SRCRCS, OPNRMS, SRCRMS, and OPNPRM are actually called, the packet depends on these subroutines.</p>

		<p>At Return (C): Abnormal I/O FLAG (A): Return codes 8C: Load area exceeds the specified memory space range. Other return codes depend on OPNRCS, SRCRCS, OPNRMS, SRCRMS and OPNPRM</p> <p>Registers retained None</p> <p>Subroutines referenced OPNRCS, SRCRCS, OPNRMS, SRCRMS, and OPNPRM</p> <p>Variables used R0, R1, R2, R3, R4, R5, R6, and R7</p> <hr/> <p>Notes: Assuming that the upper- and lower-limit values of the memory addresses that can be loaded by the packet are μ and l, respectively and that the address of a data to be loaded is α, the data can be loaded only when the following condition is satisfied.</p> $l \leq \alpha \leq \mu$ <p>If the address is not within this range, return code 8C (load area error) is output to interrupt the loading operation by force. The file is closed upon completion of the loading.</p>
BILOAD	FED7	<p>This subroutine loads the contents of the file opened by subroutine "OPNL0D" into the memory and closes the file upon completion of the loading.</p> <hr/> <p>PaRAMETERS:</p> <p>At Entry (A): Specifies whether or not the contents of the file are to be loaded into the memory. 00: Load the contents of the file into the memory. 01: Check the load module format only. Do not load the file contents.</p> <p>At Return (X): Program entry point The value specified by the offset value is added to the value of the entry point recorded in the file. (A): Return codes 00: Normal 8C: Load area exceeds the specified memory space range. Others: Depend on the return codes of a file input routine.</p> <p>Registers retained None</p> <p>Subroutines referenced READMS, READCS, REDPRM</p> <p>Variables used R0, R1, R2, R3, R4, R5, R6 and R7</p>

9.5 Binary Dump/Load Work Area

Address (From) (To)	Variable name	Bytes	Description
20F 210	DLTPAD	2	First dump address
211 212	DLBTAD	2	Last dump address
213 214	DLOFAD	2	Offset value
215 216	DLSTAD	2	Program entry point
217 217	DLDVID	1	Dump/load device
218 218	DLSTS	1	Status work area (dummy)
219 21A	DLDVIX	2	Table address of a dump/load routine

ERR SEQ LOC OBJECT PROGRAM CLOCK --- CLOCK SAMPLE PROGRAM ---

```

00001          NAM      CLOCK
00002          *
00003          * DISPLAY CURRENT TIME ON THE PHISICAL SCREEN.
00004          * MPU IS SLEEP IF CLOCK UPDATE IS NOT CAUSED.
00005          *
00006          * FILE NAME      'EX$B'      BY K.A
00007          TTL      --- CLOCK SAMPLE PROGRAM ---
00008          OPT      PAGE=55
00009          OPT      LOAD
00010A 1000    ORG      $1000
00011          *
00012          * SUBROUTINE ENTRY POINT
00013          FFA9  A    SLEEP EQU      $FFA9      * SLEEP CPU
00014          FF4C  A    DSPLCH EQU     $FF4C      * DISPLAY ONE CHARACTER ON THE PHISICAL SCREEN
00015          FF49  A    DSPLCN EQU     $FF49      * DISPLAY SOME CHARACTERS ON THE PHISICAL SCREEN
00016          *
00017          *
00018A 1000    ORG      $1000
00019          *
00020A 1000    C6 00    A    LDA B      #0          * CLEAR SCREEN
00021A 1002    8D FF49  A    JSR      DSPLCN
00022A 1005    86 FF    A    LDA A      #$FF          * ALARM INTERRUPT TIME
00023A 1007    97 41    A    STA A      $41          * = ANY TIME WHEN SECOND IS UPDATED.
00024A 1009    97 43    A    STA A      $43
00025A 100B    97 45    A    STA A      $45
00026          *
00027A 100D    72 204B  A    CLCK10 OIM     #$20,$4B * ENABLE ALARM INTERRUPT.
00028A 1010    8D FFA9  A    JSR      SLEEP      * MCU IS SLEEP FOR SAVE POWER.
00029A 1013    96 44    A    LDA A      $44          * LOAD 'HOURL'
00030A 1015    16      A    TAB          * DISPLAY 'HOURL'
00031A 1016    84 FD    A    AND A      #$F0          * (HIGH ORDER)
00032A 1018    47      A    ASR A
00033A 1019    47      A    ASR A
00034A 101A    47      A    ASR A
00035A 101B    47      A    ASR A
00036A 101C    8A 30    A    ORA A      #'0
00037A 101E    CE 0502  A    LDX      #$0502
00038A 1021    37      A    PSH B
00039A 1022    8D FF4C  A    JSR      DSPLCH
00040A 1025    32      A    PUL A          * DISPLAY (LOW ORDER)
00041A 1026    84 0F    A    AND A      #$0F
00042A 1028    8A 30    A    ORA A      #'0
00043A 102A    8D FF4C  A    JSR      DSPLCH
00044A 102D    86 3A    A    LDA A      #' :
00045A 102F    8D FF4C  A    JSR      DSPLCH
00046A 1032    96 42    A    LDA A      $42          * LOAD 'MINUTE'
00047A 1034    16      A    TAB          * DISPLAY 'MINUTE'
00048A 1035    84 FD    A    AND A      #$F0          * (HIGH ORDER)
00049A 1037    47      A    ASR A
00050A 1038    47      A    ASR A
00051A 1039    47      A    ASR A
00052A 103A    47      A    ASR A
00053A 103B    8A 30    A    ORA A      #'0
00054A 103D    CE 0802  A    LDX      #$0802
00055A 104D    37      A    PSH B
    
```

```

ERR  SEQ  LOC  OBJECT      PROGRAM  CLOCK    --- CLOCK SAMPLE PROGRAM ---
00056A 1041 8D FF4C  A      JSR      DSPLCH
00057A 1044 32          PUL A
00058A 1045 84 0F    A      AND A    #$0F          * DISPLAY (LOW ORDER)
00059A 1047 8A 30    A      ORA A    #$0
00060A 1049 8D FF4C  A      JSR      DSPLCH
00061A 104C 86 3A    A      LDA A    #':          *
00062A 104E 8D FF4C  A      JSR      DSPLCH
00063A 1051 96 40    A      LDA A    $40          * LOAD 'SECOND'
00064A 1053 16          TAB          * DISPLAY 'SECOND'
00065A 1054 84 F0    A      AND A    #$F0          * (HIGH ORDER)
00066A 1056 47          ASR A
00067A 1057 47          ASR A
00068A 1058 47          ASR A
00069A 1059 47          ASR A
00070A 105A 8A 30    A      ORA A    #$0
00071A 105C CE 0B02  A      LDX     #$0B02
00072A 105F 37          PSH B
00073A 1060 8D FF4C  A      JSR      DSPLCH
00074A 1063 32          PUL A          * DISPLAY (LOW ORDER)
00075A 1064 84 0F    A      AND A    #$0F
00076A 1066 8A 30    A      ORA A    #$0
00077A 1068 8D FF4C  A      JSR      DSPLCH
00078A 1068 20 A0 100D  BRA     CLCK10-
00079
00080          0000  A      END
***** TOTAL ERRORS. 0

```

---- BINARY DUMP FORMAT OF OBJECT CODE ----

```

13 10 00 C6 00 8D FF 49 86 FF 97 41 97 43 97 45 72 20 48 8D FF A9 8D
13 10 13 96 44 16 84 F0 47 47 47 47 8A 30 CE 05 02 37 8D FF 4C 32 4A
14 10 26 84 0F 8A 30 8D FF 4C 86 3A 8D FF 4C 96 42 16 84 F0 47 47 47 62
14 10 3A 47 8A 30 CE 08 02 37 8D FF 4C 32 84 0F 8A 30 8D FF 4C 86 3A 43
12 10 4E 8D FF 4C 96 40 16 84 F0 47 47 47 47 8A 30 CE 0B 02 37 40
0D 10 60 8D FF 4C 32 84 0F 8A 30 8D FF 4C 20 40 34
00 10 00 F0

```

CHAPTER 10 FLOPPY DISK UNIT

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CHAPTER 10 FLOPPY DISK UNIT

10.1 General

The TF-20 Terminal Floppy is an intelligent floppy disk unit which is connected to the HX-20 through a serial communication interface and transfers the data stored in a floppy disk to the HX-20 according to the commands received from the HX-20.

When the TF-20 is connected to the HX-20, the DBASIC.SYS (Disk BASIC System, which is an extended portion of BASIC) is loaded from the floppy disk into the RAM of the HX-20 upon start of BASIC. The DBASIC.SYS loaded into the RAM operates together with the interpreter on the ROM until control is returned to the MENU again. It processes the data input/output to and from the floppy disk and newly added commands, statements and functions. The interpreter on the ROM handles the conventional functions of the HX-20.

In DISK BASIC, a maximum of two TF-20 units can be connected to the HX-20. The first TF-20 unit is used as disk drives "A:" and "B:" and the second unit as disk drives "C:" and "D:". To distinguish between the first and second units, the DIP switch located in the TF-20 must be used. The 4-pin DIP switch (bits 1 to 4) of the TF-20 is factory-set to all "ON" for drives "A:" and "B:". When connecting a second TF-20 unit to the HX-20, the DIP switch setting of the second unit must be changed to "bits 1, 2, 3, 4 = ON, ON, ON, OFF" to indicate that the unit is used as drives "C:" and "D:".

Daisy-chaining method is used to interconnect an HX-20 and a TF-20 or two TF-20 units via cable set #707 (for daisy chaining). TF-20 (disk 1) and TF-20 (disk 2) can be interconnected in any order. Fig. 10-1 shows how two TF-20 units are connected to the HX-20.

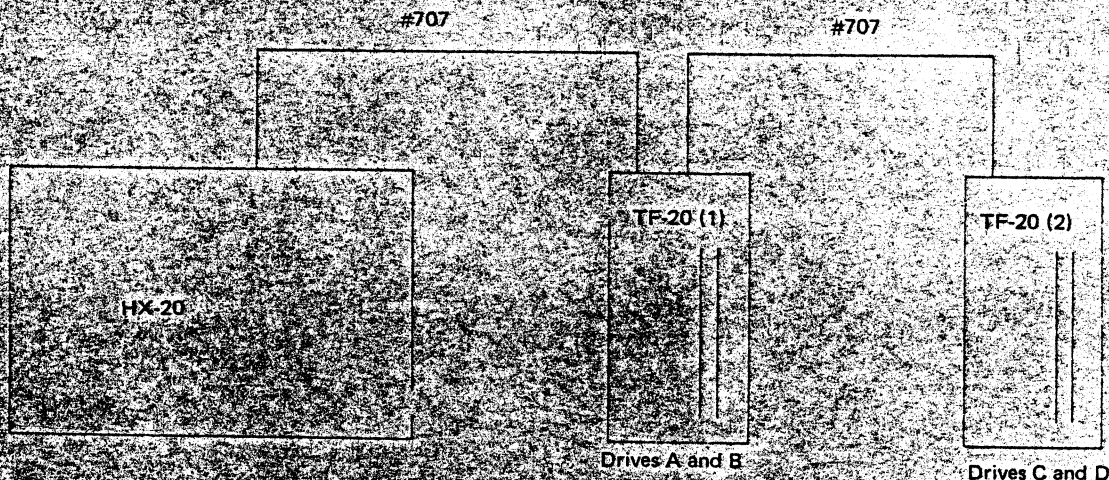


Fig. 10-1 Interconnection of HX-20 and Two TF-20 Units

10.2 Disk Format

Disk type:	Double-sided, double density (MFM)
No. of tracks:	80 tracks (40 tracks x 2 sides)
Track density:	48 TPI
No. of sectors:	16 sectors/track
Capacity per sector:	256 bytes

Total disk capacity: 320K bytes (256 x 16 x 80)
 Access time between
 tracks: 15 ms

Tracks and sectors are logically structured as shown below.

No. of tracks: 40 tracks (0 to 39)
 No. of sectors: 64 sectors/track (1 to 64)
 Capacity per sector: 128 bytes

Table 10.1 shows the relationship between the physical and logical specifications.

Table 10.1 Relationship between Physical and Logical Specifications

	Physical specifications	Logical specifications
Track	One track on one side + one track on the other side	One track
Sector	One sector (256 bytes)	Two sectors (128 bytes x 2)

10.3 System Disk and Non-system Disk

The floppy disks used in DISK BASIC can be divided into a system disk and a non-system disk. Either of these two disks must be initialized by the physical format of the TF-20 for generation of correct directories.

All the floppy disks supplied by EPSON have been initialized before shipment so that they can be used as non-system disks. Floppy disks other than those supplied by EPSON and those disks in which a read or write error has occurred must be initialized by the FORMAT command. The system disk refers to the disk which contains a system program for DISK BASIC, and must be inserted into drive "A:" when DISK BASIC is to be booted. The system disk is mapped as follows.

Track 0	Sectors 1 and 2:	Cold-start loader (loads a system contained in the system disk into the memory of the TF-20.)
	Sectors 3 to 18:	Unused
	Sectors 19 to 46:	BDOS (Basic Disk Operating System)
	Sectors 47 to 64:	BIOS (Basic Input/Output System) for the HX-20
Track 1	Sectors 1 to 42:	TFDOS (communication program with the HX-20)
	Sectors 43 to 64:	Unused
Tracks 2 and 3	Sectors 1 to 64:	Unused
Track 4	Sectors 1 to 16:	Directory area (for 64 directories max.)
	Sectors 17 to 64:	File area
Tracks 5 to 38	Sectors 1 to 64:	File area (278K bytes max.)

Two files "BOOT80.SYS" and "DBAISC.SYS" are secured for the system in the system disk. Since these files are write-protected, their filenames are not displayed even by executing the FILES command. Note that the user cannot use the same filenames as these two files. To duplicate a system disk, either copy all the contents of the existing system disk to a new floppy disk by COPY utility, or execute the SYSGEN command for a non-system disk. "SYSGEN" copies not only the system area of the disk but also copies the system file whose file type is "SYS".

10.4 Interface with DISK BASIC

The DISK BASIC is broadly divided into the following 3 modules:

- (1) BASIC interpreter (ROM version: HX-20 side)
- (2) DBASIC interpreter (DBASIC.SYS: HX-20 side)

This interpreter is an extended portion of BASIC which is loaded from a disk to the RAM of the HX-20 upon start of the BASIC and handles the data input/output to and from the disk and the processing of commands and statements, together with the BASIC interpreter described in (1) above. This module consists mainly of a portion connected to the BASIC interpreter (i.e., a BASIC driver) and a portion interfacing with the TFDOS (i.e., EPSP driver).

- (3) TFDOS (TF-20 side)

The TFDOS which is resident on the RAM of the TF-20 receives commands from the HX-20, opens and reads or writes files using the BDOS or the BIOS for the HX-20, and returns data and error codes to the HX-20.

Of the above 3 modules, the BASIC driver and EPSP driver of the DBASIC interpreter are interfaced with each other through the BSCINT (BASIC interface), while the EPSP driver is interfaced with the TFDOS through the EPSP (EPSON Serial Communication Protocol) as shown in Fig. 10-2.

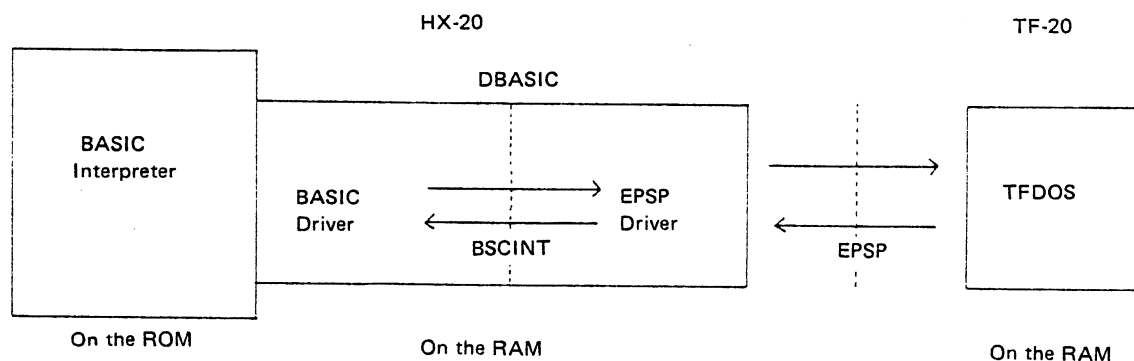


Fig. 10-2 Software Configuration of Disk BASIC

10.4.1 BASIC interface (BSCINT)

10.4.1.1 Functions of BSCINT

Interfacing of DBASIC with BASIC is supported by subroutine "BSCINT" (BASIC Interface) which has the following functions:

- (1) File open
- (2) File close
- (3) Random read (128 bytes)
- (4) Random write (128 bytes)
- (5) File delete
- (6) File rename
- (7) File size calculation
- (8) First directory search
- (9) Next directory search
- (10) Direct write into disk (DSKO\$, 128 bytes)
- (11) Disk formatting (FRMAT)
- (12) Disk system reset (RESET)
- (13) System disk generation (SYSGEN)
- (14) Disk free area calculation (DSKF)
- (15) Direct read from disk (128 bytes)
- (16) Disk all copy

10.4.1.2 Subroutine call procedure

Subroutine "BSCINT" is called as follows:

- (1) Setting the entry point for BSCINT

The contents at an address 3 bytes from addresses (0A3E and 0A3F) are "JMP BSCINT" (see Fig. 10.3). This means that the address specified by addresses (0A3E and 0A3F) is the entry point of the subroutine that includes BSCINT error processing.

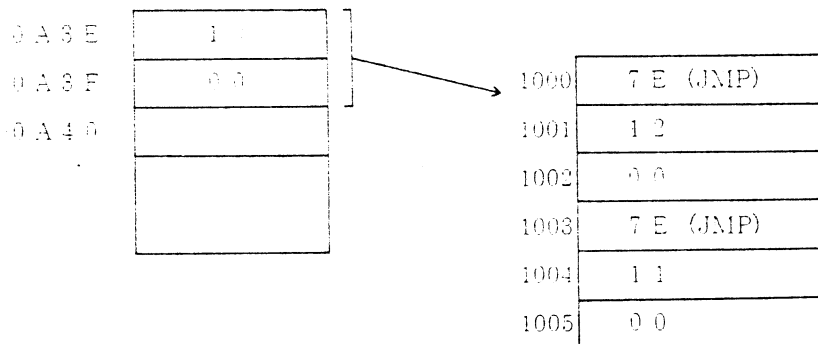


Fig. 10-3 BSCINT Entry Point

- (2) Creation of a parameter packet

Parameters are created on memory, and are given in the order of the function code, return code, and data (see Fig. 10-4). The data string has a length of one or more bytes. For details of the functions and parameters, refer to the BSCINT parameter packet table.

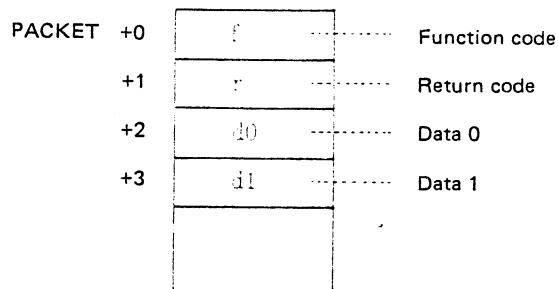


Fig. 10-4 Parameter Packet of Subroutine "BSCINT"

(3) Subroutine call

The first address of the parameter packet is set in the index register to call subroutine "BSCINT".

An example of opening a file is shown below:

[Example] File under the file descriptor "ABC.BAS" is opened in Sequential Output mode using drive "A".

```

        LDAA  =S7E      * (JMP instruction)
        STAA  BSENR
        LDD   $A3E
        STD   BSENR+1
        LDX   =CPOPC
        JSR   BSENR
        LDAA  1,X
        BNE   ERROR
        RTS
        :
ERROR   EQU   *      * error procedure
        :
BSENR   FCB   S7E      * (JMP BSCINT)
        RMB   2
CPOPC   FCB   $00
        FCB   $00
        FCB   $00
        FCC   /ABC△△△△△/
        FCC   /BAS/

```

10.4.2 BSCINT parameter packet table

*All packet data numbers are decimal numbers.

No.	Function	Packet data No.	Description
1	File open	<p>00 01 02 03 04 ~ 11 12 ~ 14 15</p>	<p>Opens the file in the specified drive according to the filename, file type, and file mode.</p> <p>00 (function code)</p> <p>Return code (set at return)</p> <p>File number (set at return)</p> <p>Drive number ("A", "B", "C" or "D")</p> <p>Filename (8 characters. If the filename is less than 8 characters, left-justify the filename and fill blank code(s) (20) in the remaining space.)</p> <p>File type (3 characters. If the file type is less than 3 characters, left-justify the file type and fill blank codes (20) in the remaining space.)</p> <p>Modes</p> <p>10₁₆: Sequential input (M.SQI) 30₁₆: Sequential output (M.SQO) 40₁₆: Random access (M.RND)</p> <p>If no file exists in M.SQI or M.SQO mode, a new file is created.</p> <p>If no file exists in M.SQI mode, it is assumed that an error has occurred.</p> <p>If a file exists in M.SQO mode, the previous file will be deleted.</p>
2	File close	<p>00 01 02</p>	<p>Closes the specified opened file.</p> <p>01 (function code)</p> <p>Return code (set at return)</p> <p>File number (i.e., the number returned at a file open)</p>
3	Random read	<p>00 01 02 03 ~ 04 05 ~ 06</p>	<p>Reads the specified record of a file. (One record consists of 128 bytes.)</p> <p>02 (function code)</p> <p>Return code (set at return)</p> <p>File number (i.e., the number returned at a file open)</p> <p>Record number (binary value in the range of 1 to 65535. Must be entered in the order of high- and low-order bytes.)</p> <p>Buffer address (must be entered in the order of high- and low-order bytes.)</p>
4	Random write	<p>00 01 02 03 ~ 04 05 ~ 06</p>	<p>Writes the specified record of a file. (One record consists of 128 bytes.)</p> <p>03 (function code)</p> <p>Return code (set at return)</p> <p>File number (i.e., the number returned at a file open)</p> <p>Record number (binary value in the range of 1 to 65535. Must be entered in the order of high- and low-order bytes.)</p> <p>Buffer address (must be entered in the order of high- and low-order bytes.)</p>

No.	Function	Packet data No.	Description
5	File delete	00 01 02 03 04 ~ 11 12 ~ 14	Deletes the specified file. 04 (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Filename (8 characters. If the filename is less than 8 characters, left-justify the filename and fill blank codes (20) in the remaining space.) File type (3 characters. If the file type is less than 3 characters, left-justify the file type and fill blank codes (20) in the remaining space.)
6	File rename	00 01 02 03 04 ~ 11 12 ~ 14 15 ~ 22 23 ~ 25	Rename the existing file. 05 (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Filename before change (8 characters) File type before change (3 characters) Filename after change (8 characters) File type after change (3 characters)
7	File size calculation	00 01 02 03 ~ 04	Returns the number of records of the specified file. (One record consists of 128 bytes.) 06 (function code) Return code (set at return) File number (i.e., the number returned at a file open) Maximum value of a record number (the value must be in the range of 0 to 65535. 0 indicates the null state.)
8	First directory search	00 01 02 03 04 ~ 11 12 ~ 14 15 16 ~ 47	Returns the FCB (file control block) address and directory code on the disk of the file for which the filename and file type were specified. If the filename and file type are all specified by character '?', it is assumed that file matching has been completed for all files. 07 (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Filename (8 characters) File type (3 characters) Directory code (set at return) Directory FCB (set at return)

No.	Function	Packet data No.	Description
9	Next directory search	00 01 02 03 04 ~ 11 12 ~ 14 15 16 ~ 47	Searches the next directory. (This function is performed next to the function No. 8 above.) The method of specifying the filename and file type is the same as function No. 8. 08 (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Filename (8 characters) File type (3 characters) Directory code (set at return) Directory FCB (set at return)
10	Direct write into disk (DSK0\$)	00 01 02 03 04 05 06 ~ 07	Writes data into the specified tracks and sectors of floppy disk. 09 (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Track number (binary value in the range of 0 to 39 ₁₀) Sector number (binary value in the range of 1 to 64 ₁₀) Buffer address (must be entered in the order of high- and low-order bytes)
11	Disk formatting (FORMAT)	00 01 02 03	Formats the floppy disk in the specified drive. 0A (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D")
12	Disk system reset	00 01 02 03	Enables a disk replacement. When the disk system is reset, all the disks can be read or written and disk drive "A" is selected. 0B (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D")
13	System disk generation (SYSGEN)	00 01	Copies the system area and file of the system disk set in drive "A", to the disk set in drive "B". After copying, the disk in drive "B" can be used as a system disk. 0C (function code) Return code (set at return)

No.	Function	Packet data No.	Description
14	Disk free area calculation (DSKF)	00 01 02 03 04	Provides the free area size of the disk in the specified drive in 2K-byte units. 0D (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Free area size (binary value in 2K-byte units set at return)
15	Direct read from disk (DSKI\$)	00 01 02 03 04 05 06 ~ 77	Reads data from the specified tracks and sectors of a floppy disk. 0E (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") Track number (binary value in the range of 0 to 39 ₁₀) Sector number (binary value in the range of 1 to 64 ₁₀) Buffer address (must be entered in the order of high- and low-order bytes. In this case, however, the message work area of EPSP driver routine is used.)
16	Disk all copy	00 01 02 03	Copies all the contents of the floppy disk in the specified drive to the disk in the other drive of the same floppy disk unit. (i.e., from "A" to "B", from "C" to "D") 0F (function code) Return code (set at return) Unused Drive name ("A", "B", "C" or "D") NOTE: With drives "A" and "B", disk copying must be from "A" to "B". With drives "C" and "D", disk copying must be from "C" to "D".

10.4.3 BSCINT return codes

Code (Hex)	Meaning
00	Normal completion of operation
01	The specified file is not found.
02	End of File (EOF) was detected during file input.
03	The file already exists.
04	The specified device is not found.
05	No directory area exists.
06	No disk area exists.
07	The specified record number is incorrect.
08	The disk is write-protected.
09	The file is not opened.
0A	The specified file number is incorrect.
0B	The specified file mode is incorrect.
0C	The specified file is already open.
0D	The number of opened files is too many.
0E	The specified file descriptor is incorrect.
0F	An error has occurred during a read operation.
10	An error has occurred during a write operation.

10.5 EPSP (EPSON Serial Communication Protocol)

10.5.1 EPSP functions

The EPSP is an interface between the EPSP driver and the TFDOS as described in Chapter 4. The EPSP on the TF-20 side has the following functions:

- (1) Disk system reset
Corresponds to Item (12) of paragraph 10.4.1.
- (2) File open
Corresponds to Item (1) of paragraph 10.4.1.
- (3) File close
Corresponds to Item (2) of paragraph 10.4.1.

- (4) First directory search
Corresponds to Item (8) of paragraph 10.4.1.
- (5) Next directory search
Corresponds to Item (9) of paragraph 10.4.1.
- (6) File delete
Corresponds to Item (5) of paragraph 10.4.1.
- (7) File creation
By this function, the directory and memory are initialized and a file empty of data is created.
- (8) Random read
Corresponds to Item (3) of paragraph 10.4.1.
- (9) Random write
Corresponds to Item (4) of paragraph 10.4.1.
- (10) File size calculation
Corresponds to Item (7) of paragraph 10.4.1.
- (11) Disk all copy
Corresponds to Item (16) of paragraph 10.4.1.
- (12) Direct write (128 bytes) into disk (DSKOS)
Corresponds to Item (10) of paragraph 10.4.1.
- (13) Disk formatting (FRMAT)
Corresponds to Item (11) of paragraph 10.4.1.
- (14) System disk generation (SYSGEN)
Corresponds to Item (13) of paragraph 10.4.1.
- (15) Disk free area calculation (DSKF)
Corresponds to Item (14) of paragraph 10.4.1.
- (16) Direct read (128 bytes) from disk (DSKIS)
Corresponds to Item (15) of paragraph 10.4.1.
- (17) Disk boot
By this function, file "BOOT80.SYS" is booted to the HX-20 from the system disk in the disk drive A of the TF-20. In other words, this function opens file "BOOT80.SYS", reads 128 bytes of data only and transfers them to the HX-20.
- (18) Load open
By this function, file "DBASIC.SYS" contained in the system disk in the drive A of the TF-20 is opened and then loaded into the RAM of the TF-20. After the loading, the file is relocated on the RAM of the TF-20 using a relocatable flag (one of the load open parameters) and an ending or starting address. Return code "FF" if the corresponding file is not found, or return code "00" if found, is returned to the HX-20 together with the file size of "DBASIC.SYS".
- (19) Load close
This function indicates that the transfer of file "DBASIC.SYS" has been completed. In this case, the TF-20 does not perform any function.
- (20) Read one block
By this function, the file "DBASIC.SYS" opened, read, and relocated in item (18) above is transferred to the HX-20 in units of 128 bytes.
Return code "FF" indicates the end of file (EOF).

10.5.2 Subroutine "OUTSRL"

Subroutine "OUTSRL" handles the data transmission/reception of EPSP as follows:

(1) Creation of a parameter packet

Parameters are given in the form of a packet as shown in Fig. 10-5.

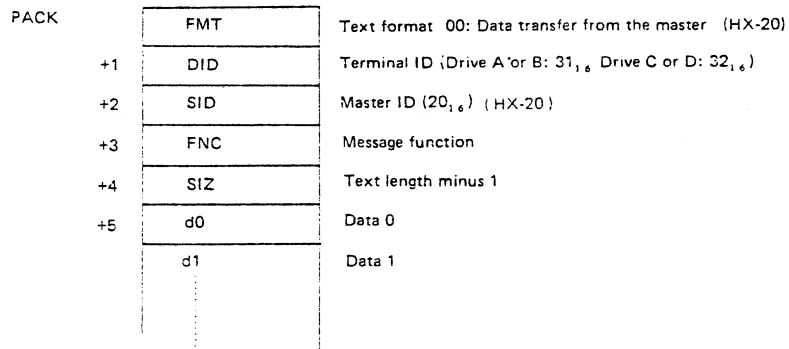


Fig. 10-5 Parameter Packet of Subroutine "OUTSRL"

(2) Subroutine call

The first address of the parameter packet is set in the index register to call subroutine "OUTSRL" (entry point: FF70). For details of the EPSP, refer to Chapter 4. For details of the EPSP functions on the TF-20 side, refer to the next page.

°EPSP side

Open file

Drive : "A", filename, file type: ABC, BAS

File mode: Sequential output "0"

```

OUTSRL EQU $FF70
        LDX =PACKET
        JSR OUTSRL      ... Routine for data output
                        to the serial interface
        :

PACKET EQU *
FMT     FCB $00, $30, $20, $0F, $0E
MSG     FCB $00, $01, $01,
        FCC /ABC△△△△△/
        FCC /BAS/
    
```

10.6 Function Table of Floppy Disk Unit

FMT	DID	SID	FNC	SIZ	Text data No.	Description of function and text
00 01	SS MM	MM SS	0E 0E	00 00	00 00	Terminal floppy reset XX Return code 00
00 01	SS MM	MM SS	0F 0F	0E 00	00 01 02 03 ~ 0A 0B ~ 0D 0E 00	File open High-order byte of FCB address in HX-20 Low-order byte of FCB address in HX-20 Drive code (1: Drive A or 2: Drive B) Filename File type Extent number (Normally 0) Return code BDOS error (See Note at the end of this table.) FF: File not found. Codes other than the above: Normal
00 01	SS MM	MM SS	10 10	01 00	00 00	File close High-order byte of FCB address in HX-20 Low-order byte of FCB address in HX-20 Return code (The same return code as that at file open.)
00 01	SS MM	MM SS	11 11	0C 20	00 01 ~ 08 09 ~ 0B 0C 00 01 ~ 20	First data search Drive code (1 or 2) Filename File type Extent number (Normally 0) Return code (The same return code as that at file open.) Directory FCB entry (The FCB of the found directory is entered.)
00 01	SS MM	MM SS	12 12	00 20	00 00 01 ~ 20	Next data search XX Return code (The same return code as that at file open.) Directory FCB entry (The FCB of the found directory is entered.)

FMT	DID	SID	FNC	SIZ	Text data No.	Description of function and text
00	SS	MM	16	0E	00	File creation High-order byte of FCB address in HX-20
					01	Low-order byte of FCB address in HX-20
					02	Drive code (1 or 2)
					03 ~ 0A	Filename
					0B ~ 0D	File type
					0E	Extent number (Normally 0)
01	MM	SS	16	00	00	Return code (The same return code as that at file open.)
00	SS	MM	17	1F	00	File rename Drive code (1 or 2)
					01 ~ 08	Filename before change (8 characters)
					09 ~ 0B	File type before change (3 characters)
					0C	Extent number
					0D ~ 0F	Unused
					10	Drive code (1 or 2)
					11 ~ 18	Filename after change (8 characters)
					19 ~ 1B	File type after change (3 characters)
					1C	Extent number
					1D ~ 1F	Unused
01	MM	SS	17	00	00	Return code (The same return code as that at file open.)
00	SS	MM	21	04	00	Random data read High-order byte of FCB address in HX-20
					01	Low-order byte of FCB address in HX-20
					02	R0
					03	R1
					04	R2
						} Random record numbers
01	MM	SS	21	82	00	Extent number
					01	Current record number
					02 ~ 81	Read data (128 bytes)
					82	Return code
						BDOS error (See Note at the end of this table.)
						Codes other than the above: Normal

FMT	DID	SID	FNC	SIZ	Text data No.	Description of function and text
00	SS	MM	22	84	00	Random data write
					01	High-order byte of FCB address in HX-20
					02 ~ 81	Low-order byte of FCB address in HX-20
					82	Write data (128 bytes)
					83	R1
					84	R1 } Random record numbers
01	MM	SS	22	02	00	R2 } Random record numbers
					01	Extent number
					02	Current record number
						Return code
						BDOS error (See Note at the end of this table.)
						Codes other than the above: Normal
00	SS	MM	23	01	00	File size calculation
					01	High-order byte of FCB address in HX-20
01	MM	SS	23	05	00	Low-order byte of FCB address in HX-20
					01	Extent number
					02	Current record number
					03	R0
					04	R1 } Random record numbers
					05	R2 } Random record numbers
						Return code (Always 0)
01	SS	MM	7A	00	00	Disk all copy
01	MM	SS	7A	02	00	Drive code (1 or 2)
					01	High-order byte of currently copied track number
					02	Low-order byte of currently copied track number
						0 to 39
						FFFF : End
					02	Return code (BDOS error or 0)
00	SS	MM	7B	82	00	Direct write into disk
					01	Drive code (1 or 2)
					02	Track number (0 to 39)
					03 ~ 82	Sector number (1 to 64)
00	MM	SS	7B	00	00	Write data (128 bytes)
						Return code (BDOS error or 0)
00	SS	MM	7C	00	00	Disk formatting (FRMAT)
01	MM	SS	7C	02	00	Drive code (1 or 2)
					01	High-order byte of currently formatted track number
						Low-order byte of currently formatted track number
						0 to 39
						FFFF : End
					02	Return code (BDOS error or 0)

FMT	DID	SID	FNC	SIZ	Text data No.	Description of function and text
00	SS	MM	7D	00	00	New system disk generation (SYSGEN) XX } 0000 : Not end } FFFF : End Return code (BDOS error or 0)
01	MM	SS	7D	02	00	
					01 02	
00	SS	MM	7E	00	00	Disk free area calculation (DSKF) Drive code (1 or 2) Free area size (in 2K-byte units) Return code (BDOS error or 0)
01	MM	SS	7E	01	00 01	
00	SS	MM	7F	02	00	Direct read from disk (DSKI\$) Drive code (1 or 2) Track number (0 to 39) Sector number (1 to 64) Read data (128 bytes) Return code (BDOS error or 0)
					01 02	
01	MM	SS	7F	80	00 ~ 7F 80	
00	SS	MM	80	00	00	Disk boot Application ID (in BASIC 80 ₁₆ ... BOOT80.SYS) Return code 00 : Normal FF : File not found. Read data
01	MM	SS	80	FF	00	
					01 ~ FF	
00	SS	MM	81	0D	00 ~ 07	Load open Filename (the filename of DISK BASIC is "DBASIC".) File type (the file type of DISK BASIC is "SYS".) Relocate flag 00: Do not relocate. 01: Relocate from the starting address. 02: Relocate from the ending address. Ending or starting address Return code 00: Normal FF: File not found. High-order byte of file size Low-order byte of file size
					08 ~ 0A	
					0B	
					0C ~ 0D	
01	MM	SS	81	02	00	
					01 02	

FMT	DID	SID	FNC	SIZ	Text data No.	Description of function and text
00	SS	MM	82	00	00	Load close
01	MM	SS	82	00	00	XX Return code (Always 0)
00	SS	MM	83	01	00	Read one block
					01	High-order byte of current record number
					01	Low-order byte of current record number
01	MM	SS	83	82	00	High-order byte of current record number
					01	Low-order byte of current record number
					02 ~ 81	Read data
					82	Return code (00: Normal; FF: End)

NOTE: The term "BDOS error" used in the above table refers to one of the following errors; a read error (error code: FA), a write error (error code: FB), a drive select error (error code: FC), and a write protect error (error code: FD or FE).

The format of the file control block (FCB) used by the floppy disk unit is as follows:

0	1			3	9	10	11	12	13	14	15	16					31	32	33	34	35		
dr				FN			t1	t2	t3	ex	s1	s2	rc				DM			CR	ro	r1	r2

dr: Disk drive code (00 to 16) (Use of code 05 to 16 will result in an error.)
 00: A file is assigned to the standard disk drive.
 01: Disk and disk drive A are selected automatically.
 02: Disk and disk drive B are selected automatically.

16: Disk and disk drive P are selected automatically.
 FN: Filename consisting of a maximum of 8 characters (in ASCII codes).
 If no filename is given by the user, blanks (20) will be filled as the filename.

t1, t2, t3: File format (in ASCII codes)
 As ASCII codes, bits in the upper row are selected and high-order bits set to 0 are used. These bits when represented by t1, t2 and t3 are as follows.

t1=1: Read only file
 t2=1: No system file, FILES list
 ex: File extent (Normally 0)
 This is a number to indicate the current location of the logical extent, and is normally set to 00 by the user. This number must be a value in the range of 0 to 31 when a file input/output is to be performed.

s1: Used within the system.
s2: Used within the system. s2 is set to 0 when a file is to be opened, created, or called for search.
rc: Record number of the logical extent indicated by "ex" and must be a value in the range of 0 to 128.
DM: A value set and used by the system.
cr: A value indicating the location of the record where data read/write is being performed in sequential file processing. This value is normally set to 0 by the user.
r0, r1, r2: Random record number indicated by a value in the range of 0 to 65535. r0, r1 and r2 are used to configure 24 bits. r0 indicates the low-order digit, r1 the high-order digit, and r2 an overflow.



CHAPTER 11 SLAVE MCU COMMANDS

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11.1 General

The interface between the master and slave MCUs consists of two signal lines. Serial communication is performed at 38.4K BPS. Slave MCU operations are performed in response to instructions (commands) sent from the main MCU. The master CPU uses the serial interface to communicate either with the slave MCU or externally.

The slave CPU supports the following functions:

- (1) Operation of the microprinter
- (2) Data reception via RS-232C port
- (3) Data I/O for external cassette
- (4) Data I/O and operation of built-in microcassette
- (5) Output for piezoelectric speaker
- (6) Control switches for serial, power supply and bar code reader power

11.2 Commands for Slave MCU Control

Commands are sent to the slave MCU via the 38.4K-BPS serial interface. Commands are one byte in length. However, for some commands, parameters are added. The standard communication procedure involves sending a command from the master MCU and receiving an ACK signal from the slave MCU in response. The sequence for commands sent with parameters is shown below.

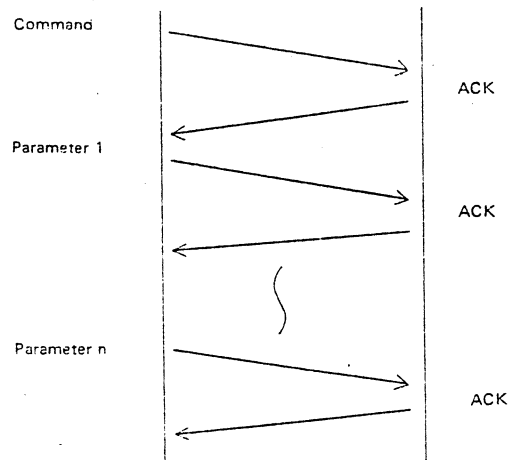


Fig. 11-1 Command Transmission Sequence

First, a 1-byte command is sent to the slave MCU. The SNSCOM subroutine (entry point FF19) is called to receive the ACK signal. For details of commands, see the command table.

For data reception from the RS-232C or cassette, the slave MCU sends serial input data to main MCU upon completion of command reception. Data received by the slave MCU under this condition are assumed to be commands and the current input mode is cancelled.

11.3 Cancelling a Command

The command being executed is cancelled if an overrun error occurs during serial communication. (For example, if overrun occurs when 100-line feed is specified for the microprinter, the current command is aborted and the system goes into WAIT status pending receipt of a fresh command.) If new data is received from main MCU while a command is being executed by the slave MCU, the data is set in the receive register but not processed. At this point, if new serial communication data is received, the data in the register is destroyed, causing an overrun error.

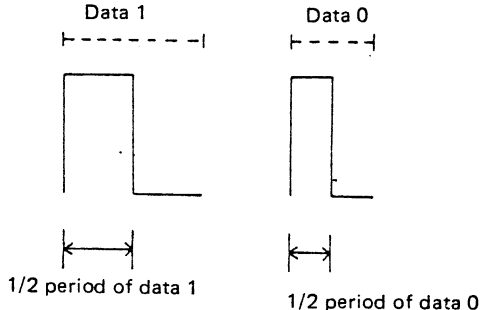
To cancel a command, the master MCU sends a series of BREAK commands to the slave MCU. Subroutine BREAKIO (entry point FFA3) is provided for this purpose.

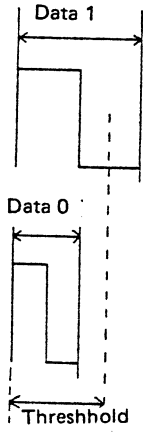
11.4 Slave MCU Command Transmission Subroutine

Subroutine name	Entry point	Description
SNSCOM	FF19	<p>Transfers a command or 1 byte of data to the slave MCU via SCI.</p> <p>Parameters:</p> <p>At Entry (A) Transmit data (Command)</p> <p>At Return (C): Abnormal I/O flag (A): Return code (Transmit data from slave MCU)</p> <p>Registers retained (B), (X)</p> <p>Subroutines referenced None</p> <p>Variables used None</p>

11.5 Commands to Slave MCU

Command	Master MCU data	Slave MCU response	Description
00	00	01 (ACK)	Slave MCU ready check. ACK is returned when the slave MCU is ready to receive a command. The slave MCU makes no response if it is not ready.
01	01	01 (ACK)	Sets the constants required by slave MCU in the field. The following values are set: Generated polynomial expressions, BCC register value, RS-232C bit rate, cassette (external or built-in microcassette), micro-cassette tape counter setting.
02	02	01 (ACK)	Initialization. The status of serial communication driver remains unchanged.
03	03 (Command) AA (Parameter)	01 (ACK)	Opens masks for special commands. Commands 06, 07, 08 and 0B cannot be executed unless the masks are opened. Any value other than AA indicates that the mask is closed.
04	04	01 (ACK)	Closes masks for special commands.
05	05 ah (Upper byte of address) al (Lower byte of address)	01 (ACK) 01 (ACK) d (Data)	Reads slave MCU memory. NAK (0F) is returned in response to 05 if the mask is not open.
06	06 ah (Upper byte of address) al (Lower byte of address) d (Data)	01 (ACK) 01 (ACK) 01 (ACK) 01 (ACK)	Stores data to the memory address specified by the slave MCU. 0F (NAK) is returned and command execution is aborted if the mask is not opened.
07	07 ah (Upper byte of address) al (Lower byte of address) d (Data)	01 (ACK) 01 (ACK) 01 (ACK) 01 (ACK)	Performs logical OR operation for the data at the memory address specified by the slave MCU and the specified data and stores the result in the specified address. 0F (NAK) is returned and command execution is aborted if the mask is not opened.
08	08 ah (Upper byte of address) al (Lower byte of address) d (Data)	01 (ACK) 01 (ACK) 01 (ACK) 01 (ACK)	Performs logical AND operation for the data at the memory address specified by the slave MCU and the specified data and stores the result in the specified address. 0F (NAK) is returned and command execution is aborted if the mask is not opened.

Command	Master MCU data	Slave MCU response	Description
09	09	01 (ACK)	Unused (In version 2, bar-code reader power ON)
0A	0A	01 (ACK)	Unused (In version 2, bar-code reader power OFF)
0B	0B ah (Upper byte of address) al (Lower byte of address)	01 (ACK) 01 (ACK) 01 (ACK)	Sets the program counter to a specified value. (Jumps execution to a specified address.) 0F is returned and command execution is aborted, if the mask is not opened.
0C	0C	02 (ACK for BREAK)	BREAK. Terminates processing and sets the system to command WAIT status.
0D	0D AA	01 (ACK) 01 (ACK)	Cuts OFF power supply. Command execution is aborted if parameter AA is omitted.
0E ~ 0F			Undefined
10	10 d (Data)	01 (ACK) 01 (ACK)	Activates the built-in printer. Prints out 6-dot data (Bit 0 to bit 5). One dot-line is printed by repeating this command procedure 24 times.
11	11 d (Number of lines)	01 (ACK) 01 (ACK)	Feeds the specified number of dot lines to the built-in printer.
12	12	01 (ACK)	Activates built-in printer motor for approx. 1.2 sec. (Paper feed operation)
13 ~ 1F			Undefined
20	20	21 (ACK)	Executes external cassette ready check. Code 21 is returned when the external cassette is ready. The external cassette makes no response if it is not ready.
21	21 d1 (Upper byte of time (MCU clocks) of 1/2 cycle for data '1') d2 (Lower byte of time (MCU clocks) of 1/2 cycle for data '1') d3 (Upper byte of time (MCU clocks) of 1/2 cycle for data '0')	01 (ACK) 21 (ACK) 21 (ACK) 21 (ACK)	Sets constants for the external cassette. 

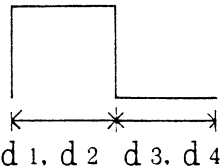
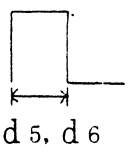
Command	Master MCU data	Slave MCU response	Description
	d4 (Lower byte of time (MCU clocks) of 1/2 cycle for data '0')	21 (ACK)	<p>The times (in MCU clock pulses) for 1/2 cycle for data '1' and for data '0' are set as constants. The bit judgment threshold value for data read is also set as the number of MCU clocks (Fig. below).</p> <p>This data represents the interblock gap length in tape stop mode (long gap) as the number of times that data FF is written to the tape.</p> 
	d5 (Upper byte of bit judgment threshold value between cycle times for '1' and '2')	21 (ACK)	
	d6 (Lower byte of bit judgment threshold value)	21 (ACK)	
	d7 (Upper byte of interblock gap length (in bytes) in stop mode (tape head stops between blocks))	21 (ACK)	
	d8 (Lower byte of interblock gap length in stop mode)	21 (ACK)	
22	22	01 (ACK)	Turns the external cassette REM terminal ON.
23	23	01 (ACK)	Turns the external cassette REM terminal OFF.
24	24 d1 (Block write start mode) d2 (Block write end mode) d3 (Upper byte of block length) d4 (Lower byte of block length) W1 (Output data) } Wm (Output data)	01 (ACK) 21 (ACK) 21 (ACK) 21 (ACK) 22 (ACK) (2F(NAK)) 22 (ACK) (2F(NAK))	<p>Writes 1 block of data in EPSON format. After synchronizing pattern is sent, the number of bytes specified as the block length is written followed by 2 CRC bytes. For output data, only the number of bytes specified as the block length are required. If data has not been received from the master MCU when the slave attempts to write data to the cassette, the slave MCU returns 2F, activates the speaker (880Hz for 1 sec.) and terminates cassette output. Block write start mode values are as follows (d1)</p> <p>00: 125-byte gap before the block (default value).</p> <p>01: 15-byte gap before the block.</p> <p>FF: 625-byte gap before the block.</p> <p>Block write start mode value (00, 01 or FF) is used as the block write end mode value at the completion of block write operation. In 00 and FF modes, the REM terminal is turned after completion of block write operation.</p>

Command	Master MCU data	Slave MCU response	Description
25	25 d1 (Upper byte of number of FF patterns) d2 (Lower byte of number of FF patterns)	01 (ACK) 21 (ACK) 21 (ACK)	Outputs number of FF patterns specified by d1 and d2 to the external cassette. Writing of data FF is unrelated to blocking.
26	26 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 21 (ACK) 21 (ACK) 21 (ACK) W1 W2 W3 { W84	Inputs files from an external cassette. Searches header block (EPSON format) and sends the contents of this block to the master MCU. Header block always begins with data H. In actual practice, however, d1 is ignored. REM is turned OFF after reading 1 block if d2 is 00. If d2 is 01, REM is left ON. If an error occurs during transmission of block data, data transmission is terminated and P34 (connected to P12 of the master MCU) is turned ON. Two CRC bytes are placed at the end of the block but are not transmitted.
27	27 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 21 (ACK) 21 (ACK) 21 (ACK) W1 W2 W3 { W84	Inputs files from an external cassette. Searches EOF block (EPSON format) and sends the contents of this block to the master MCU. EOF block always begins with data E. Parameters and execution result are identical to those for command 26.
28	28 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 21 (ACK) 21 (ACK) 21 (ACK) W1 W2 W3 { W260	Inputs files from an external cassette. Inputs the next block (EPSON format) and sends the data to the master MCU. The block may begin with any data. Parameters and execution result are identical to those for command 26.
29			Undefined
2A			Undefined

Command	Master MCU data	Slave MCU response	Description
2B	2B d1 (Specifies the pulse mode)	01 (ACK) 21 (ACK)	Specifies the input signal for the external cassette and built-in micro-cassette. d1 Bit 3: When logic '1', the microcassette input signal is as defined by bit 2. When logic '0', the microcassette input signal is judged at input. Bit 2: When logic '1', the microcassette input signal is reversed. When logic '0', the microcassette input signal is normal. Bit 1: When logic '1', the external cassette input signal is defined by bit 0. When logic '0', the external cassette input signal is judged at input. Bit 0: When logic '1', the external cassette input signal is reversed. When logic '0', the external cassette input signal is normal. NOTE: In versions 1 and 2, the slave MCU assumes (Bit 3, Bit 2) = (1, 1) when bit 3 is logic '0'.
30	30 d1 (Tone) d2 (Duration)	01 (ACK)	Specifies the tone and duration and sounds the piezoelectric speaker. The specifications for tone are as follows: 0 = pause, 1, 2, 3 ... correspond to C, D, E Values 1 to 28 ₁₀ represent a 4-octave major scale (13 = 880Hz) and values 29 to 56 ₁₀ a scale each tone of which is a half tone higher than that represented by 1 to 28. Duration is specified with 1 = 0.1 sec., 2 = 0.2 sec, etc. 0 specifies a pause (command not executed).
31	31 d1 (Upper byte of frequency specification) d2 (Lower byte of frequency specification) d3 (Upper byte of duration specification) d4 (Lower byte of duration specification)	01 (ACK) 31 (ACK) 31 (ACK) 31 (ACK)	Specifies the frequency and duration and sounds the piezoelectric speaker. Frequency is specified as the number of MCU clocks corresponding to 1/2 cycle. Example: 349 ₁₀ for 880Hz. Specification of duration: 1 = 400 μsec. (256 MCU clocks)
32	32	01 (ACK)	Sounds the speaker for 0.03 sec at tone 6 using command 30.
33	33	01 (ACK)	Sounds the speaker for 1 sec at tone 20 using command 30.

Command	Master MCU data	Slave MCU response	Description
34	34 d s1 d 11 d s2 d 12 d sn d 1n FF	01 (ACK) 31 (ACK) 31 (ACK) 31 (ACK) 31 (ACK) 31 (ACK) 31 (ACK) 31 (ACK)	Sets melody data in the slave MCU buffer. Buffer size is 48 bytes. The data set here can be output to the speaker using command 35. The format for data is the same as for command 30, i.e., tone, duration. As a pair, these data repeatedly specify the tone and duration. Due to the buffer size, the maximum number of data is 46_{10} . Data must end with FF. The data set in the buffer remains unchanged unless it is rewritten by command 34 or destroyed by a printer command. (This is because this buffer is also used by printer.)
35	35	01 (ACK)	Sounds the piezoelectric speaker in accordance with the melody data specified in command 34.
36 ~ 3F			Undefined
40	40	01 (ACK)	Turns the serial driver ON. RTS is set to low (OFF).
41	41	01 (ACK)	Turns the serial driver OFF.
42	42 d1 (Upper byte of bit rate) d2 (Lower byte of bit rate) d3 (Word length) d4 (Mode)	01 (ACK) 41 (ACK) 41 (ACK) 41 (ACK) 41 (ACK)	Selects RS-232C mode. Bit rate corresponds to bit time specified as the number of CPU clock cycles (for example, 800_{16} : 300 BPS). Word length (excluding parity bits) may be set at 5, 6, 7 or 8 bits. The significance of each bit of mode data (d4) is as follows. Bit 0: } Bit 1: } Number of stop bits (1 or 2) Bit 2: '0': Carrier check '1': No carrier check Bit 3: Controls RTS output. '0': low '1': high Bit 4: Undefined Bit 5: Undefined Bit 6: } Parity control. Bit 7: } '00': Even parity '01': Odd parity '10' or '11': None
43	43	V	Inputs RS-232C status maintained by the slave MCU. The significance of each bit of the status code is as follows. (Logic '1' indicates an error.)

Command	Master MCU data	Slave MCU response	Description
43	43	V	Bit 0: Carrier detect Bit 1: Parity Bit 2: Overrun Bit 3: Framing Bit 4: Undefined Bit 5: Undefined Bit 6: Undefined Bit 7: Undefined Error status bits are reset by a clear command (44) or when input is resumed (command 45).
44	44	01 (ACK)	Clears RS-232C error status.
45	45	01 (ACK) V1 V2	Starts RS-232C input. Input data is sent to the master MCU. If the word length of the data (including the parity bits) is less than 8 bits, the remaining bits (from MSB) are padded with data 0 (right-justified). P34 (connected to master MCU P12) is reset (logic '1') when input starts. P34 is set (logic '1') if an error (framing error, carrier OFF, etc.) occurs. Data reception terminates upon receipt of a new command from the master MCU.
46	46	01 (ACK)	Terminates RS-232C input initiated by command 45. (This is not the only way of terminating such input.)
47			Undefined
48	48 d1 (Upper byte of polynomial expression) d2 (Lower byte of polynomial expression)	01 (ACK) 41 (ACK) 41 (ACK)	Sets the polynomial expression used for CRC check. This polynomial expression can also be used for cassette files. Default value is 8408 ($1+x^5+x^{12}+x^{16}$).
49	49 d1 (Upper byte of BCC register value) d2 (Lower byte of BCC register value)	01 (ACK) 41 (ACK) 41 (ACK)	Sets BCC register values for CRC check. This value is used as the initial value when CRC calculation is performed at RS-232C input. However, the data in BCC register is lost when I/O operations to a cassette are performed.
4A	4A	V	Inputs upper byte of BCC register value.

Command	Master MCU data	Slave MCU response	Description
4B	4B	V	Inputs lower byte of BCC register value.
4C	4C	01 (ACK)	Activates the serial driver. In contrast to command 40 which turns RTS OFF, this command does not affect the status of RTS.
4D	4D	01 (ACK)	RTS high/low specification. Only bit 0 is significant. 0: low, 1: high
4E			Undefined
4F			Undefined
50	50	V	Identifies the plug-in option. Bit states of P46 and P20 are returned. Bit 0: Bit state of P46 Bit 1: Bit state of P20 Bit 2 to 7: 0 NOTE: Plug-in option power is turned OFF when this command is executed.
51	51	01 (ACK)	Turns power of plug-in ROM cartridge ON.
52	52	01 (ACK)	Turns power of plug-in ROM cartridge OFF.
53 ~ 5F			Undefined.
60	60	61 (ACK)	Executes ready check. Same MCU responds only if a microcassette command is executable. In all other cases, no response is sent.
61	61 d1 (Upper byte of signal low time of one cycle for data '1') d2 (Lower byte of signal low time of one cycle for data '1') d3 (Upper byte of signal high time of one cycle for data '1') d4 (Lower byte of signal high time of one cycle for data '1')	01 (ACK) 01 (ACK) 61 (ACK) 61 (ACK) 61 (ACK)	Sets the microcassette parameters. Parameters are specified using data d1 to d8.  <p style="text-align: right;">Data 1 (write)</p>  <p style="text-align: right;">Data 0 (write)</p>

Command	Master MCU data	Slave MCU response	Description
	d5 (Upper byte of time of 1/2 cycle for data '0') d6 (Lower byte of d5) d7 (Upper byte of '0', '1' bit judgment threshold value) d8 (Lower byte of d7)	61 (ACK) 61 (ACK) 61 (ACK) 61 (ACK)	
62	62 d1 (Upper byte of number of gap bytes) d2 (Lower byte of number of gap bytes)	01 (ACK) 61 (ACK) 61 (ACK)	Specifies the number of gap bytes for each mode when stopping the microcassette between blocks.
63	63 d1 (Upper byte of the number of bytes sent) d2 (Lower byte of the number of bytes sent)	01 (ACK) 61 (ACK) 61 (ACK)	Advances the tape (in PLAY mode) for the specified number of bytes. The bit judgement threshold value is taken as the length of one bit and 9 bits are counted as one byte. This command does not perform data read.
64	64 d1 (Block write start mode) d2 ((Block write end mode) d3 (Upper byte of block length) d4 (Lower byte of block length) W1 (Data) { Wm (Data)	01 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) (6F (NAK)) 61 (ACK)	Outputs one block to microcassette in EPSON format. Output file and command format and execution result are identical to command 24 (block output to external cassette).
65	65 d1 (Upper byte of number of bytes) d2 (Lower byte of number of bytes)	01 (ACK) 61 (ACK) 61 (ACK)	Outputs the number of bytes of data FF specified by d1 and d2 to the microcassette. Result is the same as command 25.
66	66 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 61 (ACK) 61 (ACK) 61 (ACK)	Inputs files from microcassette. Command operation and parameters are identical to command 26.

Command	Master MCU data	Slave MCU response	Description
		W2 { W84	
67	67 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) W2 { W84	Inputs files from microcassette. Command operation and parameters are identical to command 27.
68	68 d1 (Block read start mode) d2 (Block read end mode) d3 (Upper byte of block length) d4 (Lower byte of block length)	01 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) 61 (ACK) W1 W2 { W260	Inputs files from microcassette. Command operation and parameters are identical to command 28.
69			Undefined
6A			Undefined
6B			Undefined
6C			Undefined
6D	6D d1 (Upper byte of counter value) d2 (Lower byte of counter value)	01 (ACK) 61 (ACK) 61 (ACK)	Sets microcassette counter value in the slave MCU. The counter value is a 16-bit signed hexadecimal number.
6E	6E	V	Fetches microcassette counter value. Sends the upper 8 bits of counter value to the master MCU.
6F	6F	V	Fetches microcassette counter value. Sends the lower 8 bits of counter value of the master MCU.

Command	Master MCU data	Slave MCU response	Description
70	70	V	Executes microcassette write protect check. In write enable status, '0' is returned to the master MCU. In write protect status, 'FF' is returned to MCU.
71	71 d1 (Upper byte of counter value) d2 (Lower byte of counter value)	01 (ACK) 61 (ACK) 61 (ACK)	Rewinds microcassette tape to the tape counter value specified by d1 and d2. Speed of rewind is same as that of fast forward.
72	72 d1 (Upper byte of counter value) d2 (Lower byte of counter value)	01 (ACK) 61 (ACK) 61 (ACK)	Advances the microcassette tape (fast forward) to the counter value specified by d1 and d2.
73	73	01 (ACK)	Causes the microcassette to rewind up to the beginning of tape (fast rewind).
74	74	V	Inputs microcassette status to the slave MCU. Status is a one-byte code. The significance of each bit is as follows. (Logic '1' indicates an error.) Bit 0: Tape read error Bit 1: Undefined Bit 2: Header or EOF block not found Bit 3: Delay in data transmission from master MCU during data output Bit 4: Write protect Bit 5: Head error Bit 6: Microcassette not connected Bit 7: Undefined
75	75	01 (ACK)	Clears the microcassette status register.
76	76	01 (ACK) (6F (NAK))	Loads the microcassette head. If an error occurs during loading, the slave MCU returns '6F'.
77	77	01 (ACK) (6F (NAK))	Unloads the microcassette head. If an error occurs during unloading, the slave MCU returns '6F'.
78	78	01 (ACK) (6F (NAK))	Rewinds the microcassette tape. Rewind operation continues until the next command is received.
79	79	01 (ACK) (6F (NAK))	Advances the microcassette tape (fast forward). Fast forward continues until the next command is received.

Command	Master MCU data	Slave MCU response	Description
7A	7A	01 (ACK) 6F (NAK))	Advances the microcassette tape (slow forward). Slow forward continues until the next command is received.
7B	7B	01 (ACK) 6F (NAK))	Stops microcassette tape forward and rewind operations.
7C			Undefined
7D			Undefined
7E ~ 7F			Undefined
80	80 d1 (Upper byte of address) d2 (Lower byte of address) d3 (Bit position)	01 (ACK) 0F (NAK)) 01 (ACK) 01 (ACK) 01 (ACK)	Causes master MCU PLG2 port (Address 26, bit 5) value to be stored in the specified bit in the slave MCU. The PLG2 port value is stored in the bit specified by d3 at the slave MCU address specified by d1 and d2. This operation continues until the next command is received. As this is a special command, the mask must be opened prior to execution (command 03). This command will not be accepted if the mask has not been opened.
81	81 d1 (Upper byte of address) d2 (Lower byte of address) d3 (Bit position)	01 (ACK) (0F (NAK)) 01 (ACK) 01 (ACK) 01 (ACK)	Stores the value of the specified bit in the slave MCU to P12 of the master MCU. The slave MCU address is specified by d1 and d2 and the bit position is specified by d3. If any of the data at the position specified by d3 (1) is '1', '1' will be stored in P12. In all other cases, '0' will be stored in P12. Like command 80, this command is a special command.
81 ~ 8F			Undefined
90 ~ FF			Undefined

```

ERR  SEQ  LOC  OBJECT  PROGRAM  SLAVE  --- SEND SLAVE COMMAND ---

00001
00002
00003
00004
00005
00006
00007
00008
00009
00010
00011A 1000
00012
00013
00014
00015
00016
00017
00018
00019A 1000 CE 1022 A
00020A 1003 86 34 A
00021A 1005 8D 0E 1015
00022A 1007 A6 00 A
00023A 1009 8D 0A 1015
00024A 100B 08
00025A 100C 51 FF A
00026A 100E 26 F7 1007
00027
00028
00029A 1010 86 35 A
00030A 1012 8D 01 1015
00031
00032A 1014 39
00033
00034
00035
00036
00037
00038
00039
00040
00041
00042
00043
00044
00045A 1015 75 2011 A
00046A 1018 27 FB 1015
00047A 101A 97 13 A
00048
00049A 101C 7D 0011 A
00050A 101F 2A FB 101C
00051A 1021 39
00052
00053
00054
00055A 1022 29 A

*
*      NAM      SLAVE
*      TTL      --- SEND SLAVE COMMAND ---
*      OPT      LOAD
*      OPT      PAGE=55
*      FILE NAME 'EX36' BY K.A
*
* SEND COMMAND TO SLAVE MCU
* SEND MELODY PATTERN TO SLAVE MCU AND SEND COMMAND TO PLAY MELODY.
*
*      ORG      $1000
*
*
* TRCSR EQU $11
* SRDR  EQU $12
* STDR  EQU $13
*
* SET SLAVE MCU THE MELODY (YANKEE DOODLE)
* PLAY LDX #MELTBL * (X):THE ADDRESS WHERE MELODY DATA ARE STORED.
*      LDA A #S34 * SEND DATA TO SLAVE MCU.
*      BSR SNDSLVA * COMMAND 34: SET MELODY DATA
SLV10 LDA A 0,X * SET DATA
*      BSR SNDSLVA
*      INX
*      CMP A #SFF * LAST DATUM IS 'SFF'
*      BNE SLV10
*
* PLAY MELODY.
*      LDA A #S35
*      BSR SNDSLVA
*
*
*      RTS
*
*
* SUBROUTINE
* SEND COMMAND TO SLAVE MCU
* PARAMETER
* ON ENTRY
* (A): COMMAND
* ON EXIT
* (A): RECIEVED CODE
* REGISTER PRESERVE (X),(B)
*
* SNDSLVA TIM #S20,TRCSR * TX READY ?
*      BEQ SNDSLVA
*      STA A STDR * SEND COMMAND
*
* RECIVE FROM SLAVE MCU
SNDS10 TST TRCSR * RX READY ?
*      BPL SNDS10
*      RTS
*
*
* MELODY TABLE (YANKEE DOODLE)
MELTBL FCB 41,10,41,10,15,10,16,10
    
```

```

ERR  SEQ  LOC  OBJECT  PROGRAM  SLAVE  --- SEND SLAVE COMMAND ---
      A 1023  0A  A
      A 1024  29  A
      A 1025  0A  A
      A 1026  0F  A
      A 1027  0A  A
      A 1028  10  A
      A 1029  0A  A
00056A 102A  29  A          FCB  41,10,16,10,15,10,11,10
      A 102B  0A  A
      A 102C  10  A
      A 102D  0A  A
      A 102E  0F  A
      A 102F  0A  A
      A 1030  0B  A
      A 1031  0A  A
00057A 1032  29  A          FCB  41,10,41,10,15,10,16,10
      A 1033  0A  A
      A 1034  29  A
      A 1035  0A  A
      A 1036  0F  A
      A 1037  0A  A
      A 1038  10  A
      A 1039  0A  A
00058A 103A  29  A          FCB  41,20,13,10,11,10
      A 103B  14  A
      A 103C  0D  A
      A 103D  0A  A
      A 103E  0B  A
      A 103F  0A  A
00059A 1040  FF  A          FCB  3FF
00060
00061 0000  A          *  END
**** TOTAL ERRORS . 0
    
```

CHAPTER 12 BAR-CODE READER

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12.2 Input/Output Ports related to the bar-code reader	12-1
12.3 Procedure for Data Input	12-2
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12.1 General

A bar code is a code which uses combinations of bars of varying thicknesses, designed to be read by an optical wand, and provides an effective means as a consumer product information code in inventory control, etc. (The current BASIC version of the HX-20 does not support the input/output of bar codes.)

This chapter describes the methods of inputting bar codes and printing them out using MX-80 series printers. (These functions will become available only with the external BASIC.)

12.2 Input/Output Ports related to the bar-code reader

Input/output ports related to the bar-code reader are shown in Table 1 below.

Table 1 Input/Output Ports Related to the Bar-Code Reader

MCU	Port	Direction	Function
Master MCU	P20	Input	Bar-code input signals (1: Mark (black), 0: Space (white))
Slave MCU	P35	Output	Bar-code reader power supply (0: On, 1: Off)
	P41	Output	Always 0



Fig. 12-1 Bar Codes

When bar codes are to be scanned with a bar-code reader, each bar (black) is input as binary "1" (mark) and a blank (white) between bars is input as binary "0" (space) to the P20 of the master MCU. A code is input by measuring the time duration of the black and white elements of the code.

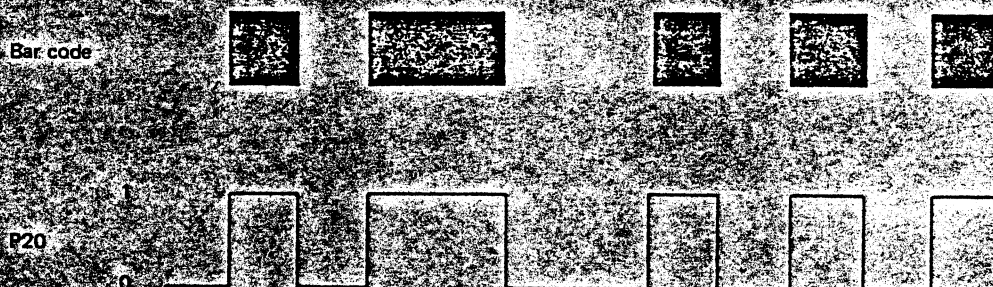


Fig. 12-2 Bar Code Scanned and Input Signal

12.3 Procedure for Data Input

12.3.1 Turning On the Power supply of the bar-code reader.

Before inputting data to the bar-code reader, its power supply must be turned on as follows:

SNSCOM	EQU		\$FF19	
	LDA	A	#\$03	* Opens the special command mask of the slave MCU.
	JSR		SNSCOM	
	LDA	A	#\$AA	
	JSR		SNSCOM	
	LDA	A	#\$08	* Turns off the P35 of the slave MCU.
	JSR		SNSCOM	
	LDA	A	#\$00	* (Turns off the bit 5 at address 0006H.)
	JSR		SNSCOM	
	LDA	A	#\$6	
	JSR		SNSCOM	
	LDA	A	#\$DF	
	JSR		SNSCOM	* Special command of slave MCU
	LDA	A	#\$04	* Closes the special command masks.
	JSR		SNSCOM	

12.3.2 Data input

Data must be input only after the power supply of the bar-code reader has been turned On. Data input is accomplished by measuring the time duration of the binary 1 or binary 0 at the P20 of the master MCU as follows:

Here, it is assumed that the initial state of P20 is binary 1 (black).

(1) Time measurement of the binary 1 (black) state

- Set the bit 1 of TCSR to "0" (by specifying as a change of the input from "1" to "0"). ("AIM #\$FD, TCSR").
- Wait until the bit 7 of TCSR becomes "1" (indicating that the edge detection has been completed). The period of FRC at this point is approximately 0.1 sec. In normal bar-code scanning, the thickness of any single bar in a bar code will not exceed this time interval of 0.1 sec. Time-out monitoring is performed by the OCR in the bar-code reader so that any bar exceeding 0.1 sec. in time duration may be detected as an error.

Data setting in the OCR is performed as follows:

LDD		FRC		* Sets the timing of the OCR interrupt at 0.1 sec.
STD		OCR		* 0.1 sec is judged.
LDA	B	TCSR		* Clears the bit 6 (Output compare flag) of TCSR.
STA	A	OCR		

Edge detection is performed as follows:

LOOP	LDA	A	TCSR	* When bit 7=1, it indicates that the edge detection has been completed.
	BMI		EDGE	
	BIT	A	#\$40	* Monitors the time-out condition.
	BEQ		LOOP	
	JMP		TIMOUT	* Executes the time-out processing.
EDGE	LDD		ICR	* (A, B) + Time duration of binary 1.
	SUBD		LSTTIM	
	LDX		ICR	* Stores the time when the edge is detected.
	STX		LSTTIM	
	.			
	.			
	.			
LSTTIM	RMB		2	

(2) Time measurement of the binary 0 (white) state

The time duration of binary 0 is measured by the same procedure as described above, except the bit 1 of TCSR is set to "1" (by specifying as a change of the input edge from "0" to "1").

12.3.3 Turning Off the power supply of the bar-code reader

Upon completion of the data input to the bar-code reader, the power supply of the bar-code reader must be turned off as follows:

SNSCOM	EQU		\$FF19	
	LDA	A	#\$03	* Opens the special command mask of the slave MCU.
	JSR		SNSCOM	
	LDA	A	#\$AA	
	JSR		SNSCOM	
	LDA	A	#\$07	* Turns On the P35 of slave MCU.
	JSR		SNSCOM	
	LDA	A	#\$00	* (Turns ON the bit 5 at address 0006H).
	JSR		SNSCOM	
	LDA	A	#\$06	
	JSR		SNSCOM	
	LDA	A	#\$20	
	JSR		SNSCOM	
	LDA	A	#\$04	* Closes the special command mask of the slave MCU.
	JSR		SNSCOM	

12.4 Printing Bar Codes with M-80 Series Printers

The method of printing bar codes is explained using the codes shown in Fig. 12-3 as an example. The codes in this figure are available in two types of bars differing in thickness or width and two types of blanks differing in width. Namely, a 0.3mm narrow bar and a 1.0mm wide bar and a 0.3mm narrow blank and 1.0mm wide blank. To print these bars at a height of 1.7cm with any MX-80 series printer, the following must be specified.

- (1) Paper feed pitch: 4/216 inch (specified with ESC, "3", 4)
- (2) Dot density : 960 dots/line (specified with ESC, "L, n₁, n₂)



Fig. 12-3 Print Sample of Bar Codes with M^X-80

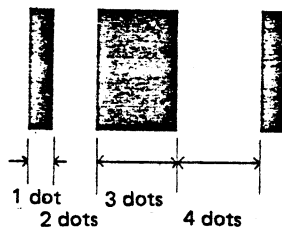


Fig. 12-4 Print Spacing with M^X-80

The print spacing must be as shown in Fig. 12.4.

Narrow bar	1-dot space
Wide bar	3-dot space
Narrow blank	2-dot space
Wide blank	4-dot space

A sequence of 8 dots is printed 16 times to produce a 1.7cm long bar (see Fig. 12.5).

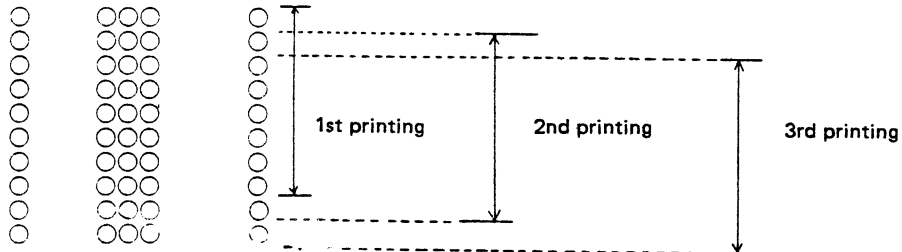


Fig. 12-5 Repetition of Graphic Printing



* 0 1 2 3 4 5 6 7 8 9 *

* A B C D E F G H I J K L M N O *

* P Q R S T U V W X Y Z # [\] ^ _ *

* ` ~ @ # \$ % & ' () * + , - . / : ; *

* : ; < = > ? @ [\] ^ _ * + , - . /

* 0 1 2 3 4 5 6 7 8 9 * + , - . /

* : ; < = > ? @ [\] ^ _ * + , - . /

* 0 1 2 3 4 5 6 7 8 9 * + , - . /

* : ; < = > ? @ [\] ^ _ * + , - . /

Bar Code Listing

12-5

ERR SEQ LOC OBJECT PROGRAM BARCOD --- BARCODE READER READ SMAPLE ---

```

0C001          NAM      BARCOD
0C002          OPT      PAGE=55
0C003          TTL      --- BARCODE READER READ SMAPLE ---
0C004          * FILE NAME "EX$D" BY KOIKE
0C005          *
0C006          *
0C007          *          BARCODE READER DECODE PROGRAM
0C008          *          CREATIVE DATE : 1982/09/30 --- VER 0.1
0C009          *
0C010          *
0C011          *
0C012          0003 A     PORT2 EQU      $3          * MAIN PORT2 ADDRESS
0C013          0006 A     PORT3 EQU      $6          * SLAVE PORT3 ADDRESS
0C014          0007 A     PORT4 EQU      $7          * SLAVE PORT4 ADDRESS
0C015          0008 A     TCSR EQU      $8          * TIMER CONTROL STATUS REGISTER
0C016          0009 A     FRC EQU      $9          * FREE RUNNING COUNTER
0C017          000B A     OCR EQU      $B          * OUTPUT COMPARE REGISTER
0C018          000D A     ICR EQU      $D          * INPUT CAPTURE REGISTER
0C019          007C A     SIOSTS EQU     $7C         * SLAVE I/O STATUS
0C020          007D A     MIOSTS EQU     $7D         * MAIN I/O STATUS
0C021          0076 A     MINVAL EQU     118        * MINIMUM WIDTH VALUE
0C022          C350 A     OVRVAL EQU     50000      * OVER FLOW VALUE
0C023          *
0C024          FF16 A     RV232C EQU     $FF16      * SLAVE RS232C RECOVERY
0C025          FF19 A     SNSCOM EQU     $FF19      * SLAVE COMMUNICATION
0C026          *
0C027          05E2 A     HKLOAD EQU     $5E2       * HOOK LOAD ADDRESS FOR BARCODE
0C028          063C A     HKABTD EQU     $63C       * HOOK ABORT ADDRESS FOR BARCODE
0C029          0665 A     DCBTAD EQU     $665       * DCB POINTER FOR BARCODE
0C030          068C A     ASCFLG EQU     $68C       * LOAD ASCII JUDGE FLAG
0C031          068F A     OPTNTB EQU     $68F       * OPTION TABLE ADDRESS
0C032          8433 A     ERROR EQU     $8433      * BASIC ERROR JUMP
0C033          8C70 A     FCERR EQU     $8C70      * BASIC FC-ERROR JUMP
0C034          A6D0 A     LODCNT EQU     $A6D0     * BASIC CONTINUE LOADING ADDRESS
0C035          A9D8 A     ABTDO EQU     $A9D8     * BASIC ABORT ADDRESS
0C036          *
0C037          TTL      TEST MAIN
0C038          *
0C039          *
0C040          *          TEST MAIN
0C041          *
0C042A 1700          ORG      $1700
0C043          *
0C044A 1700 86 01    A     LDA A      #$01
0C045A 1702 B7 173D A     STA A     CHKDGT * CHECK DIGIT JUDGE FLAG
0C046A 1705 86 01    A     LDA A      #$01
0C047A 1707 B7 173E A     STA A     FULLVER * FULL ASCII JUDGE FLAG
0C048          *
0C049A 170A BD 1B03 A     JSR      PONBAR * POWER ON BARCODE WAND
0C050          *
0C051A 170D 86 02    A     MNST     LDA A      #$2 * GATE OPEN
0C052A 170F C6 07    A     LDA B     #PORT4
0C053A 1711 BD 1C0D A     JSR      SPWRIT
0C054          *
0C055A 1714 7F 17FC A     CLR      ASCCNT
    
```

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	TEST MAIN
	00056A	1717	7F 068C	A	CLR	ASCFLG
	00057				*	
	00058A	171A	BD 1801	A	JSR	RECBAR * RECOGNITION BARCODE
	00059				*	
	00060A	171D	B7 1738	A	STA A	ANSWER * ERROR CODE BUFFER
	00061A	1720	25 06 1728		BCS	MN10
	00062A	1722	7F 1739	A	CLR	CARRY * (C) BUFFER
	00063A	1725	7E 1730	A	JMP	MN20
	00064				*	
	00065A	1728	86 FF	A	MN10 LDA A	#\$FF
	00066A	172A	B7 1739	A	STA A	CARRY
	00067A	172D	7E 1735	A	JMP	MNED
	00068				*	
	00069A	1730	B6 1738	A	MN20 LDA A	ANSWER
	00070A	1733	27 D8 170D		BEQ	MNST
	00071				*	
	00072A	1735	7E 1735	A	MNED JMP	* ERROR END
	00073				*	
	00074A	1738	0001	A	ANSWER RMB	1
	00075A	1739	0001	A	CARRY RMB	1
	00076				*	
	00077				TTL	WORK AREA
	00078				*	
	00079				*	
	00080				*	
	00081				*	
	00082A	173A	0001	A	BAR RMB	1 * BAR BIT PATTERN
	00083A	173B	0001	A	SPACE RMB	1 * SPACE BIT PATTERN
	00084A	173C	0001	A	DIRECF RMB	1 * SCAN DIRECTION FLAG
	00085A	173D	0001	A	CHKDGT RMB	1 * CHECK DIGIT FLAG
	00086A	173E	0001	A	FULVER RMB	1 * FULL ASCII VERSION JUDGE FLAG
	00087A	173F	0001	A	CHRJDG RMB	1 * INPUT ROUTINE FIRST JUDGE FLAG
	00088A	1740	0002	A	TIMOV C RMB	2 * TIMER OVER FLOW COUNTER
	00089A	1742	0002	A	TIMCT1 RMB	2 * TIMER FIRST COUNTER
	00090A	1744	0002	A	TIMCT2 RMB	2 * TIMER END COUNTER
	00091A	1746	0002	A	TIMCNT RMB	2 * TIMER COUNTER
	00092A	1748	0002	A	TIMSTC RMB	2 *
	00093A	174A	0002	A	STRIMG RMB	2 * START MARGIN
	00094A	174C	0002	A	SUMCHK RMB	2 * CHECK DIGIT SUM
	00095A	174E	0002	A	ZNKBZC RMB	2 * LAST BAR ZERO COUNTER VALUE
	00096A	1750	0002	A	ZNKB0C RMB	2 * LAST BAR ONE COUNTER VALUE
	00097A	1752	0002	A	THRS HB RMB	2 * BAR 1 OR 0 THRESH LEVEL
	00098A	1754	0002	A	ZNKSZC RMB	2 * LAST SPACE ZERO COUNTER VALUE
	00099A	1756	0002	A	ZNKS0C RMB	2 * LAST SPACE ONE COUNTER VALUE
	00100A	1758	0002	A	THRS HS RMB	2 * SPACE 1 OR 0 THRESH LEVEL
	00101A	175A	0001	A	ANSCTB RMB	1 * BUFFER
	00102A	175B	0001	A	FULHNT RMB	1 * FULL ASCII DOUBLE CHARACTER JUDGE
	00103A	175C	0001	A	ASCBF1 RMB	1 * DOUBLE CHARACTER FIRST BUFFER
	00104A	175D	0001	A	ASCBF2 RMB	1 * DOUBLE CHARACTER SECOND BUFFER
	00105A	175E	0001	A	BITCNT RMB	1 * CHARACTER BIT COUNTER
	00106A	175F	0001	A	ERRBF RMB	1 * ERROR CODE BUFFER
	00107A	1760	0001	A	ZNKOVF RMB	1 * ZENKAI OVER FLOW
	00108A	1761	0002	A	SPWRBF RMB	2 * SLAVE WRITE BUFFER
	00109A	1763	0002	A	ANSTBA RMB	2 * PRE-ANSWER TABLE ADDRESS
	00110A	1765	0002	A	ANSADR RMB	2 *

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	WORK AREA
	00111A	1767	0002 A	ANSASA	RMB 2	* ANSWER TABLE ADDRESS
	00112A	1769	0002 A	FULTBA	RMB 2	* FULL ASCII TABLE ADDRESS
	00113					*
	00114A	176B	0048 A	ANSTBL	RMB 72	* PRE-ANSWER TABLE
	00115A	17B3	0001 A	ANSCNT	RMB 1	* PRE-ANSWER COUNTER
	00116					*
	00117A	17B4	0048 A	ANSASC	RMB 72	* ANSWER TABLE
	00118A	17FC	0001 A	ASCCNT	RMB 1	* ANSWER COUNTER
	00119					*
	00120A	17FD	00 A		FCB 0	
	00121A	17FE	0001 A	STDIGT	RMB 1	* START CHECK DIGIT
	00122A	17FF	00 A		FCB 0	
	00123A	1800	0001 A	EDDIGT	RMB 1	* END CHECK DIGIT
	00124					*
	00125					*
	00126					
	00127					
	00128					
	00129					
	00130					
	00131					
	00132					
	00133					
	00134					
	00135					
	00136					
	00137					
	00138					
	00139					
	00140					
	00141					
	00142					
	00143					
	00144					
	00145					
	00146					
	00147A	1801 96 03	A	RECBAR	LDA A PORT2	* WAND PAPER ON ?
	00148A	1803 85 01	A		BIT A #1	
	00149A	1805 27 13 181A			BEQ REC50	
	00150					
	00151A	1807 78	A		FCB \$78,\$80,\$7D	* TIM #80 MIOSTS
		A 1808 90	A			
		A 1809 7D	A			
	00152A	180A 27 F5 1801			BEQ RECBAR	
	00153A	180C 0D			SEC	
	00154A	180D 20 01 1810			BRA REC800	
	00155					
	00156					
	00157					
	00158A	180F 0C			REC700 CLC	* (C) CLEAR
	00159					
	00160A	1810 86 00	A		REC800 LDA A #0	* ANSWER COUNTER CLEAR
	00161A	1812 87 17FC	A		STA A ASCCNT	
	00162					
	00163A	1815 0E			CLI	* INTERRUPT ENABLE

```

TTL RECOGNITION
*
* FUNCTION : RECOGNITION BARCODE
* CALL : JSR RECBAR
* RETURN : (A)= ERROR CODE
*          000: NORMAL
*          100: SCAN SPEED SLOWER
*          101: SCAN SPEED FASTER
*          X 102: SW BAD OPERATION -- VER 0.3
*          X 103: TIMER OVER FLOW -- VER 0.3
*          104: BUFFER OVER FLOW
*          105: NOT CODE 39
*          106: CHECK DIGIT ERROR
*          107: FULL ASCII CONVERSION ERROR
(C)= BREAK STATUS.
*          0: NORMAL
*          1: BREAK
    
```

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00164					*
	00165A	1816	B6 175F	A	LDA A	ERRBF * ERROR CODE
	00166					*
	00167A	1819	39		REC900	RTS * RETURN
	00168					*
	00169					***** MARGIN DETECT *****
	00170					*
	00171A	181A	7B	A	REC50	FCB \$7B,\$80,\$7D * TIM #580 MIOSTS
		A 181B	80	A		
		A 181C	7D	A		
	00172A	181D	27 03	1822	BEQ	REC60
	00173A	181F	0D		SEC	
	00174A	1820	20 EE	181D	BRA	REC800
	00175					*
	00176A	1822	96 08	A	REC60	LDA A TCSR * ICF CLEAR
	00177A	1824	DC 0D	A	LDD	ICR
	00178					*
	00179A	1826	DC 09	A	LDD	FRC * OVF CLEAR
	00180A	1828	FD 1742	A	STD	TIMCT1
	00181					*
	00182A	182B	C3 C350	A	ADDD	#OVRVAL * OCF CLEAR
	00183A	182E	DD 0B	A	STD	OCR
	00184A	1830	96 08	A	LDA A	TCSR
	00185A	1832	72	A	FCB	\$72,\$00,\$B * OIM #50,OCR
		A 1833	0D	A		
		A 1834	0B	A		
	00186					*
	00187A	1835	72	A	FCB	\$72,\$02,\$08 * OIM #2 TCSR * IEDG=1
		A 1836	02	A		
		A 1837	08	A		
	00188					*
	00189A	1838	BD 1AD8	A	JSR	TIMRED * MARGIN READ
	00190					*
	00191A	183B	25 02	183F	BCS	REC70 * OVER FLOW ?
	00192A	183D	20 1E	185D	BRA	REC90
	00193					*
	00194A	183F	96 08	A	REC70	LDA A TCSR
	00195A	1841	2B 02	1845	BMI	REC80 * ICF ?
	00196A	1843	20 FA	183F	BRA	REC70
	00197					*
	00198A	1845	DC 0D	A	REC80	LDD ICR * START VALUE
	00199A	1847	FD 1742	A	STD	TIMCT1
	00200A	184A	C3 C350	A	ADDD	#OVRVAL * OVER FLOW COUNTER
	00201A	184D	DD 0B	A	STD	OCR
	00202					*
	00203A	184F	96 0B	A	LDA A	TCSR * OCF CLEAR
	00204A	1851	72	A	FCB	\$72,\$00,\$0B * OIM #500,OCR
		A 1852	00	A		
		A 1853	0B	A		
	00205A	1854	71	A	FCB	\$71,\$FD,\$08 * AIM #5FD TCSR * IEDG=0
		A 1855	FD	A		
		A 1856	08	A		
	00206					*
	00207A	1857	CC FFFF	A	REC85	LDD #FFFF * OVER FLOW COUNTER SET
	00208A	185A	FD 1746	A	STD	TIMCNT

ERR

SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
00209					
00210A	185D	FC 1746	A	REC90 LDD	TIMCNT * MARGIN ENTRY
00211A	1860	FD 174A	A	STD	STRTMG
00212					
00213A	1863	BD 1AD8	A	JSR	TIMRED * START BAR READ
00214					
00215A	1866	24 02 186A		BCC	REC110
00216					
00217A	1868	20 80 181A		REC100 BRA	REC50
00218					
00219A	186A	FC 1746	A	REC110 LDD	TIMCNT
00220A	186D	83 0076	A	SUBD	#MINVAL * 118 SPEED OVER ?
00221A	1870	25 A8 181A		BCC	REC50
00222					
00223A	1872	FC 174A	A	LDD	STRTMG * MARGIN CHECK
00224A	1875	04		LSRD	* (MARGIN)/16>=(START BAR WIDTH)
00225A	1876	04		LSRD	
00226A	1877	04		LSRD	
00227A	1878	04		LSRD	
00228A	1879	B3 1746	A	SUBD	TIMCNT
00229A	187C	25 9C 181A		BCC	REC50
00230					
00231					
00232					
00233A	187E	FC 1746	A	LDD	TIMCNT * INITIAL VALUE ENTRY
00234A	1881	FD 174E	A	STD	ZNK3ZC * INITIAL NARROW BAR
00235A	1884	FD 1754	A	STD	ZNK5ZC *
00236A	1887	05		ASLD	
00237A	1888	FD 1750	A	STD	ZNK9OC * INITIAL WIDE VALUE (X 2)
00238A	1888	FD 1756	A	STD	ZNK5OC *
00239					
00240A	188E	F3 1746	A	ADD	TIMCNT * THRESH LEVEL ENTRY (X 1.5)
00241A	1891	04		LSRD	
00242A	1892	FD 1752	A	STD	THRSHB * THRESH LEVEL
00243A	1895	FD 1758	A	STD	THRSHS
00244A	1898	86 FF	A	LDA A	#5FF * PRE-ANSWER COUNTER INITIAL
00245A	189A	87 1783	A	STA A	ANSCNT
00246					
00247A	189D	86 08	A	LDA A	#8 * REST 8 BIT OF START CODE
00248A	189F	8D 1808	A	JSR	DTT0BT
00249					
00250A	18A2	27 02 18A6		BEG	REC120
00251A	18A4	20 C2 1868		BRA	REC100
00252					
00253A	18A6	86 173A	A	REC120 LDA A	BAR * NORMAL DIRECTION CHECK
00254A	18A9	81 06	A	CMP A	#6
00255A	18AB	26 0C 18B9		BNE	REC130
00256A	18AD	86 173B	A	LDA A	SPACE
00257A	18B0	81 08	A	CMP A	#8
00258A	18B2	26 34 1868		BNE	REC100 * NOT START CODE
00259A	18B4	7F 173C	A	CLR	DIRECF * L TO R DIRECTION SET
00260A	18B7	20 0E 18C7		BRA	REC140
00261					
00262A	18B9	81 0C	A	REC130 CMP A	#3C * REVERSE DIRECTION CHECK
00263A	18BB	26 AB 1868		BNE	REC100 * NOT START CODE

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00264A	185D	B6 173B	A	LDA A	SPACE
	00265A	18C0	81 01	A	CMP A	#1
	00266A	18C2	26 A4 1868		BNE	REC100
	00267A	18C4	B7 173C	A	STA A	DIRECF * R TO L DIRECTION SET
	00268				*	
	00269A	18C7	79 A		REC140 FCB	\$7B,\$B0,\$7D * TIM #B0 MIOSTS * BREAK C
		A 18C8	80 A			
		A 18C9	7D A			
	00270A	18CA	27 04 18DD		BEQ	REC150
	00271A	18CC	0D		SEC	
	00272A	18CD	7E 1810	A	JMP	REC800
	00273				*	
	00274				*****	DATA READ - IN *****
	00275				*	
	00276A	18DD	DF		REC150 SEI	* INTERRUPT MASK DISABLE
	00277				*	
	00278A	18D1	CC 0000	A	LDD	#0
	00279A	18D4	FD 174C	A	STD	SUMCHK * CHECK DIGIT SUM AREA CLEAR
	00280A	18D7	86 FF	A	LDA A	#FF
	00281A	18D9	B7 17FE	A	STA A	STDIGT * START DIGIT INITIA
	00282A	18DC	CE 176B	A	LDX	#ANSTBL * PRE-ANSWER TABLE ADDRESS
	00283A	18DF	FF 1763	A	STX	ANSTBA
	00284				*	
	00285A	18E2	BD 1AD8	A	REC16D JSR	TIMRED * CHARACTER GAP READ
	00286				*	
	00287A	18E5	24 08 18EF		BCC	REC170 * OVER FLOW ?
	00288A	18E7	86 64	A	LDA A	#100 * SCAN SPEED SLOWER
	00289A	18E9	B7 175F	A	STA A	ERRBF
	00290A	18EC	7E 180F	A	JMP	REC700
	00291				*	
	00292A	18EF	86 09	A	REC170 LDA A	#9 * 1 CHARACTER DATA BIT CONVERT
	00293A	18F1	BD 180B	A	JSR	DTT0BT
	00294				*	
	00295A	18F4	B7 175F	A	STA A	ERRBF
	00296A	18F7	27 03 18FC		BEQ	REC175
	00297A	18F9	7E 180F	A	JMP	REC700
	00298				*	
	00299A	18FC	B6 17B3	A	REC175 LDA A	ANSCNT * BUFFER OVER CHECK
	00300A	18FF	81 49	A	CMP A	#73
	00301A	1901	25 08 190B		BCS	REC180
	00302A	1903	86 68	A	LDA A	#104 * BUFFER OVER FLOW ERROR
	00303A	1905	B7 175F	A	STA A	ERRBF
	00304A	1908	7E 180F	A	JMP	REC700
	00305				*	
	00306				*****	BIT TO ASCII CODE CONVERT *****
	00307				*	
	00308A	190B	CE 1C5E	A	REC180 LDX	#SPCTBL * SPACE TABLE
	00309A	190E	F6 173B	A	LDA B	SPACE * (X)=(X)+(SPACE)X4
	00310A	1911	58		ASL B	
	00311A	1912	58		ASL B	
	00312A	1913	3A		ABX	
	00313				*	
	00314A	1914	B6 173C	A	LDA A	DIRECF * DIRECTION L TO R ?
	00315A	1917	27 02 191B		BEQ	REC190
	00316A	1919	08		INX	

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00317A	191A	08		INX	
	00318					
	00319A	191B	EC 00	A	REC190 LDD ,X	* SPACE TABLE DATA
	00320A	191D	27 0B	192A	BEQ REC200	
	00321A	191F	2B 36	1957	BMI REC280	* SPECIAL CHARACTER
	00322A	1921	18	A	FCB \$18	* XGDX * (D) TO (X)
	00323A	1922	F6 173A	A	LDA B BAR	
	00324A	1925	3A		ABX	* (X)=(X)+(BAR)
	00325A	1926	A6 00	A	LDA A ,X	* BAR TABLE DATA
	00326A	1928	26 08	1932	BNE REC210	
	00327					
	00328A	192A	86 69	A	REC200 LDA A #105	* NOT CODE 39 ERROR
	00329A	192C	B7 175F	A	STA A ERRBF	
	00330A	192F	7E 180F	A	JMP REC700	
	00331					
	00332					
	00333					
	00334A	1932	16		REC210 TAB	* (A) TO (B)
	00335A	1933	C1 41	A	CMP B #\$41	* ALPHA ?
	00336A	1935	24 1C	1953	BCC REC250	
	00337A	1937	C1 30	A	CMP B #\$30	* NUMERIC ?
	00338A	1939	24 14	194F	BCC REC240	
	00339A	193B	C1 20	A	CMP B #\$20	* SP ?
	00340A	193D	26 04	1943	BNE REC220	
	00341A	193F	C6 26	A	LDA B #38	* SP DIGIT
	00342A	1941	2C 1B	195E	BRA REC290	
	00343					
	00344A	1943	C1 2D	A	REC220 CMP B #\$2D	* - ?
	00345A	1945	26 04	194B	BNE REC230	
	00346A	1947	C6 24	A	LDA B #36	* - DIGIT
	00347A	1949	20 13	195E	BRA REC290	
	00348					
	00349A	194B	C6 25	A	REC230 LDA B #37	* . DIGIT
	00350A	194D	20 0F	195E	BRA REC290	
	00351					
	00352A	194F	C0 30	A	REC240 SUB B #\$30	* 0-9 DIGIT
	00353A	1951	20 0B	195E	BRA REC290	
	00354					
	00355A	1953	C0 37	A	REC250 SUB B #\$37	* A-Z DIGIT
	00356A	1955	20 07	195E	BRA REC290	
	00357					
	00358A	1957	84 7F	A	REC280 AND A #\$7F	* SPECIAL CHARACTER
	00359A	1959	7D 173A	A	TST BAR	
	00360A	195C	26 CC	192A	BNE REC200	* NOT CODE 39 ERROR
	00361					
	00362A	195E	81 2A	A	REC290 CMP A #\$2A	* END CODE (*) ?
	00363A	1960	27 1E	1980	BEQ REC310	
	00364					
	00365A	1962	FE 1763	A	LDA ANSTBA	
	00366A	1965	A7 00	A	STA A ,X	* ANSWER ASCII ENTRY
	00367A	1967	08		INX	
	00368A	1968	FF 1763	A	STX ANSTBA	* NEXT ADDRESS SAVE
	00369A	196B	FE 174C	A	LDA SUMCHK	* CHECK DIGIT SUM
	00370A	196E	3A		ABX	
	00371A	196F	FF 174C	A	STX SUMCHK	

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00372					*
	00373A	1972	B6 17FE	A	LDA A	STDIGT * START DIGIT ?
	00374A	1975	2A 03 197A		BPL	REC300
	00375A	1977	F7 17FE	A	STA B	STDIGT
	00376					*
	00377A	197A	F7 1800	A	REC300 STA B	EDDIGT * NEW DIGIT ENTRY
	00378A	197D	7E 18E2	A	JMP	REC160
	00379					*
	00380					***** DATA ARRANGEMENT AND CONVERSION *****
	00381					*
	00382A	1980	7A 17B3	A	REC310 DEC	ANSCNT * LAST (*) BUN COUNTER DECREMENT
	00383					*
	00384A	1983	0E		CLI	* INTERRUPT ENABLE
	00385					*
	00386A	1984	B6 173D	A	LDA A	CHKDGT
	00387A	1987	27 32 198B		BEQ	REC340
	00388					*
	00389A	1989	7A 17B3	A	DEC	ANSCNT * CHECK DIGIT BUN COUNTER DECREMENT
	00390A	198C	B6 173C	A	LDA A	DIRECF * DIRECTION CHECK
	00391A	198F	26 0B 199C		BNE	REC320
	00392					*
	00393A	1991	FC 174C	A	LDD	SUMCHK * L TO R DIRECTION
	00394A	1994	B3 17FF	A	SUBD	EDDIGT-1 * CHECK SUM
	00395A	1997	FD 174C	A	STD	SUMCHK
	00396A	199A	20 0F 19AB		BRA	REC330
	00397					*
	00398A	199C	FC 174C	A	REC320 LDD	SUMCHK * R TO L DIRECTION
	00399A	199F	B3 17FD	A	SUBD	STDIGT-1 * CHECK SUM
	00400A	19A2	FD 174C	A	STD	SUMCHK
	00401A	19A5	B6 17FE	A	LDA A	STDIGT * LAST DIGIT SHITEI
	00402A	19A8	B7 1800	A	STA A	EDDIGT
	00403					*
	00404A	19AB	BD 18C1	A	REC330 JSR	DGTCAL * CHECK DIGIT CALCULATE
	00405					*
	00406A	19AE	B1 1800	A	CMP A	EDDIGT * DIGIT OK ?
	00407A	19B1	27 08 198E		BEQ	REC340
	00408					*
	00409A	19B3	86 6A	A	LDA A	#106 * CHECK DIGIT ERROR
	00410A	19B5	B7 179F	A	STA A	ERRBF
	00411A	19B8	7E 180F	A	JMP	REC700
	00412					*
	00413					***** ANSWER ASCII REARRANGEMENT *****
	00414					*
	00415A	19BB	CE 176B	A	REC340 LDJ	#ANSTBL * PRE-ANSWER TABLE
	00416A	19BE	CC 1764	A	LDD	#ANSASC * ANSWER TABLE
	00417A	19C1	FD 1767	A	STD	ANSASA
	00418					*
	00419A	19C4	B6 173C	A	LDA A	DIRECF * DIRECTION FLAG
	00420A	19C7	27 0B 19D4		BEQ	REC360
	00421A	19C9	F6 17B3	A	LDA B	ANSCNT * R TO L DIRECTION
	00422A	19CC	B6 173D	A	LDA A	CHKDGT
	00423A	19CF	26 02 19D3		BNE	REC350
	00424A	19D1	CD 01	A	SUB B	#1 * NONE CHECK DIGIT
	00425					*
	00426A	19D3	3A		REC350 ASX	* TOP DATA ADDRESS

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00427					
	00428A	19D4	FF 1763	A	REC360 STX	ANSTBA * SOURCE ADDRESS
	00429A	19D7	86 1783	A	LDA A	ANSCNT
	00430A	19DA	87 175A	A	STA A	ANSCTB * TRANSFER COUNTER
	00431					
	00432A	19DD	86 175A	A	REC370 LDA A	ANSCTB
	00433A	19E0	27 28 1A0A		BEQ	REC400
	00434					
	00435A	19E2	FE 1763	A	LDX	ANSTBA * SOURCE ADDRESS
	00436A	19E5	A6 00	A	LDA A	,X
	00437A	19E7	FE 1767	A	LDX	ANSASA * DESTINATION ADDRESS
	00438A	19EA	A7 00	A	STA A	,X
	00439A	19EC	08		INX	
	00440A	19ED	FF 1767	A	STX	ANSASA
	00441					
	00442A	19FD	86 173C	A	LDA A	DIRECF
	00443A	19F3	26 09 19FE		BNE	REC380
	00444A	19F5	FE 1763	A	LDX	ANSTBA * L TO R DIRECTION
	00445A	19F8	08		INX	* NEXT ADDRESS
	00446A	19F9	FF 1763	A	STX	ANSTBA
	00447A	19FC	20 07 1A05		BRA	REC390
	00448					
	00449A	19FE	FE 1763	A	REC380 LDX	ANSTBA * R TO L DIRECTION
	00450A	1A01	09		DEX	* NEXT ADDRESS
	00451A	1A02	FF 1763	A	STX	ANSTBA
	00452					
	00453A	1A05	7A 175A	A	REC390 DEC	ANSCTB
	00454A	1A08	20 D3 19DD		BRA	REC370
	00455					
	00456A	1A0A	86 173E	A	REC400 LDA A	FULVER
	00457A	1A0D	26 19 1A28		BNE	REC500
	00458					
	00459				*****	END PROCESS *****
	00460					
	00461A	1A0F	86 1783	A	LDA A	ANSCNT * PRE-ANSWER COUNTER
	00462A	1A12	B7 17FC	A	STA A	ASCCNT * ANSWER COUNTER
	00463					
	00464A	1A15	8D 13A9	A	REC410 JSR	BEEPOK * OK BEEP
	00465					
	00466A	1A18	24 06 1A20		BCC	REC420
	00467A	1A1A	7F 175F	A	CLR	ERRBF * BREAK
	00468A	1A1D	7E 1810	A	JMP	REC800
	00469					
	00470A	1A20	7F 173F	A	REC420 CLR	CHRJDG * NORMAL END
	00471A	1A23	4F		CLR A	* (A) CLEAR
	00472A	1A24	0C		CLC	* (C) CLEAR
	00473A	1A25	7E 1819	A	JMP	REC900
	00474					
	00475				*****	FULL ASCII CHECK *****
	00476					
	00477A	1A28	CE 1784	A	REC500 LDX	#ANSASC
	00478A	1A28	FF 1765	A	STX	ANSADR * SOURCE ADDRESS
	00479A	1A2E	FF 1767	A	STX	ANSASA * DESTINATION ADDRESS
	00480A	1A31	7F 175B	A	CLR	FULHNT
	00481A	1A34	7F 17FC	A	CLR	ASCCNT * ANSWER COUNTER CLEAR

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
	00482					*
	00483A	1A37	B6 17B3	A	REC510 LDA A	ANSCNT
	00484A	1A3A	81 00	A	CMP A	#0
	00485A	1A3C	2F D7 1A15		BLE	REC410 * END
	00486					*
	00487A	1A3E	7A 17B3	A	DEC	ANSCNT * SOURCE COUNTER DECREMENT
	00488A	1A41	B6 175B	A	LDA A	FULHNT * DOUBLE CHARACTER JUDGE
	00489A	1A44	27 08 1A4E		BEQ	REC520
	00490A	1A46	B6 175D	A	LDA A	ASCBF2 * SPECIAL CODE (\$,+./.%)
	00491A	1A49	B7 175C	A	STA A	ASCBF1
	00492A	1A4C	20 0C 1A5A		BRA	REC530
	00493					*
	00494A	1A4E	FE 1765	A	REC520 LDX	ANSADR * SOURCE ADDRESS
	00495A	1A51	A6 00	A	LDA A	,X
	00496A	1A53	B7 175C	A	STA A	ASCBF1
	00497A	1A56	08		INX	
	00498A	1A57	FF 1765	A	STX	ANSADR
	00499					*
	00500A	1A5A	81 24	A	REC530 CMP A	#\$24 * \$
	00501A	1A5C	26 08 1A66		BNE	REC540
	00502A	1A5E	CE 1D9E	A	LDX	#FULASC
	00503A	1A61	FF 1769	A	STX	FULTBA
	00504A	1A64	20 27 1A8D		BRA	REC580
	00505					*
	00506A	1A66	81 2F	A	REC540 CMP A	#\$2F * /
	00507A	1A68	26 08 1A72		BNE	REC550
	00508A	1A6A	CE 1DB8	A	LDX	#FULASC+26
	00509A	1A6D	FF 1769	A	STX	FULTBA
	00510A	1A70	20 1B 1A8D		BRA	REC580
	00511					*
	00512A	1A72	81 28	A	REC550 CMP A	#\$28 * +
	00513A	1A74	26 08 1A7E		BNE	REC560
	00514A	1A76	CE 1DD2	A	LDX	#FULASC+52
	00515A	1A79	FF 1769	A	STX	FULTBA
	00516A	1A7C	20 0F 1A8D		BRA	REC580
	00517					*
	00518A	1A7E	81 25	A	REC560 CMP A	#\$25 * %
	00519A	1A80	27 05 1A87		BEQ	REC570
	00520A	1A82	7F 175B	A	CLR	FULHNT
	00521A	1A85	2C 3F 1AC6		BRA	REC610
	00522					*
	00523A	1A87	CE 1DEC	A	REC570 LDX	#FULASC+78 * %
	00524A	1A8A	FF 1769	A	STX	FULTBA
	00525					*
	00526A	1A8D	B6 17B3	A	REC580 LDA A	ANSCNT * SOURCE DATA END CHECK
	00527A	1A90	B1 00	A	CMP A	#0
	00528A	1A92	2F 32 1AC6		BLE	REC610 * END DATA ENTRY
	00529					*
	00530A	1A94	FE 1765	A	LDX	ANSADR * NEXT DATA PRE-READ
	00531A	1A97	A6 00	A	LDA A	,X
	00532A	1A99	B7 175D	A	STA A	ASCBF2
	00533A	1A9C	08		INX	
	00534A	1A9D	FF 1765	A	STX	ANSADR * NEXT SOURCE ADDRESS
	00535					*
	00536A	1AA0	B1 41	A	CMP A	#\$41 * ALPHA ?

SEQ	LOC	OBJECT	PROGRAM	BARCOD	RECOGNITION
00537A	1AA2	25 1D 1AC1		BCS	REC600
00538			*		
00539A	1AA4	80 41 A		SUB A	#\$41
00540A	1AA6	16		TAB	
00541A	1AA7	7F 175B A		CLR	FULHNT
00542A	1AAA	FE 1769 A		LDX	FULTBA
00543A	1AAD	3A		ABX	* DATA ADDRESS
00544			*		
00545A	1AAE	A6 00 A		LDA A	,X * CONVERSION DATA
00546A	1AB0	81 FF A		CMP A	#\$FF
00547A	1AB2	26 08 1ABC		BNE	REC590
00548			*		
00549A	1AB4	86 68 A		LDA A	#107 * FULL ASCII ERROR
00550A	1AB6	B7 175F A		STA A	ERRBF
00551A	1AB9	7E 180F A		JMP	REC700
00552			*		
00553A	1ABC	7A 17B3 A	REC590	DEC	ANSCNT * SOURCE COUNTER DECREMENT
00554A	1ABF	20 08 1AC9		BRA	REC620
00555			*		
00556A	1AC1	86 01 A	REC600	LDA A	#1 * SINGLE DATA FLAG SET
00557A	1AC3	B7 175B A		STA A	FULHNT
00558			*		
00559A	1AC6	B6 175C A	REC610	LDA A	ASCBF1 * PRE-READ DATA
00560			*		
00561A	1AC9	FE 1767 A	REC620	LDX	ANSASA * FULL ASCII ENTRY
00562A	1ACC	A7 00 A		STA A	,X
00563A	1ACE	08		INX	* DESTINATION NEXT ADDRESS
00564A	1ACF	FF 1767 A		STX	ANSASA
00565A	1AD2	7C 17FC A		INC	ASCCNT * DESTINATION COUNTER RENEW
00566A	1AD5	7E 1A37 A		JMP	REC510
00567			*		
00568				TTL	SUBROUTIN
00569			*		
00570			*		
00571			*	FUNCTION :	BAR OR SPACE WIDTH TIMER VALUE READ
00572			*	CALL :	JSR TIMRED
00573			*	RETURN :	(C)= RETURN STATUS
00574			*		0: NORMAL
00575			*		1: OVER FLOW
00576			*		TIMCNT= TIMER VALUE
00577			*		
00578			*		
00579A	1AD8	96 08 A	TIMRED	LDA A	TCSR * TIMER CONTROLL STATUS REGISTER
00580A	1ADA	85 40 A		BIT A	#\$40 * OVER FLOW CHECK
00581A	1ADC	26 24 1B02		BNE	TIM100
00582A	1ADE	85 80 A		BIT A	#\$80 * ICF CHECK
00583A	1AED	27 F6 1AD8		BEQ	TIMRED
00584			*		
00585A	1AE2	DC 0D A		LDD	ICR * TIMER READ
00586A	1AE4	FD 1744 A		STD	TIMCT2
00587A	1AE7	B3 1742 A		SUBD	TIMCT1
00588A	1AEA	FD 1746 A		STD	TIMCNT * TIMER VALUE ENTRY
00589			*		
00590A	1AED	FC 1744 A		LDD	TIMCT2 * START VALUE RENEW
00591A	1AF0	FD 1742 A		STD	TIMCT1

ERR	SEG	LOC	OBJECT	PROGRAM	BARCOD	SUBROUTIN
		00592				*
		00593A	1AF3 C3 C350 A		ADDD	#OVRVAL * OVER FLOW COUNTER SET
		00594A	1AF6 DD 0B A		STD	OCR
		00595A	1AF8 96 08 A		LDA A	TCSR
		00596A	1AFA 72 A		FCB	\$72,\$00,\$0B * OIM # \$00,OCR
			A 1AFB 00 A			
			A 1AFC 0B A			
		00597				*
		00598A	1AFD 75 A		FCB	\$75,\$02,\$08 * EIM #2 TCSR * EDGE CONVERT
			A 1AFE 02 A			
			A 1AFF 08 A			
		00599A	1B00 0C		CLC	* CARRY CLEAR
		00600				*
		00601A	1B01 39	TIM900	RTS	* RETURN
		00602				*
		00603A	1B02 CC FFFF A	TIM10D	LDD	# \$FFFF * OVER FLOW
		00604A	1B05 FD 1746 A		STD	TIMCNT
		00605A	1B08 0D		SEC	* (C) SET
		00606A	1B09 20 F6 1B01		BRA	TIM900
		00607				*
		00608				*
		00609				* FUNCTION : BAR DATA READ AND BIT CONVERT
		00610			CALL	: JSR DTT0BT
		00611				(A)= BIT NUMBER
		00612			RETURN	: (A)= RETURN STATUS
		00613				D: NORMAL
		00614				100: SCAN SPEED SLOWER
		00615				101: SCAN SPEED FASTER
		00616				BAR = BAR BIT ANSWER
		00617				SPACE = SPACE BIT ANSWER
		00618				*
		00619				*
		00620A	1B0B B7 175E A	DTT0BT	STA A	BITCNT * BIT COUNTER
		00621A	1B0E 7F 173A A		CLR	BAR
		00622A	1B11 7F 173B A		CLR	SPACE
		00623				*
		00624A	1B14 B6 175E A	DTT1D	LDA A	BITCNT * BIT END CHECK
		00625A	1B17 26 05 1B1E		BNE	DTT20
		00626				*
		00627A	1B19 7C 1783 A		INC	ANSCNT * END ENTRY CHARACTER RENEW
		00628A	1B1C 4F		CLR A	* NORMAL RETURN
		00629				*
		00630A	1B1D 39	DTT90D	RTS	* RETURN
		00631				*
		00632A	1B1E B6 175E A	DTT2D	LDA A	BITCNT * BAR , SPACE CHECK
		00633A	1B21 85 01 A		BIT A	# \$1
		00634A	1B23 26 05 1B2A		BNE	DTT3D
		00635A	1B25 78 173B A		ASL	SPACE * WHEN SPACE
		00636A	1B28 20 03 1B2D		BRA	DTT4D
		00637				*
		00638A	1B2A 78 173A A	DTT3D	ASL	BAR * WHEN BAR
		00639				*
		00640A	1B2D BD 1AD8 A	DTT4D	JSR	TIMRED * WIDTH READ
		00641				*
		00642A	1B30 24 04 1B36		BCC	DTT5D

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	SUBROUTIN
	00643					*
	00644A	1832	86 64	A	LDA A #100	* SCAN SPEED SLOWER ERROR
	00645A	1834	20 E7 181D		BRA DTT900	
	00646					*
	00647A	1836	FC 1746	A	DTT50 LDD TIMCNT	
	00648A	1839	83 0076	A	SUBD #MINVAL	* 118 SPEED OVER CHECK
	00649A	183C	24 04 1842		BCC DTT60	
	00650					*
	00651A	183E	86 65	A	LDA A #101	* SCAN SPEED FASTER
	00652A	1840	20 DB 181D		BRA DTT900	
	00653					*
	00654A	1842	86 175E	A	DTT60 LDA A BITCNT	
	00655A	1845	85 01	A	BIT A #51	* BAR OR SPACE CHECK
	00656A	1847	26 2E 1877		BNE DTT80	* BAR
	00657					*
	00658				***** SPACE *****	
	00659					*
	00660A	1849	FC 1746	A	LDD TIMCNT	
	00661A	184C	B3 1758	A	SUBD THRSHS	* COMPARE WITH SPACE THRESH
	00662A	184F	22 0F 1860		BHI DTT70	
	00663					*
	00664A	1851	FC 1746	A	LDD TIMCNT	* WHEN SPACE 0
	00665A	1854	FD 1754	A	STD ZNKSZC	* LAST SPACE ZERO COUNTER ENTRY
	00666A	1857	F3 1756	A	ADDD ZNKSOC	
	00667A	185A	04		LSRD	* / 2
	00668A	185B	FD 1758	A	STD THRSHS	* NEW SPACE THRESH
	00669A	185E	20 43 18A3		BRA DTT110	
	00670					*
	00671A	1860	FC 1746	A	DTT70 LDD TIMCNT	* WHEN SPACE 1
	00672A	1863	FD 1756	A	STD ZNKSOC	* LAST SPACE ONE COUNTER ENTRY
	00673A	1866	F3 1754	A	ADDD ZNKSZC	
	00674A	1869	04		LSRD	* / 2
	00675A	186A	FD 1758	A	STD THRSHS	* NEW SPACE THRESH
	00676					*
	00677A	186D	36 1738	A	LDA A SPACE	* SPACE BIT SET
	00678A	1870	8A 01	A	ORA A #1	
	00679A	1872	B7 1738	A	STA A SPACE	
	00680A	1875	20 2C 18A3		BRA DTT110	
	00681					*
	00682				***** BAR *****	
	00683					*
	00684A	1877	FC 1746	A	DTT80 LDD TIMCNT	
	00685A	187A	B3 1752	A	SUBD THRSBH	* COMPARE WITH BAR THRESH
	00686A	187D	22 0F 188E		BHI DTT90	*
	00687					*
	00688A	187F	FC 1746	A	LDD TIMCNT	* WHEN BAR 0
	00689A	1882	FD 174E	A	STD ZNKBZC	* LAST BAR ZERO COUNTER ENTRY
	00690A	1885	F3 1750	A	ADDD ZNK20C	
	00691A	1888	04		LSRD	* / 2
	00692A	1889	FD 1752	A	STD THRSBH	* NEW BAR THRESH
	00693A	188C	20 15 18A3		BRA DTT110	
	00694					*
	00695A	188E	FC 1746	A	DTT90 LDD TIMCNT	* WHEN BAR 1
	00696A	1891	FD 1750	A	STD ZNKBOC	* LAST BAR ONE COUNTER ENTRY
	00697A	1894	F3 174E	A	ADDD ZNKBZC	

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	SUBROUTIN
	00698A	1B97	04		LSRD	* / 2
	00699A	1B98	FD 1752	A	STD THRSB	* NEW BAR THRESH
	00700				*	
	00701A	1B9B	B6 173A	A	LDA A BAR	* BAR BIT SET
	00702A	1B9E	8A 01	A	ORA A #1	
	00703A	1BA0	B7 173A	A	STA A BAR	
	00704				*	
	00705A	1BA3	7A 175E	A	DTT110 DEC	BITCNT
	00706A	1BA6	7E 1B14	A	JMP	DTT10
	00707				*	
	00708				*	
	00709				* FUNCTION :	OK BEEP ON
	00710				* CALL :	JSR BEEPOK
	00711				* RETURN :	(C)= BREAK STATUS
	00712				*	0: NORMAL
	00713				*	1: BREAK
	00714				*	
	00715				*	
	00716A	1BA9	BD 1C53	A	BEEPOK JSR	SRWINT * SLAVE SUPER VISOR MASK OPEN
	00717				*	
	00718A	1BAC	86 30	A	LDA A #S30	* SLAVE BEEP COMMAND
	00719A	1BAE	BD FF19	A	JSR	SNSCOM
	00720				*	
	00721A	1BB1	86 1C	A	LDA A #S1C	* SOUND LEVEL
	00722A	1BB3	BD FF19	A	JSR	SNSCOM
	00723				*	
	00724A	1BB6	86 01	A	LDA A #S1	* SOUND LENGTH
	00725A	1BB8	BD FF19	A	JSR	SNSCOM
	00726				*	
	00727A	1BBB	25 03 1BCD		BCS	BEP900
	00728A	1BBD	BD FF16	A	JSR	RV232C * SLAVE COMMUNICATION INITIAL
	00729				*	
	00730A	1BC0	39		BEP900 RTS	
	00731				*	
	00732				*	
	00733				* FUNCTION :	CHECK DIGIT CALCULATE
	00734				* CALL :	JSR DGTCAL
	00735				*	SUMCHK,+1=CHECK DIGIT SUM AREA
	00736				* RETURN :	(A)= CHECK DIGIT
	00737				*	
	00738				*	
	00739A	1BC1	FC 174C	A	DGTCAL LDD	SUMCHK * SUM CHECK
	00740A	1BC4	83 0D2B	A	SUBD	#43
	00741A	1BC7	25 05 1BCE		BCS	DGT10
	00742				*	
	00743A	1BC9	FD 174C	A	STD	SUMCHK
	00744A	1BCC	20 F3 1BC1		BRA	DGTCAL
	00745				*	
	00746A	1BCE	C3 002B	A	DGT10 ADDD	#43
	00747A	1BD1	17		TBA	* REST (B) TO (A)
	00748A	1BD2	39		RTS	
	00749				*	
	00750				TTL	I/O SUBROUTINE
	00751				*	
	00752				*	

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	I/O	SUBROUTINE
	00753						* FUNCTION : BARCODE WAND POWER ON
	00754						* CALL : JSR PONBAR
	00755						* RETURN : (C)= RETURN STATUS
	00756						* 0: NORMAL
	00757						* 1: BREAK
	00758						*
	00759						*
	00760A	18D3	86 20 A	PONBAR	LDA A #S20		* BARCODE WAND POWER ON
	00761A	18D5	C6 06 A		LDA B #PORT3		
	00762A	18D7	BD 1C0D A		JSR SPWRIT		
	00763						*
	00764A	18DA	25 06 18E2		BCS PON900		* BREAK CHECK
	00765A	18DC	72 A		FCB \$72,\$40,\$7C		* OIM #S40 SIOSTS * POWER ON STATUS
		A 18DD	40 A				
		A 18DE	7C A				
	00766						*
	00767A	18DF	BD FF16 A		JSR RV232C		* SLAVE RS232C RECOVERY
	00768						*
	00769A	18E2	39		PON900 RTS		* RETURN
	00770						*
	00771						*
	00772						* FUNCTION : BARCODE WAND POWER OFF
	00773						* CALL : (C)= RETURN STATUS
	00774						* 0: NORMAL
	00775						* 1: BREAK
	00776						*
	00777						*
	00778A	18E3	86 20 A	POFBAR	LDA A #S20		* BARCODE WAND POWER OFF
	00779A	18E5	C6 06 A		LDA B #PORT3		
	00780A	18E7	CA 80 A		ORA B #S80		
	00781A	18E9	BD 1C0D A		JSR SPWRIT		
	00782						*
	00783A	18EC	25 06 18F4		BCS POF900		* BREAK CHECK
	00784A	18EE	71 A		FCB \$71,\$BF,\$7C		* AIM #S8F SIOSTS * POWER ON STATUS
		A 18EF	8F A				
		A 18F0	7C A				
	00785						*
	00786A	18F1	BD FF16 A		JSR RV232C		* SLAVE RS232C RECOVERY
	00787						*
	00788A	18F4	39		POF900 RTS		* RETURN
	00789						*
	00790						*
	00791						* FUNCTION : SLAVE PORT READ
	00792						* CALL : JSR SPREAD
	00793						* (B)= PORT ADDRESS
	00794						* RETURN : (A)= READ DATA
	00795						* (C)= RETURN STATUS
	00796						* 0: NORMAL
	00797						* 1: BREAK
	00798						*
	00799						*
	00800A	18F5	BD 1C53 A	SPREAD	JSR SRWINT		* SLAVE COMMUNICATION INITIAL
	00801A	18F8	25 12 1C0C		BCS SPR900		* ERROR
	00802						*
	00803A	18FA	86 05 A		LDA A #5		* READ COMMMAND

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	I/O	SUBROUTINE
	00804A	1BFC	BD FF19 A			JSR	SNSCOM
	00805			*			
	00806A	1BFF	4F			CLR A	* PORT ADDRESS (H)
	00807A	1C00	BD FF19 A			JSR	SNSCOM
	00808			*			
	00809A	1C03	17			TBA	* PORT ADDRESS (L)
	00810A	1C04	BD FF19 A			JSR	SNSCOM
	00811A	1C07	25 03 1C0C			BCS	SPR900 * ERROR
	00812			*			
	00813A	1C09	BD FF16 A			JSR	RV232C * SLAVE RS232C RECOVERY
	00814			*			
	00815A	1C0C	39			SPR900 RTS	* RETURN
	00816			*			
	00817			*			
	00818			*			
	00819			*			
	00820			*			
	00821			*			
	00822			*			
	00823			*			
	00824			*			
	00825			*			
	00826			*			
	00827A	1C0D	FD 1761 A			SPWRIT STD	SPWRBF * DATA SAVE
	00828A	1C10	C4 7F A			AND B #57F	* PORT ADDRESS
	00829			*			
	00830A	1C12	BD 1BF5 A			JSR	SPREAD * PORT STATUS READ
	00831A	1C15	25 3B 1C52			BCS	SPW900 * ERROR
	00832A	1C17	36			PSH A	* DATA SAVE
	00833			*			
	00834A	1C18	B6 1762 A			LDA A	SPWRBF+1
	00835A	1C1B	2B 11 1C2E			BMI	SPWR10
	00836			*			
	00837A	1C1D	B6 1761 A			LDA A	SPWRBF * DATA RESET
	00838A	1C20	38 FF A			EOR A #5FF	
	00839A	1C22	B7 1761 A			STA A	SPWRBF * DATA INVERT
	00840			*			
	00841A	1C25	32			PUL A	
	00842A	1C26	B4 1761 A			AND A	SPWRBF * OUT DATA
	00843A	1C29	B7 1761 A			STA A	SPWRBF
	00844A	1C2C	20 07 1C35			BRA	SPWR20
	00845			*			
	00846A	1C2E	32			SPWR10 PUL A	* DATA SET
	00847A	1C2F	BA 1761 A			ORA A	SPWRBF * OUT DATA
	00848A	1C32	B7 1761 A			STA A	SPWRBF
	00849			*			
	00850A	1C35	BD 1C53 A			SPWR20 JSR	SRWINT * SLAVE COMMUNICATION INITIAL
	00851A	1C38	25 18 1C52			BCS	SPW900 * ERROR
	00852			*			
	00853A	1C3A	B6 06 A			LDA A #6	* WRITE COMMAND
	00854A	1C3C	BD FF19 A			JSR	SNSCOM
	00855			*			
	00856A	1C3F	4F			CLR A	* PORT ADDRESS (H)
	00857A	1C40	BD FF19 A			JSR	SNSCOM
	00858			*			

ERR

SEQ	LOC	OBJECT	PROGRAM	BARCOD	I/O	SUBROUTINE
00859A	1C43	17		TBA		* PORT ADDRESS (L)
00860A	1C44	BD FF19	A	JSR	SNSCOM	
00861				*		
00862A	1C47	B6 1761	A	LDA A	SPWR8F	* DATA OUTPUT
00863A	1C4A	BD FF19	A	JSR	SNSCOM	
00864A	1C4D	25 03 1C52		BCS	SPW900	* ERROR
00865				*		
00866A	1C4F	BD FF16	A	JSR	RV232C	* SLAVE RS232C RECOVERY
00867				*		
00868A	1C52	39		SPW900	RTS	* RETURN
00869				*		
00870				*		
00871				*	FUNCTION :	SLAVE COMMUNICATION INITIAL
00872				*	CALL :	JSR SRWINT
00873				*	RETURN :	(C)= RETURN STATUS
00874				*		0: NORMAL
00875				*		1: BREAK
00876				*		
00877				*		
00878A	1C53	86 03	A	SRWINT LDA A	#3	* SLAVE SUPER VISOR MASK OPEN
00879A	1C55	BD FF19	A	JSR	SNSCOM	
00880				*		
00881A	1C58	86 AA	A	LDA A	#\$AA	
00882A	1C5A	BD FF19	A	JSR	SNSCOM	
00883				*		
00884A	1C5D	39		RTS		* RETURN
00885				*		
00886				*	TTL	SPACE TABLE
00887				*		
00888				*		
00889				*		
00890				*	SPACE TABLE	
00891				*		
00892				*		
00893				*		
00894A	1C5E	0000	A	SPCT3L FDB	0,0	* 0000 ERROR
	A 1C60	0000	A			
00895				*		
00896A	1C62	1C9E	A	FDB	BARTBL	* 0001 L TO R
00897A	1C64	1D7E	A	FDB	BARTBL+\$E0	* 1C00 R TO L
00898				*		
00899A	1C66	1CDE	A	FDB	BARTBL+\$40	* 0010 L TO R
00900A	1C68	1D3E	A	FDB	BARTBL+\$A0	* 0100 R TO L
00901				*		
00902A	1C6A	0000	A	FDB	0,0	* 0011 ERROR
	A 1C6C	0000	A			
00903				*		
00904A	1C6E	1D1E	A	FDB	BARTBL+\$80	* 0100 L TO R
00905A	1C70	1CFE	A	FDB	BARTBL+\$60	* 0010 R TO L
00906				*		
00907A	1C72	0000	A	FDB	0,0	* 0101 ERROR
	A 1C74	0000	A			
00908				*		
00909A	1C76	0000	A	FDB	0,0	* 0110 ERROR
	A 1C78	0000	A			

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	SPACE	TABLE
	00910			*			
	00911A	1C7A	A5 A		FCB \$A5	* 0111	L TO R % CODE
	00912A	1C7B	2A A		FCB \$2A	*	% DIGIT
	00913A	1C7C	A4 A		FCB \$A4	*	R TO L \$ CODE
	00914A	1C7D	27 A		FCB \$27	*	\$ DIGIT
	00915			*			
	00916A	1C7E	1D5E A		FDB BARTBL+\$C0	* 1000	L TO R
	00917A	1C80	1CBE A		FDB BARTBL+\$20	* 0001	R TO L
	00918			*			
	00919A	1C82	0000 A		FDB 0,0	* 1001	ERROR
		A 1C84	0000 A				
	00920			*			
	00921A	1C86	0000 A		FDB 0,0	* 1010	ERROR
		A 1C88	0000 A				
	00922			*			
	00923A	1C8A	AB A		FCB \$AB	* 1011	L TO R + CODE
	00924A	1C8B	29 A		FCB \$29	*	+ DIGIT
	00925A	1C8C	AF A		FCB \$AF	*	R TO L / CODE
	00926A	1C8D	28 A		FCB \$28	*	/ DIGIT
	00927			*			
	00928A	1C8E	0000 A		FDB 0,0	* 1100	ERROR
		A 1C90	0000 A				
	00929			*			
	00930A	1C92	AF A		FCB \$AF	* 1110	L TO R / CODE
	00931A	1C93	28 A		FCB \$28	*	/ DIGIT
	00932A	1C94	AB A		FCB \$AB	*	R TO L + CODE
	00933A	1C95	29 A		FCB \$29	*	+ DIGIT
	00934			*			
	00935A	1C96	A4 A		FCB \$A4	* 1110	L TO R \$ CODE
	00936A	1C97	27 A		FCB \$27	*	\$ DIGIT
	00937A	1C98	A5 A		FCB \$A5	*	R TO L % CODE
	00938A	1C99	2A A		FCB \$2A	*	% DIGIT
	00939			*			
	00940A	1C9A	0000 A		FDB 0,0	* 1111	ERROR
		A 1C9C	0000 A				
	00941			*			
	00942				TTL		BAR TABLE
	00943			*			
	00944			*			
	00945			*			
	00946			*			
	00947			*			
	00948			*			
	00949			*			
	00950A	1C9E	00 A		BARTBL FCB 0,0,0	* SPACE=0001	L TO R
		A 1C9F	00 A				
		A 1CA0	00 A				
	00951A	1CA1	51 A		FCB \$51	* Q	
	00952A	1CA2	00 A		FCB 0		
	00953A	1CA3	4E A		FCB \$4E	* N	
	00954A	1CA4	54 A		FCB \$54	* T	
	00955A	1CA5	00 A		FCB 0,0		
		A 1CA6	00 A				
	00956A	1CA7	4C A		FCB \$4C	* L	
	00957A	1CA8	53 A		FCB \$53	* S	

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	BAR	TABLE
	00958A	1CA9	00	A	FCB	0	
	00959A	1CAA	50	A	FCB	\$50	* P
	00960A	1CAB	00	A	FCB	0,0,0,0	
		A 1CAC	00	A			
		A 1CAD	00	A			
		A 1CAE	00	A			
	00961A	1CAF	4B	A	FCB	\$4B	* K
	00962A	1CB0	52	A	FCB	\$52	* R
	00963A	1CB1	00	A	FCB	0	
	00964A	1CB2	4F	A	FCB	\$4F	* O
	00965A	1CB3	00	A	FCB	0,0,0	
		A 1CB4	00	A			
		A 1CB5	00	A			
	00966A	1CB6	4D	A	FCB	\$4D	* M
	00967A	1CB7	00	A	FCB	0,0,0,0,0,0,0	
		A 1CB8	00	A			
		A 1CB9	00	A			
		A 1CBA	00	A			
		A 1CBB	00	A			
		A 1CBC	00	A			
		A 1CBD	00	A			
	00968						*
	00969A	1CBE	00	A	FCB	0,0,0	* SPACE=0001 R TO L
		A 1CBF	00	A			
		A 1CC0	00	A			
	00970A	1CC1	4D	A	FCB	\$4D	* M
	00971A	1CC2	00	A	FCB	0	
	00972A	1CC3	4F	A	FCB	\$4F	* O
	00973A	1CC4	50	A	FCB	\$50	* P
	00974A	1CC5	00	A	FCB	0,0	
		A 1CC6	00	A			
	00975A	1CC7	52	A	FCB	\$52	* R
	00976A	1CC8	53	A	FCB	\$53	* S
	00977A	1CC9	00	A	FCB	0	
	00978A	1CCA	54	A	FCB	\$54	* T
	00979A	1CCB	00	A	FCB	0,0,0,0	
		A 1CCC	00	A			
		A 1CCD	00	A			
		A 1CCE	00	A			
	00980A	1CCF	4B	A	FCB	\$4B	* K
	00981A	1CD0	4C	A	FCB	\$4C	* L
	00982A	1CD1	00	A	FCB	0	
	00983A	1CD2	4E	A	FCB	\$4E	* N
	00984A	1CD3	00	A	FCB	0,0,0	
		A 1CD4	00	A			
		A 1CD5	00	A			
	00985A	1CD6	51	A	FCB	\$51	* Q
	00986A	1CD7	00	A	FCB	0,0,0,0,0,0,0	
		A 1CD8	00	A			
		A 1CD9	00	A			
		A 1CDA	00	A			
		A 1CDB	00	A			
		A 1CDC	00	A			
		A 1CDD	00	A			
	00987						*

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	BAR	TABLE
	00988A	1CDE	00	A		FCB	0,0,0 * SPACE= 0010 L TO R
		A 1CDF	00	A			
		A 1CED	00	A			
	00989A	1CE1	47	A		FCB	\$47 * G
	00990A	1CE2	00	A		FCB	0
	00991A	1CE3	44	A		FCB	\$44 * D
	00992A	1CE4	4A	A		FCB	\$4A * J
	00993A	1CE5	00	A		FCB	0,0
		A 1CE6	00	A			
	00994A	1CE7	42	A		FCB	\$42 * B
	00995A	1CE8	49	A		FCB	\$49 * I
	00996A	1CE9	00	A		FCB	0
	00997A	1CEA	46	A		FCB	\$46 * F
	00998A	1CEB	00	A		FCB	0,0,0,0
		A 1CEC	00	A			
		A 1CED	00	A			
		A 1CEE	00	A			
	00999A	1CEF	41	A		FCB	\$41 * A
	01000A	1CF0	48	A		FCB	\$48 * H
	01001A	1CF1	00	A		FCB	0
	01002A	1CF2	45	A		FCB	\$45 * E
	01003A	1CF3	00	A		FCB	0,0,0
		A 1CF4	00	A			
		A 1CF5	00	A			
	01004A	1CF6	43	A		FCB	\$43 * C
	01005A	1CF7	00	A		FCB	0,0,0,0,0,0,0
		A 1CF8	00	A			
		A 1CF9	00	A			
		A 1CFA	00	A			
		A 1CFB	00	A			
		A 1CFC	00	A			
		A 1CFD	00	A			
	01006				*		
	01007A	1CFE	00	A		FCB	0,0,0 * SPACE=0010 R TO L
		A 1CFF	00	A			
		A 1D00	00	A			
	01008A	1D01	43	A		FCB	\$43 * C
	01009A	1D02	00	A		FCB	0
	01010A	1D03	45	A		FCB	\$45 * E
	01011A	1D04	46	A		FCB	\$46 * F
	01012A	1D05	00	A		FCB	0,0
		A 1D06	00	A			
	01013A	1D07	48	A		FCB	\$48 * H
	01014A	1D08	49	A		FCB	\$49 * I
	01015A	1D09	00	A		FCB	0
	01016A	1D0A	4A	A		FCB	\$4A * J
	01017A	1D0B	00	A		FCB	0,0,0,0
		A 1D0C	00	A			
		A 1D0D	00	A			
		A 1D0E	00	A			
	01018A	1D0F	41	A		FCB	\$41 * A
	01019A	1D10	42	A		FCB	\$42 * B
	01020A	1D11	00	A		FCB	0
	01021A	1D12	44	A		FCB	\$44 * D
	01022A	1D13	00	A		FCB	0,0,0

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	BAR	TABLE
	A	1D14	00	A			
	A	1D15	00	A			
01023A	1D16	47	A		FCB	\$47	* G
01024A	1D17	00	A		FCB	0,0,0,0,0,0,0	
	A	1D18	00	A			
	A	1D19	00	A			
	A	1D1A	00	A			
	A	1D1B	00	A			
	A	1D1C	00	A			
	A	1D1D	00	A			
01025							
01026A	1D1E	00	A	*	FCB	0,0,0	* SPACE=0100 L TO R
	A	1D1F	00	A			
	A	1D20	00	A			
01027A	1D21	37	A		FCB	\$37	* 7
01028A	1D22	00	A		FCB	0	
01029A	1D23	34	A		FCB	\$34	* 4
01030A	1D24	30	A		FCB	\$30	* 0
01031A	1D25	00	A		FCB	0,0	
	A	1D26	00	A			
01032A	1D27	32	A		FCB	\$32	* 2
01033A	1D28	39	A		FCB	\$39	* 9
01034A	1D29	00	A		FCB	0	
01035A	1D2A	36	A		FCB	\$36	* 6
01036A	1D2B	00	A		FCB	0,0,0,0	
	A	1D2C	00	A			
	A	1D2D	00	A			
	A	1D2E	00	A			
01037A	1D2F	31	A		FCB	\$31	* 1
01038A	1D30	38	A		FCB	\$38	* 8
01039A	1D31	00	A		FCB	0	
01040A	1D32	35	A		FCB	\$35	* 5
01041A	1D33	00	A		FCB	0,0,0	
	A	1D34	00	A			
	A	1D35	00	A			
01042A	1D36	33	A		FCB	\$33	* 3
01043A	1D37	00	A		FCB	0,0,0,0,0,0,0	
	A	1D38	00	A			
	A	1D39	00	A			
	A	1D3A	00	A			
	A	1D3B	00	A			
	A	1D3C	00	A			
	A	1D3D	00	A			
01044							
01045A	1D3E	00	A	*	FCB	0,0,0	* SPACE= 0100 R TO L
	A	1D3F	00	A			
	A	1D40	00	A			
01046A	1D41	33	A		FCB	\$33	* 3
01047A	1D42	00	A		FCB	0	
01048A	1D43	35	A		FCB	\$35	* 5
01049A	1D44	36	A		FCB	\$36	* 6
01050A	1D45	00	A		FCB	0,0	
	A	1D46	00	A			
01051A	1D47	38	A		FCB	\$38	* 8
01052A	1D48	39	A		FCB	\$39	* 9

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	BAR	TABLE
	01053A	1D49	00	A	FCB	0	
	01054A	1D4A	30	A	FCB	\$30	* 0
	01055A	1D4B	00	A	FCB	0,0,0,0	
		A 1D4C	00	A			
		A 1D4D	00	A			
		A 1D4E	00	A			
	01056A	1D4F	31	A	FCB	\$31	* 1
	01057A	1D50	32	A	FCB	\$32	* 2
	01058A	1D51	00	A	FCB	0	
	01059A	1D52	34	A	FCB	\$34	* 4
	01060A	1D53	00	A	FCB	0,0,0	
		A 1D54	00	A			
		A 1D55	00	A			
	01061A	1D56	37	A	FCB	\$37	* 7
	01062A	1D57	00	A	FCB	0,0,0,0,0,0,0	
		A 1D58	00	A			
		A 1D59	00	A			
		A 1D5A	00	A			
		A 1D5B	00	A			
		A 1D5C	00	A			
		A 1D5D	00	A			
	01063				*		
	01064A	1D5E	00	A	FCB	0,0,0	* SPACE=1000 L TO R
		A 1D5F	00	A			
		A 1D60	00	A			
	01065A	1D61	2D	A	FCB	\$2D	* -
	01066A	1D62	00	A	FCB	0	
	01067A	1D63	58	A	FCB	\$58	* X
	01068A	1D64	2A	A	FCB	\$2A	* *
	01069A	1D65	00	A	FCB	0,0	
		A 1D66	00	A			
	01070A	1D67	56	A	FCB	\$56	* V
	01071A	1D68	20	A	FCB	\$20	* SP
	01072A	1D69	00	A	FCB	0	
	01073A	1D6A	5A	A	FCB	\$5A	* Z
	01074A	1D6B	00	A	FCB	0,0,0,0	
		A 1D6C	00	A			
		A 1D6D	00	A			
		A 1D6E	00	A			
	01075A	1D6F	55	A	FCB	\$55	
	01076A	1D70	2E	A	FCB	\$2E	* .
	01077A	1D71	00	A	FCB	0	
	01078A	1D72	59	A	FCB	\$59	* Y
	01079A	1D73	00	A	FCB	0,0,0	
		A 1D74	00	A			
		A 1D75	00	A			
	01080A	1D76	57	A	FCB	\$57	* W
	01081A	1D77	00	A	FCB	0,0,0,0,0,0,0	
		A 1D78	00	A			
		A 1D79	00	A			
		A 1D7A	00	A			
		A 1D7B	00	A			
		A 1D7C	00	A			
		A 1D7D	00	A			
	01082				*		

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	BAR	TABLE
	01083A	1D7E	00	A	FCB	0,0,0	* SPACE=1000 R TO L
	A	1D7F	00	A			
	A	1D80	00	A			
	01084A	1D81	57	A	FCB	\$57	* W
	01085A	1D82	00	A	FCB	0	
	01086A	1D83	59	A	FCB	\$59	* Y
	01087A	1D84	5A	A	FCB	\$5A	* Z
	01088A	1D85	00	A	FCB	0,0	
	A	1D86	00	A			
	01089A	1D87	2E	A	FCB	\$2E	* .
	01090A	1D88	20	A	FCB	\$20	* SP
	01091A	1D89	00	A	FCB	0	
	01092A	1D8A	2A	A	FCB	\$2A	* *
	01093A	1D8B	00	A	FCB	0,0,0,0	
	A	1D8C	00	A			
	A	1D8D	00	A			
	A	1D8E	00	A			
	01094A	1D8F	55	A	FCB	\$55	* U
	01095A	1D90	56	A	FCB	\$56	* V
	01096A	1D91	00	A	FCB	0	
	01097A	1D92	58	A	FCB	\$58	* X
	01098A	1D93	00	A	FCB	0,0,0	
	A	1D94	00	A			
	A	1D95	00	A			
	01099A	1D96	2D	A	FCB	\$2D	* -
	01100A	1D97	00	A	FCB	0,0,0,0,0,0,0	
	A	1D98	00	A			
	A	1D99	00	A			
	A	1D9A	00	A			
	A	1D9B	00	A			
	A	1D9C	00	A			
	A	1D9D	00	A			
	01101						
	01102						
	01103						
	01104						
	01105						
	01106						
	01107						
	01108						
	01109						
	01110A	1D9E	01	A	FULASC FCB	\$01	* \$A= SOH
	01111A	1D9F	02	A	FCB	\$02	* \$B= STX
	01112A	1DA0	03	A	FCB	\$03	* \$C= ETX
	01113A	1DA1	04	A	FCB	\$04	* \$D= EOT
	01114A	1DA2	05	A	FCB	\$05	* \$E= ENQ
	01115A	1DA3	06	A	FCB	\$06	* \$F= ACK
	01116A	1DA4	07	A	FCB	\$07	* \$G= BEL
	01117A	1DA5	08	A	FCB	\$08	* \$H= BS
	01118A	1DA6	09	A	FCB	\$09	* \$I= HT
	01119A	1DA7	0A	A	FCB	\$0A	* \$J= LF
	01120A	1DA8	0B	A	FCB	\$0B	* \$K= VT
	01121A	1DA9	0C	A	FCB	\$0C	* \$L= FF
	01122A	1DAA	0D	A	FCB	\$0D	* \$M= CR
	01123A	1DAB	0E	A	FCB	\$0E	* \$N= SO

```

*
*           TTL      FULL ASCII TABLE
*
*
*-----*
*           FULL ASCII CONVERSION TABLE
*-----*
*
FULASC FCB      $01      * $A= SOH
FCB      $02      * $B= STX
FCB      $03      * $C= ETX
FCB      $04      * $D= EOT
FCB      $05      * $E= ENQ
FCB      $06      * $F= ACK
FCB      $07      * $G= BEL
FCB      $08      * $H= BS
FCB      $09      * $I= HT
FCB      $0A      * $J= LF
FCB      $0B      * $K= VT
FCB      $0C      * $L= FF
FCB      $0D      * $M= CR
FCB      $0E      * $N= SO

```

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	FULL ASCII TABLE
	01124A	1DAC	0F	A	FCB	\$0F * \$0= SI
	01125A	1DAD	10	A	FCB	\$10 * \$P= DLE
	01126A	1DAE	11	A	FCB	\$11 * \$Q= DC1
	01127A	1DAF	12	A	FCB	\$12 * \$R= DC2
	01128A	1DB0	13	A	FCB	\$13 * \$S= DC3
	01129A	1DB1	14	A	FCB	\$14 * \$T= DC4
	01130A	1DB2	15	A	FCB	\$15 * \$U= NAK
	01131A	1DB3	16	A	FCB	\$16 * \$V= SYN
	01132A	1DB4	17	A	FCB	\$17 * \$W= ETB
	01133A	1DB5	18	A	FCB	\$18 * \$X= CAN
	01134A	1DB6	19	A	FCB	\$19 * \$Y= EM
	01135A	1DB7	1A	A	FCB	\$1A * \$Z= SUB
	01136					
	01137A	1DB8	21	A	FCB	\$21 * /A= !
	01138A	1DB9	22	A	FCB	\$22 * /B=
	01139A	1DBA	23	A	FCB	\$23 * /C= #
	01140A	1DBB	24	A	FCB	\$24 * /D= \$
	01141A	1DBC	25	A	FCB	\$25 * /E= %
	01142A	1DBD	26	A	FCB	\$26 * /F= &
	01143A	1DBE	27	A	FCB	\$27 * /G= *
	01144A	1DBF	28	A	FCB	\$28 * /H= (
	01145A	1DC0	29	A	FCB	\$29 * /I=)
	01146A	1DC1	2A	A	FCB	\$2A * /J= *
	01147A	1DC2	2B	A	FCB	\$2B * /K= +
	01148A	1DC3	2C	A	FCB	\$2C * /L= ,
	01149A	1DC4	FF	A	FCB	\$FF * /M= - ERROR
	01150A	1DC5	FF	A	FCB	\$FF * /N= . ERROR
	01151A	1DC6	2F	A	FCB	\$2F * /O= /
	01152A	1DC7	30	A	FCB	\$30 * /P= 0
	01153A	1DC8	31	A	FCB	\$31 * /Q= 1
	01154A	1DC9	32	A	FCB	\$32 * /R= 2
	01155A	1DCA	33	A	FCB	\$33 * /S= 3
	01156A	1DCB	34	A	FCB	\$34 * /T= 4
	01157A	1DCC	35	A	FCB	\$35 * /U= 5
	01158A	1DCD	36	A	FCB	\$36 * /V= 6
	01159A	1DCE	37	A	FCB	\$37 * /W= 7
	01160A	1DCF	38	A	FCB	\$38 * /X= 8
	01161A	1DD0	39	A	FCB	\$39 * /Y= 9
	01162A	1DD1	3A	A	FCB	\$3A * /Z= :
	01163					
	01164A	1DD2	61	A	FCB	\$61 * +A= SMALL A
	01165A	1DD3	62	A	FCB	\$62 * +B= SMALL B
	01166A	1DD4	63	A	FCB	\$63 * +C= SMALL C
	01167A	1DD5	64	A	FCB	\$64 * +D= SMALL D
	01168A	1DD6	65	A	FCB	\$65 * +E= SMALL E
	01169A	1DD7	66	A	FCB	\$66 * +F= SMALL F
	01170A	1DD8	67	A	FCB	\$67 * +G= SMALL G
	01171A	1DD9	68	A	FCB	\$68 * +H= SMALL H
	01172A	1DDA	69	A	FCB	\$69 * +I= SMALL I
	01173A	1ddb	6A	A	FCB	\$6A * +J= SMALL J
	01174A	1DDC	6B	A	FCB	\$6B * +K= SMALL K
	01175A	1DDD	6C	A	FCB	\$6C * +L= SMALL L
	01176A	1DDE	6D	A	FCB	\$6D * +M= SMALL M
	01177A	1DDF	6E	A	FCB	\$6E * +N= SMALL N
	01178A	1DE0	6F	A	FCB	\$6F * +O= SMALL O

ERR	SEQ	LOC	OBJECT	PROGRAM	BARCOD	FULL ASCII TABLE
	01179A	1DE1	70	A	FCB	\$70 * +P= SMALL P
	01180A	1DE2	71	A	FCB	\$71 * +Q= SMALL Q
	01181A	1DE3	72	A	FCB	\$72 * +R= SMALL R
	01182A	1DE4	73	A	FCB	\$73 * +S= SMALL S
	01183A	1DE5	74	A	FCB	\$74 * +T= SMALL T
	01184A	1DE6	75	A	FCB	\$75 * +U= SMALL U
	01185A	1DE7	76	A	FCB	\$76 * +V= SMALL V
	01186A	1DE8	77	A	FCB	\$77 * +W= SMALL W
	01187A	1DE9	78	A	FCB	\$78 * +X= SMALL X
	01188A	1DEA	79	A	FCB	\$79 * +Y= SMALL Y
	01189A	1DEB	7A	A	FCB	\$7A * +Z= SMALL Z
	01190					
	01191A	1DEC	1B	A	FCB	\$1B * %A= ESC
	01192A	1DED	1C	A	FCB	\$1C * %B= FS
	01193A	1DEE	1D	A	FCB	\$1D * %C= GS
	01194A	1DEF	1E	A	FCB	\$1E * %D= RS
	01195A	1DF0	1F	A	FCB	\$1F * %E= US
	01196A	1DF1	3B	A	FCB	\$3B * %F= ;
	01197A	1DF2	3C	A	FCB	\$3C * %G= <
	01198A	1DF3	3D	A	FCB	\$3D * %H= =
	01199A	1DF4	3E	A	FCB	\$3E * %I= >
	01200A	1DF5	3F	A	FCB	\$3F * %J= ?
	01201A	1DF6	5B	A	FCB	\$5B * %K= LEFT SQUARE BRACKET
	01202A	1DF7	5C	A	FCB	\$5C * %L= REVERSE /
	01203A	1DF8	5D	A	FCB	\$5D * %M= RIGHT SQUARE BRACKET
	01204A	1DF9	5E	A	FCB	\$5E * %N= 0
	01205A	1DFA	5F	A	FCB	\$5F * %O= HAT
	01206A	1DFB	7B	A	FCB	\$7B * %P= LEFT KAGI KAKKO
	01207A	1DFC	7C	A	FCB	\$7C * %Q= VERTICAL DASHU
	01208A	1DFD	7D	A	FCB	\$7D * %R= RIGHT KAGI KAKKO
	01209A	1DFE	7E	A	FCB	\$7E * %S= WAVE
	01210A	1DFE	7F	A	FCB	\$7F * %T= DEL
	01211A	1E00	00	A	FCB	\$00 * %U= NUL
	01212A	1E01	40	A	FCB	\$40 * %V= @
	01213A	1E02	60	A	FCB	\$60 * %W= APOSTROPHY
	01214A	1E03	7F	A	FCB	\$7F * %X= DEL
	01215A	1E04	7F	A	FCB	\$7F * %Y= DEL
	01216A	1E05	7F	A	FCB	\$7F * %Z= DEL
	01217					
	01218	0000	A		END	
*****	TOTAL ERRORS		0			

12-30

CHAPTER 13 MISCELLANEOUS I/O

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13.1 Speaker Output

Slave MCU port 15 supplies the output to the speaker. The required square wave frequencies are obtained by dividing this signal and outputting them to the piezoelectric speaker. To obtain a 1,000Hz output at the piezoelectric speaker, the output at port 15 should be as shown in Fig. 13-1.

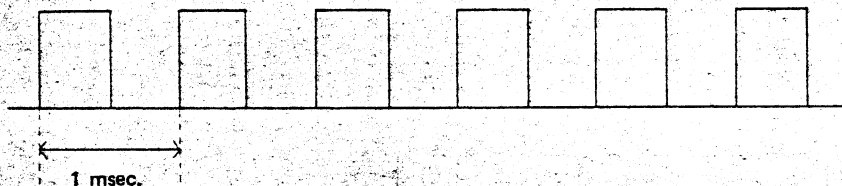


Fig. 13-1 Output to the Piezoelectric Speaker

The SOUND subroutine has been provided to specify the tone and duration of the speaker output.

13.2 Expansion Unit

The expansion unit features a 16K-byte RAM and 16K-byte ROM (only socket is provided). Addresses 0080 to 7FFF can be used as a RAM. A ROM, addresses 8000 to BFFF, may be selected by switching the HX-20 and expansion unit banks.

(1) Memory area

When the expansion unit is connected, addresses 4000 to 7FFF (16K bytes) may be used as a RAM. Data in the RAM is battery-backed up and protected. The ROM (8000-BFFF) is assigned as follows: bank 0 to the HX-20 and bank 1 to the expansion unit. Several memory configurations for the expansion unit are available. For details, refer to the hardware section of this manual.

(2) Switching ROM banks

When the ROM is mounted in the expansion unit, it is selected by switching banks. Banks are switched as follows.

(a) To select the expansion unit ROM (bank 1), access address 0030 (either input or output is fine).

(b) To select the ROM of the HX-20 (bank 0), access address 0032 or 0033 (either input or output is fine).

None of these operations will be possible if the expansion unit is not connected to the HX-20. Also, switching can be performed for ROM area of the expansion unit. The HX-20 ROM (bank 0) is automatically selected when power is turned ON or upon reset.

13.3 Clock applications

The HX-20 clocks may be classified into two types: MCU clocks and IC clocks. The ports and registers related to clocks used in the HX-20 are as follows.

MCU clocks

OCR (Output Compare Register)

- (1) Keyboard input sampling
(Uses OCR interrupt)
- (2) RS-232C output timing setting

ICR (Input Capture Register)

- (1) Barcode reader timing setting

TOF (Overflow of free running counter)

- (1) Built-in microcassette counter sampling

Real-time clock

The real-time clock uses MCU area 4E to 7F as a RAM.

(1) Use of clocks with application software

(a) OCR

An OCF interrupt is generated using OCR when a key on the keyboard is pressed. Sampling (key scanning) is then performed. Therefore, when OCR is used for this purpose, there is a strong chance that input from the keyboard will not be accepted.

A function is also provided whereby, when OCF is set, RS-232C output will be performed by outputting the value of bit 0 of TCSR to P21.

(b) TOF

Counter sampling is executed using the TOF interrupt (at approx. 0.1 sec intervals) during I/O of files by the built-in microcassette.

(c) ICR

This register is used for barcode reader input. ICR measures the interval between pulse edges. However, barcode reader input software is not supported in the basic system of the HX-20.

(d) Real-time clock

The real-time clock is normally employed only to maintain the date and time. It can therefore be used freely in various applications. Sampling may be performed at intervals ranging from 4 to 500msec. Clock registers and RAMs are allocated as shown in Table 13-1.

Table 13-1 Memory Map of Real-time Clock

sec 64

Address	Input/Output	Description
0040	I/O	Seconds
0041	I/O	Alarm (sec.)
0042	I/O	Minutes
0043	I/O	Alarm (min.)
0044	I/O	Hour
0045	I/O	Alarm (hour)
0046	I/O	Day
0047	I/O	Date
0048	I/O	Month
0049	I/O	Year
004A		Control register A
004B		Control register B
004C		Control register C
004D		Control register D
004E~007F		RAM 50 bytes

A 32.768Hz clock pulse is used as the master clock. RAM area 004E to 007F is used as an I/O flag area. Accessing this area can cause an I/O overrun.

13.4 Interrupts

MCU interrupt vectors are assigned as follows in ROM area FFEE~FFFF (Table 13-2).

Table 13-2 Interrupt Vectors

Address	Value	Description
FFEE, FFEF	0106	TRAP
FFF0, FFF1	0109	SCI interrupt

Address	Value	Description
FFF2, FFF3	010C	OCF interrupt
FFF4, FFF5	010F	OCF interrupt
FFF6, FFF7	0112	ICF interrupt
FFF8, FFF9	0115	IRQ1 (Keyboard, power supply switch, clock, voltage down and external interrupts)
FFFA, FFFB	0118	SWI
FFFC, FFFD	011B	NMI
FFFE, FFFF	E000	Reset

Addresses 0106 to 011D are RAM addresses and addresses 0100 to 0105 are used as entry points for interrupts. The initial values for addresses 0110 to 011D are stored in addresses FFB5 to FFCC (Table 13-4). Currently, 5 kinds of IRQ1 interrupts are supported.

Table 13-3: RAM Area Entry Points for Interrupt Processing

Address	Description	Initialize timing
0100~0102	'JMP XXX' command Referenced by IRQ1 interrupt routine (not supported in version 1) when IRQ1 clock interrupt is generated.	Reset (power ON)
0103~0105	'JMP XXX' command Referenced by IRQ1 interrupt routine when external IRQ1 interrupt is generated	Reset (power ON)
0106~0108	'JMP XXX' command (TRAP)	Reset (power ON)
0109~010B	'JNP XXX' command (SCI)	Reset (power ON)
010C~010E	'JNP XXX' command (TOF)	Reset (power ON)
010F~0111	'JNP XXX' command (OCF)	Reset (power ON)
0112~0114	'JNP XXX' command (ICF)	Reset (power ON)
0115~0117	'JNP XXX' command (IRQ1)	Reset (power ON)
0118~011A	Value not set (SWI)	No initialization
011B~011D	Value not set (NMI)	No initialization

Table 13-4 Initial Values for Interrupt Entry Points

Address	Description
FFB5~FFB7	'JMP XXX' command Initial values for addresses 0100 to 0102 (Entry point for clock interrupt)
FFB8~FFBA	'JMP XXX' command Initial values for addresses 0103 to 0105
FFBB~FFBD	'JMP XXX' command Initial values for addresses 0106 to 0108
FFBE~FFC0	'JMP XXX' command Initial values for addresses 0109 to 010B
FFC1~FFC3	'JMP XXX' command Initial values for addresses 010C to 010E
FFC4~FFC6	'JMP XXX' command Initial values for addresses 010F to 0111
FFC7~FFC9	'JMP XXX' command Initial values for addresses 0112 to 0114
FFCA~FFCC	'JMP XXX' command Initial values for addresses 0115 to 0117

Table 13-5 IRQ1 Interrupts

Item	Description	Interrupt confirmation	Interrupt mask
Keyboard	Interrupt is generated while a key is being pressed	P15=0	Set P264 to '0'
Battery Voltage	Interrupt is generated when the battery voltage falls below a specified level	P14=0	None
External interrupt	External bus terminal	P13=0	None
Power switch	Interrupt generated when power switch is turned OFF	P286=0	None
Real-time clock	Real-time clock interrupt is generated	One of the address 004C bits 4, 5, 6 or 7 is set to '1'.	Set address 004B bits 3, 4, 5 and 6 to '0'.

13.5 I/O Initialization and Termination

When the BREAK key is pressed, the interrupt processing routine issues a break command to the slave MCU to terminate the current I/O processing. Then bit 7 of address 007C (variable name SIOSTS) and bit 7 of address 007D (MIOSTS) are turned ON. When the bits 7 of SIOSTS and MIOSTS have been turned ON, the I/O routine assumes that I/O processing has been aborted by BREAK, sets the carry bit to logic '1' and terminates processing.

The following subroutines have been provided to initialize or restart I/O processing.

(1) I/O initialization

Subroutine INITIO initializes I/O operations. Initialization is performed for the keyboard, LCD, microprinter, cassette I/O, ROM cartridge input and RS-232C input. Variables SIOSTS and MIOSTS are cleared. The serial communication driver is not informed. An initialize command is issued to the slave MCU.

(2) I/O restart

Subroutine RSTRIO is used to restart I/O operations. Variables SIOSTS and MIOSTS are cleared. I/O flags for the external cassette, built-in microcassette, ROM cartridge and RS-232C port are also cleared. The microprinter output buffer is also cleared.

(3) Warm start initialization

Subroutine HSTRIO performs warm start initialization. The operation is identical to (1) I/O initialization, above, except that keyboard and LCD initialization are not performed.

(4) Cold start

Subroutine REQINI is provided for cold start processing. The RAM is cleared when the current date and time are entered from the keyboard. The RAM area is checked and the last address of the RAM +1 and stored in addresses 012C, 012D and 0134, 0135. From this point, the processing is the same as that when power is turned ON.

13.6 Master MCU Sleep

The master MCU may be set in the sleep mode to reduce power consumption. The master MCU is reactivated when an interrupt is generated. In the current version, the master MCU enters the sleep mode while awaiting key input. There are restriction on the sleep mode and subroutine SLEEP is called to set the master MCU in the sleep mode.

13.7 Output of Address 26 Port

The value of output port 26 is not actually read. Instead this value is set in address 004F (variable name 'P26') and the value of address 0026 can be obtained by inputting the contents of address 004F. Output of this value is performed by subroutine WRT26.

13.8 General-purpose Subroutines

Entry points have been provided for the following two general-purpose subroutines.

- (1) Subroutine HEXBIN converts an ASCII code hexadecimal number into a binary number.
- (2) Subroutine BINDEC converts an unsigned 16-bit binary number into an ASCII code decimal number.

13.9 Subroutine Table

Subroutine name	Entry Point	Description																								
SOUND	FF64	<p>Sounds the speaker</p> <hr/> <p>Parameters:</p> <p>At Entry</p> <p>(A): Tone: 00=pause, 06=440Hz, 0D=880Hz 1,2,3.... 1C:4-octave major scale (from C) 1D, 1E....38:4 octaves a half-tone higher than that for 1,2,3...IC. 39-FF : assumed to be 0</p> <p>(B): Duration: 1 specifies a duration of 0.1 sec. Duration may be specified in the range 01 to FF. Speaker is not activated when 00 is specified.</p> <p>At Return</p> <p>(C) Abnormal I/O flag</p> <p>Registers retained</p> <p>(A), (B), (X)</p> <p>Subroutines referenced</p> <p>SNSCOM, SNSCOW, CHKRS</p> <p>Variables used</p> <p>None</p>																								
SLEEP	FFA9	<p>Sets the master MCU in the sleep mode. Control is returned from the SLEEP subroutine when the sleep mode is exited.</p> <hr/> <p>Parameters:</p> <p>At Entry</p> <p>None</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>(A), (B), (C)</p> <p>Subroutines referenced</p> <p>None</p> <p>Variables used</p> <p>None</p>																								
CHKPLG	FF2E	<p>Identifies plug-in options currently connected. The value of register (A) is also stored in variable PLGSTS (address 0079).</p> <hr/> <p>Parameters:</p> <p>At Entry</p> <p>None</p> <p>At Return</p> <p>(C): Abnormal I/O flag</p> <p>(A): Connected device code</p> <table border="0"> <thead> <tr> <th>Bit 2</th> <th>Bit 1</th> <th>Bit 0</th> <th></th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>ROM cartridge</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>Not connected</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>x</td> <td>x</td> <td>Microcassette</td> </tr> </tbody> </table> <p>(X: don't care)</p> <p>Registers retained</p> <p>(B), (X)</p> <p>Subroutines referenced</p> <p>CHKRS, SNSCOM</p> <p>Variables used</p> <p>None</p>	Bit 2	Bit 1	Bit 0		0	0	0	ROM cartridge	0	0	1	Reserved	0	1	0	Not connected	0	1	1	Reserved	1	x	x	Microcassette
Bit 2	Bit 1	Bit 0																								
0	0	0	ROM cartridge																							
0	0	1	Reserved																							
0	1	0	Not connected																							
0	1	1	Reserved																							
1	x	x	Microcassette																							

PWROFF	FFAC	Turns power supply of the HX-20 OFF. (The power switch is not actually turned OFF.) There is therefore no exit from this subroutine.
		Parameters: At Entry None Subroutines referenced SNSCOM Variables used None
PWRDWN	FF1F	Displays the message "CHARGE BATTERY!" on the LCD. Control is returned from this subroutine when power supply voltage recovers. Otherwise, the power supply is turned OFF after the message has been flashed on the LCD 60 times.
		Parameters: At Entry None At Return None Subroutines referenced DSPLCN, PWROFF Variables used None
REQINI	FF13	Outputs the message "Enter DATE and TIME" at cold start. When the date and time are entered, the extent of the RAM is checked and the memory is cleared. Jumps to the entry point for reset.
		Parameters: At Entry None Subroutines referenced DSPLCN, DSPLCH, KEYIN, HEXBIN
WRTP26	FED4	Port 26 data output. This subroutine is used to output data to port 26. Address 26 data is retained by address 4F.
		Parameters: At Entry (A):Bit positions to be output (for each bit, '1' indicates output and '0', that the bit is not to be output.) (To specify output of bits 0 and 1, set 05 in this register, that is, bits 0 and 1 ON) (B):Output data (Bits not specified in (A) are ignored) Registers retained (A), (B), (X) Subroutines referenced None Variables used ROH (Value is recovered)
BREKIO	FFA3	I/O break. Executes break processing sequence for the slave MCU and turns bits 7 of variables MIOSTS and SIOSTS ON (logic '1').
		Parameters: At Entry None At Return None

Subroutine name	Entry Point	Description
		Registers retained None Subroutines referenced WRTP26, SNSCOM, RSONOF Variables used None
RSTRIO	FFA6	Sets the value of variables to enable restarting of I/O processing after BREAK. Bits 0, 1 and 2 of the following variables are set to '0': MIOSTS, SIOSTS, CSMOD (external cassette status), PRMSTS (ROM cartridge status) and SRSTS. Print buffer is cleared and interrupt is enabled. Paramaters: At Entry None At Return None Registers retained (X) Subroutines referenced None Variables used None
CONTIO	FFAF	Clears bits 7 of variables MIOSTS and SIOSTS and restarts RS-232C input. Parameters: At Entry None At Return None Registers retained None Subroutines referenced CHKRS Variables used None
INITIO	FFCD	Initializes I/O, keyboard and LCD. Sends command 02 to the slave MCU (initialize command). Subroutine RSTRO initialize also performed. Identifies plug-in options and removes interrupt mask. Does not perform initialization for serial communication. Paramaters: At Entry None At Return None Registers retained None Subroutines referenced INITKY, INITLC, SNSCOM, HSTRIO, RSTRIO Variables used None

Subroutine name	Entry Point	Description
HSTRIO	FED1	<p>Initializes I/O operation. Does not initialize keyboard and LCD.</p> <p>Parameters:</p> <p>At Entry None</p> <p>At Return None</p> <p>Registers retained None</p> <p>Subroutines referenced SNSCOM</p> <p>Variables used None</p>
HEXBIN	FF2B	<p>Converts an ASCII code hexadecimal number into a binary number. Data is not converted in series but only 1 byte of data can be converted.</p> <p>Parameters:</p> <p>At Entry (A, B): ASCII code 2-digit hexadecimal number</p> <p>At Return (A) Binary number (result of conversion) (B) Return code 00: Normal 01: Data error ((A, B) not in range 0 to F) (Z) According to the value of (B)</p> <p>Subroutines retained None</p> <p>Variables used Other</p> <p>Reentrant</p>
BINDEC	FF28	<p>Converts unsigned 16-bit binary number into an ASCII code decimal number.</p> <p>Parameters:</p> <p>At Entry (A, B): Unsigned 16-bit binary number (0-65535) (X): Address for storing 5-bit result of conversion. Zero are not suppressed.</p> <p>At Return None</p> <p>Registers retained (X)</p> <p>Subroutines referenced None</p> <p>Variables used None</p> <p>Others None</p> <p>Reentrant</p>

Subroutine name	Entry Point	Description
GETCLK	FF31	<p>Inputs the current date and time from the real-time clock (version 2 or better).</p> <p>Parameters:</p> <p>At Entry</p> <p>(X): Starting address of the memory area where the input data is to be stored. Data is 6 bytes: Month, Day, Year, Hour, Minutes, Seconds. Each item is in a 2-digit BCD code (one byte).</p> <p>At Return</p> <p>The result is entered in the specified memory address.</p> <p>Registers retained</p> <p>(X)</p> <p>Subroutines referenced</p> <p>None</p> <p>Variables used</p> <p>None</p>
SETCLK	FFF8	<p>Sets the current date in the real-time clock (version 2 or better).</p> <p>Parameters:</p> <p>At Entry</p> <p>(X): The starting address of the memory where the specified data is to be stored. The format of the data is the same as for GETCLK.</p> <p>At Return</p> <p>None</p> <p>Registers retained</p> <p>None</p> <p>Subroutines referenced</p> <p>None</p> <p>Variables used</p> <p>None</p>

ERR SEQ LOC OBJECT PROGRAM ALARM --- ALARM INTERRUPT (BASIC) ---

```

00001          NAM      ALARM
00002          TTL      --- ALARM INTERRUPT (BASIC) ---
00003          OPT      LOAD
00004          OPT      PAGE=55
00005          *
00006          * SAMPLE PROGRAM OF 'ALARM INTERRUPT'
00007          * DISPLAY CURRENT TIME.
00008          * THE MELODY IS PLAYED WHEN MINUTES IS UPDATED (SECOND = 00). BECAUSE
00009          * ALARM INTERRUPT IS CAUSED AND MELODY COMMANDS ARE SENT TO SLAVE MCU
00010          * IN INTERRUPT ROUTINE.
00011          *
00012          * FILE NAME 'EXSC' BY K.A
00013          * BASIC PROGRAM
00014          * 10 CLS
00015          * 20 FOR I=&HB00 TO &HB06
00016          * 30 READ J
00017          * 40 POKE I,J
00018          * 50 NEXT I
00019          * 60 FOR I=&HB10 TO &HB45
00020          * 70 READ J
00021          * 80 POKE I,J
00022          * 90 NEXT I
00023          * 100 EXEC &HB00
00024          * 105 'WRITE INTERRUPT VECTOR
00025          * 110 POKE &H116,&H0B
00026          * 120 POKE &H117,&H10
00027          * 130 POKE &H7E,&H80
00028          * 135 'ENABLE ALARM INTERRUPT
00029          * 140 POKE &H4B,&H22
00030          * 150 POKE &H41,&H00
00031          * 160 POKE &H43,&HFF
00032          * 170 POKE &H45,&HFF
00033          * 180 LOCATE 5,2
00034          * 190 PRINT TIMES
00035          * 200 GOTO 180
00036          * 1000 DATA &HFC,&HFF,&HCB,&HFD,&H0B,&H07,&H39
00037          * 1010 DATA &H96,&H4C,&H2B,&H05,&HFE,&H0B,&H07,&H6E,&H00
00038          * 1020 DATA &HCE,&H0B,&H33,&H86,&H34,&HED,&HFF,&H19,&HA6,&H00,&H3.
00039          * 1030 DATA &H3D,&HFF,&H19,&H32,&H08,&H81,&HFF,&H26,&HFF4
00040          * 1040 DATA &H86,&H35,&H3D,&HFF,&H19,&H3B
00041          * 1050 DATA 17,06,44,06,17,06,44,06,17,06,14,06,16,06,15,06,13,18,&HFF
00042          *
00043          *
00044          *
00045A 0800          ORG      $B00
00046          *
00047          * STORE INTERRUPT VECTOR
00048          FF19  A      SNSCOM EQU      $FF19
00049          FFCA  A      INTIR1 EQU     $FFCA      * IRQ1 INTERRUPT INITIAL ADDRESS
00050          *
00051A 0800 FC  FFCB  A      LDD      INTIR1+1
00052A 0803 FD  0807  A      STD      SAVADD
00053A 0806 39          RTS
00054          *
00055A 0807 0002  A      SAVADD RMB    2
    
```

ERR SEQ LOC OBJECT PROGRAM ALARM --- ALARM INTERRUPT (BASIC) ---

```

00056          * IRQ1 INTERRUPT ROUTINE
00057A 0B10          ORG      $B10
00058A 0B10 96 4C    A      LDA A  $4C      * IS INTERRUPT CAUSED BY CLOCK ?
00059A 0B12 2B 05 0B19 BMI    CLKINT
00060A 0B14 FE 0B07  A      LDX   SAVADD
00061A 0B17 6E 00    A      JMP   0,X
00062
00063          *
00064A 0B19 CE 0B33  A      * SEND SLAVE MCU DATA OF MELODY.
CLKINT LDX   #MELTBL  * (X):THE ADDRESS WHERE MELODY DATA ARE STORED.
00065A 0B1C 86 34    A      LDA A  #$34  * SEND DATA TO SLAVE MCU.
00066A 0B1E BD FF19  A      JSR   SNSCOM * COMMAND 34: SET MELODY DATA
00067A 0B21 A6 00    A      SLV10 LDA A  0,X  * SET DATA
00068A 0B23 36
00069A 0B24 BD FF19  A      JSR   SNSCOM
00070A 0B27 32
00071A 0B28 0B
00072A 0B29 81 FF    A      INX
00073A 0B2B 26 F4 0B21 CMP A  #$FF  * LAST CHARACTER IS $FF
00074          BNE   SLV10
00075          *
00076A 0B2D 86 35    A      * PLAY MELODY.
00077A 0B2F BD FF19  A      LDA A  #$35
00078A 0B32 3B      JSR   SNSCOM
00079          RTI
00080          *
00081A 0B33 11 A      * MELODY TABLE (FOR ELISE)
MELTBL FCB 17,06,44,06,17,06,44,06
A 0B34 06 A
A 0B35 2C A
A 0B36 06 A
A 0B37 11 A
A 0B38 06 A
A 0B39 2C A
A 0B3A 06 A
00082A 0B3B 11 A      FCB 17,06,14,06,16,06,15,06
A 0B3C 06 A
A 0B3D 0E A
A 0B3E 06 A
A 0B3F 10 A
A 0B40 06 A
A 0B41 0F A
A 0B42 06 A
00083A 0B43 0D A      FCB 13,1B
A 0B44 12 A
00084A 0B45 FF A      FCB $FF
00085
00086          *
00086          0000 A      END
***** TOTAL ERRORS 0
    
```


CHAPTER 14 MEMORY MAP

	<u>Page</u>
14.1 Memory Allocation	14-1
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14.1 Memory Allocation

The memory of HX-20 is divided into the following areas.

Table 14-1 Memory Map

Address	Without expansion unit	With expansion unit	Applications
0000 to 004D	I/O ports	←	This area is used by I/O routines as work and flag area.
004E to 007F	RAM (Real-time clock)	←	
0080 to 00FF	RAM	←	This area is used as a work area by the BASIC interpreter.
0100 to 04AF	RAM	←	This area is used by I/O routines as work area and I/O buffer.
04B0 to 0A3F	RAM	←	This area is used as a work area by the BASIC interpreter.
0A40 to 3FFF	RAM	←	
4000 to 5FFF	None	RAM (in expansion unit)	
6000 to 7FFF	ROM (ROM5) (Only socket provided.)	RAM (in expansion unit)	
8000 to 9FFF	ROM (ROM4)	ROM (ROM2) Can be switched to ROM in expansion unit.	ROM in the HX-20 is the BASIC interpreter.
A000 to BFFF	ROM (ROM3)	ROM (ROM1). Can be switched to ROM in expansion unit.	ROM in the HX-20 is the BASIC interpreter.
C000 to DFFF	ROM (ROM2)	←	C000 to CFFF is memory area for the BASIC interpreter. D000 to DFFF contains Menu, Monitor and virtual screen routines.

Address	Without expansion unit	With expansion unit	Applications
E000 to FFFF	ROM (ROM1)	←	This area is used by I/O routines.

14.2 Jump Table

Jump tables show the entry points of various subroutines. Entry points are indicated by a 3-byte address specification. Initial byte specifies 7E (JPM command) followed by high and low bytes of the address.

Table 14-2 Jump Table

Address (from)(to)	Contents	Remarks	For details, refer to this manual, Chapter:
FED1 FED3	JMP HSTRIO	I/O restart, Initialize	13
FED4 FED6	JMP WRTP26	Address 26 port output	13
FED7 FED9	JMP BILOAD	Memory Load: Load, Close after end of processing	9
FEDA FEDC	JMP OPNLOD	Memory Load: Load Open	9
FEOB FEOD	JMP BIDUMP	Memory Dump: Dump and Close after end of processing	9
FEE0 FEE2	JMP OPNDMP	Memory Dump: Dump Open	9
FEE3 FEE5	JMP DIRPRM	Read PROM cartridge directory	8
FEE6 FEE8	JMP CLSPRM	Closes PROM cartridge file.	8
FEE9 FEEB	JMP REDPRM	Reads 1 character from PROM cartridge file.	8
FEEC FEEE	JMP OPNPRM	Opens PROM cartridge file.	8
FEF0 FEF1	JMP CNTMCS	Read/Write to built-in microcassette counter value.	6
FEF2 FEF4	JMP SECMCS	Advances tape to the specified built-in microcassette counter value.	6
FEF5 FEF7	JMP REWMCS	Rewinds built-in microcassette.	6
FEF8 FEFA	JMP SETCLK	Inputs time and date. (Version 2 or better)	6
FEFB FEFD	JMP CLSMCS	Closes built-in microcassette files.	6
FEFE FEF0	JMP WRTMCS	Outputs one character to built-in microcassette.	6
FF01 FF03	JMP OPNWMS	Opens built-in microcassette file for output.	6
FF04 FF06	JMP READMS	Inputs one character from built-in microcassette.	6
FF07 FF09	JMP SRCRMS	Opens built-in microcassette file for input (initializes file).	6
FF0A FF0C	JMP OPNRMS	Opens built-in microcassette file for input (searches specified file).	6
FF0D FF0F	JMP MCSMAN	Sets built-in microcassette in manual operation mode.	6
FF10 FF12	JMP \$DFF7	Jumps to address DFF7.	
FF13 FF15	JMP REQINI	Initializes HX-20 cold start.	13
FF16 FF18	JMP CHKRS	RS-232C recovery after aborting input processing	5
FF19 FF1B	JMP SNSCOM	Sends one command byte to slave CPU.	11
FF1C FF1E	JMP SRINIT	Initializes high-speed serial communication.	4
FF1F FF21	JMP PWRDWN	Battery Low message	13
FF22 FF24	JMP KYSTK	Stores data in the initial key stack.	2
FF25 FF27	JMP \$DFFD	Jumps to address DFFD (MENU).	
FF28 FF2A	JMP BINDEC	Converts binary numbers into ASCII decimal code.	13
FF2B FF2D	JMP HEXBIN	Converts ASCII hexadecimal code into binary code.	13
FF2E FF30	JMP CHKPLG	Identification of plug-in options	13
FF31 FF33	JMP GETCLK	Sets time and date (Version 2 or better)	13
FF34 FF36	JMP CLSCS	Closes external cassette file.	6
FF37 FF39	JMP WRITCS	Outputs one byte to external cassette file.	6

Address (from)(to)	Contents	Remarks	For details, refer to this manual, Chapter:
FF3A FF3C	JMP OPNWCS	Opens external cassette file for output.	6
FF3D FF3F	JMP READCS	Inputs 1 byte from external cassette file.	6
FF40 FF42	JMP SRCRCS	Opens external cassette file for input (initializes file).	6
FF43 FF45	JMP OPNRCS	Opens external cassette file for input.	6
FF46 FF48	JMP OPNFCS	External cassette file remote (ON/OFF)	6
FF49 FF4B	JMP DSPLCN	Displays n characters on LCD (Physical screen).	3
FF4C FF4E	JMP DSPLCH	Displays one character on LCD (Physical screen).	3
FF4F FF51	JMP \$DFFI	Displays one character on virtual screen.	15
FF52 FF54	JMP LCADDR	Link table for LCD routines. Selects LCD driver.	
FF55 FF57	JMP LCDMOO	Link table for LCD routines. Selects LCD driver mode.	
FF58 FF5A	JMP DATMOD	Link table for LCD routines. Outputs data to LCD driver.	
FF5B FF5D	JMP DISPIT	Displays one character on LCD. (Data is not entered in physical screen buffer.)	3
FF5E FF60	JMP \$DFF4	Calls virtual screen function.	4
FF61 FF63	JMP \$DFEE	Displays (recovers) current virtual screen data.	
FF64 FF66	JMP SOUND	Speaker output	13
FF67 FF69	JMP CHRGEN	Generates character font.	3
FF6A FF6C	JMP KEYSN	Scans key matrix.	2
FF6D FF6F	JMP SERIN	High-speed serial data input	4
FF70 FF72	JMP SEROUT	High-speed serial data output	4
FF73 FF75	JMP SERONF	High-speed driver ON/OFF	4
FF76 FF78	JMP RSPUT	Outputs one character to RS-232C.	5
FF79 FF7B	JMP RSGET	Inputs one character to RS-232C.	5
FF7C FF7E	JMP RSGSTS	Inputs RS-232C status register value.	5
FF7F FF81	JMP RSCLOS	Closes RS-232C input.	5
FF83 FF84	JMP RSOPEN	Opens RS-232C output.	5
FF85 FF87	JMP RSONOF	Controls RS-232C driver (ON/OFF)	5
FF88 FF8A	JMP RSMST	Sets RS-232C status register mode.	5
FF8B FF8D	JMP SCRCPY	Screen copy (LCD to microprinter).	7
FF8E FF90	JMP NFEED	Performs n dot-lines of line feed on microprinter.	
FF91 FF93	JMP PRTDOT	Prints one dot-line (bit pattern) on the microprinter.	7
FF94 FF96	JMP LNPRNT	Prints one character-line on the microprinter.	7
FF97 FF99	JMP CHPRNT	Prints one character on the microprinter.	7
FF9A FF9C	JMP KEYIN	Enters one character from keyboard.	2
FF9D FF9F	JMP KEYSTS	Enters keyboard key status.	2
FFA0 FFA2	JMP INITKY	Initializes keyboard.	2
FFA3 FFA5	JMP BREKIO	I/O break	13
FFA6 FFA8	JMP RSTRIO	Restart after I/O break	13
FFA9 FFAB	JMP SLEEP	Master MCU sleep	13

Address (from)(to)	Contents	Remarks	For details, refer to this manual, Chapter:
FFAC FFAE	JMP PWROFF	Power supply OFF	13
FFAF FFB1	JMP CONTIO	Continuation after I/O break	13
FFB2 FFB4	JMP BRKIN	Entry point after break break key has been pressed.)	
FFB5 FFB7	JMP CLKINT	Initial value for clock interrupt entry point	
FFB8 FFBA	JMP IRQI80	Initial value for IRQ1 external interrupt entry point	
FFBB FFBD	JMP SDFFA	Initial value for TRAP interrupt entry point	
FFBE FFC0	JMP SERINT	Initial value for SCI interrupt entry point	
FFC1 FFC3	JMP TOFINT	Initial value for TOF interrupt entry point	
FFC4 FFC6	JMP OCFINT	Initial value for OCF interrupt entry point	
FFC7 FFC9	JMP IRQI80	Initial value for ICF interrupt entry point	
FFCA FFCC	JMP IRQINT	Initial value for IRQ1 interrupt entry point	
FFCD FFCE	JMP INITIO	I/O initialize	

(1) ROM (ROM2) jump tables (Addresses C000 to DFFF)

Address	Contents	Notes
DFEE to DFF0	JMP LCRECV	Covers the virtual screen and rewrites only the physical screen.
DFE1 to DFF3	JMP SCRCHR	Displays one character on the virtual screen.
DFE4 to DFF6	JMP SCRFNC	Screen functions of the virtual screen.
DFE7 to DFF9	JMP MON	Monitor entry
DFFA to DFFC	JMP MONTRP	Monitor entry on TRAP
DFFD to DFFF	JMP MENU	Menu entry

14.3 ROM Vectors

Address (from) (to)	Variable name	Number of bytes	Description
FFD0 FFD1	NEWKTB	2	Shows the address at which the matrix data is stored after key scanning (NEWKTB).
FFD2 FFD3	COLCNT	2	Shows the address where the amount of data in the built-in microprinter buffer is stored (COLCNT).
FFD4 FFD5	CSBFCM	2	Shows the address where the amount of data in the external cassette buffer is stored (CSBFCM). Used for data read and write.
FFD6 FFD7	MSBFCM	2	Shows the address where the amount of data in built-in microcassette buffer is stored (MSBFCM). Used for data read and write.
FFD8 FFD9	RSDCNT	2	Shows the address where the amount of data in the RS-232C input buffer is stored (RSDCNT).
FFDA FFDB		2	Shows the starting address of the LCD physical screen buffer.
FFDC FFDD	CASBUF	2	Shows the starting address of the 260-byte buffer used by the monitor (CASBUF).
FFDE FFEF		2	Shows the address where the scroll speed data is stored.
FFE0 FFE1	CSHBUF	2	Shows the starting address of the external cassette header buffer (CSHBUF).
FFE2 FFE3	MSHBUF	2	Shows the starting address of the built-in microcassette header buffer (MSHBUF).
FFE4 FFE5	KEYMOD	2	Shows the address where the key input mode data is stored (KEYMOD).

NOTE: Addresses are shown as two bytes in upper- and lower-byte sequence.

FFEE FFEF		2	Shows the address where the TRAP entry point is stored. Set to 0106.
FFF0 FFF1		2	Shows the address where the SCI interrupt entry point is stored. Set to 0109.
FFF2 FFF3		2	Shows the address where the TOF interrupt entry point is stored. Set to 010C.
FFF4 FFF5		2	Shows the address where the OCF interrupt entry point is stored. Set to 010F.
FFF6 FFF7		2	Shows the address where the ICF interrupt entry point is stored. Set to 0112.

Address (from) (to)	Variable name	Number of bytes	Description
FFF8 FFF9		2	Shows the address where the IRQ1 interrupt entry point is stored. Set to 0115.
FFFA FFFB		2	Shows the address where the SWI interrupt entry point is stored. Set to 0118.
FFFC FFFD		2	Shows the address where the NMI interrupt entry point is stored. Set to 011B.
FFFE FFFF		2	Shows the address where the RESET interrupt entry point is stored. Set to E000.

14.4 RAM page 0 vectors

Address (from) (to)	Variable name	Number of bytes	Description																				
4E 4E	PWRFLG	1	<p>Bits 0 to 3: Reserved for selecting processing to be executed when power supply is turned ON.</p> <p>Bits 4 to 7: Indicates the processing to be executed when power supply is turned OFF.</p> <table border="0"> <tr> <td>Bit 7</td> <td>Bit 6</td> <td>Bit 5</td> <td>Bit 4</td> <td></td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>No operation</td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>1</td> <td>Executes the subroutine specified in addresses 132~133 (POFADR) prior to turning OFF the power supply.</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>0</td> <td></td> </tr> </table> <p>All other bit values No operation.</p>	Bit 7	Bit 6	Bit 5	Bit 4		0	0	0	0	No operation	0	0	0	1	Executes the subroutine specified in addresses 132~133 (POFADR) prior to turning OFF the power supply.	0	0	1	0	
Bit 7	Bit 6	Bit 5	Bit 4																				
0	0	0	0	No operation																			
0	0	0	1	Executes the subroutine specified in addresses 132~133 (POFADR) prior to turning OFF the power supply.																			
0	0	1	0																				
4F 4F	P26	1	Address 26 port data. Note: Read of address 26 is inhibited.																				
50 51	R0	2	This area is used as a work area by I/O routine.																				
52 53	R1	2	Same as R0																				
54 55	R2	2	Same as R0																				
56 57	R4	2	Same as R0																				
58 59	R3	2	Same as R0																				
5A 5B	R5	2	Same as R0																				
5C 5D	R6	2	Same as R0																				
5E 5F	R7	2	Same as R0																				
60 61	M0	2	This area is used as a work area by Monitor and screen routines.																				

Address (from) (to)	Variable name	Number of bytes	Description																								
62 63	M1	2	Same as M0																								
64 65	M2	2	Same as M0																								
66 67	M3	2	Same as M0																								
68 69	M4	2	Same as M0																								
6A 6B	M5	2	Same as M0																								
6C 6D	M6	2	Same as M0																								
6E 6F	M7	2	Same as M0																								
70 71	K0	2	The area is used as a work area by the key input routine.																								
72 73	K1	2	Same as K0																								
74 75	S0	2	Same as K0																								
76 77	S1	2	Same as K0																								
78 78	INIPL1	1	Indicates application program cold start. For each bit, '0' indicates cold start and '1', warm start Bit 1: Bit 2: Bit 3: Bit 4: Bit 5: Bit 6: BASIC application programs Bit 7: BASIC interpreter																								
79 79	PLGSTS	1	Bits 0 to 2: Indicate the plug-in option. <table style="margin-left: 40px;"> <tr> <td>Bit 2</td> <td>Bit 1</td> <td>Bit 0</td> <td></td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>ROM cassette</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>Not connected</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>x</td> <td>x</td> <td>Microcassette</td> </tr> </table> (x: don't care) Bit 3: 0 Bits 4 to 6: not used Bit 7: Specifies whether RS-232C driver will be turned OFF when the BREAK key is pressed. 0: Not turned OFF 1: Turned OFF.	Bit 2	Bit 1	Bit 0		0	0	0	ROM cassette	0	0	1	Reserved	0	1	0	Not connected	0	1	1	Reserved	1	x	x	Microcassette
Bit 2	Bit 1	Bit 0																									
0	0	0	ROM cassette																								
0	0	1	Reserved																								
0	1	0	Not connected																								
0	1	1	Reserved																								
1	x	x	Microcassette																								

Address (from) (to)	Variable name	Number of bytes	Description																																																												
7A 7A	SRSTS	1	<p>Bits 0 to 2: Indicate current RS-232C status.</p> <table border="0"> <tr> <td>Bit 2</td> <td>Bit 1</td> <td>Bit 0</td> <td></td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Input operation is not being performed.</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Input operation is being executed.</td> </tr> <tr> <td>0</td> <td>1</td> <td>x</td> <td>Not used in current version</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>Undefined.</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>Input. Operation enters wait state when the slave MCU is busy with other I/O devices such as microprinter.</td> </tr> <tr> <td>1</td> <td>1</td> <td>x</td> <td>Undefined</td> </tr> </table> <p>Bit 3: Indicates RS-232C driver status (ON/OFF) 0: OFF 1: ON</p> <p>Bit 4: Serial I/F driver status The same driver is used as the RS-232C and Serial I/F driver. However, in terms of operation by software, they are treated independently.</p> <p>Bits 5 to 7: SCI (Serial Communication Interface) interrupt mode</p> <table border="0"> <tr> <td>Bit 7</td> <td>Bit 6</td> <td>Bit 5</td> <td></td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Input of external cassette data</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Input of internal microcassette data</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>RS-232C data input</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Serial I/F data input</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>Output of external cassette data</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>Output of built-in microcassette data</td> </tr> <tr> <td>1</td> <td>1</td> <td>x</td> <td>Undefined</td> </tr> </table>	Bit 2	Bit 1	Bit 0		0	0	0	Input operation is not being performed.	0	0	1	Input operation is being executed.	0	1	x	Not used in current version	1	0	0	Undefined.	1	0	1	Input. Operation enters wait state when the slave MCU is busy with other I/O devices such as microprinter.	1	1	x	Undefined	Bit 7	Bit 6	Bit 5		0	0	0	Input of external cassette data	0	0	1	Input of internal microcassette data	0	1	0	RS-232C data input	0	1	1	Serial I/F data input	1	0	0	Output of external cassette data	1	0	1	Output of built-in microcassette data	1	1	x	Undefined
Bit 2	Bit 1	Bit 0																																																													
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1	1	x	Undefined																																																												
7B 7B	RUNMOD	1	<p>Program execution mode</p> <p>Bits 0 to 3: Reserved for specifying program number, etc.</p> <p>Bits 4 to 5: Undefined</p> <p>Bit 6: Flag indicating whether the virtual screen is being used 0: Virtual screen being used 1: Virtual not being used</p> <p>Bit 7: Indicates the interpreter mode 0: Machine language mode 1: Interpreter mode</p>																																																												

Address (from) (to)	Variable name	Number of bytes	Description									
			<p>NOTE:</p> <p>In machine language mode, the program jumps to the specified address when the BREAK key is pressed, power is turned OFF or the voltage falls.</p> <p>In interpreter mode when one of these interrupts is generated, the appropriate flag is set (MIOSIS) and control is returned. In BASIC the values of bit 7 and bit 6 are 1, 0 and in Monitor 0, 1.</p>									
7C 7D	SIOSTS	1	<p>Flags to indicate the current I/O status of the slave MCU I/O</p> <p>Bit 0: Microprinter control (1: being executed)</p> <p>Bit 1: External cassette Read/Write (1: being executed)</p> <p>Bit 2: Internal microcassette Read/Write or control (1: being executed)</p> <p>Bit 3: RS-232C Receive (1: being executed)</p> <p>Bit 5: ROM cartridge power supply (1: ON)</p> <p>Bit 6: Bar-code reader power supply (1: ON)</p> <p>Bit 7: BREAK (1: Slave MCU I/O control forcibly terminated by master MCU).</p>									
7D 7D	MIOSTS	1	<p>Indicates the I/O status of the master MCU.</p> <p>Bit 0: Read/Write to LCD (1: being executed)</p> <p>Bit 1: Command transmit and response with slave MCU (1: being executed)</p> <p>Bit 2: Data communication using the external serial port (Floppy disk unit), (1: being executed)</p> <p>Bit 3: Clock interrupt (alarm, square wave, update), (1: Interrupt)</p> <p>Bit 4: Voltage low (1: Voltage low interrupt)</p> <p>Bit 5: Power OFF (1: Power switch interrupt)</p> <p>Bit 6: PAUSE key ON (1: PAUSE key pressed)</p> <p>Bit 7: BREAK key ON (1: BREAK key pressed)</p>									
7E 7E	SDIPS1	1	<p>Software switch</p> <p>Bit 0, Bit 1:</p> <p>Specify the type of waveform from the external cassette.</p> <p>Bit 0 Bit 1</p> <table style="margin-left: 40px;"> <tr> <td>0</td> <td>x</td> <td>Decided automatically</td> </tr> <tr> <td>1</td> <td>0</td> <td>Normal waveform</td> </tr> <tr> <td>1</td> <td>1</td> <td>Reverse waveform</td> </tr> </table>	0	x	Decided automatically	1	0	Normal waveform	1	1	Reverse waveform
0	x	Decided automatically										
1	0	Normal waveform										
1	1	Reverse waveform										

Address (from) (to)	Variable name	Number of bytes	Description									
			<p>Bit 2, Bit 3 Specify the type of waveform from internal microcassette</p> <p>Bit 3 Bit 2</p> <table border="0"> <tr> <td>0</td> <td>x</td> <td>Decided automatically</td> </tr> <tr> <td>1</td> <td>0</td> <td>Normal waveform</td> </tr> <tr> <td>1</td> <td>1</td> <td>Reverse waveform</td> </tr> </table> <p>Bit 4, Bit 5 Memory bank selection</p> <p>Bit 6: Indicates the memory bank in which the BASIC interpreter is located. (Value is set when the menu is initialized.) 0: Bank 0 1: Bank 1</p> <p>Bit 7: Specifies access of addresses 0000 to 004D 0: Access disabled 1: Access enabled</p>	0	x	Decided automatically	1	0	Normal waveform	1	1	Reverse waveform
0	x	Decided automatically										
1	0	Normal waveform										
1	1	Reverse waveform										
7E 7F	SDIPS2	1	<p>Software switch</p> <p>Bits 0 to 3: Correspond to DIP switches 1 to 4 0: OFF 1: ON</p> <p>Bit 4: Flag indicating whether DIP switches 1 to 4 will be controlled by software (bits 0 to 3 above) or by the actual setting. 0: Actual DIP switch setting 1: Bits 0 to 3</p> <p>Bit 5: Flag indicating whether bit 7 will control the printer ON/OFF switch. 0: Actual printer ON/OFF switch setting 1: Bit 7</p> <p>Bit 6: Undefined</p> <p>Bit 7: Controls the printer ON/OFF switch 0: OFF 1: ON</p> <p>Note: These switches are included in the key matrix. The values of these switches are therefore set in the key matrix (NEWKTB) after key scanning.</p>									

14.5 RAM system variables

Address (from) (to)	Variable name	Number of bytes	Description
0100 0102	INTCLK	3	Address of real-time clock interrupt routine (for alarm, etc.) Address 0100 contains 7E (JMP command) and 0101, 0102 the upper and lower bytes of the jump address. Address values are initialized on reset.
0103 0105	INTEXT	3	Address of IRQ1 external port interrupt routine. Contents are identical to INTCLK.
0106 0108		3	Address of TRAP interrupt routine. Contents are identical to INTCLK.
0109 010B		3	Address of the IRQ1 SCI interrupt routine. Contents are identical to INTCLK.
010C 010E	INTOF	3	Address of the IRQ1 TOF interrupt routine. Contents are identical to INTCLK.
010F 0111		3	Address of the IRQ1 OCF routine. Contents are identical to INTCLK.
0112 0114		3	Address of the IRQ1 ICF routine. Contents are identical to INTCLK.
0115 0117		3	Address of the IRQ1 interrupt routine. Contents are identical to INTCLK.
0118 011A	INTSW1	3	Address of the SW1 routine. Three bytes are reserved.
011B 011D		3	Address of the NMI interrupt routine. Three bytes are reserved.
011E 011F	FNTGPN	2	Address of the character fonts for codes E0-FF (Upper- and lower-byte sequence).
0120 0121	BRKADR	2	Address of the subroutine to be executed when the BREAK key is pressed. This specification is valid only when RUNMOD is in machine language mode.
0122 0123	MENADR	2	Address of the subroutine to be executed when the MENU key is pressed. Contents are identical to BRKADR.
0124 0125	PAUADR	2	Address of the subroutine to be executed when the PAUSE key is pressed. Contents are identical to BRKADR.

Address (from) (to)	Variable name	Number of bytes	Description
0126 0127	CT3ADR	2	Address of the subroutine to be executed when CTRL/PS3 key is pressed. Control jumps unconditionally to this address. Address value is initialized at reset.
0128 0129		2	Address of the subroutine to be executed when CTRL/PF4 key is pressed. Contents are identical to CT3ADR.
012A 012B		2	Address of the subroutine to be executed when CTRL/PF5 key is pressed. Contents are identical to CT3ADR.
012C 012D	RMBADR	2	Shows the end of the RAM area. This variable is set when the RAM is checked at initialization (CTRL/@ input from MENU). Last address of the RAM +1 is stored in upper- and lower-byte sequence.
012E 012F	PRMCNT	2	Address where the amount of data remaining in the PROM cartridge file data is stored.
0130 0131	WAKADR	2	Address of the subroutine executed by the clock alarm interrupt at reset (Power ON). Address is in upper- and lower-byte sequence. This address is initialized at reset.
0132 0133	POFADR	2	Address of the last subroutine called prior to turning OFF the power supply. Address is in upper- and lower- byte sequence. This address is initialized at reset.
0134 0135	BSWTAD	2	Starting address of the BASIC application area. Value of RMBADR is set at MENU initialization (CTRL/@). Set to same value as RMBADR.
0136 0137	BSWBAD	2	Starting address of BASIC program area.
0138 0139		2	Address of the BASIC work area save and condense routine.
013A 013A	BITMP0	1	Bank 0 bit map.
013B 013B	BITMP1	1	Bank 1 bit map.
013C 013F	LNKTBL	4	Address of the RAM application program link table.

14.6 RAM area used by I/O routines

Memory range	Description
004E to 007F	Flag and work area
0100 to 0110	Interrupt entry pointer
011E to 0139	Vector
013A to 013F	Menu and Link tables
0140 to 018F	Keyboard work area
0190 to 01AE	Microprinter work area
01AF to 01C3	RS-232C work area
01C4 to 01D5	Serial communication work area
01D6 to 01EB	External cassette work area
01EC to 0207	Built-in microcassette work area
0208 to 020E	ROM cartridge work area

Memory range	Description
020F to 021A	Binary memory dump, memory load work area.
021B to 021F	Reserved
0220 to 029F	Screen (including LCD routine) routine work area.
02A0 to 02CF	Monitor work area
02D0 to 0323	External cassette header work area.
0324 to 0377	Built-in microcassette header work area.
0380 to 047C	Reserved for system buffer (260 bytes)

CHAPTER 15 VIRTUAL SCREEN

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15.1 General

Note: This chapter contains descriptions related to the display controller for external display. This hardware is not available in every country. In countries where the display controller is not available, this chapter should be ignoring all references to the display controller and the external display.

The virtual screen is intended to allow the HX-20 to use a larger screen than the physical screen size of its LCD (20 columns by 4 lines). This function is good for both the LCD and the display controller (for external display).

The virtual screen has a maximum size of 255 columns by 255 lines. The display area where characters actually appear is called a "window". (The size of this window become 32 columns by 16 lines with the display controller.) It functions as a viewing window through which any part of the large internal screen can be seen. The virtual screen on the LCD is controlled by the master MCU, whereas that on the external display is controlled by the display controller via a high-speed serial communication interface.

15.2 Names and Technical Terms

(1) Virtual screen and physical screen

Only character (or text) information is handled by the virtual screen. Its maximum size is 255 columns by 255 lines. For the LCD, a screen image is produced on the MCU memory. As opposed to the virtual screen, the screen used for actual display is called a "physical screen".

The size of the physical screen is 20 columns by 4 lines for the LCD display and 32 columns by 16 lines for the display controller. Graphic display (straight line, etc.) is applicable to the physical screen only.

(2) Window

The window is a portion of the virtual screen that is actually displayed for viewing. The contents of the window are the same as those of the physical screen.

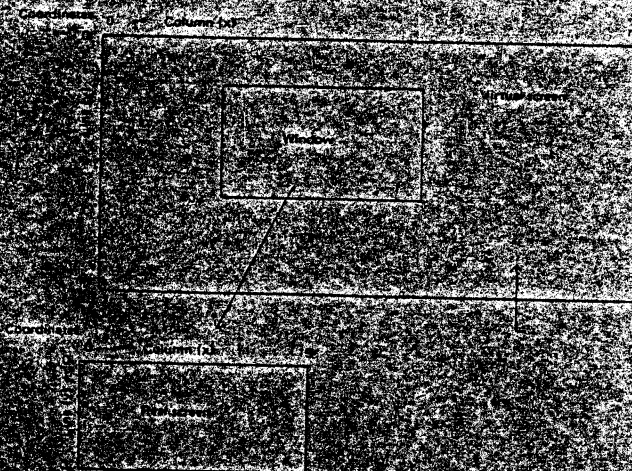


Fig. 15-1 Virtual Screen, Physical Screen and Window

- (3) Coordinates on the screen
 The screen in a horizontal direction is called "columns", while that in a vertical direction is called "lines". Coordinates are represented by x and y, which correspond to columns and lines, respectively. Column 0 indicates the left end of the screen, while line 0 indicates the top end of the screen. When the screen size is (m,n), the upper left end of the screen is identified by coordinates (0,0) and the lower right end by coordinates (m-1,n-1).
- (4) Scroll
 The scroll refers to the movement of the contents of the window up by one line. (Namely, the contents of the 4th line appear in the 3rd line, the contents of the 3rd line in the 2nd line, and the contents of the 2nd line in the 1st line. New data appears in the 4th line. In the HX-20, this function is also applicable to the movement of the screen in the upward, left and right directions.
- (5) Scroll step
 A character code to specify the number of scroll steps. When this code is accepted, the screen scrolls by the number of columns or lines specified by this code.
- (6) Scroll of virtual screen
 The scroll of virtual screen refers to the movement of the contents of the virtual screen up or down by one line.
- (7) Line status
 In some cases, two lines of data to be displayed are desired to be handled as a single line. To support this, a flag is provided to indicate a continuation line for each line. This flag is called a "line status flag" (see Fig. 9-2). The line status has a value "FF" if the line is a continuation of the preceding line and a value "00" if the line is a new line.

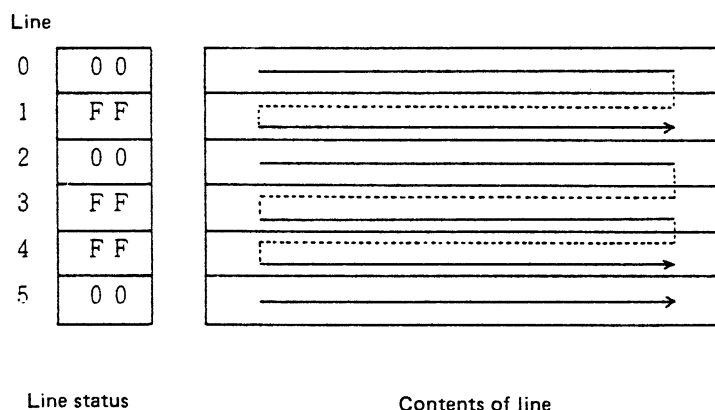


Fig. 15-2 Line Status

In Fig. 9-2, 0th and 1st lines, 2nd through 4th lines, and 5th line are logical single lines, respectively. The conditions for composing a logical single line are detailed in Section 9.4, Virtual Screen Functions.

(8) Cursor and cursor margin

The cursor indicates the position of a character to be displayed. At the same time, it also serves as a reference point for screen control.

The cursor is designed to always stay within the window. If the cursor moves out of the window, the window also moves with the cursor. When the cursor is at either end of the window, the next character cannot be identified. Therefore, a certain width from either end of the window must be predetermined so that the window moves when the cursor reaches this position. This width is called a "cursor margin".

In the following example, the screen size of 40 columns by 8 lines has been defined for LCD display. Assume that the cursor margin is set to a value of 3 and the position of the right margin is "RM", while that of the left margin is "LM". When the cursor is between the positions "LM" and "RM" (i.e., the shaded section in Fig. 9-3), window movement will not take place. When the cursor moves and reaches position "RM" (3rd column from the right), the cursor will not advance; instead the window will move to the right even if an attempt is made to move the cursor. This movement of the window stops when it reaches the right end of the virtual screen. From this point, the cursor moves again.

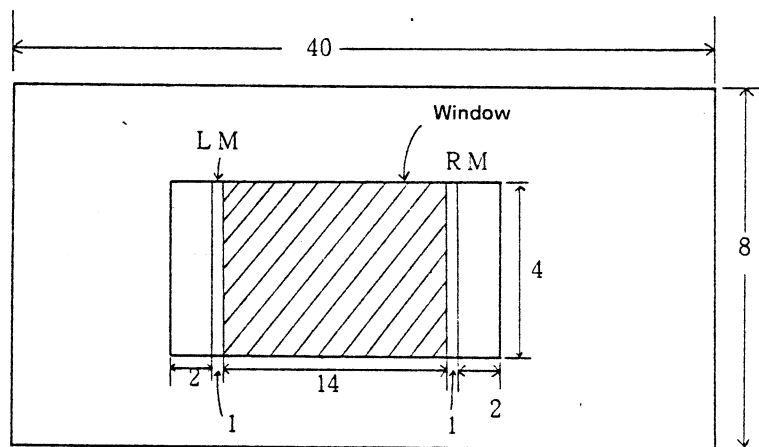


Fig. 15-3 Cursor Margin and Window Movement

The cursor margin may be specified by a value in the range of 1 to 10. If the value is 1, it indicates that no cursor margin is specified.

(9) List flag

If the window moves so that it contains the cursor, the displayed data is difficult to read. In some cases, the window may be desired to be fixed at the left end of the virtual screen (e.g., LIST command in BASIC.) The list flag controls the movement of the window. When the list flag is set, the window moves along the left end of the virtual screen (see the shaded section in Fig. 9-4).

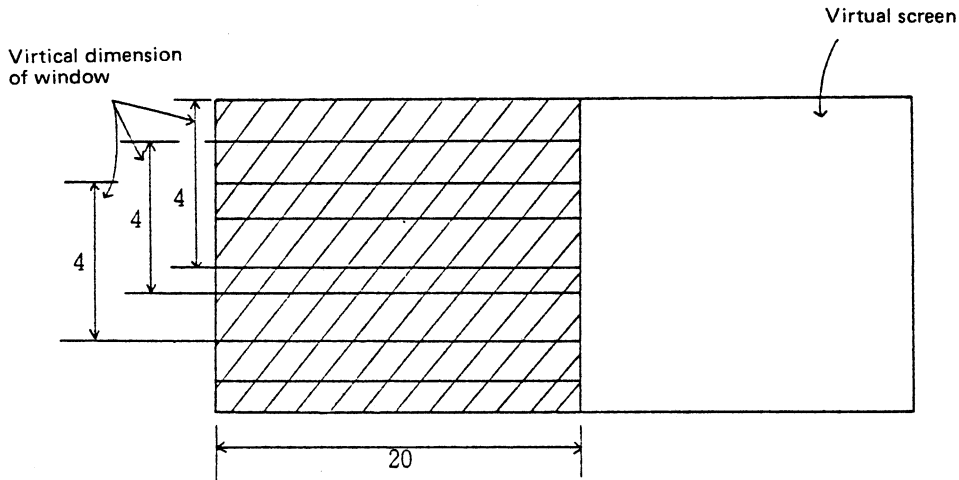


Fig. 15-4 Moving Range of Window when List Flag is ON.

When the list flag is ON, the window cannot move horizontally. However, its vertical movement is not restricted.

(10) Access pointer

When a character is to be input or output to or from the display controller, the location (i.e., coordinates on the virtual screen) where the character may be accessed for input/output must be specified. The access pointer functions to indicate this location.

15.3 Graphic Display

Only character codes may be handled by the virtual screen. It cannot handle graphic data. Graphic data processing is supported by both the LCD and display controller but in a manner different supported by both the LCD and display controller but in a manner different from each other.

(1) LCD

Graphic data is processed only on the physical screen. Display functions such as dot ON/OFF, straight line drawing, etc., are controlled directly against the controller. Therefore, the contents of the virtual screen will not be lost even if the graphic display is activated.

(2) Display controller

On the display controller, both text and graphic data cannot be displayed concurrently. Therefore, either the mode to effect the text display or that to effect the graphic display must be

selected by changing the display mode. Moreover, because of the limited memory size of the display controller, the contents of the virtual screen will be lost when the graphic display is activated. The display controller is capable of color selection, which is different depending on the display mode. In Text display mode, the background colors are green or orange with the color of all characters fixed. In Graphic display mode, there are two color sets 0 and 1. All the colors in the same color set can be used as background colors. Other colors are available for dots.

<u>Color set 0</u>	<u>Color set 1</u>
Green	White
Yellow	Cyan
Blue	Magenta
Red	Orange

15.4 Virtual Screen Control

The movement of the cursor, deletion of one character, and other controls related to the display contents on the virtual screen are performed by using character codes. Special controls such as screen size specification, list control, etc., are provided as the functions of the virtual screen.

The character codes used are 00 through FF. Codes 20 through FF are those to be displayed on the screen as graphic characters. Code 00 through 1F are non-graphic characters which are not displayed on the screen. They are used as control characters for cursor movement, etc. The description of each character code follows.

(1) Graphic characters

- (a) When not at the right-hand end on the bottom line

The next line is assumed to be a continuation line. (Line status is FF.) (See Fig. 9-6.)

- (b) When at the right-hand end on the bottom line

The display contents are scrolled up by one line. The bottom line becomes a continuation line filled with blank codes (20).

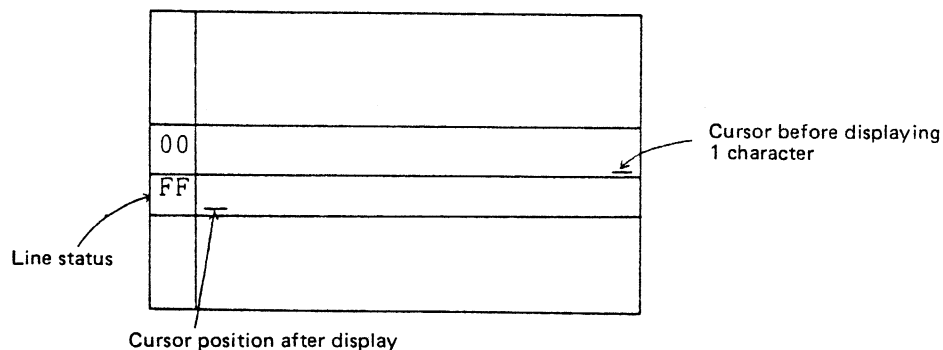


Fig. 15-5 Continuation Line

(2) Control codes

19 character codes can be used as control codes. The functions of the respective control codes are as follows:

- (a) 01 (Window Left)
Positions the window to the left end of the virtual screen. The cursor moves to the 10th column of the window.
- (b) 04 (Scroll Right)
Moves the window to the right by the number of columns specified by the horizontal scroll steps. However, the window will not move beyond the right end of the virtual screen.
- (c) 05 (Clear to End of Line)
Changes all the characters from the cursor position to the end of the logical single line to blank codes (20).
- (d) 06 (Window Right)
Positions the window to the right end of the virtual screen. The cursor moves to the 10th column of the window.
- (e) 08 (Delete one Character)
Moves the cursor position back by one character and deletes the character at the cursor position. All the data following the deleted character on the line are shifted and a blank code (20) is entered at the end of the line. When the cursor is at the beginning of the line and therefore cannot be moved back, the character at the current cursor position is deleted.
- (f) 09 (TAB)
Moves the cursor to the next Tab position. Tab positions are set at every 8 columns such as 0, 8, 16
- (g) 0A (Line Feed)
Moves the cursor down by one line. When the cursor is at the bottom line of the virtual screen, the virtual screen scrolls one line and the bottom line will be filled with blank codes.
- (h) 0B (Home)
Positions the cursor to the upper left corner of the virtual screen. The window moves along with the cursor. (This position is referred to as "Home position").
- (i) 0C (Clear)
Changes all the contents of the virtual screen to blank codes (20). The logical single line is set to the virtual screen width and the cursor returns to the home position.
- (j) 0D (Carriage Return)
Terminates the logical single line. (The line status of the next line becomes 00.) The cursor moves to the left end of the line.
- (k) 10 (Scroll Up)
Moves the window up by the number of lines specified by the vertical scroll steps. The window will not move beyond the top end of the virtual screen. The cursor moves to the 10th column of the virtual screen.
- (l) 11 (Scroll Down)
Moves the window down by the number of lines specified by the vertical scroll steps. The window will not move below the bottom end of the virtual screen. The cursor moves to the 10th column of the virtual screen.

- (m) 12 (Insert)
 Inserts a blank code (20) into the cursor position. All the characters following the cursor position are shifted to the right by 1 column. If the last character in the logical single line is a blank code, that character is deleted. If the last character is not a blank code, another line filled with blank codes will be inserted (i.e., scrolling takes place above the cursor position) and the last character is positioned at the beginning of the inserted line.
- (n) 13 (Scroll Left)
 Moves the window to the left by the number of columns specified by the horizontal scroll steps. However, the window will not move beyond the left end of the virtual screen.
- (q) 1A (Clear to End of Screen)
 Changes the contents of the virtual screen from the current cursor position to the end of the virtual screen to blank codes. The logical single line is set to the virtual screen width. (Line status is changed to "00".)
- (p) 1C (Cursor Right)
 Moves the cursor to the right by one column. The cursor at the right end of a line will move to the beginning of the next line. If the cursor is on the bottom line, it will move to the left end of the same line.
- (q) 1D (Cursor Left)
 Moves the cursor to the left by one column. The cursor at the left end of a line will move to the right end of one immediately above the line. If the cursor is in the top line, it will move to the right end of the same line.
- (r) 1E (Cursor Up)
 Moves the cursor up by one line. The cursor will not move if it is in the top line.
- (s) 1F (Cursor Down)
 Moves the cursor down by one line. The cursor will not move if it is in the bottom line.

(3) Subroutine call for virtual screen

The virtual screen is supported by subroutine "SCRFNC". Parameters for this subroutine are given by the parameter packet used on the memory. The packet begins with a 1-byte function code which is followed by a series of several data. The return information is also included in the packet.

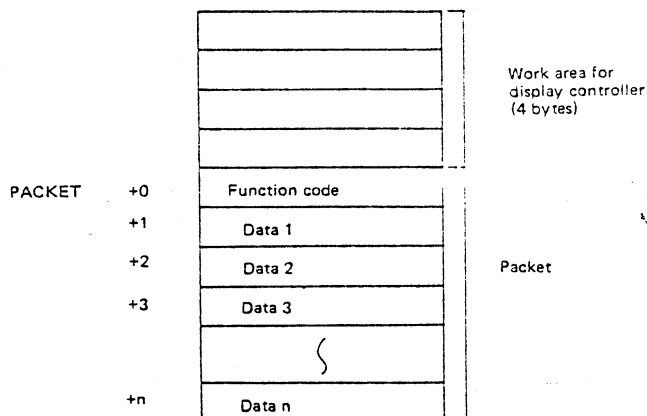


Fig. 15-6 Parameter Packet

A 4-byte work area is required before the packet for the display controller functions. (See Fig. 9-6.)
 To call subroutine "SCRFNC" (Entry point FF5E), the top address of the packet must be given to the index register.
 Example: To call the function to set the virtual screen. In this example, the screen size of 40 x 8 is defined for the LCD and the buffer address is specified at 5000.

```

SCRFNC    EQU    $FF5E
          LDX    #PACKET
          JSR    SCRFNC
          .
          .
PACKET    FCB    $87      *Function code(define screen size)
          FCB    39      *Screen width
          FCB    7       *Screen depth
          FDB    $5000   *Buffer address
          .
          .
          ORG    $5000
          RMB    40*9 + 1 *Buffer size
  
```

° Functions for Initialization of Virtual Screen

The following functions must be executed to initialize the virtual screen.

1. Function 84 (Screen device select)
2. Function 87 (Specification of screen size and buffer address)
3. Function C3 (Specification of scroll margin)
4. Function C4 (Specification of scroll steps)
5. Function CB (Specification of scrolling speed)

(Refer to Section 9.5 for detailed description of each function code.)

15.5 Virtual Screen Function Table

Packets for the virtual screen are as listed below. The virtual screen functions are divided into those shared by both the LCD and the display controller and those peculiar to either one. The device to which the particular function is applicable is shown in the "Function (Application)" column as (LCD) for the display and as (Disp) for the display controller. Data in each packet are numbered as 0, 1, 2, ... for each byte and their descriptions are given in order of the data number. These packets are used at the time of both the entry and return of each subroutine. In the following table, "XX" indicates that arbitrary 2-digit values may be used, and unless otherwise specified, all numeric values are hexadecimal.

Function (Application)	Packet data number	Description	
		(At Entry)	(At Return)
84		Screen device select.	
(Disp) (LCD)	00	84 (Function code) Device code 30: Disp 22: LCD	Return code 00: Normal FE: Device is not connected. FF: Device specification is invalid.
85		Initialization of the Display controller. The Display controller is initialized at the default value.	
(Disp)	00 01	85 (Function code) XX	Return code 00: Normal FF: I/O error
87		Specification of the virtual screen. By this function, the screen size and the top address of the buffer are specified. When the screen size is m columns by n lines, the size of the buffer must be m x n + 1 bytes.	
(Disp) (LCD)	00 01	87 (Function code) Screen width (Specify m - 1 for m columns.) Screen length (Specify n - 1 for n lines.) High-order byte of buffer's top address Low-order byte of buffer's top address NOTE: Buffer addressing is not required if the display controller is specified.	Return code 00: Normal FF: Screen oversize

Function (Applica- tion)	Packet data number	Description	
		(At Entry)	(At Return)
88 (Disp) (LCD)		Input of the virtual screen size. By this function, the currently defined size of the virtual screen is obtained.	
	00	88 (Function code)	
	01	XX	Screen width (m - 1 for m columns)
	02	XX	Screen length (n - 1 for n lines)
89 (Disp) (LCD)		Input of the window size.	
	00	89 (Function code)	
	01	XX	Width: 19 (D) for LCD 31 (D) for Display controller
	02	XX	Length: 3 (D) for LCD 15 (D) for Display controller
8A (Disp) (LCD)		Input of the window position. By this function, the coordinate values at the upper left corner of the window on the virtual screen are given.	
	00	8A (Function code)	
	01	XX	Coordinate x
	02	XX	Coordinate y
8C (Disp) (LCD)		Input of the cursor position. By this function, the position of the cursor on the virtual screen is obtained.	
	00	8C (Function code)	
	01	XX	Coordinate x
	02	XX	Coordinate y
8D (Disp) (LCD)		Input of the cursor margin value.	
	00	8D (Function code)	
	01	XX	Margin value
8E (Disp) (LCD)		Input of the scroll steps.	
	00	8E (Function code)	
	01		Number of horizontal scroll steps
	02		Number of vertical scroll steps

Function (Applica- tion)	Packet data number	Description	
		(At Entry)	(At Return)
8F		By this function, the dot status at the specified position on the physical screen is obtained.	
(Disp) (LCD)	00	8F (Function code)	XX
	01	High-order byte of coordinate x	(1) LCD FF: ON 00: OFF (2) Display controller Color code
	02	Low-order byte of coordinate x	XX
	03	High-order byte of coordinate y	XX
	04	Low-order byte of coordinate y	XX
91		Input of the range of the logical single line. By this function, the range of the logical single line containing the cursor on the virtual screen is specified.	
(Disp) (LCD)	00	91 (Function code)	XX
	01	XX	First column in the logical single line (Coordinate x with a value 0)
	02	XX	First line in the logical single line (Coordinate y)
	03	XX	Physical screen width (LCD: 19 (D), Disp: 32 (D))
	04	XX	Last line in the logical single line (Coordinate y)
92		Display of one character on the virtual screen.	
(Disp)	00	Character code	Coordinate x of the new cursor position
(LCD)	01	XX	Coordinate y of the new cursor position
93		Specification of a display mode for the display controller.	
(Disp)	00	93 (Character code)	XX
	01	Text mode	Return code
		00: Graphic mode	00: Normal
		01: Text mode	FF: An error has occurred.
	02	Graphic mode	XX
		00: Text mode	
		01: Color graphic mode	
		02: Monochromatic graphic (high-resolution) mode	
		Note: Text mode and graphic mode must be specified exclusively. In other words, either data 00 or 01 must be 00.	

Function (Applica- tion)	Packet data number	Description	
		(At Entry)	(At Return)
	03	<p>Graphic mode is supported on the physical screen. The resolution of the display is 128 x 64 dots in color graphic mode and 128 x 96 dots in monochromatic graphic mode (i.e., high-resolution mode).</p> <p>Background color 00: Green 04: White 01: Yellow 05: Cyan 02: Blue 06: Magenta 03: Red 07: Orange</p> <p>Note: Background color selection is effective in Graphic mode only. A color set is defined by the COLOR command in Text mode.</p>	XX
95		Input of one character on the display. By this command, the character at the coordinates specified by the access pointer is input.	
(Disp)	00	95 (Function code)	XX
	01	XX	Character code
	02	XX	Color code (Background color code)
97		Consecutive input of characters from the virtual screen. By this function, characters are input in the number specified from the coordinate positions where data read starts.	
(Disp) (LCD)	00	97 (Function code)	XX
	01	Coordinate x at the read start point	Input character 1
	02	Coordinate y at the read start point	Input character 2
	03	Number of read characters	Input characters 3
	04	XX	
98		Display of one character on the virtual screen. (Note that the packet generation in this case is different from that of function 92.)	
(Disp) (LCD)	00	98 (Function code)	XX
	01	XX	Coordinate x of the new cursor position
	02	XX	Coordinate y of the new cursor position
	03	XX	First line number in the logical single line containing the new cursor (Coordinate y)
	04	XX	Last line number in the logical single line containing the new cursor (Coordinate y)

Function (Applica- tion)	Packet data number	Description	
		(At Entry)	(At Return)
C0 (Disp) (LCD)		Setting of the window position. By this function, the upper left edge of the window is positioned at the specified address on the virtual screen.	
	00	C0 (Function code)	XX
	01	Coordinate x on the virtual screen	XX
	02	Coordinate y on the virtual screen Note: If the window position is outside the bounds of the virtual screen, the maximum values are set for both coordinates x and y.	XX
C2 (Disp) (LCD)		Specification of the cursor position. By this function, the cursor is placed at the specified position on the virtual screen, resulting in the movement of the window.	
	00	C2 (Function code)	XX
	01	Coordinate x of the cursor position	XX
	02	Coordinate y of the cursor position Note: The window movement is controlled as follows: (1) The window does not move when the specified cursor position is within the window area. (2) When the specified cursor position is not within the window area, the window moves so that the new cursor is located at the home position of the window. The cursor position cannot be located at the home position of the window, if the bottom edge of the window is in alignment with the bottom edge of the virtual screen. In such a case, the cursor position is set within the window area according to the same rule as that of function code C0.	XX
C3 (Disp) (LCD)		Setting of the value of the cursor margin.	
	00	C3 (Function code)	XX
	01	Cursor margin value (This value must be in the range from 1 to half the window value.)	XX
C4 (Disp) (LCD)		Setting of the number of scroll steps.	
	00	C4 (Function code)	XX
	01	Number of horizontal scroll steps (0 to 255 (D)) Number of vertical scroll steps (0 to 255 (D))	XX XX

Function (Application)	Packet data number	Description	
		(At Entry)	(At Return)
C5 (Disp) (LCD)	00	Turning the list flag ON.	
		C5 (Function code)	XX
C6 (Disp)	00	Resetting of the list flag.	
		C6 (Function code)	XX
C7 (Disp) (LCD)		Setting of a dot at the specified position. This function is effective in Graphic mode.	
	00	C7 (Function code)	XX
	01	High-order byte of coordinate x	XX
	02	Low-order byte of coordinate x	XX
	03	High-order byte of coordinate y	XX
	04	Low-order byte of coordinate y	XX
	05	Color code With LCD, 00: OFF, FF: ON With Display controller, if color set 0 is specified 00: Green 01: Yellow 02: Blue 03: Red if color set 1 is specified 00: White 01: Cyan 02: Magenta 03: Orange	
C8 (Disp) (LCD)		Drawing a straight line between any two points on the graphic screen.	
	00	C8 (Function code)	XX
	01	High-order byte of coordinate x at the start point	XX
	02	Low-order byte of coordinate x at the start point	XX
	03	High-order byte of coordinate y at the start point	XX
	04	Low-order byte of coordinate y at the start point	XX
	05	High-order byte of coordinate x at the end point	XX
	06	Low-order byte of coordinate x at the end point	XX
	07	High-order byte of coordinate y at the end point	XX
	08	Low-order byte of coordinate y at the end point	XX
09	Color code. Same as function code 07	XX	

Function (Applica- tion)	Packet data number	Description	
		(At Entry)	(At Return)
C9 (Disp) (LCD)		Termination of the logical single line. By this function, the line status of the specified line is reset to 00.	
	00	C9 (Function code)	XX
	01	Line number (coordinate y)	XX
CA (Disp)		Clearing of the screen in Graphic mode. This function is effective for the graphic screen when the Display controller is used, and for the physical screen when the LCD display is used.	
	00	CA (Function code)	XX
	01	Background color (Effective only with Display controller)	XX
CB (LCD)		Setting of the scrolling speed. This function specifies the scrolling speed of the physical screen.	
	00	CB (Function code)	XX
	01	Speed A value in the range of 00 to 09 is used to specify the scrolling speed. 9 is the highest scrolling speed.	
CD (Disp)		Output of one character to the position specified by the access pointer.	
	00	CD (Function code)	XX
	01	Character code	XX
CE (Disp)		Specification of the access pointer. By this function, the character position that can read/write on the virtual screen when the Display controller is used is specified.	
	00	CE (Function code)	XX
	01	Coordinate x of the access pointer	XX
	02	Coordinate y of the access pointer	XX
CF (Disp)		Specification of a color set. Two color sets each consisting of 4 different colors are selectable when the Display controller is used.	
	00	CF (Function code)	XX
	01	Color set 00: Color set 0 01: Color set 1 If color set 0 is specified, green, yellow, blue and red can be used. If color set 1 is specified, white, cyan, magenta and orange can be used.	XX

15.6 EPSP Message Format Table for Screen

In the following table, SS and MM refer to the slave and master device numbers, respectively. Numeric values are all hexadecimal.
 "XX" indicates that arbitrary 2-digit values may be used.

(1) Function Codes for Display Controller

Function code	FMT	DID	SID	FNC	SIZ	Text data number	Description of function and text
84	00	SS	MM	84	00	00	Screen device select Device number (30)
	01	MM	SS	84	00	00	Return code 00: Normal FE: Device is not ready. FF: Device number is invalid.
85	00	SS	MM	85	00	00	Initialization of screen XX
	01	MM	SS	85	00	00	Return code 00: Normal FF: An error has occurred.
87	00	SS	MM	87	03	00	Specification of the screen size
						01	Virtual screen width (maximum value of coordinate x)
						02	Virtual screen length (maximum value of coordinate y)
01	MM	SS	87	00	00	Return code 00: Normal FF: Size specification is invalid.	
88	00	SS	MM	88	00	00	Input of the virtual screen size. XX
	01	MM	SS	88	01	00	Virtual screen width (maximum value of coordinate x) 01 Virtual screen length (maximum value of coordinate y)
89	00	SS	MM	89	00	00	Input of the physical screen
	01	MM	SS	89	01	00	Screen width (maximum value of coordinate x) 01 Screen length (maximum value of coordinate y)

Function code	FMT	DID	SID	FNC	SIZ	Text data number	Description of function and text
C0	00	SS	MM	C0	01	00	Positioning of the physical screen on the virtual screen. Position values are given with respect to the position (0,0) of the physical screen. Coordinate x of the specified position.
						01	Coordinate y of the specified position.
	01	MM	SS	C0	00	00	XX
8A	00	SS	MM	8A	00	00	Input of the physical screen position on the virtual screen. Position values are given with respect to the position (0,0) of the physical screen. XX
						01	Coordinate x of the specified position
	01	MM	SS	8A	01	00	01 Coordinate y of the specified position
C2	00	SS	MM	C2	01	00	Specification of the cursor position on the virtual screen. Coordinate x of the specified position
						01	Coordinate y of the specified position
	01	MM	SS	C2	00	00	XX
8C	00	SS	MM	8C	00	00	Input of the cursor position on the virtual screen XX
						01	Coordinate x of the specified position
	01	MM	SS	8C	01	00	01 Coordinate y of the specified position
C3	00	SS	MM	C3	00	00	Setting of the margin value of the cursor Margin value
	01	MM	SS	C3	00	00	XX
8D	00	SS	MM	8D	00	00	Input of the cursor margin value XX
	01	MM	SS	8D	00	00	Margin value
C4	00	SS	MM	C4	01	00	Setting of the number of scroll steps Number of horizontal scroll steps
						01	Number of vertical scroll steps
	01	MM	SS	C4	00	00	XX

Function code	FMT	DID	SID	FNC	SIZ	Text data number	Description of function and text
8E	00	SS	MM	8E	00	00	Input of scroll steps XX
	01	MM	SS	8E	01	00 01	Number of horizontal scroll steps Number of vertical scroll steps
C5	00	SS	MM	C5	00	00	Setting of the list flag XX
	01	MM	SS	C5	00	00	XX
C6	00	SS	MM	C6	00	00	Resetting of the list flag XX
	01	MM	SS	C6	00	00	XX
C7	00	SS	MM	C7	04	00	Setting of a dot at the specified position
						01	High-order byte of coordinate x
						02	Low-order byte of coordinate x
						03	High-order byte of coordinate y
	04	Low-order byte of coordinate y					
01	MM	SS	C7	00	00	Color code XX	
8F	00	SS	MM	8F	03	00	Input of the dot status at the specified position
						01	High-order byte of coordinate x
						02	Low-order byte of coordinate x
						03	High-order byte of coordinate y
	04	Low-order byte of coordinate y					
01	MM	SS	8F	00	00	Color code	
C8	00	SS	MM	C8	08	00	Drawing of a straight line
						01	High-order byte of coordinate x at the start point
						02	Low-order byte of coordinate x at the start point
						03	High-order byte of coordinate y at the start point
						04	Low-order byte of coordinate y at the start point
						05	High-order byte of coordinate x at the end point
						06	Low-order byte of coordinate x at the end point
						07	High-order byte of coordinate y at the end point
	08	Low-order byte of coordinate y at the end point					
00	MM	SS	C8	00	00	Color code XX	

Function code	FMT	DID	SID	FNC	SIZ	Text data number	Description of function and text
91							Input of the range of the logical single line containing the cursor
	00	SS	MM	91	00	00	XX
	01	MM	SS	91	03	00	00
						01	Coordinate y of the first line in the logical single line
02						Column size of the physical screen	
03	Coordinate y of the last line in the logical single line						
C9							Resetting of the line status of the specified line (i.e., partitioning of the logical single line)
	00	SS	MM	C9	00	00	Line number
	01	MM	SS	C9	00	00	XX
92							Display of one character on the virtual screen
	00	SS	MM	92	00	00	Character code
	01	MM	SS	92	01	00	Coordinate x of the cursor Coordinate y of the cursor
	CA						Specification of the background color in Graphic mode
00		SS	MM	CA	00	00	Color code
01		MM	SS	CA	00	00	XX
CB							Setting of the scrolling speed
	00	SS	MM	CB	00	00	A value in the range of 0 to 9 is used to specify the scroll.
	01	MM	SS	CB	00	00	XX
	93	00	SS	MM	93	02	00
01							Text mode
							Graphic mode
02							Background color
01	MM	SS	93	00	00	00: Mode other than Text mode	
						01: Text mode	
						00: Mode other than Graphic mode	
						01: Graphic mode 1	
						02: Graphic mode 2	
						Note:	
						Either data 00 or data 01 must be "00". Both data must not be "00".	
						00: Green 01: Yellow	
						02: Blue 03: Red	
						04: White 05: Cyan	
						06: Magenta 07: Orange	
						Return code	
						00: Normal	
						FF: An error has occurred.	

Function code	FMT	DID	SID	FNC	SIZ	Text data number	Description of function and text
CD	00	SS	MM	CD	01	00 01	Writing of one character into the access pointer Character code Color code
	01	MM	SS	CD	00	00	XX
CE	00	SS	MM	CE	01	00 01	Specification of the access pointer against the virtual screen Coordinate x Coordinate y
	01	MM	SS	CE	00	00	XX
95	00	SS	MM	95	00	00	Input of one character from the access pointer XX
	01	MM	SS	95	01	00 01	Character code Color code
CF	00	SS	MM	CF	00	00	Selection of a color set 00: Color set 0 01: Color set 1
	01	MM	SS	CF	00	00	XX
97	00	SS	MM	97	03	00 01 02 03	Input of characters at the positions specified consecutively on the virtual screen Coordinate x of the start point Coordinate y of the start point High-order byte of the number of input characters Low-order byte of the number of input characters
	01	MM	SS	97	mm	00 mm	00~mm denote the character codes of the input characters.
98	00	SS	MM	98	00	00	Display of one character on the virtual screen followed by the input of the first and last line numbers of the logical single line including the newly set cursor position. Character code.
	01	MM	SS	98	03	00 01 02 03	Coordinate x of the new cursor position Coordinate y of the new cursor position First line number in the logical single line Last line number in the logical single line.

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CHAPTER 16 MENU

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16.1 General

The title or entry point of a program can be registered or displayed by the MENU function of the HX-20. This chapter first describes the ID structure of the application programs stored in the ROMs of the HX-20, then explains how the ID information is displayed by the MENU with examples.

16.2 ID Structure

The ID (identifying information also called a "header") for both the ROM and user (RAM) application programs is structured as described below.

When the user writes an application program into a ROM or RAM and wishes to display the program on the MENU, he must write the header information to identify the program. Particularly, for an application program stored in a ROM, this header information must be at the top address (low-order address) of the ROM.

16.2.1 Header of ROM/RAM application program

(1) ID 1 (1 byte)

Bit 0 - bit 6 ':' (Code 3A)

Bit 7

0 = The header contains a link address to the next program on the ROM or RAM. The linked program is not displayed on the MENU. This bit can be used when the user writes programs using an EPROM. In other words, if the user wishes to erase a program on the EPROM, bit 7 should be changed from logic "1" to "0" using an EPROM writer. (Bit 7 is "1" with the EPROM in the initialized state.)

1 = Header contains a link address with the next program on the ROM or RAM, the starting address (entry point) of a program and its program name.

(2) ID 2 (1 byte)

Bit 0 - bit 6 = The header information contains one of the following codes:

"A" = Application program (application for general use)

"B" = BASIC interpreter

"E" = End of link (No application program follows this header information.)

(RAM application for general use)

Bit 7

0 = Indicates that the linkage with the next program is an absolute value (i.e., absolute address).

1 = Indicates that the linkage with the next program is a relative value (i.e., offset value from the header).

If the ROMs are made available for use on any sockets, programs are relocatable and thus bit 7 must be set to logic "1".

(3) Pointer to next header (2 bytes)

This header information is also called a "link address".

This two-byte data is used as a pointer to the location of the next header. If no next header exists within the same ROM, the value of this data is "FFFF".

If the MENU finds value "FFFF" on a ROM, it scans the next ROM for header information.

- (4) Starting address of program (entry point) (2 bytes)
 This header information indicates the starting address of a program. The starting address is an absolute value if the bit 7 of ID2 is logic "1" and an offset value from the beginning of this header information if bit 7 is "0".
- (5) Filename (program name) (17 bytes max.)
 A filename is entered in a maximum of 16 bytes in ASCII code. The last byte of this header information is always "00".

16.2.2 Header of BASIC application program

The header of a BASIC application program (i.e., an application program written in BASIC by the user) is different from that of a ROM/RAM application program.

BASIC application programs have no linkage with ROM/RAM application programs. However ROM/RAM application programs are displayed automatically by the MENU function.

- (1) Link offset (2 bytes)
 This is a pointer to indicate the starting address of the header of the next BASIC program. For example, program 1 points at program 2, while program 2 points at program 3. When the link offset value is FFFF, it indicates that no next header exists.
- (2) Filename (program name) (8 bytes)
 The filename of a program is specified by the TITLE command of BASIC. If the program has no filename, blanks must be entered as the filename in the header.

16.2.3 Bit map (2 bytes) and link tables (4 bytes, 013C to 013F)

After the input of "CTRL/@"; the MENU generates a bit map which indicates the presence of the header of a ROM application program, and a link table for linkage with an RAM application program. Bit map addresses are 013A and 013B.

013A	Bit 7	*	ROM at addresses E000 to FFFF of bank 0
	Bit 6	*	ROM at addresses C000 to DFFF of bank 0
	Bit 5	*	ROM at addresses A000 to BFFF of bank 0
	Bit 4	*	ROM at addresses 8000 to 9FFF of bank 0
	Bit 3	*	ROM at addresses 6000 to 7FFF of bank 0
	Bit 2	*	ROM at addresses 4000 to 5FFF of bank 0
	Bit 1	*	ROM at addresses 2000 to 3FFF of bank 0
	Bit 0	*	ROM at addresses 0000 to 1FFF of bank 0
013B	Bit 7	*	ROM at addresses E000 to FFFF of bank 1
	Bit 6	*	ROM at addresses C000 to DFFF of bank 1
	Bit 5	*	ROM at addresses A000 to BFFF of bank 1
	Bit 4	*	ROM at addresses 8000 to 9FFF of bank 1
	Bit 3	*	ROM at addresses 6000 to 7FFF of bank 1
	Bit 2	*	ROM at addresses 4000 to 5FFF of bank 1
	Bit 1	*	ROM at addresses 2000 to 3FFF of bank 1
	Bit 0	*	ROM at addresses 0000 to 1FFF of bank 1

* = 0 : No header exists in the specified ROM socket.
* = 1 : Header exists in the specified ROM socket.
Bank 0 : Main memory of HX-20
Bank 1 : Memory in the expansion unit for HX-20

The link table after the input of "CTRL/@" contains 4-byte data "1:/'E'/FF/FF/". If the user wishes to display any program on the RAM in the MENU, he just needs to link this 4-byte data in the link table to his object program. For example, if the user writes an application program from address 1000, the header of the RAM application program and its link table should be written as follows.

```
1000  /: (bit7=1)/'A'/FF/FF/10/20/U/S/E/R/00/  
13C   /: (bit7=0)/'A'/10/00/
```

16.2.4 How bit map and link table are generated

Neither a bit map nor a link table exists before the HX-20 system is initialized (by pressing CTRL and @ keys) (see Section 1.3). Before the system is cold started by "CTRL/@", "CTRL/@ Initialize", "1 MONITOR" and dummy names (19 max.) will appear in the MENU on the LCD. After pressing CTRL and @ keys, the MENU generates a bit map and a link table. When generating a bit map by the MENU, program linking starts from address D000 (MONITOR). Next, scanning of addresses starts from A000 (bank 1 also if an expansion unit is connected) and progresses to addresses 8000, 6000 and 4000 in the order named. The MENU sets the bit map depending on whether or not the header of an application program exists, and writes ":/'E'/FF/FF/" into the link table.

Subsequently, the MENU displays the filename of a ROM application filename according to the bit map. Next, if there is any linked RAM (user) application program, then the name of the RAM application program is displayed, followed by BASIC application programs.

16.3 Examples

	Bank 0	Bank 1
0000	_____	
1000	BA 'A' FF FF 10 20	
	'USER-A' 00	
2000	_____	
4000	_____	_____
		BA 'A' 50 00 40 18
		APLC-5 00
5000		BA 'A' FF FF 50 25
		'APLC-4' 00
6000	_____	_____
	BA 'A' FF FF 60 20	
	'APLC-2' 00	
8000	_____	_____
	BA B FF FF 80 10	BA 'A' FF FF 80 33
	'BASIC' 00	'APLC-3' 00
A000	_____	_____
C000	_____	_____
D000	BA 'A' FF FF D0 33	
	'MONITOR' 00	
E000	_____	
FFFF	_____	

Assume that there are 2 BASIC application programs (APLC-1 and APLC-2) in addition to the above ROM/RAM application program.

The bit map in this case will be as follows:

	MSB	LSB
13A	01011000	
13B	00010100	

and the link table will be as follows.

13C /:/'A'/10/00

The following information will appear in the MENU on the LCD display.

```
CTRL/@            Initialize
1 MONITOR
2 BASIC
3 APLC-3
4 APLC-2
5 APLC-5
6 APLC-4
7 USER-A
8 APLC-1
9 APLC-2
```

16.4 MENU Work Areas

Address (from)(to)	Variable name	Bytes	Description
2D0 48A	SCNBUF	442	Buffer for MENU display
78 78	INTFLG	1	Initialize flag (0: Request; 1: Complete) Bit 0: MENU Bit 7: BASIC Condense (garbage collection) flag (1: Condense request) Bit 6: (BASIC, Application) Condense
7B 7B	RUNMOD	1	Run mode 01: MENU
7E 7E	SFTSWH	1	Software switch 1 Bit 4: Bank switch number currently selected (0: Bank 0; 1: Bank 1) Bit 5: Bank switch number selected before current number Bit 6: Bank number in which BASIC programs are stored Bits 5 and 6 are used to condense application.
80 81	TMPBF1	2	Temporary buffer
82 83	CNTMNU	2	Indicates the top address of ROM (C000, A000, 8000, ...).
84 84	CNTMNU	1	Number of items currently on the MENU display - 1
85 85	MNUNUB	1	MENU number
86 86	BITMP	1	Bit map value of a bank (for temporary use)
87 87	BBTMP0	1	Buffer for BITMP0 (bit map of bank 0)
88 88	BBTMP1	1	Buffer for BITMP1 (bit map of bank 1)
89 89	STKLIN	1	Maximum number of lines on MENU display
8A 8A	MXMNUB	1	Maximum number of MENUs (ASCII code)
8B 8B	BSAPNB	1	BASIC application number
8C 8C	CNTFLG	1	Work area for temporary use
8D 8D	DISFLG	1	Work area for temporary use

Address (from)(to)	Variable name	Bytes	Description
8E 92	PCKT	5	LCD buffer work area for virtual screen packet
13A 13A	BITMP0	1	<p>Bit map for bank 0</p> <p>Indicates whether the header of a ROM application program exists in one of the ROM chips in bank 0. (0: No header exists; 1: A header exists.)</p> <p>Bit 0: Address 0000 of bank 0 Bit 1: Address 2000 of bank 0 Bit 2: Address 4000 of bank 0 Bit 3: Address 6000 of bank 0 Bit 4: Address 8000 of bank 0 Bit 5: Address A000 of bank 0 Bit 6: Address C000 of bank 0 Bit 7: Address E000 of bank 0</p>
13B 13B	BITMP1	1	<p>Bit map for bank 1</p> <p>Indicates whether the header of a ROM application program exists in one of the ROM chips in bank 1. (0: Header does not exist; 1: Header exists.)</p> <p>Bit 0: Address 0000 of bank 1 Bit 1: Address 2000 of bank 1 Bit 2: Address 4000 of bank 1 Bit 3: Address 6000 of bank 1 Bit 4: Address 8000 of bank 1 Bit 5: Address A000 of bank 1 Bit 6: Address C000 of bank 1 Bit 7: Address E000 of bank 1</p>
13C 140	LNKTBL	4	<p>Link table for RAM application programs</p> <p>(I) When RAM application program does not exist : E FF FF</p> <p>(II) When the header of a RAM application program exists : A Address of the RAM application program</p>



CHAPTER 17 MONITOR

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17.1 General

The Monitor is located in the ROM (ROM2) area from C000 to DFFF and has two entry points DFF7-DFF9 and DFFA-DFFC. The former is for entry from the menu display, etc., while the latter is for entry when a trap interrupt is generated. If one of the trap interrupt addresses (0106 through 0108) is specified, the default assumption is "JMP \$DFFA". The display of data by the Monitor is always on the physical screen and the virtual screen is never used for the monitor display.

The HX-20 Monitor has 10 types of commands as listed below.

- (1) S (Set) command : Displays and changes the contents of the memory.
- (2) D (Dump) command : Displays the contents of the memory.
- (3) G (Go) command : Executes a program.
- (4) X (Examine) command : Displays and changes the contents of each register.
- (5) R (Read) command : Loads a program or data into the memory from an external storage.
- (6) W (Write) command : Saves the contents of the memory to an external storage.
- (7) V (Verify) command: Verifies the data output to an external storage.
- (8) K (Key) command : Specifies the data for automatic key input when the power switch is turned ON.
- (9) A (Address) command : Specifies the range of the memory space when loading from an external storage or saving data to an external storage.
- (10) B (Back) command : Returns control to the procedure by which the Monitor was called.

Refer to the HX-20 OPERATION MANUAL for detailed description of each monitor command.

17.2 About Trap

If an attempt to execute a command not defined for the MCU is made, a trap interrupt is generated. By utilizing this characteristic, a breakpoint is set by the G command. For example, write "00" (undefined code) in the address specified as a breakpoint. Then, try to execute the command at this address, and a trap interrupt will be generated, causing the HX-20 to return to the Monitor mode again.

Address (from)(to)	Variable name	Bytes	Description
2A0 2A1	BP1	2	Stores the address specified as a breakpoint.
2A2 2A2	BPD1	1	Stores the contents of the breakpoint address.
2A3 2A3	LCDSTS	1	Stores the LCD status ('DISSTS': Address 0280) when the HX-20 enters Monitor mode.
2A4 2BE		27	Work area for packets of binary dump/load routine.
2BF 2C0	PC	2	Stores the program counter value.
2C1 2C2	RTNADD	2	Stores Return address on execution of B command.
2C3 2C4	LINLST	2	Stores the Buffer address corresponding to the end of the first line of the physical screen.
2C5 2C5	SRNMOD	1	Stores the R option of R command.
2C6 2CF		10	Unused.

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CHAPTER 18 Interfacing with BASIC

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18.1 Interfacing with Sequential Access Devices

18.1.1 DCB (Device Control Blocks)

To perform I/O operations with sequential access devices such as cassette tapes, etc., a DCB is necessary to specify the conditions for interfacing. DCBs are required for each type of sequential access device ("CAS0:", "COM0:", etc.). The contents of the DCBs are shown below.

Item	Data No. (Size)	Description
1	0 - 3 (4 bytes)	Device name (ASCII code). The four-character device name specified in the file descriptor is entered here.
2	4 (1 byte)	I/O mode. Specified as one of the following values. 10 ₁₆ : Sequential input 20 ₁₆ : Sequential output 30 ₁₆ : Sequential input/output
3	5 - 6 (2 bytes)	Entry point for the OPEN routine. The mode of the file (10 ₁₆ : input, 20 ₁₆ : output) is stored in variable FILMOD (address 068A). The OPEN routine references the mode data and opens the file for input or output.
4	7 - 8 (2 bytes)	Entry point for the CLOSE routine. The CLOSE routine also references variable FILMOD and performs close for input or output.
5	9 - 10 (2 bytes)	Entry point for the input routine for one byte. The input routine inputs one byte is then stored in accumulator A. When the end of the file is detected, FF is entered in variable EOFLG (address 00F8).
6	11 - 12 (2 bytes)	Entry point for the output routine for one byte. This routine outputs the contents of accumulator A.
7	13 - 14 (2 bytes)	Entry point for EOF routine. This routine sets data FF in accumulator B if the EOF is detected during input. Otherwise, 00 is entered in accumulator B.
8	15 - 16 (2 bytes)	Entry point for EOF routine. This routine enters the number of characters in the buffer or the remaining characters in the file in register D (accumulators A, B).
9	17 - 20	Reserved for data unique to each device.
10	21 (1 byte)	Specifies the column position of the next character to be output (leftmost column is taken to be column 0). This value is returned when the POS function is called. Normally, this value is initialized to 0 and incremented by 1 each time one byte is output by the output routine. Reset to 0 by CR (code 0D) or LF (code 0A). When this value exceeds the range for the length of one line, and the next character is not CR or LF, the output routine for one byte automatically generates CR or LF and resets the column position to 0.

18.1.3 Error processing

When an I/O error occurs during the execution of a routine or when the required device is busy, the corresponding error code is set in accumulator B and the following procedure is executed.

```
ERROR      EQU          $8433
           LDAB         #XX      ; SET THE ERROR CODE.
           JMP          ERROR    ; JUMP TO THE ERROR HANDLER.
```

The following error codes are commonly used.

<u>Error code</u>	<u>Message</u>	<u>Description</u>
53 ₁₀	IO	Error in communication with a peripheral device.
59 ₁₀	IU	Specified device is in use (busy).
60 ₁₀	DU	Device is unavailable.

18.1.4 BREAK key processing

The following two procedures are available when BREAK signal is detected during execution of an I/O operation with a peripheral device.

(1) Processing BREAK as an error

In this case, processing is identical to that for an I/O error. Error code 53 (I/O error) is set in accumulator B and control is transferred to the error handler subroutine (label name ERROR).

```
LDAB      #53      ; ERROR CODE FOR I/O ERROR.
JMP       ERROR
```

This procedure does not effect the other open devices or variables. When an ON ERROR GOTO statement has not been executed in the program mode, or when the I/O error occurs in the direct mode, the following error message will be displayed.

I/O ERROR (IN XXXX)

If an ON ERROR GOTO statement has been executed in the program mode, control is transferred to the specified error trap routine.

(2) Abort processing

Control jumps to label name ABTDO (address A908₁₆). The BASIC interpreter clears all variables, closes all files and initializes all I/O devices. Then, the following message is displayed.

ABORT (IN XXXX)

18.2 Loading from Expansion Devices

The BASIC interpreter inhibits load from any device other than "CAS0:", "CAS1:", "PAC0:" and "COM0". Loading from any device other than these will result in an FC error. However, load from expansion devices can be enabled by rewriting the hook on the RAM (normally set to jump to the FC error routine). The RAM hook is 3 bytes long and has a format: JMP XXX.

Write the entry point address of the program enabling loading from the expanded device into the address portion of the hook. For load processing, when control is returned from the OPEN routine, variable ASCFLG (one byte, address 068C) is checked, and if ASCFLG is 00, binary format load is performed.

The following two routes are used by the OPEN routine to set the value of variable ASCFLG.

- (1) FF is set in variable ASCFLG when the A option is specified in the SAVE statement and 00 is set when the A option is not specified. This data is written to the file header during program save and set in variable ASCFLG by the OPEN routine during load processing.
- (2) If the A option is specified in the SAVE statement, a value other than FF is written as the first character of the file. If the A option is not specified, FF is written as the above character. Therefore, the value of ASCFLG can be set by reading of the first character of the file using the OPEN routine.

Hook name
HKLOAD

Address
05E2

Parameters
(A): Device number

Processing sequence

HKLOAD	EQU	\$05E2	
FCERR	EQU	\$8C70	
LODCNT	EQU	\$A6D0	
	:		
	LDD	#LOADC	
	STD	HKLOAD+1	
	:		
LOADCK	CMPA	XX	* check the device number
	BEQ	LOADOK	
	JMP	FCERR	* GIVE 'FC Error'
LOADOK	JMP	LODCNT	* CONTINUE LOADING
	:		

18.3 ABORT Processing

If an I/O operation is aborted by pressing the BREAK key, the BASIC interpreter initializes all devices and closes all files (communications channels). When one of the devices in the DCB table has been expanded, these devices will also have to be initialized if I/O to another device is aborted. This initialization is also performed using a hook.

Hook name

HKABTD

Address

063C

Note:

Normally, 39₁₆ (RTS command) is stored at address 063C.

18.4 RAM Management

18.4.1 Application files

Application programs (BASIC interpreter, word processor, etc.) can use the RAM to store the data required by their systems as application files.

Application files are protected against use and accidental destruction by other application programs. Required data can be stored in these files in the same manner as data for BASIC programs can be stored in RAM files.

(1) Before execution of an application program (Fig. 18-2)

All application files are stored in the upper addresses of the RAM.

(2) During execution of an application program (Fig. 18-3)

The application program reserves a work area for itself by moving the application files stored at addresses lower than its own to addresses lower down in the free area. However, the location of this work area varies according to the status of the other application files. Therefore, if a fixed work area is required, the area immediately following the system area is reserved for this purpose. To secure work areas for execution, each application program expands its application files into the fixed and variable work areas.

(3) Upon termination of application program execution

Upon termination of execution of an application program (power switch is turned OFF, RESET switch is pressed or normal completion), control returns to the Menu leaving the RAM allocation as it was during the execution of the application program.

Then, when the same or another application program is selected from the Menu, the menu program calls the file reform routine for the files of the previously executed application program.

The file reform routine selects only the required data from the fixed and variable work areas to create an application file and returns the RAM to the status in (1) above. Control is then transferred to the application program selected from the menu.

For application programs which do not require application files, the free area is used as work area as shown in Fig. 18-2.

In this case, the file reform routine is not called.

18.4.2 RAM map

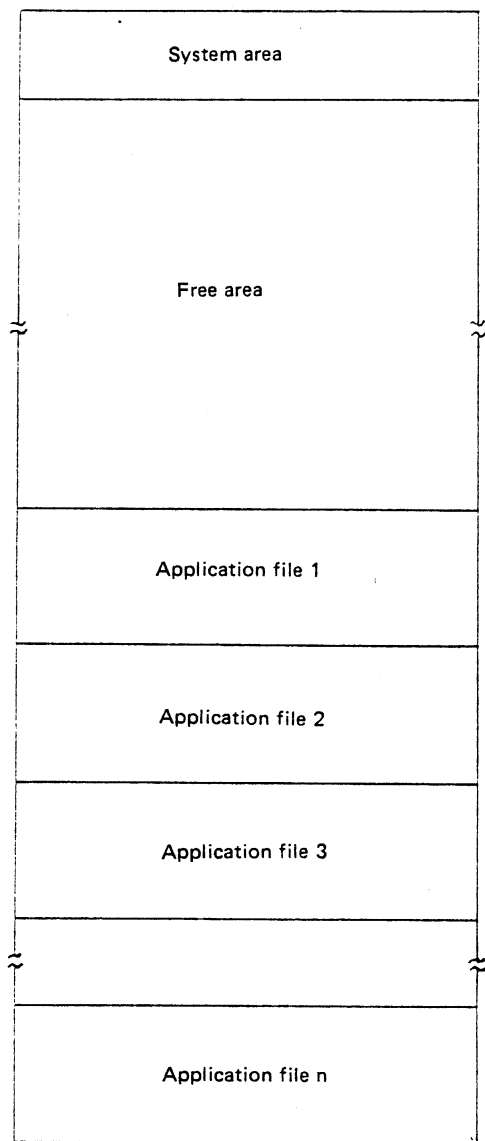
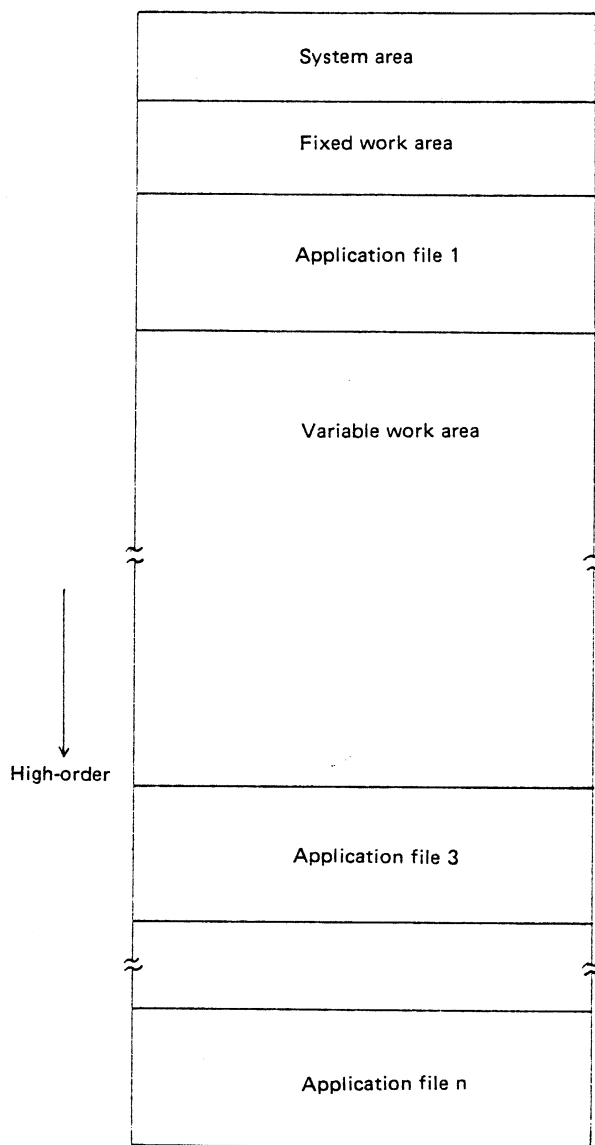


Fig. 18-2 RAM map (1)



When application file 2 is used

Fig. 18-3 RAM map (2)

18.4.3 Data configuration

BASTAB

Indicates the beginning of the application file. When the system is initialized, the address set here is the same as that indicated by RMLTAD.

RMLTAD

Indicates the last address in the RAM +1. The value of RMLTAD is set when the RAM is checked during system initialization.

CNDADR

Indicates the entry point of the file reform routine. The address of the file reform routine for the application program is set in this variable when the application program is executed and the application files are expanded.

INITAB

INITAB bit 6 is set (logic '1') to indicate that the files must be reformed before the next application program can be executed. This flag is set when the value of CNDADR is set.

When this flag is set, the Menu program calls the subroutine whose address is stored in CNDADR (file reform routine for the previously executed application program) before transferring control to the application program selected from the menu. This flag is reset within the subroutine after the application files are reformed. When application files are not used, this flag must not be set.

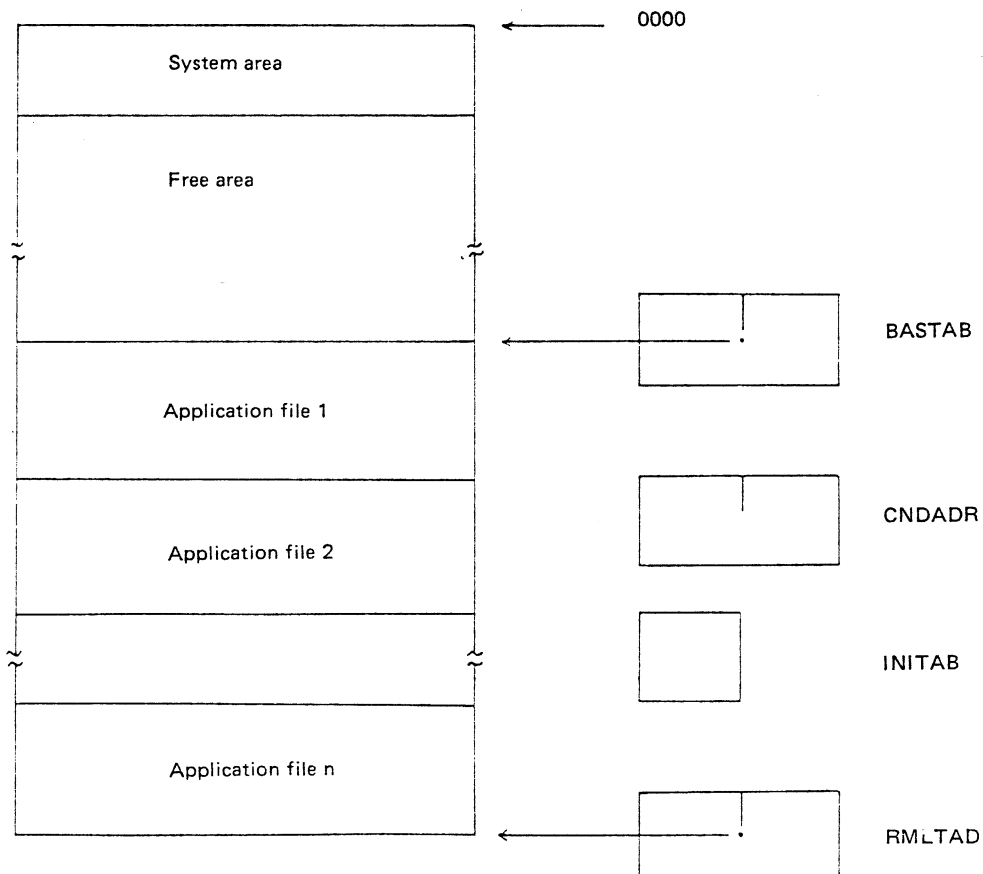


Fig. 18-4 Pointers Used for Application Files

Fig. 18-5 shows an example of when two application files exist simultaneously. The beginning of application file 1 is indicated by BASTAB while the end of application file 2 is indicated by RMLTAD.

(1) File size

The file size is shown by the first two bytes of the file in higher- and lower-order byte sequence. The starting address of the next application file can be obtained by adding the file size to the beginning address of the current file.

(2) Application ID

Application programs are assigned unique one-byte values which are used as IDs. These application IDs are used by application programs when searching for their files.

(3) Data

The data length is the file size - 3 bytes. Data format is optional. Unique formats may be used for individual application programs.

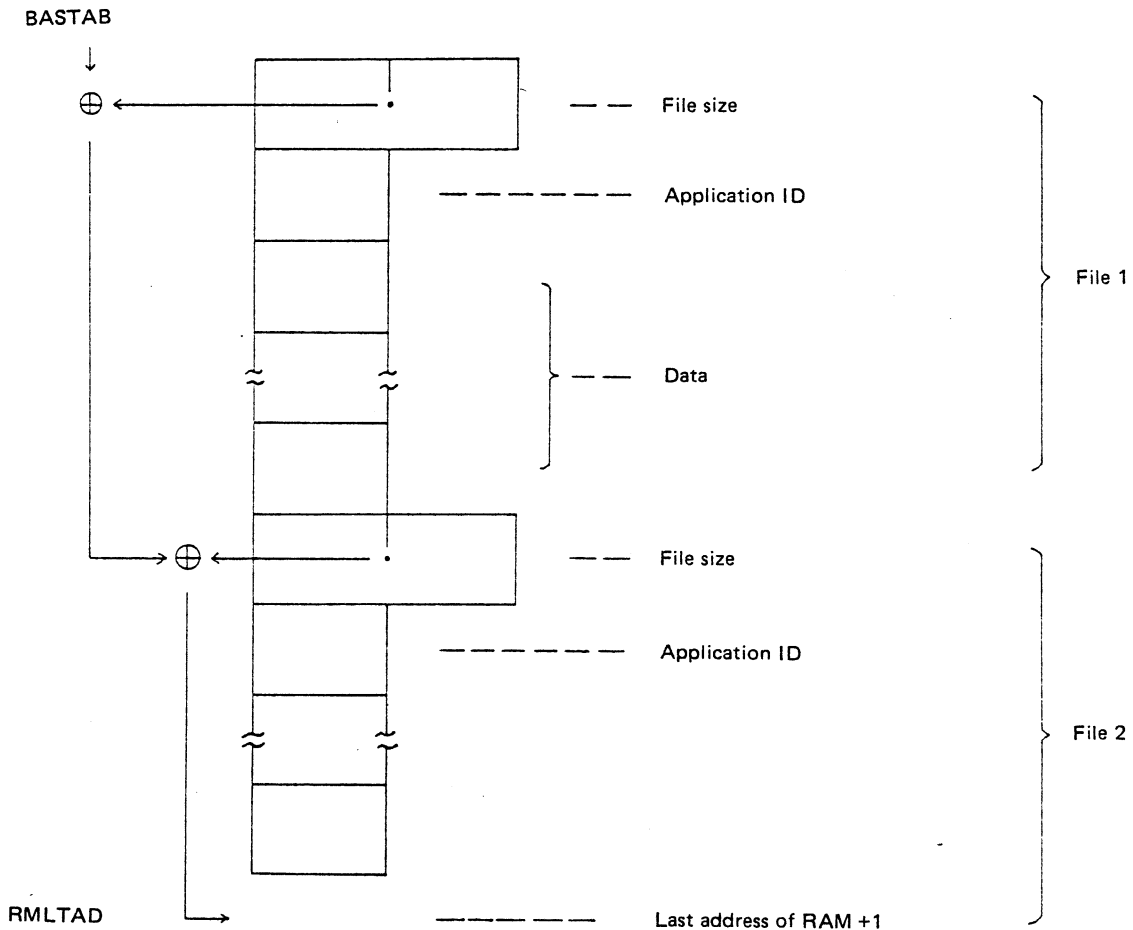


Fig. 18-5 Use of Pointers for Two Application Files

18.4.4 Configuration of BASIC application files

BASIC application files must be stored at the end of the application file area.

(1) Application ID

BASIC : 80_{16}

(2) Warm start hook

The one- to three-byte machine language command stored in this hook is executed to execute BASIC warm start. 39_{16} (RTS command) is set here when the system is initialized.

When the expanded BASIC code is stored in the RAM, a JMP command (C3XXXX) is set in this hook to transfer control to the initialize routine for expanded BASIC.

(3) Lowest address used by BASIC

The address specified in the MEMSET statement is set.

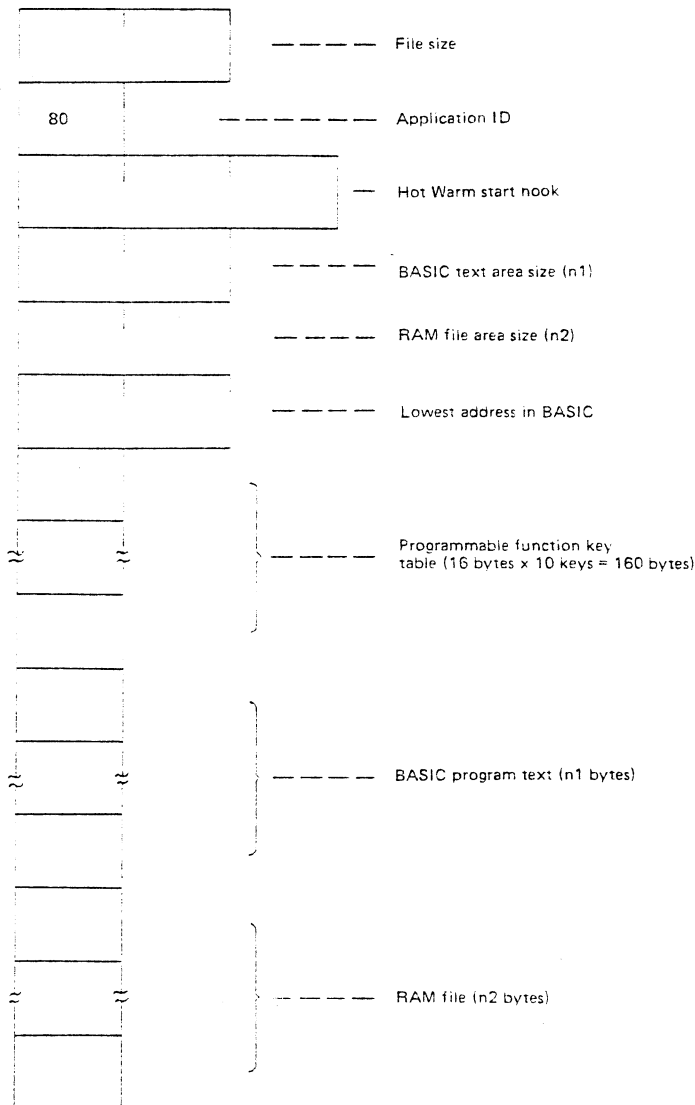


Fig. 18-6 Application File

18.5 Initializing Extended BASIC

18.5.1 Expansion method

When executing warm start, the BASIC interpreter copies the DCBs and the DCB tables from the ROM and initialize the hooks and pointers. To expand BASIC, these hooks and DCBs must be changed after warm start has been executed. Three methods of expanding BASIC (ROM base, RAM base and Disk base) are available.

After initialization has been completed, the BASIC interpreter executes BASIC expansion in the following sequence. The DCBs and hooks are rewritten by the initialize routines in ROM or RAM or by the DISK boot program.

- (1) Check executed for whether the expansion ROM has been set in the memory bank in which the BASIC interpreter is currently located. Control is transferred to (3) below, if the expansion ROM is not stored in this memory bank.
- (2) The initialize routine for the expansion ROM is executed.
- (3) Check executed for whether the floppy disk unit is available for serial communications. If the disk unit is not connected, control is transferred to (5) below.
- (4) The boot program is loaded from the floppy disk unit and then executed.
- (5) Warm start hook is executed. (If RAM-base expansion is to be executed, a JMP command to transfer control to the initialize routine is set in this hook.)

18.5.2 Expanded ROM format

Format for expanding BASIC on a ROM base is shown below.

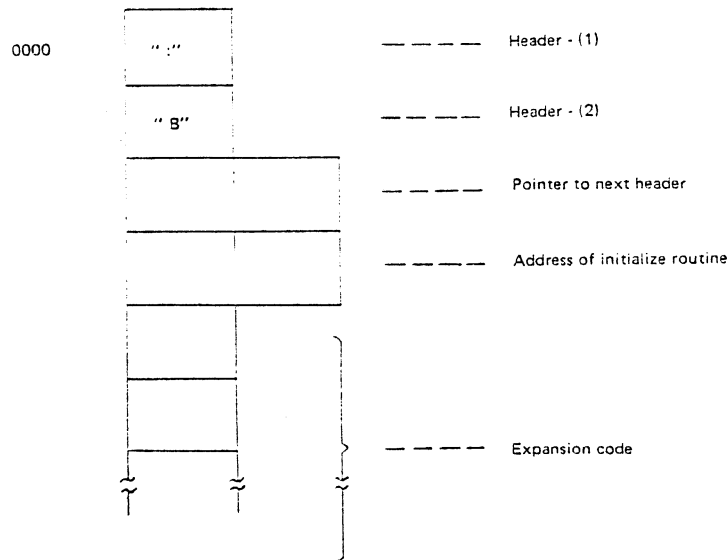


Fig. 18-7 Expanded ROM Format

Notes:

- (1) The expanded ROM for extended BASIC must be located in address 6000_{16} .
- (2) Other application programs may be stored in the same ROM with extended BASIC. However, the header of extended BASIC must be located at the starting address of the ROM.

18.5.3 Expansion on RAM base

18.5.3.1 Loading extended BASIC

The memory area for extended BASIC is reserved by creating a special application file at the end of the other application files. The procedure for loading extended BASIC is described below.

- (1) The BASIC interpreter is executed after initialization (CTRL/@).
- (2) Load extended BASIC and the program to reserve the necessary memory area into the machine language area (LOADM command).
- (3) Execute the program for reserving the memory area.

This program renews BASTAB and RMLTAD and reserves a RAM area sufficient to store extended BASIC. It then moves extended BASIC from the machine language area to these files. Also, the warm start hooks, etc., in the BASIC application file are rewritten and the initialize routine for extended BASIC is attached at the end of the initialize routine chain which starts from the warm start hook.

- (4) Transfer control to the BASIC interpreter warm start routine. The above sequence makes extended BASIC resident in the RAM. Thereafter, when warm start is executed, the initialize routine in extended BASIC rewrites the DCBs and hooks to expand BASIC.

As the area reserved for extended BASIC is at the end of the application files area, it remains unaffected even if the application files are used by other application programs.

The extended BASIC codes must be assembled to enable their use at the destination addresses. However, these addresses of course vary with the current RAM capacity. In order to enable use of the codes irrespective of the RAM capacity, extended BASIC must be relocated after it is moved to the RAM.

18.5.3.2 Program for reserving extended BASIC area

The procedure for reserving the necessary memory area for extended BASIC is described below.

- (1) When control is transferred to the program for reserving memory area, the BASIC interpreter is already running and the BASIC application files are already extended. The file reform routine is therefore called to store only the necessary data in the application files. (Fig. 18-8)

```
LDX    CNDADR
JSR    , X
AIM    #$BF, INITAB
```

- (2) Next, the BASIC application files are moved forward (BASTAB → RMLTAD-1) to reserve the area for extended BASIC. (BASTAB is also updated).

Simultaneously, (RMLTAD) is also updated and set at the head of the extended BASIC area to protect extended BASIC. (Fig. 18-9)

- (3) Extended BASIC, loaded simultaneously with the memory reserve program, is then moved to the newly reserved application files.

- (4) A jump command to transfer control to the initialize routine for extended BASIC is set in the warm start hook in the BASIC application file (currently, RTS command) or in the initialize hook for extended BASIC already existing in the RAM.
- (5) Control jumps to the BASIC interpreter warm start entry point.

```
LDX    $8004
JMP    0, X
```

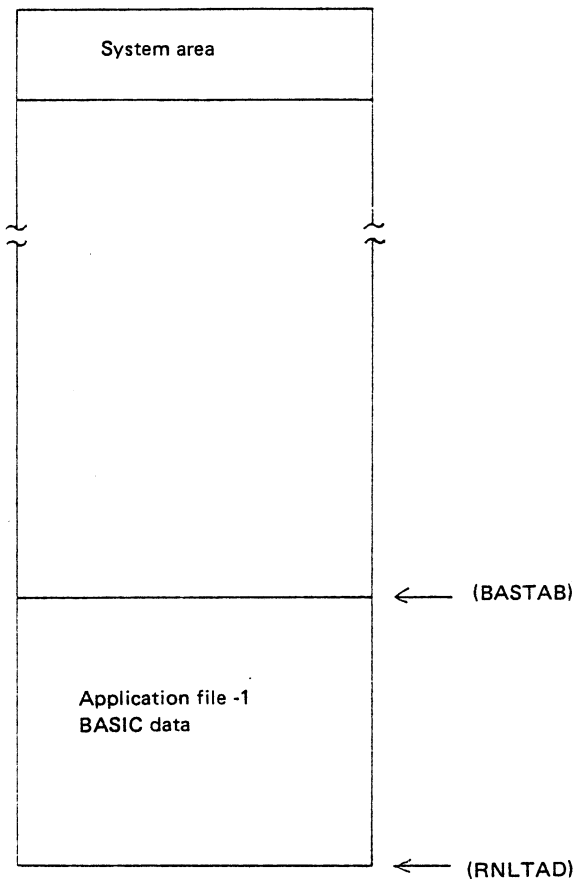


Fig. 18-8 Status before Reserving Memory Area

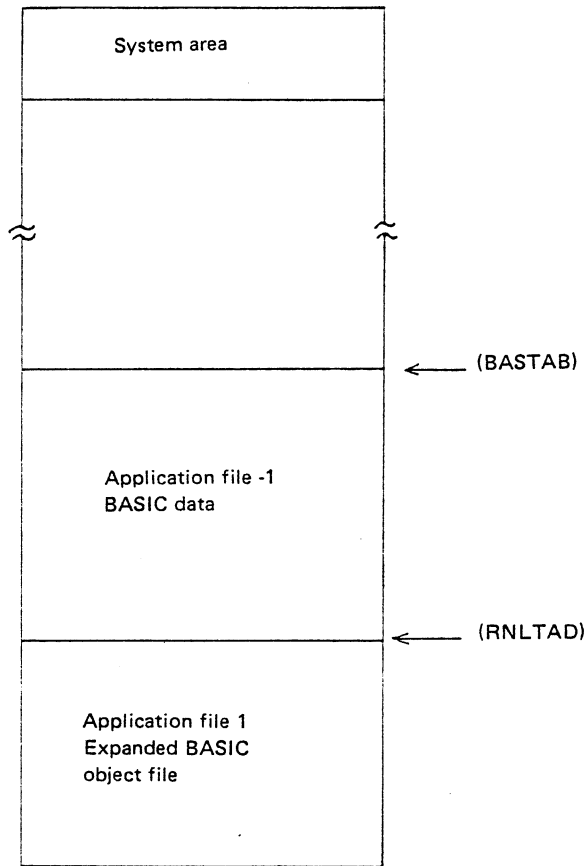
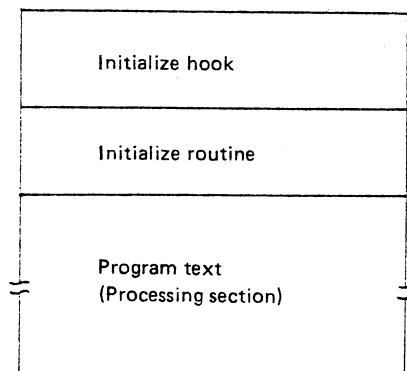


Fig. 18-9 Status after Reserving Memory Area

18.5.3.3 Configuration of extended BASIC object file
 The configuration of the extended BASIC object file is shown below.



(1) Initialize hooks

The initialize hook consists of the 3 bytes shown below. When multiple extended BASICs reside in the RAM, this hook is used to link the different initialize routines.

The initial value of the hook is RTS (39₁₆)

39	00	00
----	----	----

(2) Initialize routine

The initialize routine starts from the next address following the initialize hook. Each time BASIC is warm started, this routine rewrites the hooks, adds DCBs, etc.

When the initialize routine is entered, the pointer to the sign-on message is stored in register (X). This is either the current BASIC sign-on message or else the sign-on message set by the previous initialize routine for extended BASIC. The pointer to the sign-on message must be set in register (X) when the initialize routine is existed. To display a sign-on message for extended BASIC, set the pointer for the sign-on message in register (X) on exit from the initialize routine for extended BASIC. The sign-on message will then be output when control is returned to the BASIC interpreter or when control is transferred to the next initialize routine for extended BASIC. If the set message is to be output when the initialize routine is entered, STROUT should be called on entry.

If above sign-on message is not to be output, the value of register (X) should be retained so that this register can be returned to its initial value on exit from the initialize routine. In this case, the normal message or the message set by the previous initialize routine will be output.

(3) Chaining initialize routines

When multiple extended BASICs are to be expanded on the RAM, the initialize routines for all of these BASICs must be executed at warm start. First, as the warm start hook has been rewritten to transfer control to the first BASIC initialize routine, this routine is executed.

Upon completion of execution of the initialize routine, control jumps to the initialize hook. At this stage, if the initialize hook is still set to its initial value, the RTS command will be executed and control returned to the BASIC interpreter. If the initialize hook has been rewritten to jump to another BASIC initialize routine, that routine will be executed next. Initialize routines can in this way be chained and executed in succession until the RTS command is encountered.

18.5.3.4 Rewriting warm start and initialize hooks

The procedure for adding the initialize routine for an extended BASIC, newly loaded in the RAM, to the end of the execution chain starting from the warm start hook is described below.

- (1) The warm start hook in the BASIC application file is checked. If the value of the warm start hook has not been rewritten (that is, if it is still RTS), it is rewritten to jump to the initialize routine for extended BASIC.

If the warm start hook has already been rewritten (if a jump command has been set), operation proceeds to (2) below.

- (2) The extended BASIC initialize hook at the jump destination of the warm start hook is checked. If it has not been rewritten, it is rewritten to jump to the initialize routine for the newly loaded extended BASIC.

If the initialize hook has already been rewritten (if a jump command has been set), control is returned to (2). This operation is repeated until an initialize hook in which RTS has not been rewritten is encountered.

18.5.4 Extended BASIC work area

The following RAM area is used as the work area for extended BASIC irrespective of whether BASIC has been expanded on the ROM or on the RAM.

0A38 -- 0A3D 6 bytes

For RAM base expansion, if the work area is insufficient, a work area in the application files is reserved along with the area required for loading extended BASIC. For ROM base expansion, a RAM area is reserved with the application files as in RAM base. This area is then used as the work area. (Subroutines are set in the ROM and executed manually (EXEC command) after system initialize.)

The same procedure is followed to retain data in extended BASIC.

18.6 System Variables and Hook Table

18.6.1 System variables

(1) INITAB (address 0078₁₆, 1 byte)

Bits 0 to 5 and bit 7 are initialize request flags. One bit is assigned for each application. The flag is set (logic "1") to indicate that initialization has been executed. It is reset at system initialize.

The bit of this variable corresponding to the application program to be executed is checked prior to execution if the program requires initialization for its files, etc. If the flag is reset (logic "0"), initialize processing is performed to reserve the necessary work areas, etc., for the files and execution of the program is performed only after the INITAB flag becomes "1". If the flag is set (logic "1"), this means that the application program has already been initialized. It can therefore be executed immediately. INITAB flags are not assigned to application programs which do not require initialization.

Bits currently used are as follows.

Bit 0 ----- Menu program

Bit 7 ----- BASIC interpreter

Bit 6 is a file reform request flag. For application programs which require their files be expanded, the pointer to the file reform routine must be set in variable CNDADR and bit 6 of INITAB must also be set after file expansion has completed.

The file reform routine is called by the menu program and resets bit 6 of INITAB after reforming the files.

(2) RMLTAD (address 012C₁₆, 2 bytes)

This is the pointer for the last address in the RAM +1. This variable is set at system initialize. Also functions as the pointer for the last address of the application files +1.

(3) BASTAB (address 0134₁₆, 2 bytes)

Pointer to the starting address of the application files. Set to the same address as RMLTAD at system initialize.

(4) CNDADR (address 0136₁₆, 2 bytes)

Pointer to the file reform routine. Set by the application program. Valid only if INITAB bit 6 is also set.

(5) DCTAB (address 0657₁₆)

DCB table

(6) DEVNUM (address 063E₁₆)

Enables LOAD from expansion devices.

(7) ASCFLG (address 068C, 2 bytes)

Specifies mode (ASCII or binary) for load. Set by the device OPEN routine.

The BASIC interpreter interprets the flag status as follows:

FF: ASCII load

0: Binary load

(8) OPTBUF (address 068F)

The character string in the file descriptor used to specify options is set in this buffer. The option routine uses this data. The file descriptor option statement is set in this buffer in its original form. It is not placed in brackets. (00) is used as the end mark. If (00) is entered as the first character, option is assumed not to have been specified.

18.6.2 Hook table

(1) HKLOAD (address 05E2₁₆)

Enables LOAD from expansion devices.

(2) HKABTD (address 063C₁₆)

Used to initialize expansion devices in case of ABORT.

18.6.3 Entry Point Table

	<u>Label name</u>	<u>Address</u>
(1)	ERROR	8433
(2)	ABTDO	A9D8
(3)	FCERR	8C70
(4)	LODCNT	A6D0

18-19

2

1. LCD CONTROLLER/DRIVER HD1220
2. HD1468 RTC (real time clock)
3. HD5301V MCU (Microcomputer Unit)
4. MNEMONIC CODES
5. INSTRUCTION CODES

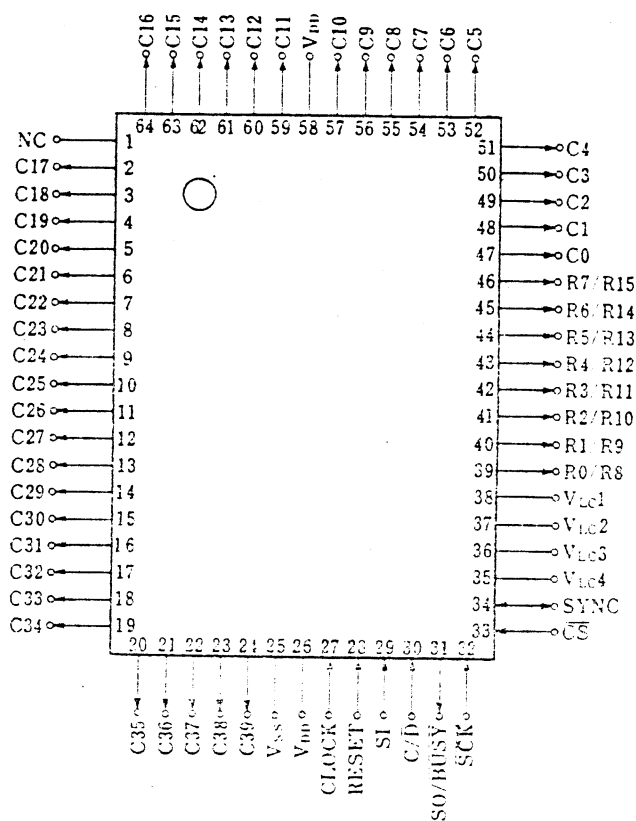
1. LCD CONTROLLER/DRIVER μ PD7227G

The μ PD7227G, an LCD (Liquid Crystal Display) controller/driver programmable by software, interfaces with the CPU in the microcomputer application system and can directly drive the 8 or 16 time-sharing dot matrix LCD. It also incorporates a character generator that generates specific patterns.

FEATURES

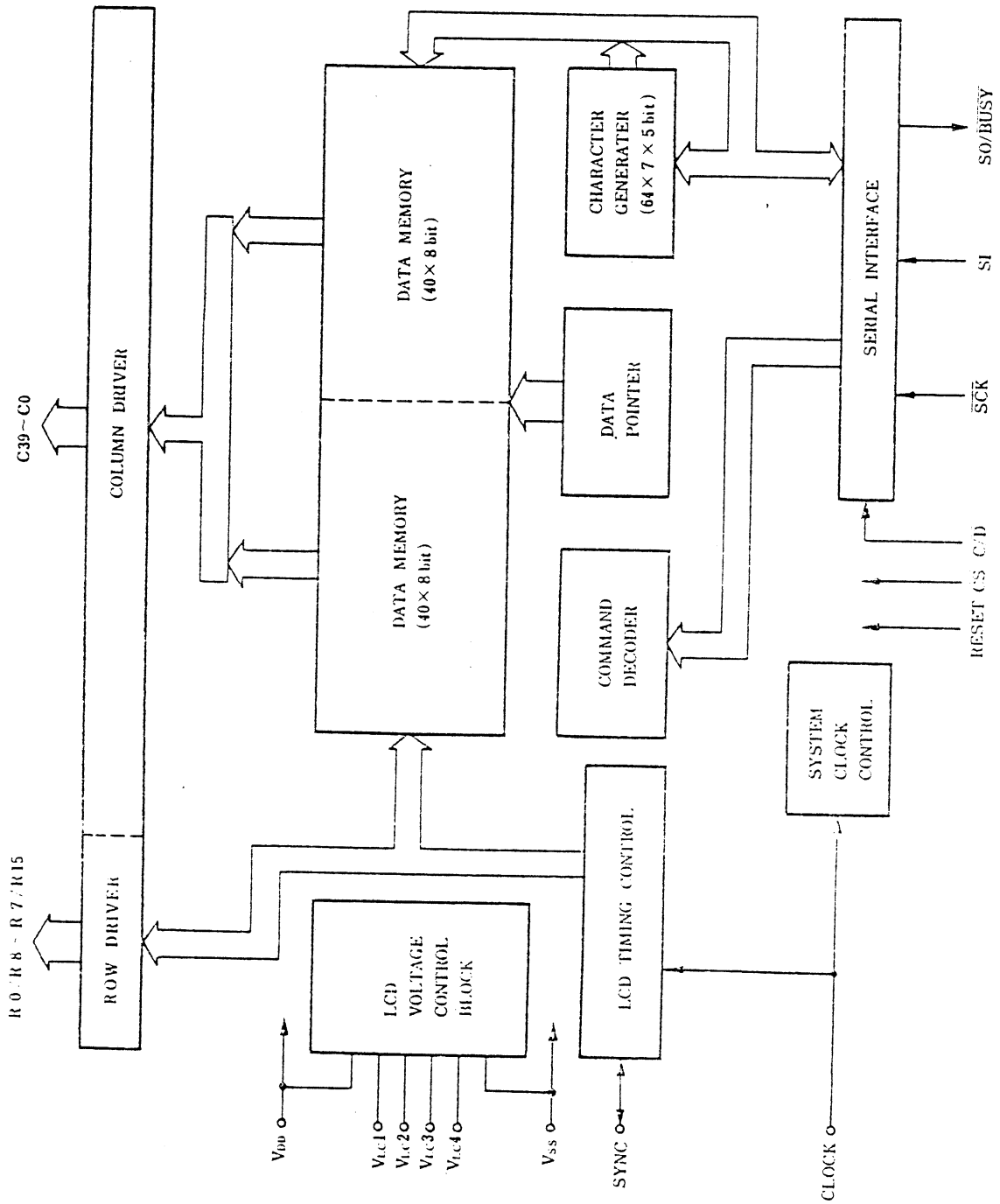
- Direct LCD drive
- Time-sharing for drive (Note 1)
 - 8 time-sharing (single/multi-chip structure)
 - 16 time-sharing (2-chip structure or above)
- Expandable multi-chip display digits
- Expandable multi-chip display digits
- 5 x 7 character generator which can generate 36 alphanumeric characters and 28 symbols
- 8-bit serial I/O compatible with μ PD7500 series, μ COM-43n series, and μ COM-87 serial interface
- 12 types of controller commands
- CMOS
- Single power supply
- 64-pin plastic flat package

Terminal assignment diagram (Top view)



Note 1: The HX-20 is a 16 time-sharing type.

BLOCK DIAGRAM



FUNCTIONS OF TERMINALS

(1) SI (Serial Input) terminal: Input
This terminal inputs serial commands and data from the μ PD7227.

(2) $\overline{\text{SO/BUSY}}$ terminal: Output
This terminal functions not only as the serial data output terminal (SO function) but also as the BUSY signal that permits and inhibits the serial data transfer. The SO and BUSY functions are switched according to the state of the C/D terminal only in the read mode set by an SRM command.

The BUSY function is always used in modes other than Read mode. The $\overline{\text{SO/BUSY}}$ terminal enters a high-impedance state when the CS terminal becomes High level.

The SO function is selected in read mode when the $\overline{\text{C/D}}$ terminal is Low level and is used to output the contents of data memory.

The BUSY function is used when the CPU checks whether or not the μ PD7227 can input and output serial data.

(3) $\overline{\text{SCK}}$ terminal: Input
This terminal inputs the serial clock that shifts the contents of the serial register and latches a signal from the SI terminal, and inputs and outputs serial data in synchronization with the input serial clock.

The serial clock input when the $\overline{\text{CS}}$ terminal is High level is ignored.

(4) $\overline{\text{C/D}}$ terminal: Input
This terminal specifies the serial command and data input from the SI terminal. When the $\overline{\text{C/D}}$ terminal become High level, the BUSY function of the $\overline{\text{SO/BUSY}}$ terminal is selected. When the terminal becomes Low level, the SO function is selected.

Operating mode	C/D	$\overline{\text{SO/BUSY}}$	SI
Write, AND, OR, and Character modes	0	<u>BUSY</u>	Data input
	1	$\overline{\text{BUSY}}$	Command input
Read mode	0	SO	Invalid
	1	<u>BUSY</u>	Command input

(5) SYNC (Synchronous) terminal: I/O
This terminal performs the wire-OR operation to increase the number of multi-chip display digits. When multi-chips are configured (a row/drive signal is used together), one of the chips is selected as a master chip and the SYNC terminal of that selected master chip is used as output mode. The SYNC terminal of the slave chip is used as input mode. An SMM (Set Multiplexing Mode) command is used to specify I/O. The master chip outputs a SYNC signal per frame. Other slave chips fetch the output SYNC signals to the LCD timing controller to tune the alternating drive signal and the frame cycle to the master chip.

- (6) \overline{CS} (Chip Select) terminal: Input
This is a low active chip select input terminal. When this terminal becomes Low level, the serial data transmission/reception between the μ PD7227 and a microcomputer, etc., is enabled.
- (7) C0~C39 column terminals: Output
These output terminals function as the column drive signals.
- (8) R0/R7-R8/R15 row terminals: Output
These output terminals function as the ROW0-ROW7 or the ROW8-ROW15 row drive signals. The SMM command is used to select these signals.
- (9) V_{LC1} - V_{LC4} (LCD Drive Voltage) terminals: Input
These are the LCD drive voltage input terminals that generate the LCD drive signals (row/column drive signals).
- (10) RESET terminal: Input
This is a high active reset input terminal.
- (11) CLOCK terminal: Input
This terminal directly inputs an external clock. When multi-chips are configured, a clock with the same frequency and phase must be supplied to the CLOCK terminal of each μ PD7227.
- (12) V_{DD}
This is a positive power supply terminal for the system.
- (13) V_{SS}
This is a ground (GND) potential terminal for the system.

μPD7227 Commands

Both the $\overline{C/D}$ terminal and the \overline{BUSY} signal must become High level before μPD7227 commands are input. The μPD7227 commands are stored in the serial register via the SI terminal in synchronization with the serial clock to be input from the \overline{SCK} terminal. The command decoder decodes the commands in the serial register and then performs processing according to the decoded commands.

- (1) LCD display mode commands
 - i) SFF (Set Frame Frequency)

0 0 0 1 0 F₂ F₁ F₀

Sets the frame frequencies. The frame frequencies are obtained by demultiplying the clocks input from the CLOCK terminal by the demultiply rates specified by bits F₂ through F₀ of the SFF command.

F ₂	F ₁	F ₀	Frame frequency
0	0	0	$f_{cl}/2^{14}$ ← HX-20
0	0	1	$f_{cl}/2^{13}$
0	1	0	$f_{cl}/2^{12}$
0	1	1	$f_{cl}/2^{11}$
1	0	0	$f_{cl}/2^{10}$

NOTE: fcl indicates the clock frequency.

- ii) SMM (Set Multiplexing Mode)

0 0 0 1 1 M₂ M₁ M₀

Specifies the time-sharing count, the I/O operation of the SYNC terminal, and data memory banks (effective only for the 8 time-sharing specification). This command is also used to select the row driver functions.

M ₂	M ₁	M ₀	Time-sharing count	Selection of driver functions	SYNC terminal	Data memory bank spec.
0	0	0	↑ 8 ↓	ROW0-ROW7	Input	Bank 0
0	0	1		ROW0-ROW7	Input	Bank 1
0	1	0		ROW0-ROW7	Output	Bank 0
0	1	1		ROW0-ROW7	Output	Bank 1
1	0	0	↑ 16 ↓	ROW8-ROW15	Input	Banks 0 and 1
1	0	1		ROW8-ROW15	Input	Banks 0 and 1
1	1	0		ROW0-ROW7	Output	Banks 0 and 1
1	1	1		ROW0-ROW7	Output	Banks 0 and 1

HX-20 ←

iii) DISP OFF (Display Off)

0 0 0 0 1 0 0 0

Erases the LCD display indicating the relationship between the row and column signals regardless of the displayed data.

iv) DISP ON (Display On)

0 0 0 0 1 0 0 1

Displays data according to the displayed data.

(2) Mode setting commands for data processing

Five mode setting commands are available: SRM (Set Read Mode), SWM (Set Write Mode), SANDM (Set AND Mode), SORM (Set OR Mode), and SCM (Set Character Mode). These commands are used to set the modes to control the I/O operations and specify the update operation of a data pointer according to the states of bits I_1 and I_0 of each command. Note that the update operation is performed only when data is input/output.

I_1	I_0	Data pointer operation
0	0	The pointer is incremented by 1 each time data is input/output.
0	1	The pointer is decremented by 1 each time data is input/output.
1	0	Inhibited
1	1	The same address is retained even after data I/O operation.

For example, if $I_1, I_0=00$ is specified in the SWM command, the data pointer is incremented by 1 each time data is written. After execution of the SWM command, data is sequentially written into the data memory indicated by the data pointer.

In this case, the set mode is retained until other I/O command is executed.

i) SRM (Set Read Mode)

0 1 1 0 0 0 1 0

Sets read mode, specifies to update the data pointer according to the state of bits I_1 and I_0 of this command each time data is read, and loads the contents of the memory indicated by the current data pointer to the serial register.

ii) SWM (Set Write Mode)

0 1 1 0 0 1 1 0

Sets write mode and specifies to update the data pointer according to the specification of I_1 and I_0 of this command each time data is written. In this mode, the serial data in the serial register is directly written into the data memory by the μ PP7227.

iii) SANDM (Set AND mode)

0 1 1 0 1 1 I₁ I₀

Sets AND mode and specifies to update the data pointer according to the specification of I₁ and I₀ of this command each time data is written. In this mode, the serial data in the serial register is ANDed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory by the μ PD7227.

iv) SORM (Set OR Mode)

0 1 1 0 1 0 I₁ I₀

Sets OR mode and specifies to update the data pointer according to the specification of I₁ and I₀ of this command each time data is written.

In this mode, the serial data in the serial register is ORed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory by the μ PD7227.

v) SCM (Set Character Mode)

0 1 1 1 0 0 1 0

Sets character mode. In this mode, the serial data in the serial register is written into the data memory via the character generator. In this mode, the data pointer is incremented by 5 each time one character (5 x 7 bits) is written into the data memory.

(3) Memory bit manipulation commands

i) BSET (Bit Set)

0 1 0 B₂ B₁ B₀ J₁ J₀

Sets the bits specified by B₀ through B₂ of the data memory addressed by the data pointer and updates the data pointer according to the specification of codes J₁ and J₀ of this command.

The data pointer can be updated according to the specification of J₁ and J₀ only when the BSET or the BRESET command is executed. Control returns to one of the SRM, SWM, SANDM, and SORM commands after the data pointer is updated by the BSET or the BRESET command.

For example, suppose that data is read from address 15. After address 15 after I₁, I₀=00 (auto increment) is specified in the SRM command. In this case, the data pointer indicates address 16 because it is incremented by 1 after data is read from address 15. If the BSET command where J₁, J₀=01 (auto decrement) is specified is executed, the specified bit of address 16 is set and the data pointer indicates address 15 because it is decremented by 1. If data is read from address 15 again, the data pointer indicates address 16 because it is incremented by 1.

J ₁	J ₀	Data pointer operation
0	0	The data pointer is incremented by 1.
0	1	The data pointer is decremented by 1.
1	0	Inhibited
1	1	The same address is retained.

ii) BRESET (Bit Reset)

0	0	1	B ₂	B ₁	B ₀	J ₁	J ₀
---	---	---	----------------	----------------	----------------	----------------	----------------

Resets the bits specified by B₀ through B₂ of the data memory addressed by the data pointer and updates the data pointer according to the specification of codes J₁ and J₀ of this command after the reset.

J₁ and J₀ of the BRESET command have the same meaning as those of the BSET command.

(4) Data pointer specification command

LDPI (Load Data Pointer with Immediate Data)

1	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
---	----------------	----------------	----------------	----------------	----------------	----------------	----------------

Sets immediate data D₀ through D₆ in the data pointer.

DATA I/O

(1) Data input

i) Write mode

Write mode is set by the SWM command. Serial data must be input after checking that the $\overline{\text{BUSY}}$ signal output from the SO/ $\overline{\text{BUSY}}$ terminal becomes High level. 8-bit serial data beginning with an MSB (Most Significant Bit) is first supplied to the SI terminal, concurrently with the serial clock supplied to the SCK terminal. The μPD7227 then stores the serial data input from the SI terminal in the serial register in synchronization with the serial clock and directly writes it in the data memory addressed by the data pointer when the eighth serial clock rises. The μPD7227 updates the data pointer according to the specification of codes I_1 and I_0 . Once 8-bit serial data is stored in the serial register, the μPD7227 enters the busy state and outputs the $\overline{\text{BUSY}}$ signal (SO/ $\overline{\text{BUSY}}$ =Low) from the SO/ $\overline{\text{BUSY}}$ terminal. $\overline{\text{BUSY}}$ remains effective while the serial data in the serial register is internally being processed. No new serial data can be input during this period. In other words, new serial data can be input after $\overline{\text{BUSY}}$ is released (SO/ $\overline{\text{BUSY}}$ =High).

ii) AND mode

AND mode means the same as Write mode except that the serial data in the serial register is ANDed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory by the μPD7227 .

iii) OR mode

OR mode means the same as Write mode except that the serial data in the serial register is ORed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory by the μPD7227 .

iv) Character mode

In Character mode, the serial data (5 x 7 bits) in the serial register is decoded by the character generator and is stored in the data memory. In this mode, the data pointer is incremented by 5 each time one decoded character is written into the data memory. The I/O operations of serial data in this mode are the same as those in Write mode.

(2) Data output

i) Read mode

The $\overline{\text{C/D}}$ terminal and the $\overline{\text{BUSY}}$ output from the SO/ $\overline{\text{BUSY}}$ terminal must be High level before serial data is read from the serial register. If $\overline{\text{BUSY}}$ is already High level, the $\overline{\text{C/D}}$ is set to Low level and the SO/ $\overline{\text{BUSY}}$ to the SO function to initiate the serial data output. 8-bit serial data beginning with an MSB is first supplied to the SO/ $\overline{\text{BUSY}}$ (SO function) in synchronization with the 8-clock serial clock. The μPD7227 then loads the contents of the data memory addressed by the data pointer to the serial register when the eighth serial clock rises. The μPD7227 enters the $\overline{\text{BUSY}}$ state after the load. To read serial data from the serial register, the $\overline{\text{C/D}}$ and the $\overline{\text{BUSY}}$ of the SO/ $\overline{\text{BUSY}}$ must be set to High level again.

ii) Command input during Read mode

When an SWM, SANDM, SORM, or SCM command is input, the current mode changes to that specified by the input command. If another command is input, the contents of the data memory addressed by the data pointer are stored in the serial register by the μ PD7227 after that command is processed. In this case, the μ PD7227 updates the data pointer according to the specification of I_1 and I_0 of the SRM command. If the BSET or the BRESET command is input, the contents of the serial register addressed by the data pointer updated according to the specification of J_1 and J_0 after execution of the input command are stored in the serial register by the μ PD7227. Always note the data pointer operation because the μ PD7227 updates the data pointer according to the specification of I_1 and I_0 or J_1 and J_0 after serial data is written or read. For example, if the contents of address n are stored in the serial register by the μ PD7227 after $I_1, I_0=0,0$ is specified in the SRM command, the data pointer indicates address n+1. If the DISP OFF command is input, the current mode changes to read mode and the contents of address n+1 are stored in the serial register by the μ PD7227. Note that the contents of address n is not output from the SO/BUSY. (Since DISP OFF command is input with C/D=High level, the SO/BUSY becomes BUSY.)

Internal Clock Function

(1) Serial interface

The serial interface, which consists of an 8-bit serial register and a 3-bit SCK counter, inputs μ PD7227 commands, and inputs and outputs data in units of 8 bits.

i) Serial data input

Serial data is stored in the serial interface in synchronization with the serial clock to be output to the $\overline{\text{SCK}}$ terminal.

Serial data is input from the SI terminal per bit each time a serial clock rises (the first bit to be input is an MSB) and then stored in the μ PD7227 serial register starting from the LSB (bit 0).

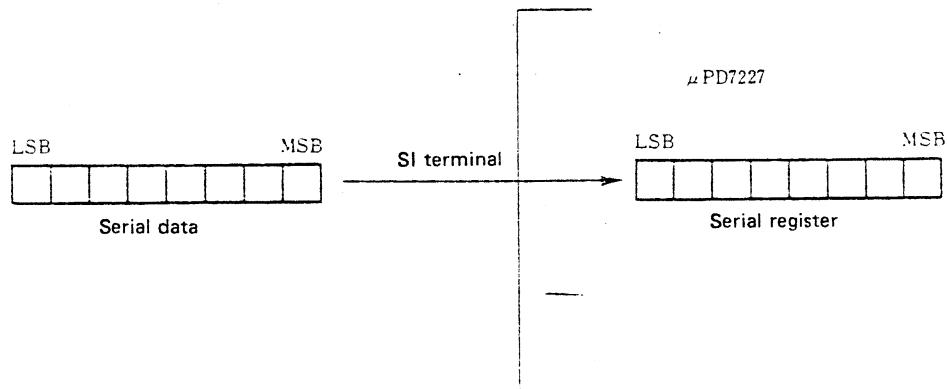


Fig. 3 Structure of Serial Data

The serial data stored in the serial register shifts when the next serial clock falls. The SCK counter counts up when the serial clock rises and issues an overflow indicating that 1-byte (8 bits) serial data has been input when the eighth serial clock rises. In this case, the serial interface stores the contents of the $\overline{\text{C/D}}$ terminal in the serial register in synchronization with the eighth serial clock and checks whether the stored contents are data or commands. If the contents are those of a command ($\overline{\text{C/D}}=\text{High}$), the serial interface stores them in the command decoder. If they are data ($\overline{\text{C/D}}=\text{Low}$), the interface processes them in Write, AND, OR, or Character mode. When 8-bit serial data (8 serial clocks) is sent, $\overline{\text{BUSY}}$ ($\text{SO}/\overline{\text{BUSY}}=\text{Low}$) is also output. This $\overline{\text{BUSY}}$ remains effective while the μ PD7227 is in process of the previously input serial data. No new serial data can be input during this period. In other words, new serial data can be input any after $\overline{\text{BUSY}}$ is released ($\text{SO}/\overline{\text{BUSY}}=\text{High}$).

ii) Serial data output

Serial data is output from the serial register when a serial clock is supplied to the \overline{SCK} terminal as in the case of the data input. Serial data is output from the serial register in turn via the SO/\overline{BUSY} terminal if serial register shifts when serial clock falls. In this case, the first bit to be output is an MSB.

The SCK counter counts up when a serial clock rises and issues an overflow indicating that one-byte data (8-bit data) has been output when the eighth serial clock rises.

The contents of the data memory addressed by the data pointer are stored in the serial register when the eighth bit rises. These contents are output via the SO/\overline{BUSY} terminal (C/\overline{D} =Low) when a serial clock is supplied. The input of the \overline{SCK} is inhibited until next serial data is stored in the serial register after output of 8-bit serial data but \overline{BUSY} (SO/\overline{BUSY} =Low) is output. Note that the C/\overline{D} terminal must be set to High and the \overline{BUSY} of the SO/\overline{BUSY} must be released (SO/\overline{BUSY} =High) before serial data is output from the serial register.

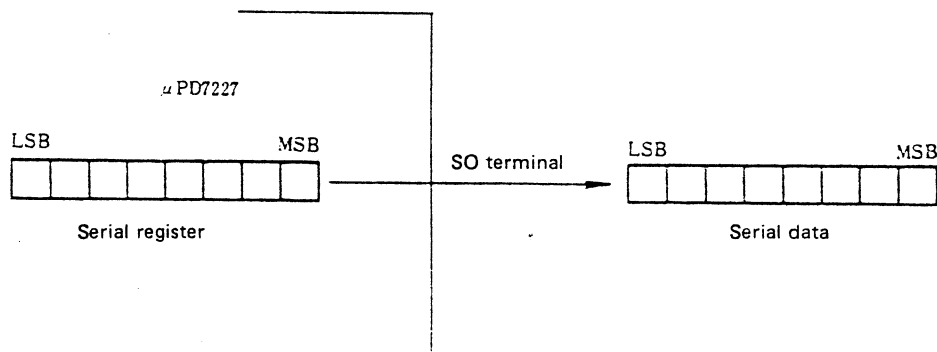


Fig. 4 Structure of Serial Data

(2) Command decoder

The command decoder decodes the commands fetched from the serial register and controls the $\mu PD7227$ according to the decoded commands.

(3) Character generator

The character generator, which can be used in Character mode only after execution of the SCM command, generates 36 alphanumeric characters and 28 symbols from the input data (7 x 5 dot matrix). In Character mode, the character generator decodes the serial data sent from the serial register and stores in it in the corresponding data memory (C/\overline{D} =Low). Since decoded data is written into the data memory in 7 x 5 bit format, bit 7 of each data memory address can hold the previous data because it is not affected at all by the write operation. The data pointer is incremented by 5 each time one character is written into the data memory.

Fig. 5 shows the structure of the 8 time-sharing LCD when the character generator is used. Fig. 6 shows the structure of the 16 time-sharing LCD.

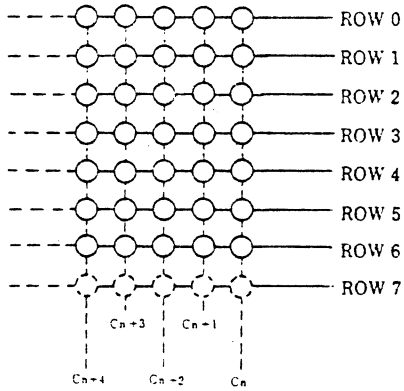


Fig. 5 Structure of 8 time-sharing LCD

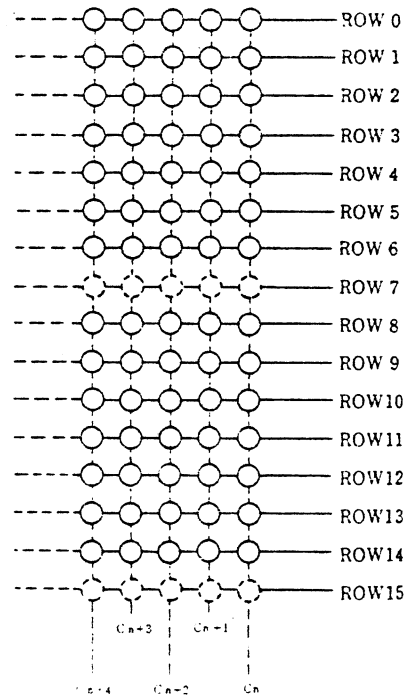


Fig. 6 Structure of 16 time-sharing LCD

NOTE: The portions indicated by can be used as a cursor and an indicator because they display the contents of bit 7 in each data memory address regardless of the displayed characters.

Fig. 7 shows the correspondence between serial data and display patterns in character mode.
 When D6 through D0 are 1111111 or 00000000, all the dots light up.

				0	0	1	1	D6
				1	1	0	0	D5
D3	D2	D1	D0	0	1	0	1	D4
0	0	0	0					
0	0	0	1					
0	0	1	0					
0	0	1	1					
0	1	0	0					
0	1	0	1					
0	1	1	0					
0	1	1	1					
1	0	0	0					
1	0	0	1					
1	0	1	0					
1	0	1	1					
1	1	0	0					
1	1	0	1					
1	1	1	0					
1	1	1	1					



Fig. 7 Correspondence between Serial Data and Display Patterns in Character Mode

(4) Data pointer

The data pointer, which consists of a 6-bit binary counter and a 1-bit bank flag, specifies the memory bank and its addresses.

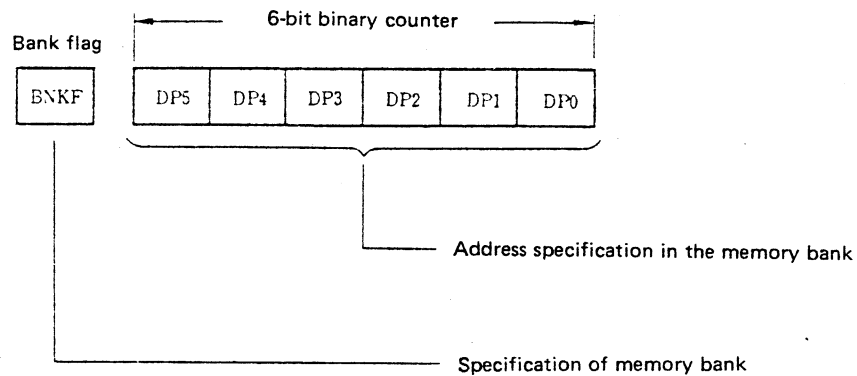


Fig. 8 Structure of the Data Pointer

The bank flag specifies banks 0 and 1 (40 x 8 bits) and is set/reset by the D₆ of an LDPI command. D₆=0 specifies bank 0 and D₆=1 specifies bank 1.

The 6-bit binary counter specifies the bank address and is set by the D₅ through D₀ of the LDPI command. The address specification area of each bank is from address 0 through address 39. Although the 6-bit binary counter can take 40 through 63 (for example, if decrement is performed from 0, 63 is assumed) by setting immediate data or using the automatic increment or decrement function, nothing is performed because there is no data memories corresponding to these values.

The data pointer is updated as follows when data is input and output:

i) Data I/O

In Read, Write, AND, and OR modes, the μ PD7227 updates the data pointer according to the specifications of I₁ and I₀ of the commands that set the above modes each time data is input and output.

In Character mode, the data pointer is incremented by 5 each time 8-bit data is input.

ii) Command input or execution

When the BSET or the BRESET command is executed, the μ PD7227 updates the data pointer according to the specifications of J₁ and J₀ of the command. After the update, the data pointer returns to the state of I₁ and I₀ before execution of the BSET or BRESET command.

When Read mode is set by the SRM command, the μ PD7227 loads the contents of the data memory to the serial register according to the data pointer and updates the data pointer according to the specification of I₁ and I₀ of this command. The data pointer is not updated if commands other than the BSET, BRESET, SRM, and LDPI commands are executed.

(5) Data memory

The μ PD7227 incorporates two 40 x 80 bit data memories each of which consists of banks 0 and 1. Display data from the character generator (Character mode) and the serial register (Write mode) are written into these memories. They can be used not only to execute the AND (AND mode) and OR (OR mode) operations for the serial register but also to set/reset the specific bits. The specific bits are set when the BSET command is executed and are reset when the BRESET command is executed. In Read mode, the contents of the data memory addressed by the data pointer are loaded to the serial register. As explained in (4), the data pointer specifies banks 0 and 1.

Since the μ PD7227 automatically sends the contents of the data memory to the column driver in bits independently of the I/O operations of the serial register, converts them into appropriate column driver signals, and outputs the signals from the column driver signal output terminal, the data write operation, etc., is not affected at all by the serial data transmission. The relationship between the column drive signals and the row drive signals is determined according to the bit contents read from the data memory. If the bit contents are 1, the corresponding LCD element goes to the selection level and then lights up. If they are 0, the corresponding LCD element goes to the nonselection element and then goes out.

i) Writing data into a data memory

Serial data is written into the data memory in the following four modes: The bit set/reset operations can also be used when serial data is written into the data memory.

◦ Write mode

Write mode is set by the SWM command. In this mode, serial register data is directly written into the memory bank addressed by the data pointer.

◦ Character mode

Character mode is set by the SCM command. In Character mode, serial register data is decoded in 7 x 5 bit format (one character) by the character generator and is written into the data memory addressed by the data pointer. This means that each decoded data is written into the data memory in 5 bytes. Since the MSB (Most Significant Bit) of each address is not used in this mode, the previous data still remains effective even after decoded data is written into the data memory.

◦ AND mode

AND mode is set by the SANDM command. In this mode, serial register data is ANDed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory.

◦ OR mode

OR mode is set by the SORM command. In this mode, serial register data is ORed with the contents of the data memory addressed by the data pointer and then the result is stored in the data memory.

- Bit set operation
Three bits of the data memory addressed by the data pointer are set by specifying B₂ through B₀ of the BSET command. The set bits are released when the command execution terminates and the current mode returns to the mode (Write, Character, AND, OR, or Read mode) before execution of the BSET command.
- Bit reset operation
Three bits of the data memory addressed by the data memory are reset by specifying B₂ through B₀ of the BRESET command. The reset command bits are released when the command execution terminates and the current mode returns to the mode (Write, Character, AND, OR, or Read mode) before execution of the BRESET command.
- ii) Loading the contents of the data memory to the serial register
The contents of the data memory addressed by the data pointer are loaded to the serial register by specifying the SRM command.
- iii) Reading display data from the data memory
Display data to drive the LCD is read from the data memory in bits. The column driver converts the read display data into an appropriate column driver signal and outputs it from the column driver signal output terminal. The read operation of display data depends on the time-sharing count.

◦ 16 time-sharing

In 16 time-sharing drive, banks 0 and 1 function as 16 x 40 bit data memory. Display data is read in turn from bit 0 of each address in bank 0 in synchronization with the row drive signals. Fig. 10 shows how row drive signals ROW0 through ROW7 and ROW8 through ROW15 are supplied.

μ PD7227

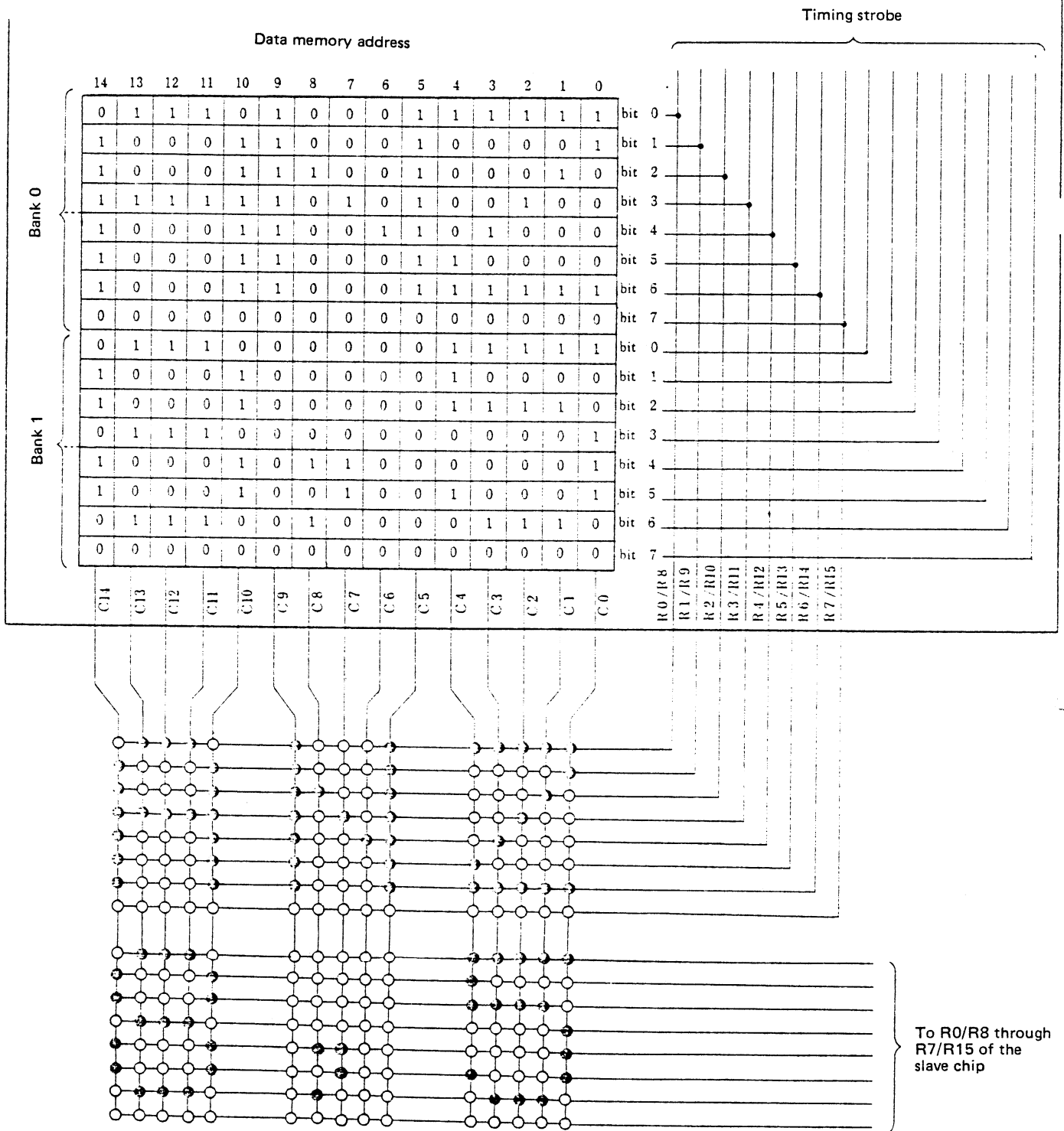


Fig. 10 16 Time-sharing

- (6) Column driver signals C0 through C39
The column driver converts the display data read from address 0 through address 39 of the data memory into appropriate column drive signals and outputs them from the column drive signal output terminal. C0 through C39 are selected by the LCD timing controller and display data based on the LCD drive standard voltage input from the LCD voltage control block. The 1 alternating drive signal of each column drive signal contains one bit display information.
- (7) Row driver signals R0/R7 through R8/R15
The row driver generates row drive signals ROW0 through ROW7 and ROW8 through ROW15. When M2-M0=0-3 is executed by the SMM command, the row driver generates ROW0 through ROW7 at the timing of 8 time-sharing drive input from the LCD timing controller and outputs them from the row drive signal output terminal. When M2-M0=6,7 is executed by the SMM command, the row driver generates ROW0 through ROW7 at the timing of 16 time sharing drive input from the LCD timing controller and outputs them from the row drive signal output terminal. When M2-M0=4,5 is executed by the SMM command, the row driver generators ROW8 through ROW15 at the timing of the 16 time-sharing drive input from the LCD timing controller and outputs them from the row drive signal output terminal. The row driver can only generate either ROW0 through ROW7 or ROW8 through ROW15 at 16 time-sharing. Therefore, to display the LCD at 16 time-sharing, the following must be satisfied:
- ° Two or more μ PD7227s are provided.
A set of ROW0 through ROW15 is created by outputting ROW0 through ROW7 from the master chip and ROW8 through ROW15 from the slave chip.
- (8) LCD timing controller
The LCD timing controller generates an LCD drive timing using the time-sharing count and the demultiply rate, supplies it to the column and row drivers, and at the same time outputs the SYNC signal from the SYNC terminal that synchronizes with the display timing of each μ PD7227 when multi-chips are configured. When the SYNC terminal of each μ PD7227 is wired OR, the ROW signal can be used, enabling the display digit area to be expanded.
- (9) LCD voltage control block
The LCD voltage control block inputs LCD drive standard voltages from V_{LC1} through V_{LC4} and supplies them to the column and row drivers.
The column and row drivers generate the drive voltages for the column and row drive signals from these supplied voltages.

Control Function

(1) Chip select function

When the \overline{CS} terminal becomes Low level, the μPD7227 is activated, enabling serial data to be input/output.

i) $\overline{CS}=1$

When the \overline{CS} terminal is 1 (high), the \overline{SI} , \overline{SCK} , and $\overline{C/\overline{D}}$ terminals becomes High level in the μPD7227 regardless of the input level and the $\text{SO}/\overline{\text{BUSY}}$ terminal enters the high-impedance state.

ii) \overline{CS} rise

When the \overline{CS} becomes High level (rises) during I/O operation, the SCK counter is cleared, invalidating the transmission/reception of 8-bit data.

When the \overline{CS} becomes Low level, the transmission/reception of 8-bit data is enabled.

(2) RESET function

When a high 3-clock cycle is input from the RESET terminal, the μPD7227 is reset and then enters the states in i) and ii) below.

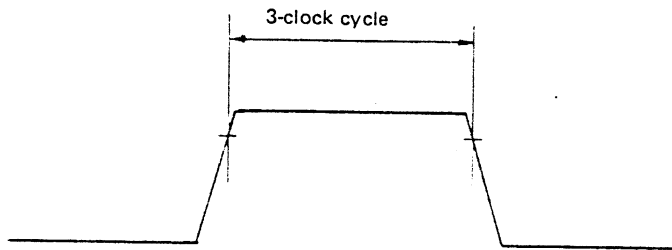


Fig. 13 RESET Waveform

i) Reset state

- When the \overline{CS} is Low level, the $\text{SO}/\overline{\text{BUSY}}$ also becomes Low level. When the \overline{CS} is High level, the $\text{SO}/\overline{\text{BUSY}}$ enters the high impedance state.

- The VLC3 signal is output from both the column drive signal output terminal and the row drive signal output terminal.

ii) State after reset

When the μPD7227 is reset, the SCK counter is cleared and then enters the state when one of the following commands is executed:

$\text{SWM}(I_1, I_0=00)$:

The data pointer is incremented by 1 in Write mode each time data is input.

$\text{LDPI}(D_6-D_0=0000000)$:

The data pointer is cleared.

DISP OFF :

Both the row drive and column signals go to the nonselection level.

$\text{SMM}(M_2-M_0=000)$:

The LCD uses an 8 time-sharing drive; the $\text{R0}/\text{R7}$ through $\text{R8}/\text{R15}$ terminals output ROW0 through ROW7 ; the SYNC terminal is used for input; the display data memory specifies bank 0.

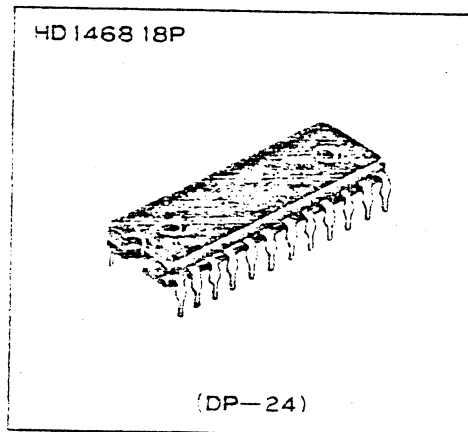
$\text{SFF}(F_2-F_0=000)$:

The frame frequency is set to $f_{cl}/2^{14}$.

2. HD146818RTC (Real Time Clock)

The HD146818RTC is an HMCS6800 microcomputer peripheral LSI with the clock/calendar function that can count year, month, day, day of the week, hour, etc.

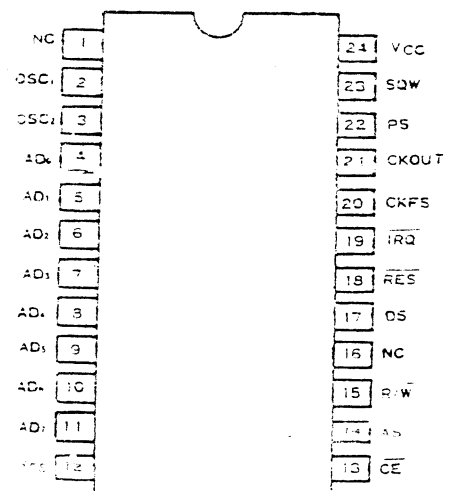
It incorporates a 50-byte user RAM and has the timer function that generates square waves, periodic interrupts, etc. The HD146818RTC can be directly connected to MCUs such as HD6801 and HD6301 through the multiplexed bus interface. It can also be directly connected to the 8085-system microprocessor because it incorporates the 8085-system interface circuit. The HD146818RTC is also designed to save power consumption.



FEATURES

- Clock/calendar function that can count second, minute, day, day of the week, year, and month.
- 64-byte address spaces
 - 10 bytes for clock, alarm, and calendar RAMs
 - 4 bytes for a control register
 - 50 bytes for a general user RAM
- Three types of interrupts
 - Periodic interrupt
 - Alarm interrupt
 - Update ended interrupt
- Square wave output
- Three types of standard clocks
 - 4.194304 MHz
 - 1.048576 MHz
 - 32.768 KHz
- Binary/BCD display switching of the clock and calendar
- 12- and 24-hour mode switching for hour display
- Built-in automatic leap-year compensation circuit
- Direct connection of the HD146818RTC to the HD6801 and HD6301 via the multiplexed bus

Pin Arrangement



Top View

- Built-in 80-system interface circuit
- Lower CMOS power consumption
- Compatible with the MC146818 (Motorola Corporation)

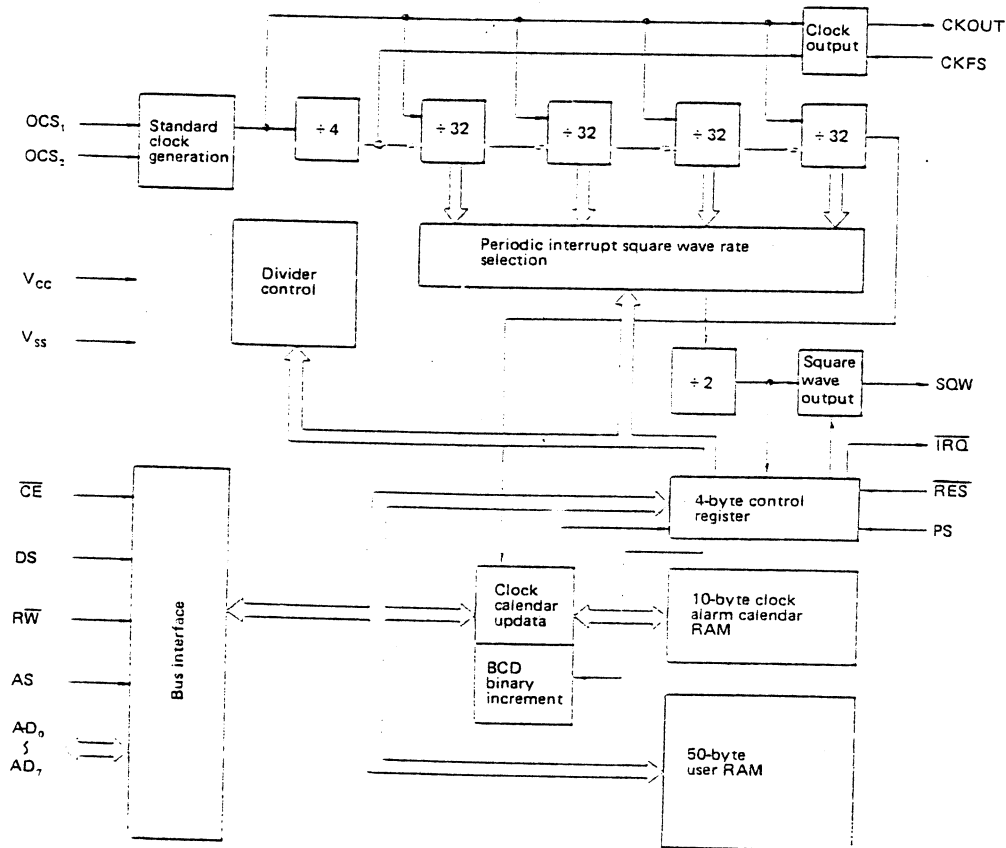


Fig. 1 Internal Block Diagram

LSI FUNCTIONS

Clock Function

The RTC updates the contents of the RAM areas for hour, calendar, and display using the update cycle function once per second and displays the updated year, month, day, day of the week, and hour on the internal RAM.

The processor reads the contents of the internal RAM. Table 2 lists the data displayed on the internal RAM.

Static CMOS RAM (general-purpose 50-byte user RAM)

Necessary data maintained by the system can be stored in this RAM because the RTC is used after battery backup.

Square Wave Generation

The demultiply circuit in the RTC generates a square wave to be supplied to the SQW terminal. The frequency of the generated square wave can be selected by the program. The SQW signal is used as a standard clock signal in the system.

Square Wave Generation

The demultiply circuit in the RTC generates a square wave to be supplied to the SQW terminal. The frequency of the generated square wave can be selected by the program. The SQW signal is used as a standard clock signal in the system.

Three Independent Interrupts

Periodic interrupt

This interrupt can occur once per 30 μ s to per 500 ms.

Alarm interrupt

This interrupt can occur only when the time set for this matches that (hour, minute, second) set for an alarm. The interrupt is usually specified so that it can occur at the specified time of a day. When the "11xxxxxx" codes (don't care codes) are written for an alarm, an alarm interrupt occurs per the specified hour, minute, and second. Example: If the "don't care" codes are written in the RAM for an hour alarm when 13:25:30 is specified, an alarm interrupt occurs.

Update ended interrupt

This interrupt occurs each time the time update terminates.

HD146818

Update Cycle Function

The HD146818 updates the calendar once per second when the SET bit of register B is 0. The basic update cycle function is that it reads the second, minute, hour, day of the week, day, month, and year displayed on the internal RAM, updates them if necessary, and writes them into the corresponding areas. The HD146818 compares each alarm specification byte and each time during the update cycle for the alarm judgment.

The update time required for 4.19340- and 1.048576-MHz standard clocks is 248 μ s while that required for the 32.768 MHz standard clock is 1984 μ s. The time, calendar, and alarm bytes cannot be accessed by the program during the update cycle. If the RAM is read before update processing completes, "FF" indicating that update processing is in progress is output. The program may read this "FF" value because it accesses the RAM asynchronously. The RAM can be accessed in the following three methods without the update cycle function:

In the first method, an update ended interrupt is used to access the RAM. Since the date to be used for approx. 999 ms after this interrupt occurs is already decided in this method, no update cycle occurs.

In the second method, the UIP (Update In Progress) bit of register B is used to check whether or not the update cycle is in progress. The UIP bit is set once per second. The update cycle starts 244 μ s after the UIP bit is set. Since the contents of the time/calendar do not change for at least 244 μ s (Buc) after the UIP bit is cleared if register A is read, the RAM can be accessed during this period. When the UIP bit is 1, the contents of the time/calendar becomes "FF".

In the third method, the periodic interrupt is used to check whether or not the update cycle is in progress.

This interrupt is designed to avoid the update cycle when it is issued. In other words, since the update cycle is not performed during $(tpI/2)+t_{BUC}$ if the periodic interrupt cycle is greater than the value obtained by adding t_{UC} to t_{BUC} , the contents of the time/calendar do not change.

Table 1 lists the update cycle time.

Table 1 Update Cycle Time

UIP Bit	Time Base (OSC1)	Update Cycle Time t_{UC}	Minimum Time Before Update Cycle Starts
1	4.194304MHz	248 μ s	—
1	1.048576MHz	248 μ s	—
1	32.768kHz	1984 μ s	—
0	4.194304MHz	—	244 μ s
0	1.048576MHz	—	244 μ s
0	32.768kHz	—	244 μ s

* The update cycle time for the HX-20 is 32.768 kHz.

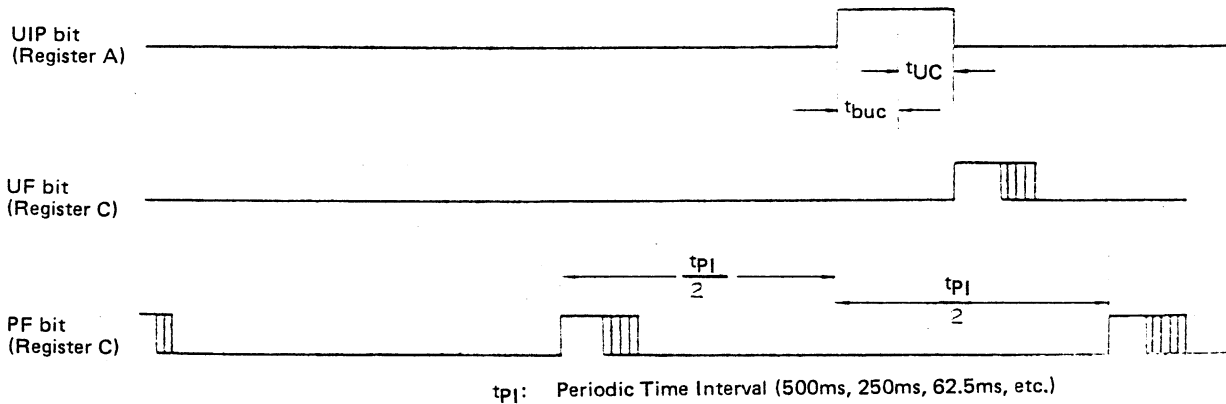


Table 2 Data Format of Time, Calendar and Alarm

Address	Function		Decimal data range	Hexadecimal data range	
				Binary data mode	CD data mode
0	SECONDS		0 to 59	00 to 3B	0 to 59
1	SECONDS ALARM		0 to 59	00 to 3B	0 to 59
2	MINUTES		0 to 59	00 to 3B	0 to 59
3	MINUTES ALARM		0 to 59	00 to 3B	00 to 59
4 (Note 1)	HOURS	12-hour mode	1 to 12	01 to 0C/31 to 8C*	01 to 12/81 to 92C*
		24-hour mode	0 to 23	00 to 17	00 to 23
5 (Note 2)	HOURS ALARM	12-hour mode	1 to 12	01 to 0C/81 to 8C*	01 to 12/81 to 92*
		24-hour	0 to 23	00 to 17	00 to 23
6	DAY OF THE WEEK		1 to 7**	01 to 07	01 to 07
7	DATE OF THE MONTH		1 to 31	01 to 1F	01 to 31
8	MONTH		1 to 12	01 to 0C	01 to 12
9	YEAR		0 to 99***	00 to 63	00 to 99

Note 2

*: The highest-order bit (MSB) is used to distinguish a.m. from p.m.

0: a.m. (AM)

1: p.m. (PM)

** : 1: Sunday

2: Monday

Note 1: The HX-20 uses 24-hour mode.

3: Tuesday

Note 2: The HX-20 uses BCD data mode.

4: Wednesday

5: Thursday

6: Friday

7: Saturday

***: The lower-order 2 digits are set in A.D.

LSI STRUCTURE

Address Map

The HD146818 incorporates the 64-byte memory address consisting of the general-purpose 5-byte RAM, 10-byte RAM for time, day, and alarm data, and four 1-byte registers. The processor can directly read the contents of this memory address.

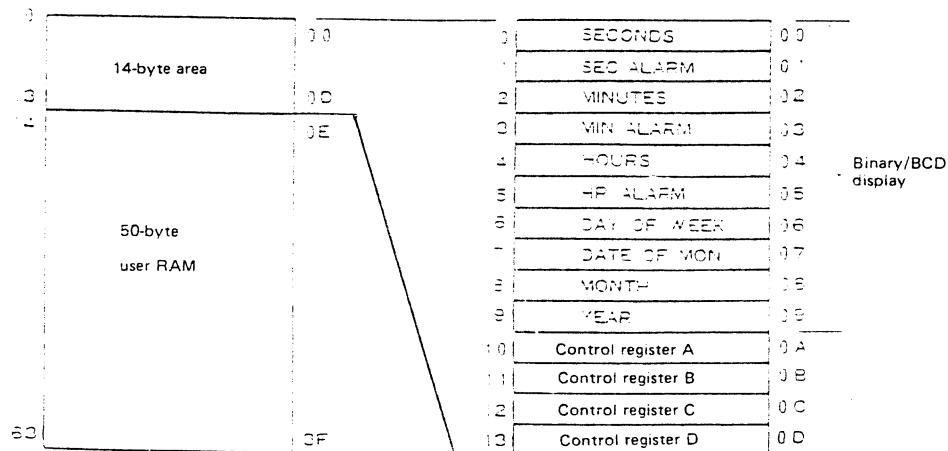


Fig. 2 Address Map

EXPLANATION OF TERMINALS

V_{CC} and V_{SS}

The power supply is connected between these two terminals. The V_{CC} is connected to the plus side of the power supply. The V_{SS} is connected to the ground side.

OSC1 and OSC2 (standard clocks): Input

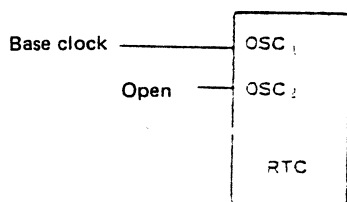
These terminals are used to connect a crystal oscillator or an external base clock. 4.19430 MHz is used for the crystal oscillator as its frequency. Either 4.19430 MHz or 32.768 kHz is used for the external base clock. The bits of control register A are used to specify these frequencies.

Table 3 Base clocks

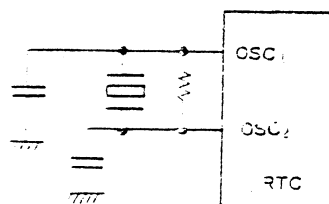
Base clock frequency	CKFS input signal	CKOUT output signal frequency
4.194304 MHz	"High"	4.194304 MHz
	"Low"	1.048578 MHz
1.048576 MHz	"High"	1.04857 MHz
	"Low"	262.144 kHz
32.768 kHz	"High"	32.768 kHz
	"Low"	8.192 kHz

*: These frequencies apply only to the external clocks.

→
HX-20 clock



(External base clock connection)



(Crystal oscillator connection)

CKOUT (Clock Out): Output

This terminal is a clock output signal created by demultiplying the base clock signal by $\div 1$ or $\div 4$. The level of the CKFS input signal is used to specify the demultiply rate. This terminal can also be used as a system base clock (Table 3).

CKFS (Clock Out Frequency Select): Input

This terminal is the input signal that specifies the demultiply rate for the CKOUT output signal. When this terminal is connected to the V_{CC} , the frequency same as that of the OSC1 pin is specified for the CKOUT output.

When this terminal is connected to the V_{SS} , the 4 demultiplied frequency ($\div 4$) is specified (Table 3).

AD₀ through AD₇ (Multiplexed Address/Data Bus)

AD₀ through AD₇ are the bi directional buses that not only send address information used by the processor to access the RTC but also inputs and outputs data. The first half of the cycle is used to send address information while the second half of the cycle is used to send data. The address information to be used must be determined before the AS signal falls. The RTC uses AD₀ through AD₇ as address information in the first half of the cycle. Data to be used must be determined before the second half of the cycle.

The data bus driver used as the three-state output buffer is always in the high-impedance state unless the RTC outputs data.

AS (Multiplexed Address Strobe): Input

This strobe signal fetches address information from the multiplexed address bus. Address information to be fetched is stored in the RTC when this signal falls.

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Table 4 Divider Selection Bits

Base clock frequency	Divider selection			CKFS Input	CKOUT Output	Norm. mode	Test mode	Div. reset	No. of dividers bypassed
	DV2	DV1	DV0						
4.194304 MHz	0	0	0	High Low	4.194304 MHz 1.048576 MHz	o	-	-	N=0
1.048576 MHz	0	0	0	High Low	1.048576 MHz 262.144 kHz	o	o	-	N=2
32.768 kHz	0	1	0	High Low	32.768 kHz 8.192 kHz	o	o	-	N=7
--	0	1	1	-	-	o	o	-	N=12
--	1	0	0	-	-	-	o	-	N=17
--	1	0	1	-	-	-	o	-	N=22
--	1	1	0/1	-	-	-	-	o	-

Bits RS3 through RS0 (Rate Selection)

Bits RS3 through RS0 are used to tap the divider circuits to generate square waves and periodic interrupts. These bits can be set only by the program but are not affected by \overline{RES} at all. They can be read and written.

Table 5 Relationship between the rate selection bits, periodic interrupts, and SQW

Rate selection bit				4.194304 MHz or 1.048576 MHz		32.768 kHz	
RS3	RS2	RS1	RS0	Periodic interrupt cycle	SQW output frequency	Periodic interrupt cycle	SQW output frequency
0	0	0	0	-	-	-	-
0	0	0	1	80.517 μ s	32.768 kHz	23.90625 ms	256 Hz
0	0	1	0	61.035 μ s	16.384 kHz	7.8125 ms	128 Hz
0	0	1	1	122.070 μ s	8.192 kHz	122.070 μ s	8.192 kHz
0	1	0	0	244.141 μ s	4.096 kHz	244.141 μ s	4.096 kHz
0	1	0	1	488.281 μ s	2.048 kHz	488.281 μ s	2.048 kHz
0	1	1	0	976.562 μ s	1.042 kHz	976.562 μ s	1.024 kHz
0	1	1	1	1.953125 ms	512 Hz	1.953125 ms	512 Hz
1	0	0	0	3.960625 ms	256 Hz	3.960625 ms	256 Hz
1	0	0	1	7.8125 ms	128 Hz	7.8125 ms	128 Hz
1	0	1	0	15.625 ms	64 Hz	15.625 ms	64 Hz
1	0	1	1	31.25 ms	32 Hz	31.25 ms	32 Hz
1	1	0	0	62.5 ms	16 Hz	62.5 ms	16 Hz
1	1	0	1	125 ms	6 Hz	125 ms	8 Hz
1	1	1	0	250 ms	4 Hz	250 ms	4 Hz
1	1	1	1	500 ms	2 Hz	500 ms	2 Hz

HX-20

DS (Data Strobe): Input

This terminal inputs the $\phi 2$ clock (E: Enable) signal of the HMCS6800 system. This signal becomes High level when the processor reads data from the RTC and becomes Low level when the processor writes data into the RTC. The RD signal is input when the 8085 system is used.

R/ \overline{W} (Read/Write): Input

This terminal inputs the R/ \overline{W} signal of the HMCS6800 system. This signal becomes High level when the processor reads data from the RTC and becomes Low level when the processor writes data into the RTC. The \overline{WR} signal is input when the 8085 system is used.

\overline{CE} (Chip Enable): Input

This input terminal (signal) becomes Low level when the LSI is accessed. The level of this signal must be determined during one cycle. The RTC cannot be accessed when the signal is High level.

\overline{IRO} (Interrupt Request): Open drain output

This active low level output signal requests the processor to issue an interrupt. If the interrupt factor is set in the start bit when the interrupt enable bit is set, this signal becomes Low level.

This signal is released when the processor reads control register C. In other words, this signal is released because the pending interrupt factor is cleared when the \overline{RES} signal becomes Low level. If no interrupt request is issued, the signal enters the high-impedance state. It can be connected to other \overline{IRQ} signal using a pull-up resistor.

\overline{RES} (Reset): Input

This input signal resets the RTC. When this signal becomes Low level, the write/read operations of the internal register and the RAM are inhibited and the following operations are performed:

- (1) The Periodic Interrupt Enable (PIE) bit is cleared.
- (2) The Alarm Interrupt Enable (AIE) bit is cleared.
- (3) The Update Ended Interrupt Enable (UIE) bit is cleared.
- (4) The interrupt request status flag is cleared.
- (5) The Periodic Interrupt Flag (PF) is cleared.
- (6) The Alarm Interrupt Flag (AF) is cleared.
- (7) The Update Ended Interrupt Flag (UF) is cleared.
- (8) The \overline{IRQ} terminal enters the high impedance state.
- (9) The Square Wave Output Enable (SQWE) bit is cleared.

\overline{RES} does not affect the functions of the clock calendar and the RAM. When the power is turned on, the RLH of this signal listed in the Electric Characteristic Table must be Low level.

PS (Power Sense): Input

This input signal is used along with the VRT (Valid RAM and Times) bit of control register 4. When PS becomes Low level, the VRT bit is cleared.

Control Registers

The RTC incorporates four control registers accessible by the program. These registers can be accessed even during update cycle.

Control register A

b7	b6	b5	b4	b3	b2	b1	b0
UIP	DV2	DV1	DV0	RS3	RS2	RS1	RS0

Bit UIP (Update in Progress)

Bit UIP is a read-only status flag that can be monitored by the program. When this bit is 1, the update cycle is in progress or is initiated immediately. When the bit is 0, the update cycle is not in progress but the program can use information on the RAM time, a calendar, and an alarm. This bit is not affected by \overline{RES} at all.

Bits DV2, DV1, and DV0 (Divider Selection)

These bits are used:

- (1) To specify the basic frequencies: 4.19 MHz, 1 MHz, and 32 kHz.
- (2) To reset and restart the internal 22-tier (row) divider circuit.
- (3) To specify the LSI test mode.

The update cycle starts one second after the reset status is released. These bits can be read/written but only the program can set them. They are not affected by RES at all.

Control register B

b7	b6	b5	b4	b3	b2	b1	b0
SET	PIE	AIE	UIE	SQWE	DM	24/12	DSE

Bit SET (Set)

Bit SET is used to interrupt the update cycle when the time and date are set. When this bit is 0, the update cycle is performed once per second. When this bit is 1, the update cycle is interrupted, causing the UIE bit to be cleared. This bit can be set only by the program but is not affected by RES at all.

Bit PIE (Periodic Interrupt Enable)

Bit PIE is used to specify whether or not to output the $\overline{\text{IRQ}}$ signal according to the status of the periodic interrupt flag (PF). When this bit is 1, the periodic interrupt request is output from $\overline{\text{IRQ}}$. When this bit is 0, no periodic interrupt request is output from $\overline{\text{IRQ}}$ but the PF bit is periodically set. The program can set/reset this bit but RES can only reset it.

Bit AIE (Alarm Interrupt Enable)

Bit AIE is used to specify whether or not to output $\overline{\text{IRQ}}$ according to the status of the alarm interrupt flag (AF). An alarm interrupt occurs when the three bytes of second, minute, and hour correspond to the three alarm bytes. When this bit is 1, an update ended interrupt request is output from $\overline{\text{IRQ}}$. When this bit is 0, no update ended interrupt request is output but the AF bit is set if the condition is established. The program can set/reset this bit but RES can only reset it.

Bit UIE (Update Ended Interrupt Enable)

Bit UIE is used to specify whether or not to output $\overline{\text{IRQ}}$ according to the status of the update ended interrupt flag (UF). When this bit is 1, an update ended interrupt request is output from $\overline{\text{IRQ}}$. When this bit is 0, no update ended interrupt request is output from $\overline{\text{IRQ}}$ but the UF bit is set even if the update cycle completes. The program can set/reset this bit but RES can only reset it.

Bit SQWE (Square Wave Enable)

When bit SQWE is set, the square wave with the frequency specified by one of rate selection bits RE3 through RE0 is output from the SQW terminal. When this bit is 0, SQW remains at Low level. This bit is specified only by the program but is not affected by RES at all.

Bit DM (Data Mode)

Bit DM is used to specify the binary or BCD mode in whose mode the time and calendar are displayed.

DM=1: Binary mode

DM=0: BCD mode

Only the program can specify this bit.

Bit 24/12 (24/12 Control)

Bit 24/12 is used to specify the 24- or 12-hour mode.

24/12=1: 24-hour mode

24/12=0: 12-hour mode

Only the program can specify this bit.

Bit DSE (Daylight Saving Enable)

When bit DSE is 1, the following special update operations are performed:

(1) Last Sunday of April From 1:59:59AM
to 3:00:00AM

(2) Last Sunday of October From 1:59:00AM
to 1:00:00AM

When this bit is 0, these operations are not performed. Only the program can specify this bit.

Control register C

b7	b6	b5	b4	b3	b2	b1	b0
IRQF	PF	AF	UF	0	0	0	0

(Read only)

Bit IRQF (Interrupt Request Flag) Not used (0 is set when this bit is read.)

Bit IRQF is set when the following conditions are satisfied:

PF=PIE=1

AF=AIE=1

UF=UIE=1

IRQF=PF.PIE+AF.AIE+UF.UIE

When this bit is set, $\overline{\text{IRQ}}$ always becomes Low level. This bit is cleared when control register 3 is read or RES becomes Low level.

Bit PF (Periodic Interrupt Flag)

Bit PF is set according to the cycle specified by one of RS3 through RS0. This bit is set independently of the PIPF bit but the $\overline{\text{IRQ}}$ signal and the IRQF bit become Low level or are set only when the PIE bit is 1. This bit is cleared when control register 3 is read.

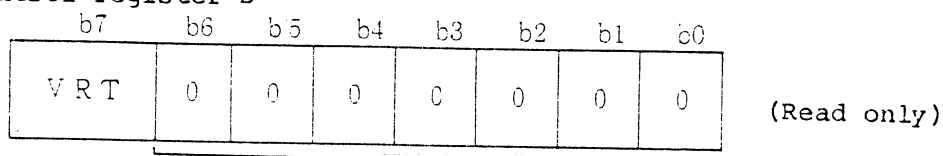
Bit AF (Alarm Interrupt Flag)

Bit AF is set when the specified time matches the set alarm time. This bit is set independently of the AIE bit but the \overline{IRQ} signal and the IRQF bit become Low level or are set only when the AIE bit is 1. This bit is cleared when control register 3 is read or \overline{RES} becomes Low level.

Bit UF (Update Ended Interrupt Flag)

Bit UF is set each time each update cycle completes. This bit is set independently of the UIE bit but the \overline{IRQ} signal and the IRQF bit become Low level or are set only when the UIE bit is 1. This bit is cleared when control register 3 is read or \overline{RES} becomes Low level.

Control register D



Not used (0 is set when this bit is read.)

Bit VRT (Valid RAM and Time)

Bit VRT indicates the status of the RAM for general purpose and time display. When this bit is 0, the RAM contents and the time display are not guaranteed because V_{CC} is too low. The processor must be set to provide against the power cut and error after initializing the contents of the RTC. This bit is set when a control register is read.

Table 6 RTC Control Register

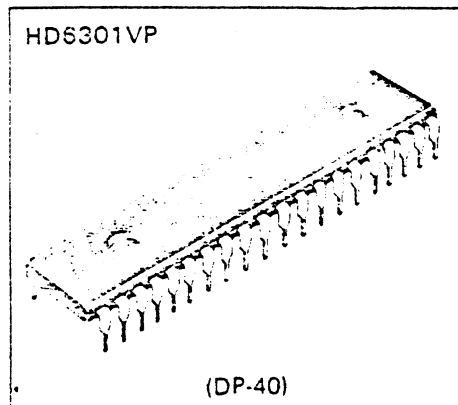
Address								Reg. name	Rd	Wt	Control register bit							
A7	A6	A5	A4	A3	A2	A1	A0				b7	b6	b5	b4	b3	b2	b1	b0
x	x	0	0	1	0	1	0	Ctrl reg.A	0	0	UIP*	DV2	DV1	DV0	RS3	RS2	RS1	RS0
x	x	0	0	1	0	1	1	Ctrl reg.B	0	0	SET	PIE	AIE	UIE	SQWE	DM	24/12	DSE
x	x	0	0	1	1	0	0	Ctrl reg.C	0	x	IRQF	PF	AF	UF	0	0	0	0
x	x	0	0	1	1	0	1	Ctrl reg.D	0	x	VRT**	0	0	0	0	0	0	0

* Read only bit

** Set to '1' by read out of control register 4.

3. HD6301V MCU (Microcomputer Unit)

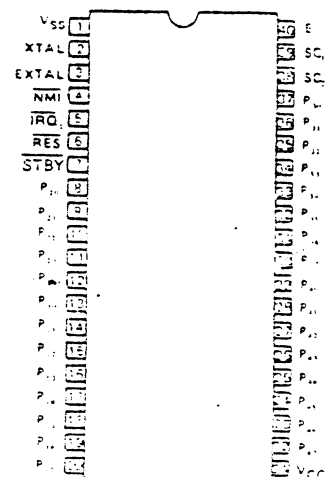
The HD6301V, a single-chip microcomputer unit, provides command object codes compatible with the HD6801, 4K-byte ROM, 128-byte RAM, serial communication interface (SCI), parallel I/O terminals as well as 3 functions of timers on same chips. It is bus compatible with the HMCS6800 and has some additional functions such as an improved execution time plus several new instructions of operation to increase system throughput. The HD6301V can also access the address space of up to 65K words. Like the HMCS6800 family, the I/O level of the HD6301V is compatible with TTL and can operate on +5 V single power supply.



FEATURES

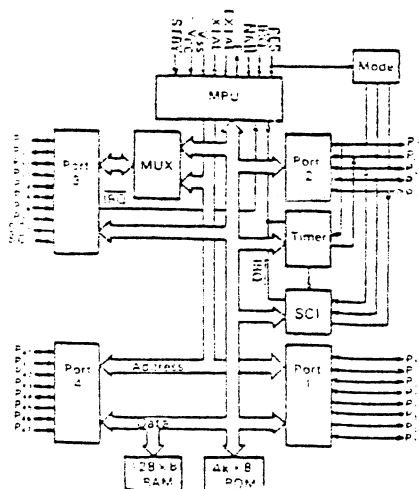
- Extended instruction sets of the HD6801 family
- Abundant incorporated functions compatible with the HD6801V0:
4K-byte ROM, 128-byte RAM, 29 parallel I/O terminals, 2 terminals of data strobe, 16-bit timer, and SCI
- Low power consumption modes:
Sleep and standby modes
- Minimum instruction execution time
1 μ s ($f=1\text{MHz}$), 0.67 μ s ($f=1.5\text{MHz}$), 0.5 μ s (2MHz)
- Bit manipulation and bit test instruction
- Error detect function
Address trap and op-code trap
- Up to 65K-word address space
- Wide operation range
VCC=3 through 7 V ($f=0.5$ MHz)
 $f=0.1$ through 2 MRz ($V_{cc}=5$ V $\pm 10\%$)

Pin Arrangement



Top View

BLOCK DIAGRAM



AC Characteristics

Bus timing (Vcc=5.0 V ± 10%, Vss=0 V and Ta=0 ~ +70°C unless otherwise noted)

Item	Symbol	Test condition	1MHz version			1.5MHz version			2MHz version			Unit
			min	typ	max	min	typ	max	min	typ	max	
Cycle time	t _{cyc}	Figs. 1, 2	1	-	10	0.666	-	10	0.5	-	10	μ
Address strobe pulse width ("High" level)	PWASH		200	-	-	150	-	-	120	-	-	ns
Address strobe rise time	T _{ASr}		-	-	20	-	-	20	-	-	20	ns
Address strobe fall time	T _{ASff}		-	-	20	-	-	20	-	-	20	ns
Address strobe delay time	T _{ASD}		60	-	-	40	-	-	20	-	-	ns
Enable rise time	t _{Er}		-	-	20	-	-	20	-	-	20	ns
Enable fall time	t _{Ef}		-	-	20	-	-	20	-	-	20	ns
Enable pulse width ("High" level)	PWEH		450	-	-	330	-	-	220	-	-	ns
Enable pulse width ("Low" level)	PWEL		450	-	-	330	-	-	220	-	-	ns
Delay time address strobe to enable	t _{ASED}		60	-	-	40	-	-	20	-	-	ns
Address delay time	t _{AD}		-	-	250	-	-	170	-	-	120	ns
Address delay time for latch	t _{ADL}		-	-	250	-	-	170	-	-	120	ns
Data set-up time for write	t _{DSW}		225	-	-	150	-	-	120	-	-	ns
Data set-up time for read	t _{DSR}		90	-	-	60	-	-	40	-	-	ns
Data hold time for read	t _{HR}		10	-	-	10	-	-	10	-	-	ns
Data hold time for write	t _{HW}		20	-	-	20	-	-	20	-	-	ns
Address set-up time for latch	t _{ASL}		20	-	-	20	-	-	20	-	-	ns
Address hold time for latch	t _{AHL}		20	-	-	20	-	-	20	-	-	ns
Address hold time	t _{AH}		10	-	-	10	-	-	10	-	-	ns
A0-A7 set-up time for enable rise	t _{ASM}		200	-	-	180	-	-	120	-	-	ns
Peripheral read access time for nonmultiplexed bus	(t _{ACCN})	-	-	600	-	-	400	-	-	300	ns	
Peripheral read access time for multiplexed buses	(t _{ACCM})	-	-	600	-	-	400	-	-	300	ns	
Oscillator stabilization time (power ON reset time)	(t _{RC})	Figs. 10, 11	20	-	-	20	-	-	20	-	-	ms
Processor control set-up time	(t _{PCCS})		200	-	-	200	-	-	200	-	-	ns

Peripheral port timing (Vcc=5.0 V ± 10%, Vss=0 V and Ta=0 to +70°C unless otherwise specified)

Item	Symbol	Test condition	1MHz version			1.5MHz version			2MHz version			Unit
			min	typ	max	min	typ	max	min	typ	max	
Peripheral data set-up time	Ports 1, 2, 3 and 4 t _{PDSU}	Fig. 3	200	-	-	200	-	-	200	-	-	ns
Peripheral data hold time	Ports 1, 2, 3 and 4 t _{PDH}	Fig. 3	200	-	-	200	-	-	200	-	-	ns
Delay time (Enable rise to OS 3)	t _{OSD1}	Fig. 5	-	-	300	-	-	300	-	-	300	ns
Delay time (Enable rise to OS 3)	t _{OSD2}	Fig. 5	-	-	300	-	-	300	-	-	300	ns
Delay time (Enable fall to peripheral data output)	Ports 1, 2, 3 and 4 t _{PWD}	Fig. 4	-	-	300	-	-	300	-	-	300	ns
Input strobe pulse width	t _{PWIS}	Fig. 6	200	-	-	200	-	-	200	-	-	ns
Input data hold time	Port 3 t _{IH}	Fig. 6	50	-	-	50	-	-	50	-	-	ns
Input data set-up time	Port 3 t _{IS}	Fig. 6	20	-	-	20	-	-	20	-	-	ns

* Except P21

Timer and SCI timing (usual case: $V_{CC}=5.0\text{ V} \pm 10\%$, $V_{SS}=0\text{ V}$ Usual Case: $0 \sim +70^\circ\text{C}$)

Item	Symbol	Test condition	1MHz version			1.5MHz version			2MHz version			Unit
			min	typ	max	min	typ	max	min	typ	max	
Timer input pulse width	t_{pwt}		2.0	-	-	2.0	-	-	2.0	-	-	t_{cyc}
Delay time (enable rise to timer output)	t_{TOd}	Fig.7	-	-	400	-	-	400	-	-	400	ns
SCI input clock cycle	t_{scyc}		1.0	-	-	1.0	-	-	1.0	-	-	t_{cyc}
SCI input clock pulse width	t_{pwsck}		0.4	-	0.6	0.4	-	0.6	0.4	-	0.6	t_{cyc}

Mode programming ($V_{CC}=5.0\text{ V} \pm 10\%$, $V_{SS}=0\text{ V}$ Usual case: $T_a=0 \sim +70^\circ\text{C}$)

Item	Symbol	Test condition	1MHz version			1.5MHz version			2MHz version			Unit
			min	typ	max	min	typ	max	min	typ	max	
Low level voltage for mode programming input	V_{MPL}	Fig.8	-	-	0.8	-	-	0.8	-	-	0.8	V
High level voltage for mode programming input	V_{MPH}		2.0	-	-	2.0	-	-	2.0	-	-	V
RES pulse width (low)	PW_{RSTL}		3	-	-	3	-	-	3	-	-	t_{cyc}
Mode programming set-up time	t_{MPS}		2	-	-	2	-	-	2	-	-	t_{cyc}
Mode programming hold time	t_{HMP}		150	-	-	150	-	-	150	-	-	ns

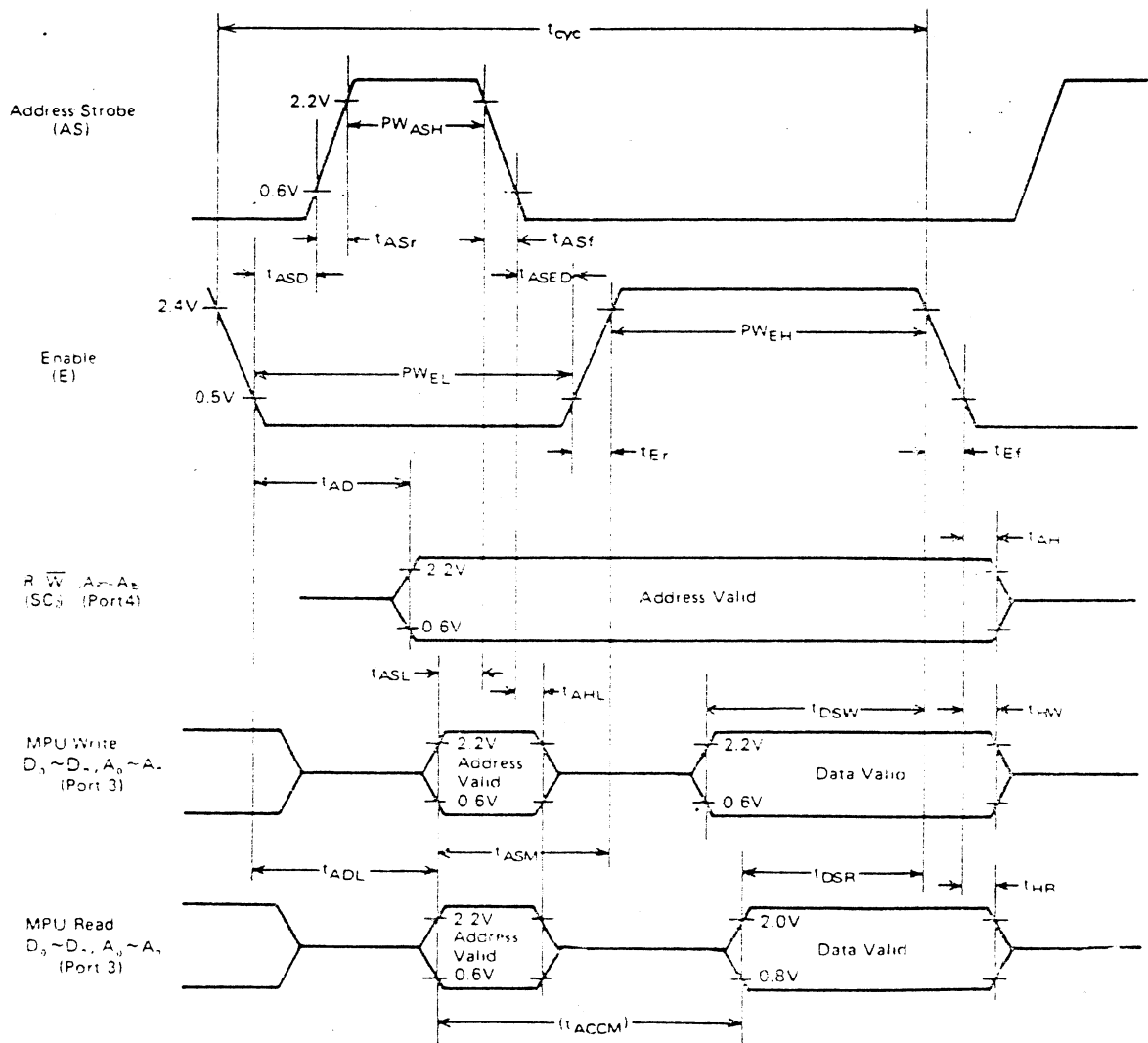


Fig. 1 Expanded Multiplexed Bus Timing

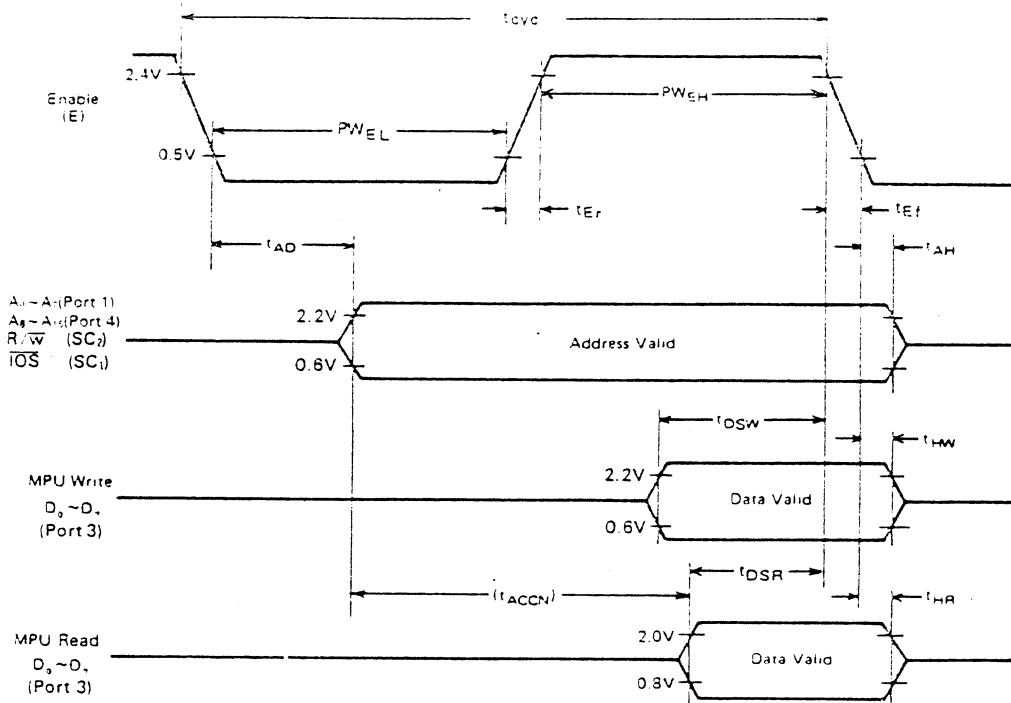
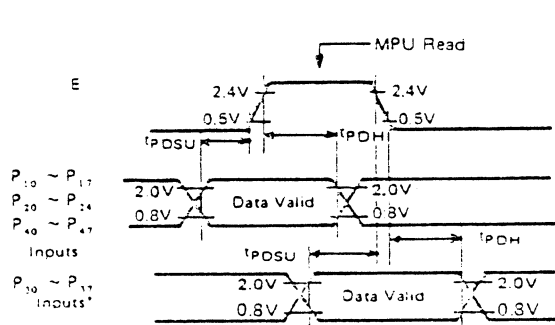
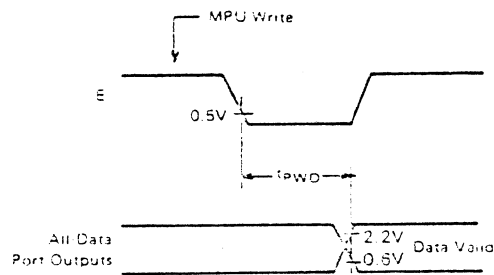


Fig. 2 Expanded Non-Multiplexed Bus Timing



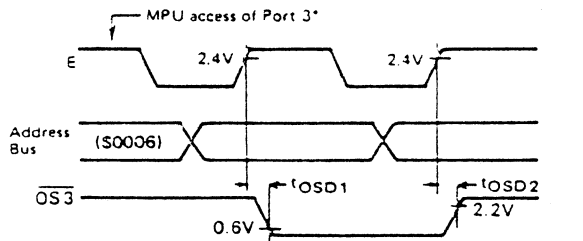
* Port 3 Non-Latched operation

Fig. 3 Port Data Set-up and Hold Times (MPU Read)



Note: Port 2, Except P₂₁

Fig. 4 Port Data Delay Times (MPU Write)



* Access matches Output Strobe Select (OSS=0, a read; OSS=1, a write)

Fig. 5 Port 3 Output Strobe Timing (Single Chip Mode)

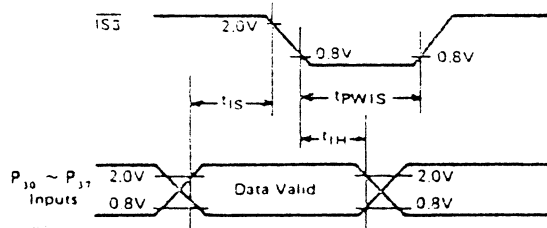


Fig. 6 Port 3 Latch Timing (Single Chip Mode)

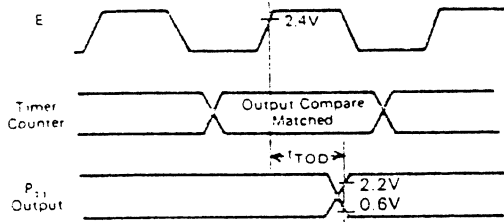


Fig. 7 Timer Output Timing

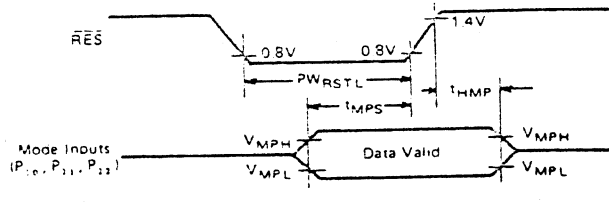
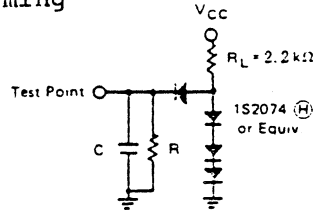


Fig. 8 Mode Programming Timing



C = 90 pF for P₁₀~P₁₇, P₂₀~P₂₇, E, SC₁, SC₂
 = 30 pF for P₁₀~P₁₇, P₂₀~P₂₇
 R = 12 kΩ for P₁₀~P₁₇, P₂₀~P₂₇, E, SC₁, SC₂
 = 24 kΩ for P₁₀~P₁₇, P₂₀~P₂₇

Fig. 9 Bus Timing Test Loads (TTL Load)

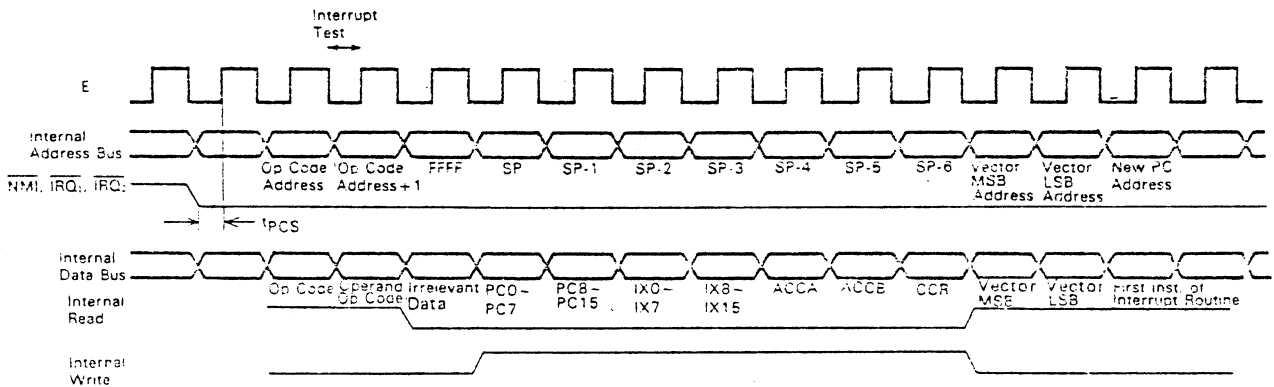


Fig. 10 Interrupt Sequence

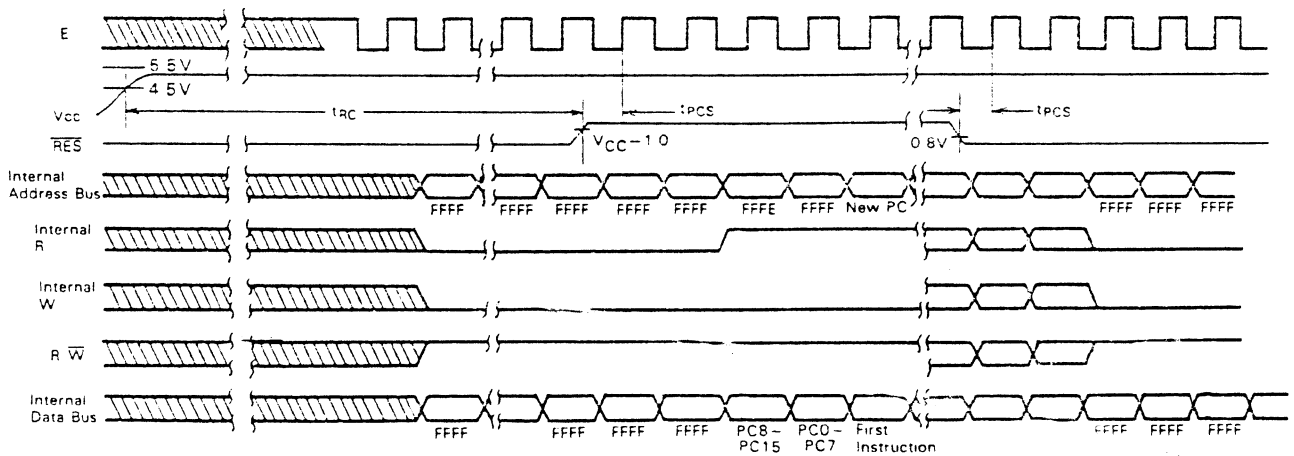


Fig. 11 Reset Timing

DESCRIPTION ON FUNCTIONS OF PIN

-VCC and VSS

These two pins are used for the power supply and the ground (GND). Recommended power supply voltage is +5 V $\pm 10\%$. 3 through 7 V are used for low speed operation.

- XTAL and EXTAL

An AT-cut parallel resonant fundamental crystal is connected to these two pins. For instance, to obtain the 1-MHz system clock, a 4-MHz resonant fundamental crystal is used because the 4-demultiply circuit is incorporated.

The EXTAL receives an external clock input of duty 50% ($\pm 10\%$) to drive. In this case, the LSI internally obtains the system clock which is a quarter the frequency of an external clock. The external driving frequency less than 4 times the maximum operating frequency (maximum internal clock) can be used. For external driving, no XTAL should be connected. Fig. 12 is an example of the connected crystal circuit.

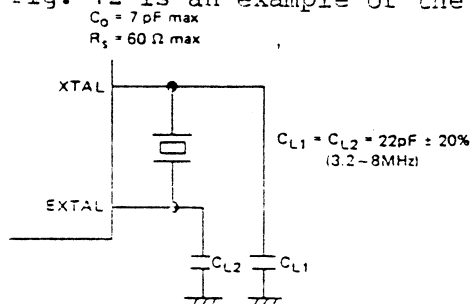


Fig. 12 Example of the connected crystal circuit

- STBY

This pin is used to place the MCU in standby mode. When this pin is set to LOW, the internal condition is reset because the oscillation is inactivated and the internal clock is fixed. To retain information in RAM during standby, 0 must be written into RAM enable bit (RAME). The RAM is bit 6 of the RAM control register at address \$0@14. Since this operation disables the RAM, the contents of that RAM is guaranteed in standby mode. For details on the standby mode, see the STANDBY section.

- Reset (RES)

This pin is used to reset and start the MCU from the power off state. The RES must be held at Low level for at least 20 ms when the power is on. To reset the MCU during system operation, it must be held at Low level for at least 3 system clock cycles. From the third cycle on, address buses go High with the RES at Low level.

When the "High" level is detected, the MCU performs the following:

- 1) The MCU latches bits 0, 1, and 2 of I/O port 2 into bits PC0, PC1, and PC2 of the program control register, respectively.
- 2) The MCU stores the contents of two start addresses \$FFFE and \$FFFF in the program counter from which the program starts (Table 1).
- 3) The MCU sets the interrupt mask bit. To allow the MCU to recognize maskable interrupts an IRQ1 and IRQ2, these interrupts must be cleared beforehand.

- Enable (E)

This pin is used to supply a system clock to the rest of the system when the internal oscillator is being used. The output is a single-phase and compatible with the TTL. The clock frequency is quarter the crystal oscillation frequency. This pin can drive one TTL load and 90 pF capacity.

- Nonmaskable interrupt (NMI)

If the fall of the input signal of this pin is detected, the NMI sequence starts in the MCU. As in the case of the interrupt request IRQ1, the instruction being executed when the NMI is detected continues to be executed to the last. The interrupt mask bit in the condition code register does not affect the NMI at all.

When a response is made to the NMI, the contents of the program counter, index register, accumulators, and condition code register are saved to the stack area. When this sequence terminates, vector addresses \$FFFC and FFFD occur to read the contents of these addresses into the program counter and branch to the nonmaskable interrupt service routine. IRQ1 and NMI are hardware interrupt pins sampled by an internal clock. After execution of the instruction, the interrupt routine must be generated in synchronization with the E.

- Interrupt request (IRQ1)

This level detection pin is used to generate an interrupt sequence in the MPU. If there is any instruction being executed when an interrupt request is issued, the MPU holds the request until it completes the execution of that instruction. If the interrupt mask bit in the condition code register is not set, the MPU initiates the interrupt sequence; otherwise, the interrupt request is ignored.

Once the sequence has started, the MPU saves the contents of the program counter, index register, accumulators, and condition code register to the stack area, and sets the interrupt mask bit, inhibiting further maskable interrupts to occur. At the end of the cycle, the MPU generates a 16-bit vector address indicating memory addresses \$FFF8 and \$FFF9, stores the contents of these addresses into the program counter, and branches to the interrupt service routine.

Table 1 Interrupt vectoring memory map

	Vector		Interrupt
	MSB	LSB	
Highest Priority	FFFE	FFFF	RES
	FFEE	FFEF	TRAP
	FFFC	FFFD	NMI
	FFFA	FFFB	Software Interrupt (SWI)
	FFF8	FFF9	IRQ ₁ (or IS3)
	FFF6	FFF7	ICF (Timer Input Capture)
	FFF4	FFF5	OCF (Timer Output Compare)
	FFF2	FFF3	TOF (Timer Overflow)
Lowest Priority	FFF0	FFF1	SCI (RDRF + ORFE + TDRE)

The internal interrupt generates internal interrupt signal IRQ2, which is the same as the IRQ1, except that it uses vector addresses \$FFF0 through \$FFF7. If IRQ1 and IRQ2 are generated at the same time, the former precedes the latter. The interrupt mask bit in the condition code register disables these interrupts if it is set. If an address error or an op-code error occurs, the TRAP interrupt, the second highest priority interrupt next to the RES, will also occur. In this case, the MPU starts the interrupt sequence independently of the mask bit condition. The vector for this interrupt is FFEE, FFEF.

The following 3 pins apply only to port 3 in single chip mode.

- Input strobe (IS3) (SC1)

This signal controls the IS3 interrupt and the latch of port 3. When the fall of this signal is detected, the IS3 flag of the port 3 control status register is set. For details on the bits of the port 3 control status register, see the I/O PORT 3 CONTROL STATUS REGISTER section.

- Output strobe (OS3) (SC2)

This signal is used when the processor informs the external device that effective data is on the I/O pins. Fig. 5 shows the timing of the port 3 output strobe.

The following pins apply to expanded mode.

-Read/write (R/W) (SC2)

This TTL compatible output signal is used to inform the peripheral device and memory whether the MCU is in the read (High) or write (Low) state. This signal is usually in the standby state. The output drives one TTL load and 90-pF capacitor.

- I/O strobe (IOS) (SC1)

In expanded nonmultiplexed mode 5 of operation, this signal internally decodes A9 through A15 as "0" and A8 as "1", allowing the access of up to 256 addresses from \$0100 to \$01FF in external memory.

Fig. 2 shows the timing of expanded nonmultiplexed bus.

-Address strobe (AS) (SC1)

In expanded multiplexed mode, an address strobe signal appears at this pin. This signal is used to latch the lower 8-bit addressed multiplexed with data on port 3 and to control the 8-bit latch using the address strobe as shown in Fig. 18.

This allows the user to use I/O port 3 as a data bus during E pulse. Fig. 19 shows the timing of the expanded multiplexed bus.

PORTS

The HD6301V MCU provides 4 I/O ports (three 8-bit ports and one 5-bit port). 2 control pins are connected to one of the 8-bit ports. Each port has an independent write-only data direction register to program individual I/O pins for input and output.

When the bit of the corresponding data direction register is 1, the I/O pin is programmed for output. When the bit is "0", The I/O pin is programmed for input. There are 4 ports: port 1, port 2, port 3, and port 4. Table 2 lists the correspondence between the 4 I/O port addresses and data direction register addresses.

: Only one exception is bit 1 of port 2. Since this bit (terminal) is used as a data input or a timer output, it cannot be used as an output port.

Table 2 Port and data direction register addresses

Ports	Port Address	Data Direction Register Address
I/O Port 1	\$0002	\$0000
I/O Port 2	\$0003	\$0001
I/O Port 3	\$0006	\$0004
I/O Port 4	\$0007	\$0005

- I/O port 1

This is an 8-bit port, each bit being defined as input or output according to the contents of the corresponding data direction register.

The 8-bit, three-state output buffer changes to the high-impedance state when it is used for input. For accurate data read, the voltage on the input line (pin) must be 2.0 V or above when the logic is 1 and must be 0.8 V or below when the logic is 0.

These input lines (pins) compatible with the TTL can be used not only as the 1-mA or less drive source with 1.5 V but also to directly drive the darlington transistor base.

After the MCU is reset, all the I/O lines (pins) function as input. In modes other than expanded nonmultiplexed mode 1, port 1 always functions as the parallel I/O line (pin). In expanded nonmultiplexed mode 1, port 1 functions as the output line (pin) for lower address lines A0 through A7.

- I/O port 2

This port has 5 lines (pins), whose I/O directions depend on the data direction register.

The 5-bit, three-state output buffer changes to the high-impedance state when it is used for input. For accurate data read, the voltage on the input line (pin) must be 2.0 V or above when the logic is 1 and must be 0.8 V or below when the logic is 0.

After the MCU is reset, all I/O lines (pins) function as input. Pins 8 through 10 of port 2 are used for mode programming during reset. The values of these 3 pins during reset are latched into the upper 3 bits (bits 5, 6, and 7) of port 2. For details, see the MODE SELECTION section.

In all modes, port 2 not only functions as the I/O line (pin) but also provides access to the SCI and timer. Note that bit 1 (P21) can be used only for the data input port and the timer output.

- I/O port 3

This 8-bit port can be used as an I/O terminal, a data bus, or an address but multiplexed with a data bus. The function depends on hardware operation mode programmed by the user using 3 bits of port 2 during reset. Port 3 used as a data bus is bidirectional. For an input from a peripheral device, a standard TTL level must be supplied. In other words, the level must be 2.0 V or above when the logic is 1 and must be 0.8 V or below when it is 0. This TTL compatible, 3-state buffer can drive one TTL load and the 90 pF capacitor.

In expanded mode, the use of the data direction register is inhibited and the data flow depends on the status of the R/W signal (line). Port 3 has the following functions in each mode:

Single chip mode (mode 7)

In this mode, port 3 is used for parallel I/O and defined as input or output using the corresponding data direction register. In this mode, two control lines (pins) input strobe (IS3) and output strobe (OS3), are used for handshaking and controlled by the I/O port 3 control/status register.

Three additional characteristics of this register are summarized as follows:

- (1) Input data of port 3 can be latched using IS3 (SC1) as a control signal.
- (2) OS3 (SC2) is generated when the port 3 data register is read or written.
- (3) Interrupt IRQ1 is generated when the IS3 falls. Figs. 5 and 6 show the timings of port 3 strobe and latch, respectively.

I/O port 3 control/status register

	7	6	5	4	3	2	1	0
	IS3	IS3	X	OSS	LATCH	X	X	X
5000F	FLAG	IRQ1 ENABLE			ENABLE			

Bit 0: Not used.

Bit 1: Not used.

Bit 2: Not used.

Bit 3: LATCH ENABLE

This bit is used to control the input latch of I/O port 3. If the bit is set at 1, the input data on port 3 is latched by the falling edge of the IS3. This latch is cleared and then enters the latch possible state again when a signal is read from I/O port 3. This bit is cleared by a reset.

Bit 4: OSS (Output Strobe Selection)

This bit is used to identify the cause of the output strobe generation. The output strobe is generated when a signal is read and written to and from I/O port 3. In other words, the strobe is generated in the following cases:

- A signal is read from I/O port 3 and bit 4 is cleared.
- A signal is written into I/O port 3 and bit 4 is set.

This bit is cleared by a reset.

Bit 5: Not used.

Bit 6: IS3 ENABLE

If both bit 6 and bit 7 (IS3 flag) are set, the interrupt is enabled. If the flag is cleared, the interrupt is disabled. This bit is cleared by a reset.

Bit 7: IS3 FLAG

This read-only bit is set by the falling edge of the IS3 (SC1). The bit is cleared when a signal is read from or written into I/O port 3 after the control/status register is read. It is cleared by a reset.

Expanded nonmultiplexed mode (modes 1 and 5)

In this mode, port 3 is used as data buses D0 through D7.

Expanded multiplexed mode (modes 0, 4, and 6)

In this mode, port 3 is used as data buses D0 through D7 and multiplexed lower 8 bits of addresses buses A0 through A7.

- I/O port 4

This 8-bit port functions as either the I/O line (pin) or the address output line (pin) depending on the operation mode selected.

The voltage on the input line (pin) must be 2.0 V or above when the logic is 1 and must be 0.8 V or below when it is 0. The line (pin) compatible with the TTL can drive one TTL load and the 90 pF.

Since this port is used for input after reset, it must be programmed as output when the lines (pins) are used as addresses.

Port 4 has the following characteristics in each mode:

Single chip mode (mode 7)

In this mode, port 4 is used for parallel I/O and defined (programmed) as input or output using the corresponding data direction register.

Expanded nonmultiplexed mode (mode 5)

In this mode, port 4 function as lower address lines (pins) A0 through A7 when 1 is written into the data direction register. If some of the 8 bits are not required as addresses, the remaining lines (pins) can be used as the I/O lines (pins).

Expanded nonmultiplexed mode (mode 1)

In this mode, port 4 functions as upper address output lines A8 through A15 when 1 is written into the data direction register. If some of the 8 bits are not required as addresses, the remaining lines (pins) can be used as the I/O lines (pins) starting with the MSB.

Expanded multiplexed mode (modes 0 and 4)

In this mode, port 4 functions as upper address output lines A8 through A15 regardless of the value of the data direction register. Table 3 lists the relationship between the modes and I/O ports 1 through 4.

MODE SELECTION

The user must determine the operation mode used after the HD6301V is reset by wiring pins 8, 9, and 10 externally. These 3 pins, which correspond to lower 3 bits (I/O 0, I/O 1, and I/O 3) of port 2, respectively, are latched into program control bits PC0, PS1, and PC2 of the I/O port 2 register when the reset goes High.

The format of the I/O port 2 register is as follows:

Port 2 data register

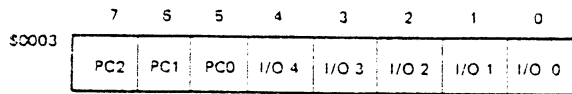


Fig. 13 shows an example of the external hardware used for mode selection. The HD14053B, which separates the peripheral device from the MCU during reset, is necessary when a data contention occurs between the peripheral device and the mode generation circuit. The mode cannot be changed by software because bits 5, 6, and 7 of port 2 are for read only. Table 3 lists the modes selected by the HD6301V.

The HD6301V operates in the following 3 basic modes:

- (1) Single chip
- (2) Expanded multiplexed (compatible with the HMCS6800 peripheral LSI)
- (3) Expanded nonmultiplexed (compatible with the HMCS6800 peripheral LSI)

- Single chip mode

In this mode, all ports are used for the I/O functions. Fig. 15 shows the MCU single chip mode.

In this mode, pins SC1 and SC2 function as control lines (pins) of port 3 and can also be used as input strobe signal IS3 and output strobe signal OS3.

- Expanded multiplexed mode

In this mode, port 4 functions as I/O or address lines (pins). The data bus and the lower address buses multiplexed in port 3 can be separated by the address strobe output. Port 2 functions as 5 parallel I/O lines (pins), a serial I/O, or a timer. Any combination of these functions is also possible. Port 1 functions as 8 parallel I/O lines (pins) and can be expanded to the address space of up to 65K words (Fig. 16).

- Expanded nonmultiplexed mode

In this mode, the HD6301V can directly address the HMCS6800 peripheral devices with no external logics. Port 1 can be used only as the parallel I/O lines (pins). Port 2 functions as the parallel I/O lines (pins) for the serial I/O, or a timer. Any combination of these functions is also possible. Port 3 functions as a data bus. Port 4 functions as address buses A0 through A7, a part of an address bus, or I/O (input only). In this mode, the HD6301V can address up to 256 addresses. In the application system with fewer addresses, the remaining pins of port 4 can be used as I/O lines (input only) (Fig. 17).

In mode 1, port 1 functions as address buses A0 through A7; port 2 functions as parallel I/O lines, serial I/O lines, or a timer (any combination of these functions is also possible) port 3 functions as a data bus; port 4 functions as address buses A8 through A15 or a part of an address bus, or I/O (input only). In this mode, the HD6301V can be expanded to the address space of up to 65K words without external logics. In the application system with fewer addresses, the remaining pins of port 4 can be used as the I/O lines (input only) (Fig. 17).

- Lower address bus latch

Since the data bus is multiplexed with the lower address bus of port 3 in expanded multiplexed mode, the address bits must be externally latched. The lower address bytes can be latched by using the 74LS373 with 8 D-byte flip-flops. Fig. 18 shows how the HD6301V and the 74LS373 are connected.

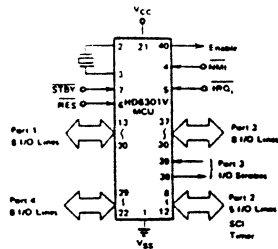


Fig. 15 HD6301V MCU single chip mode

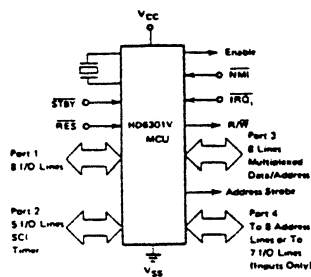


Fig. 16 HD6301V MCU expanded multiple ed mode

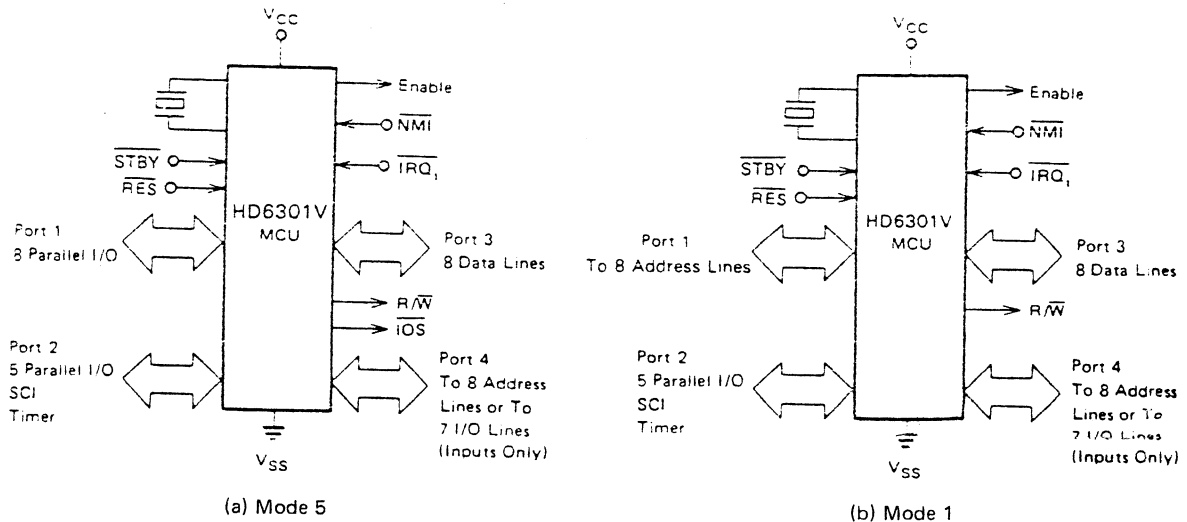


Fig. 17 HD6301V MCU expanded nonmultiplexed mode

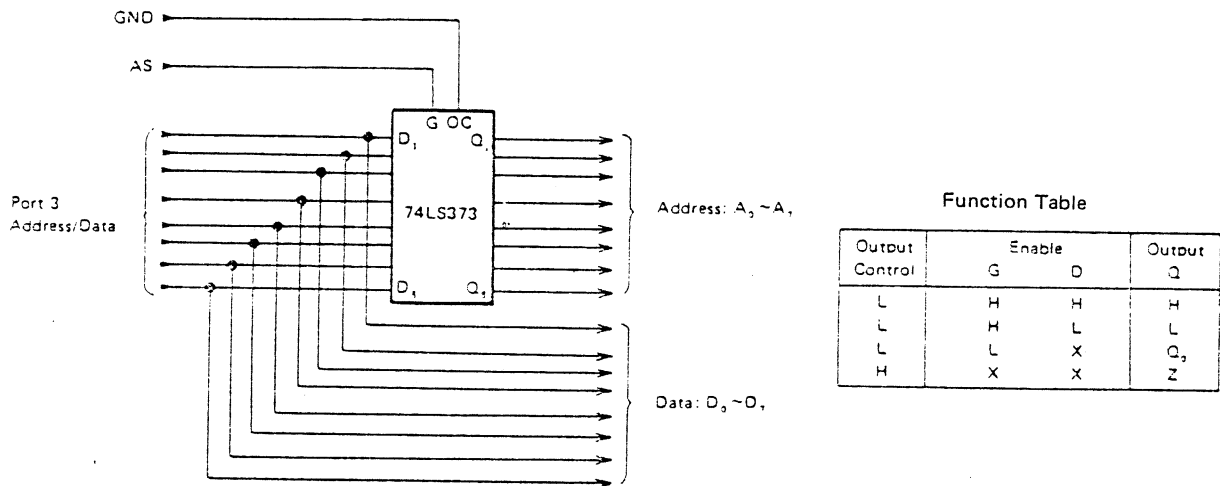


Fig. 18 Latch connection

- Outline of the modes and ports and MCU signals
 This section explains the MCU signals operating in various modes. The SCI and SC2 signals vary with the state of the chip mode.

Table 3 Features of each mode and line

MODE	PORT 1 Eight Lines	PORT 2 Five Lines	PORT 3 Eight Lines	PORT 4 Eight Lines	SC ₁	SC ₂
SINGLE CHIP	I/O	I/O	I/O	I/O	$\overline{IS3}$ (I)	$\overline{OS3}$ (O)
EXPANDED MUX	I/O	I/O	ADDRESS BUS (A ₀ -A ₇) DATA BUS (D ₀ -D ₇)	ADDRESS BUS* (A ₈ -A ₁₅)	AS(O)	R \overline{W} (O)
EXPANDED Mode 5	I/O	I/O	DATA BUS (D ₀ -D ₇)	ADDRESS BUS* (A ₀ -A ₇)	\overline{IOS} (O)	R \overline{W} (O)
NON-MUX Mode 1	ADDRESS BUS (A ₀ -A ₇)	I/O	DATA BUS (D ₀ -D ₇)	ADDRESS BUS* (A ₈ -A ₁₅)	Not Used	R \overline{W} (O)

*: If these lines (pins) are unnecessary to be used as the address lines, they can be used as the I/O lines (only for input) starting with the MSB (excluding modes 0 and 4).

I=Input IS3=Input Strobe SC=Strobe Control
 O=Output OS3=Output Strobe AS=Address Strobe
 R/W=Read/Write IOS=I/O Select

Table 4 Mode selection Summary

Mode	P ₁₃ (PC2)	P ₁₁ (PC1)	P ₁₀ (PC0)	ROM	RAM	Interrupt Vectors	Bus Mode	Operating Mode
7	H	H	H	I	I	I	I	Single Chip
6	H	H	L	I	I	I	MUX ⁽⁴⁾	Multiplexed/Partial Decode
5	H	L	H	I	I	I	NMUX ⁽⁴⁾	Non-Multiplexed/Partial Decode
4	H	L	L	E ⁽²⁾	I ⁽¹⁾	E	MUX	Multiplexed/RAM
3	L	H	H	-	-	-	-	Not Used
2	L	H	L	-	-	-	-	Not Used
1	L	L	H	I	I	I	NMUX ⁽⁴⁾	Non-Multiplexed/Partial Decode
0	L	L	L	I	I	I ⁽³⁾	MUX	Multiplexed Test

HX-20 is set to Mode 4.

Legends

- I-Internal
- E-External
- MUX-Multiplexed
- NMUX-Nonmultiplexed
- L-Logic "0"
- H-Logic "1"

Notes:

- 1) The internal RAM is addressed at \$0080.
- 2) The internal ROM cannot be used.
- 3) The RES vector is external for 3 cycles after RES goes High.
- 4) Unnecessary address output lines (pins) of port 4 can be used as the input port.

MEMORY MAP

The MCU can address up to 65K bytes depending on the operation mode used. Fig. 19 shows a memory map for each operation mode. The first 32 addresses of each memory map are for exclusive use of the internal register as shown in Table 5.

Table 5 Internal register Area

Register	Address
Port 1 Data Direction Register****	00*
Port 2 Data Direction Register****	01
Port 1 Data Register	02*
Port 2 Data Register	03
Port 3 Data Direction Register****	04**
Port 4 Data Direction Register****	05***
Port 3 Data Register	06**
Port 4 Data Register	07***
Timer Control and Status Register	08
Counter (High Byte)	09
Counter (Low Byte)	0A
Output Compare Register (High Byte)	0B
Output Compare Register (Low Byte)	0C
Input Capture Register (High Byte)	0D
Input Capture Register (Low Byte)	0E
Port 3 Control and Status Register	0F**
Rate and Mode Control Register	10
Transmit/Receive Control and Status Register	11
Receive Data Register	12
Transmit Data Register	13
RAM Control Register	14
Reserved	15-1F

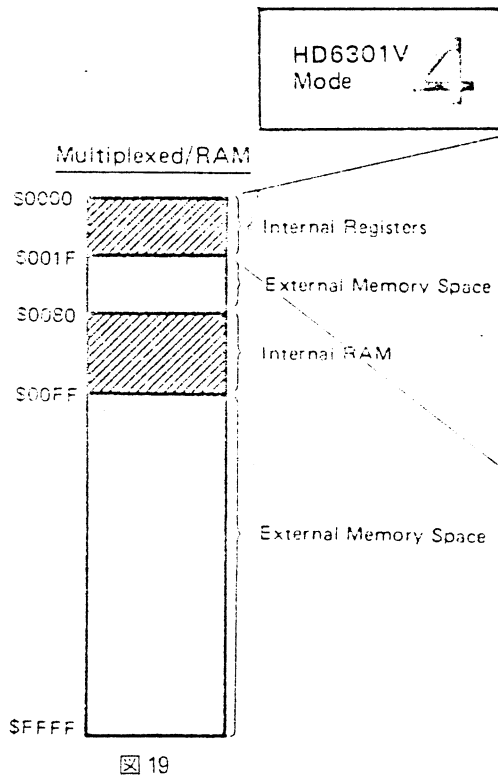


Fig. 19

Note: Addresses \$04, \$05, \$06, \$07 and \$0F which can be externally used are not excluded.

Programmable Options

The HD6301V provides the following programmable options for the serial I/O section:

- Data format: Standard mark/space (NRZ)
- Clock source: External or internal
- Baud rate: One of 4 baud rates is selected for the E clock of the MCU or 1/8 of the external clock is selected.
- Wake-up function: Enable or disable
- Interrupt request: Used to enable or mask the transmit and receive data registers.
- Clock output: Used to enable or disable the output to bit 2 of internal-clock port 2.
- Port 2 (bit 3, 4): Indicates whether or not to use bits 3 and 4 of port 2 for the receiver and transmitter.

Serial Communication Hardware

The serial communication hardware is controlled by the following 4 registers as shown in Fig. 22.

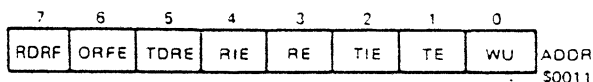
- 8-bit control/status register
- 4-bit transfer rate/mode control register (write-only)
- 8-bit read-only receive register
- 8-bit write-only transmit data register

In addition to these 4 registers, the serial communication section uses bit 3 (input) and bit 4 (output) of port 2. Bit 2 is used when an option that externally outputs an internal clock or an option that internally inputs an internal clock is selected.

Transmit/Receive Control Status Register (TRCSR)

The TRCSR consists of 8 bits. All these bits can be read and bits 0 through 4 can also be written. RES initializes this register for \$20. The structure of the TRCSR is:

Transmit/receive control status register (TRCSR)



Bit 0: WU (Wake-up)

This bit is set by software and cleared by hardware when 10 1s are consecutively received. Note that this bit must be set before the RE flag is set.

Bit 1: TE (Transmit Enable)

When this bit is set, a preamble of 10 consecutive 1 bits is generated, enabling the output of transmitter data to bit 4 of port 2 independently of the value of the DDR bit corresponding to this bit. When this bit is cleared, the serial I/O section does not affect bit 4 of port 2 at all.

Bit 2: TIE (Transmit Interrupt Enable)

When this bit and bit 5 (TDRE) are both set, internal interrupt IRQ2 can be generated. When this bit is cleared, internal interrupt IRQ2 of bit 5 (TDRE) is masked.

Bit 3: RE (Receive Enable)

When this bit is set, the bit 3 signal of port 2 is sent to the receiver regardless of the contents of the DDR corresponding to this bit. If this bit is cleared, the serial I/O section does not affect bit 3 of port 2 at all.

Bit 4: RIE (Receive Interrupt Enable)

If bit 7 (RDRF) or bit 6 (ORFE) is set when this bit is set, IRQ2 can be generated. When this bit is cleared, IRQ2 is masked.

Bit 5: TDRE (Transmit Data Register Empty)

This bit is set by hardware when data is sent from the transmit data register to the output shift register. This bit is cleared when next new data is written into the transmit data register following the status register RES sets this bit to the 1.

Bit 6: ORFE (Overrun Framing Error)

This bit is set by hardware when an overrun or framing error occurs. The overrun error occurs if new data is sent to the receive register when bit 7 (RDRF) is set.

The framing error occurs when the bit counter does not synchronize with the byte boundary of the bit stream. This bit is cleared when the receive data register is read following the status register. RES can also be used to clear the bit.

Bit 7: RDRF (Receive Data Register Full)

This bit is set by hardware when data is sent from the receive shift register to the receive data register. The bit is cleared when the receive data register is read following the status register. RES can also be used to clear the bit.

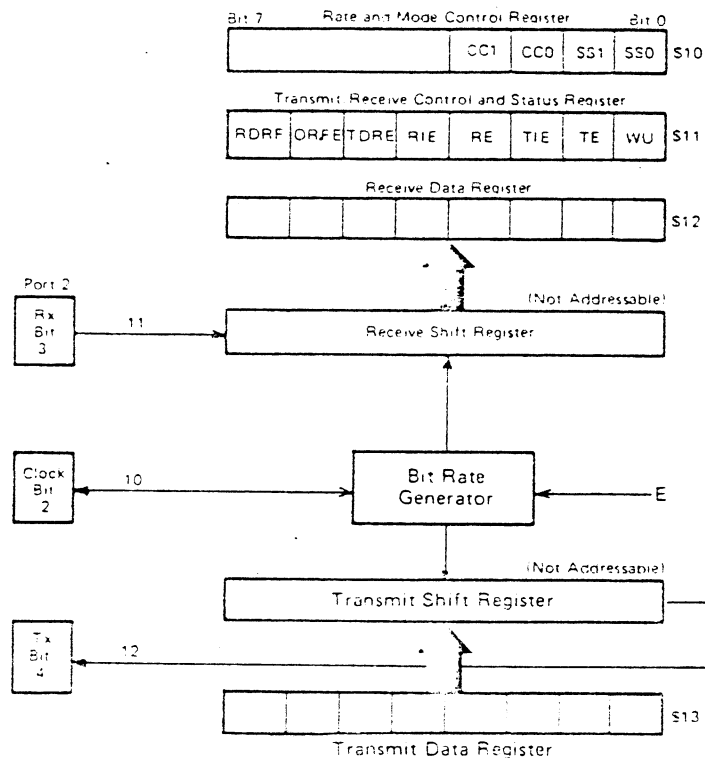


Fig. 22 Serial I/O register

Transfer rate/mode control register

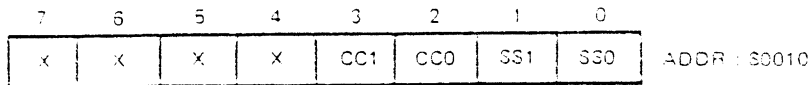


Table 6 SCI bit times and transfer rates

SS1 : SS0	XTAL	2.4576 MHz	4.0 MHz	4.9152MHz
	E	614.4 kHz	1.0 MHz	1.2288MHz
0 0	E ÷ 16	26 μ s/38,400 Baud	16 μ s/62,500 Baud	13 μ s 76,800Baud
0 1	E ÷ 128	208 μ s/4,800 Baud	128 μ s/7812.5 Baud	104.2 μ s 9,600Baud
1 0	E ÷ 1024	1.67ms/600 Baud	1.024ms/976.6 Baud	833.3 μ s 1,200Baud
1 1	E ÷ 4096	6.67ms/150 Baud	4.096ms/244.1 Baud	3.333ms 300Baud

Table 7 SCI format and clock source control

CC1, CC0	Format	Clock Source	Port 2 Bit 2	Port 2 Bit 3	Port 2 Bit 4
00	-	-	-	-	-
01	NRZ	Internal	Not Used	**	**
10	NRZ	Internal	Output*	**	**
11	NRZ	External	Input	**	**

- *: A clock is output regardless of the status of TE in the TRCSR.
- **: When RE bit of TRCS is "1", bit is used as the serial input.
When TE bit of TRCS is "1", bit 4 if is used as the serial output.

Transfer Rate/Mode Control Register (RMCR)

This register controls the following variables of the serial I/O section:

- Baud rates
- Data format
- Clock source
- Bit 2 function of port 2

This 4-bit write-only register is cleared by RES. Each 2 bits consistutes one field. The lower 2 bits are used to control the bit rates for the internal clocks while the upper 2 bits are used to control the data format and the clock selection logic.

Bit 0: SSO

Speed selection

Bit 1: SS1

These bits are used to select the baud rates for the internal clocks. These selectable 4 rates can be used as the functions of the E clock frequencies in the MPU. Table 6 lists the baud rates to be selected.

Bit 2: CC0

Clock control/format selection

Bit 3: CC1

These bits are used to control the data format and the clock source selection logic. Table 7 defines these two bits.

- Internally generated Clock

The following points should be taken into consideration when the user externally uses an internal clock for the serial I/O:

- The values of bit 1 (RE) and bit 3 (RE) can be ignored.
- CC0 and CC1 are set to "10".
- The available maximum clock rate is E ÷ 16.
- The clock is one time the bit rate.

- Externally Generated Clock

The following should be taken into consideration when the user supplies an external clock to the serial I/O:

- . Bits 2 (CC0) and 3 (CC1) of the RMC register are set to "11" (Table 7).
- . The external clock frequency is 8 times the baud rate to be used.
- . The maximum external clock frequency is the same as the E clock frequency.

- Serial Operation

The serial I/O hardware must be initialized by the HD6301V software in the following sequence before operation:

- . A desired operation control bit is written into the RMC register.
 - . A desired operation control bit is written into the TRCS register.
- If bits 3 and 4 of port 2 are exclusively used for the serial I/O hardware, bit 1 (TE) and bit 3 (RE) need not be cleared. If these bits (TE and RE) are temporarily cleared during the SCI operation and then set again, they must be set at least one bit after the current baud rate. Note that if bit 1 (TE) and bit 3 (RE) are set within one bit interval, the internal status for reception and transmission may not be initialized.

- Transmit Operation

When bit 1 (TE) of the TRCS register is set, the transmit operation starts. In other words, when this bit is set, the contents of the serial transmit shift register are unconditionally output to bit 4 of port 2 regardless of the value of the DDR corresponding to bit 4 of port 2.

After RES is output, both the RMC and TRCS registers must be set to the desired operation conditions. If bit 1 (TE) is set during this procedure, a preamble of 10 consecutive "1" bits is transmitted. After the preamble transmission, internal synchronization is established and the transmitter enters the operable state.

At this point, one of the following operations is performed:

- (1) If the transmit data register is empty (TDRE=1), 1 bits are consecutively sent, indicating that the idle state is kept.
- (2) If data is already stored in the transmit data register (TDRE=0), data is sent to the output shift register to start the data transmission.

The "0" start bit is first sent, and then 8 bit data (beginning with bit 0), and the stop bit follows.

If the transmit data register becomes empty, hardware sets the TDRE flag bit.

If the MCU fails to respond to the flag within a specified time, 1 bits are consecutively output instead of the 0 start bit until data is supplied to the data register. Note that in this case, the TDRE flag bit remains to be set until next correct data is sent from the parallel data register to the serial output register. When the TDRE bit keeps 1, no 0 bits are sent.

- Receive Operation

When bit 3 (RE) is set, the receive operation starts and enables the bit 3 of port 2 to be used as the serial input.

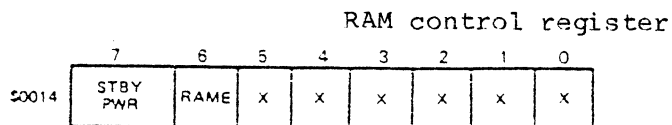
The operation conditions of the receiver are determined according to the contents of the TRCS and RMC registers. In ordinary non-biphase mode, the flow of the received bit is synchronized by the first input 0 (space). During 10-bit time, each bit is strobed in the almost middle of it.

If the tenth bit is not 1 (stop bit), a framing error assumes to occur, causing the ORFE bit to be set. When the tenth bit is 1, data is transmitted to the receive data register to set the RDRF interrupt flag. If the RDRF flag still remains to be set although the tenth bit of next data is received, the ORFE flag indicating that an overrun has occurred is set.

If the MCU reads the data register following the status register in response to the RDRF or ORFE flag, the RDRF or ORFE flag is cleared.

RAM CONTROL REGISTER

The register assigned to address \$0014 specifies information on the standby RAM.



Bit 0: Not used.

Bit 1: Not used.

Bit 2: Not used.

Bit 3: Not used.

Bit 4: Not used.

Bit 5: Not used.

Bit 6: RAM Enable

This bit is used to disable the standby RAM. When the MPU is reset, 1 is set in this bit, enabling the standby RAM. 1 and 0 can also be written into the bit by using the program control.

When the RAM is disabled (logic 0), the RAM address is internally invalidated, allowing the MPU to read data from external memory.

Bit 7: Standby bit

This bit is cleared when no Vcc voltage is impressed. The user can also read this bit using the read/write flags. When this bit is set, it indicates that the Vcc voltage has been impressed and data in the standby RAM is effective.

OUTLINE OF INSTRUCTION SET

The HD6301V has HD6801 upward compatible object codes to use all HMCS6800 instruction sets and the execution time of the key instructions is designed to improve the system throughput.

Bit manipulation instructions, change instructions and sleep instructions for indexes and accumulators are also added.

This section describes:

- MCU programming model (Fig. 23).
- Addressing mode
- Manipulation instructions for accumulators and memory (Table 8).
- New instructions.
- Manipulation instructions for index registers and stacks (Table 9).
- Jump and branch instructions (Table 10).
- Manipulation instructions for condition code registers (Table 11).
- Op-code Map (Table 12).

- MCU Programming Model

Fig. 23 shows the HD6301V programming model. Since double accumulator D is a combination of accumulators A and B, the contents of A and B are destroyed when the instructions that use accumulator D are specified.

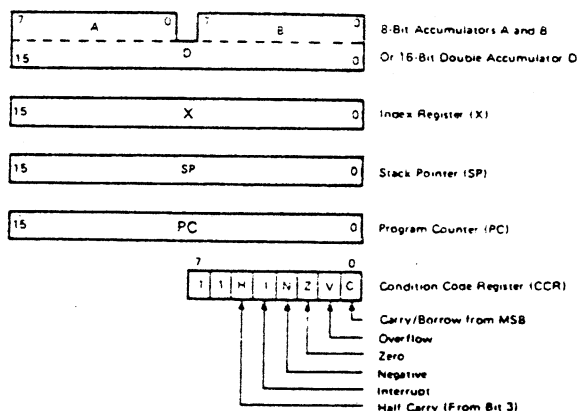


Fig. 23 MCU programming model

MCU Addressing Mode

The HD6301 is provided with 7 addressing modes each of which is selected according to both the instruction type and code. Tables 8 through 12 show the addressing mode for each instruction together with the execution time represented by the number of machine cycles. When the clock frequency is 4 MHz, microseconds replace the machine cycles.

Accumulator (ACCX) Addressing

Only the accumulator is addressed. In other words, either accumulator A or B is specified. 1-byte instructions are used to specify this mode.

Immediate Addressing

In this mode, an operand is included in the second byte of an instruction, but in the LDS and LDX, the operand is included both in the second and third bytes. 2- or 3-byte instructions are used to specify this mode.

Direct Addressing

The second byte of an instruction indicates the address that contains the operand in this mode so that the 256-byte area from address 0 through address 255 can be directly accessed. Since storing data in this area reduces the execution time, it is recommended that the user define this area as the RAM area when designing the system configuration and use it as the user data area. 2-byte instructions are usually used to specify this mode but 3-byte instructions such as AIM, OIM, EIM, and TIM can also be used.

Extended Addressing

In this mode, the second byte indicates the high-order 8 bits of the address that contains the operand and the third byte indicates the low-order 8 bits. This address indicates an absolute address in memory. 3-byte instructions are used to specify this mode.

Indexed Addressing

In this mode, the contents of the second byte of an instruction and the low-order 8 bits of the indexed register are added. The contents of the third of an instruction byte and the low-order 8 bits are added for the AIM, OIM, EIM, and TIM,.

This carry is also added to the high-order 8 bits of the index register and the resulting values are used as memory addresses. The contents of the index register do not change because the temporary address register holds this modified address. 2-byte instructions are usually used to specify this mode but 3-byte instructions such as AIM, OIM, EIM, and TIM can also be used.

Implied Addressing

In this mode, the instruction itself specifies the address, i.e., it addresses the stack pointer and index registers, etc. 1-byte instructions are used to specify this mode.

Relative Addressing

In this mode, the contents of the second byte of an instruction and the low-order 8 bits of the program counter are added and then the resulting carry or borrow is added to the high-order 8 bits. This means that the user can address data within the range of -126 through +129 bytes of the instruction currently being executed. 2-byte instructions are used to specify this mode.

Table 8 Manipulation instructions for accumulators and memory

Operations	Mnemonic	Addressing Modes															Boolean/ Arithmetic Operation	Condition Code Register								
		IMMED			DIRECT			INDEX			EXTEND			IMPLIED				5	4	3	2	1	0			
		OP	~	=	OP	~	=	OP	~	=	OP	~	=	OP	~	=		H	I	N	Z	V	C			
Add	ADDA	8B	2	2	9B	3	2	AB	4	2	BB	4	3			A + M → A				
	ADDB	C8	2	2	DB	3	2	EB	4	2	FB	4	3			B + M → B				
Add Double	ADDD	C3	4	3	D3	4	2	E3	5	2	F3	5	3			A : B + M : M + 1 → A : B				
Add Accumulators	ABA													1B	1	1	A + B → A				
Add With Carry	ADCA	89	2	2	99	3	2	A9	4	2	B9	4	3			A + M + C → A				
	ADCB	C9	2	2	D9	3	2	E9	4	2	F9	4	3			B + M + C → B				
AND	ANDA	84	2	2	94	3	2	A4	4	2	B4	4	3			A · M → A	R	.				
	ANDB	C4	2	2	D4	3	2	E4	4	2	F4	4	3			B · M → B	R	.				
Bit Test	BIT A	85	2	2	95	3	2	A5	4	2	B5	4	3			A · M	R	.				
	BIT B	C5	2	2	D5	3	2	E5	4	2	F5	4	3			B · M	R	.				
Clear	CLR							6F	5	2	7F	5	3			00 → M	R	R			
	CLRA													4F	1	1	00 → A	.	.	R	S	R	R			
	CLRB													5F	1	1	00 → B	.	.	R	S	R	R			
Compare	CMPA	81	2	2	91	3	2	A1	4	2	B1	4	3			A - M				
	CMPB	C1	2	2	D1	3	2	E1	4	2	F1	4	3			B - M				
Compare Accumulators	CBA													11	1	1	A - B				
Complement, 1's	COM							63	6	2	73	6	3			M̄ → M	R	S				
	COMA													43	1	1	Ā → A	R	S			
	COMB													53	1	1	B̄ → B	R	S			
Complement, 2's (Negate)	NEG							60	6	2	70	6	3			00 - M → M	1	2				
	NEGA													40	1	1	00 - A → A	1	2			
	NEGB													50	1	1	00 - B → B	1	2			
Decimal Adjust, A	DAA													19	1	1	Converts binary add of BCD characters into BCD format	3				
Decrement	DEC							6A	6	2	7A	6	3			M - 1 → M				
	DECA													4A	1	1	A - 1 → A			
	DECB													5A	1	1	B - 1 → B			
Exclusive OR	EORA	88	2	2	98	3	2	A8	4	2	B8	4	3			A ⊕ M → A	R	.				
	EORB	C8	2	2	D8	3	2	E8	4	2	F8	4	3			B ⊕ M → B	R	.				
Increment	INC							6C	6	2	7C	6	3			M + 1 → M				
	INCA													4C	1	1	A + 1 → A			
	INCB													5C	1	1	B + 1 → B			
Load Accumulator	LDAA	86	2	2	96	3	2	A6	4	2	B6	4	3			M → A	R	.				
	LDAB	C6	2	2	D6	3	2	E6	4	2	F6	4	3			M → B	R	.				
Load Double Accumulator	LDD	CC	3	3	DC	4	2	EC	5	2	FC	5	3			M + 1 → B, M → A	R	.				
Multiply Unsigned	MUL													3D	6	1	A × B → A, B				
OR, Inclusive	ORAA	8A	2	2	9A	3	2	AA	4	2	BA	4	3			A + M → A	R	.				
	ORAB	CA	2	2	DA	3	2	EA	4	2	FA	4	3			B + M → B	R	.				
Push Data	PSHA													36	4	1	A → M _{sp} , SP - 1 → SP			
	PSHB													37	4	1	B → M _{sp} , SP - 1 → SP			
Pull Data	PULA													32	3	1	SP + 1 → SP, M _{sp} → A			
	PULB													33	3	1	SP + 1 → SP, M _{sp} → B			
Rotate Left	ROL							69	6	2	79	6	3			M						
	ROLA													49	1	1	A					
	ROLB													59	1	1	B					
Rotate Right	ROR							65	6	2	75	6	3			M						
	RORA													46	1	1	A					
	RORB													56	1	1	B					

Note: Table 11 lists the manipulation instructions for the condition code register.

Operations	Mnemonic	Addressing Modes															Boolean/ Arithmetic Operation	Condition Code Register									
		IMMED			DIRECT			INDEX			EXTEND			IMPLIED				5	4	3	2	1	0				
		OP	~	=	OP	~	=	OP	~	=	OP	~	=	OP	~	=		H	I	N	Z	V	C				
Shift Left Arithmetic	ASL							68	6	2	78	6	3									⑤					
	ASLA													43	1	1											
	ASLB													58	1	1											
Double Shift Left, Arithmetic	ASLD													05	1	1											
Shift Right Arithmetic	ASR							67	6	2	77	6	3														
	ASRA													47	1	1											
	ASRB													57	1	1											
Shift Right Logical	LSR							64	6	2	74	6	3														
	LSRA													44	1	1											
	LSRB													54	1	1											
Double Shift Right Logical	LSRD													04	1	1											
Store Accumulator	STAA				97	3	2	A7	4	2	B7	4	3				A → M										
	STAB				D7	3	2	E7	4	2	F7	4	3				B → M										
Store Double Accumulator	STD				DD	4	2	ED	5	2	FD	5	3				A → M B → M + 1										
Subtract	SUBA	80	2	2	90	3	2	A0	4	2	B0	4	3				A - M - A										
	SUBB	C0	2	2	D0	3	2	E0	4	2	F0	4	3				B - M - B										
Double Subtract	SUBD	83	4	3	93	4	2	A3	5	2	B3	5	3				A : B - M : M + 1 - A : B										
Subtract Accumulators	SBA													10	1	1	A - B - A										
Subtract With Carry	SBCA	82	2	2	92	3	2	A2	4	2	B2	4	3				A - M - C - A										
	SBCB	C2	2	2	D2	3	2	E2	4	2	F2	4	3				B - M - C - B										
Transfer Accumulators	TAB																16	1	1	A → B							
	TBA																	17	1	1	B → A						
Test Zero or Minus	TST							6D	4	2	7D	4	3				M - 00										
	TSTA																	4D	1	1	A - 00						
	TSTB																		5D	1	1	B - 00					
And Immediate	AIM				71	6	3	61	7	3							M · IMM → M										
OR Immediate	OIM				72	6	3	62	7	3							M + IMM → M										
EOR Immediate	EIM				75	6	3	65	7	3							M ⊕ IMM → M										
Test Immediate	TIM				7B	4	3	6B	5	3							M · IMM										

New Instructions

In addition to the HD6801 instruction sets, the HD6301V has the following new instructions:

AIM (M) · (IMM) → (M)

This instruction ANDs immediate data and the memory contents and then stores the result in memory.

OIM (M) + (IMM) → (M)

This instruction ORs between immediate data and the memory contents and then stores the result in memory.

EIM (M) ⊕ (IMM) → (M)

This instruction EORs between immediate data and the memory contents and then stores the results in memory.

TIM (M) · (IMM)

This instruction ANDs between immediate data and the memory contents and then modifies the flags of the associated condition code register. All these instructions each consist of 3 bytes. The first byte of each instruction is an op-code, the second byte is immediate data, and the third byte is the address modification field.

XGDY (ACCD) ↔ (IX)

This instruction exchange the contents of the accumulator with those of the index register.

SLP

This instruction places the MPU in sleep mode. For details on the sleep mode, see the SLEEP MODE section.

Table 9 Manipulation instructions for the index register and stacks

Table 9 Manipulation instructions for the index register and stacks

Pointer Operations	Mnemonic	Addressing Modes										Boolean/ Arithmetic Operation	Condition Code Register					
		IMMED.		DIRECT		INDEX		EXTEND		IMPLIED			5	4	3	2	1	0
		OP	~ =	OP	~ =	OP	~ =	OP	~ =	OP	~ =							
Compare Index Reg	CPX	9C	4 3	9C	4 2	AC	5 2	BC	5 3			X-M, M-1	•	•	•	•	•	•
Decrement Index Reg	DEX									09	1 1	X-1-X	•	•	•	•	•	•
Decrement Stack Ptr	DES									34	1 1	SP-1-SP	•	•	•	•	•	•
Increment Index Reg	INX									08	1 1	X+1-X	•	•	•	•	•	•
Increment Stack Ptr	INS									31	1 1	SP+1-SP	•	•	•	•	•	•
Load Index Reg	LDX	CE	3 3	DE	4 2	EE	5 2	FE	5 3			M-X _H , (M+1)-X _L	•	•	•	•	•	•
Load Stack Ptr	LDS	8E	3 3	9E	4 2	AE	5 2	BE	5 3			M-SP _H , (M+1)-SP _L	•	•	•	•	•	•
Store Index Reg	STX			DF	4 2	EF	5 2	FF	5 3			X _H -M, X _L -(M+1)	•	•	•	•	•	•
Store Stack Ptr	STS			9F	4 2	AF	5 2	BF	5 3			SP _H -M, SP _L -(M+1)	•	•	•	•	•	•
Index Reg → Stack Ptr	TXS									35	1 1	X-1-SP	•	•	•	•	•	•
Stack Ptr → Index Reg	TSX									30	1 1	SP+1-X	•	•	•	•	•	•
Add	ABX									3A	1 1	B+X-X	•	•	•	•	•	•
Push Data	PSHX									3C	5 1	X _L -M _{sp} , SP-1-SP X _H -M _{sp} , SP-1-SP	•	•	•	•	•	•
Pull Data	PULX									38	4 1	SP+1-SP, M _{sp} →X _H SP+1-SP, M _{sp} →X _L	•	•	•	•	•	•
Exchange	XGDX									18	2 1	ACCD→IX	•	•	•	•	•	•

Note: Table 11 lists the manipulation instructions for the condition code register.

Table 10 Jump and branch instructions

Operations	Mnemonic	Addressing Modes										Branch Test	Condition Code Register					
		RELATIVE		DIRECT		INDEX		EXTEND		IMPLIED			5	4	3	2	1	0
		OP	~ =	OP	~ =	OP	~ =	OP	~ =	OP	~ =							
Branch Always	BRA	20	3 2									None	•	•	•	•	•	•
Branch Never	BRN	21	3 2									None	•	•	•	•	•	•
Branch If Carry Clear	BCC	24	3 2									C=0	•	•	•	•	•	•
Branch If Carry Set	BCS	25	3 2									C=1	•	•	•	•	•	•
Branch If = Zero	BEQ	27	3 2									Z=1	•	•	•	•	•	•
Branch If > Zero	BGE	2C	3 2									N ⊕ V = 0	•	•	•	•	•	•
Branch If > Zero	BGT	2E	3 2									Z + (N ⊕ V) = 0	•	•	•	•	•	•
Branch If Higher	BHI	22	3 2									C + Z = 0	•	•	•	•	•	•
Branch If < Zero	SLE	2F	3 2									Z - (N ⊕ V) = 1	•	•	•	•	•	•
Branch If Lower Or Same	BLS	23	3 2									C - Z = 1	•	•	•	•	•	•
Branch If < Zero	BLT	2D	3 2									N ⊕ V = 1	•	•	•	•	•	•
Branch If Minus	BMI	28	3 2									N = 1	•	•	•	•	•	•
Branch If Not Equal Zero	BNE	26	3 2									Z = 0	•	•	•	•	•	•
Branch If Overflow Clear	BVC	28	3 2									V = 0	•	•	•	•	•	•
Branch If Overflow Set	BVS	29	3 2									V = 1	•	•	•	•	•	•
Branch If Plus	BPL	2A	3 2									N = 0	•	•	•	•	•	•
Branch To Subroutine	BSR	8D	6 2										•	•	•	•	•	•
Jump	JMP					6E	3 2	7E	3 3					•	•	•	•	•
Jump To Subroutine	JSR					9D	5 2	AD	5 2	BD	6 3			•	•	•	•	•
No Operation	NOP									01	2 1	Advances Prog. Cntr. Only	•	•	•	•	•	•
Return From Interrupt	RTI									3B	10 1		•	•	•	•	•	•
Return From Subroutine	RTS									39	5 1		•	•	•	•	•	•
Software Interrupt	SWI									3F	12 1		•	•	•	•	•	•
Wait for Interrupt*	WAI									3E	9 1		•	•	•	•	•	•
Sleep	SLP									1A	4 1		•	•	•	•	•	•

*: WAI places R/W in "High" level; the address bus changes to FFFF; the data bus changes to the three-state level.

Note: Table 11 lists the manipulation instructions for the condition code register.

Table 11 Manipulation instructions for the condition code register

Operations	Mnemonic	Addressing Modes			Boolean Operation	Condition Code Register						
		IMPLIED				5	4	3	2	1	0	
		OP	~	≠		H	I	N	Z	V	C	
Clear Carry	CLC	0C	1	1	0 → C	•	•	•	•	•	•	R
Clear Interrupt Mask	CLI	0E	1	1	0 → I	•	R	•	•	•	•	•
Clear Overflow	CLV	0A	1	1	0 → V	•	•	•	•	•	R	•
Set Carry	SEC	0D	1	1	1 → C	•	•	•	•	•	•	S
Set Interrupt Mask	SEI	0F	1	1	1 → I	•	S	•	•	•	•	•
Set Overflow	SEV	0B	1	1	1 → V	•	•	•	•	•	S	•
Accumulator A → CCR	TAP	06	1	1	A → CCR	————— 10 —————						
CCR → Accumulator A	TPA	07	1	1	CCR → A	•	•	•	•	•	•	•

Note: Each bit of the condition code register is set when the test result is true and cleared otherwise.

- 1 (Bit V) Test: Result=10000000?
- 2 (Bit C) Test: Result=00000000?
- 3 (Bit C) Test: Is the BCD character of the high-order
byte greater than 10?
If this bit is set beforehand, it is not
cleared.
- 4 (Bit V) Test: Operand before execution=10000000?
- 5 (Bit V) Test: Operand before execution=01111111?
- 6 (Bit V) Test: Set when N+C=1 after execution of an
instruction.
- 7 (Bit N) Test: Is the result less than 0?
(Bit 15=1)
- 8 (All) Data is loaded from the stack to the condition
code register.
- 9 (Bit 1) T This bit is set when an interrupt occurs.
When the bit is set beforehand, to clear the
set bit, a non maskable interrupt is required.
- 10 (all bits) All the bits are set according to the contents
of accumulator A.
- 11 (Bit C) Bit 7 of the ACCB after multiplication=1?

Table 12 Op-code map

OP CODE					ACC	ACC	IND	EXT	ACCA or SP				ACCB or X				
	HI	0000	0001	0010	0011	0100	0101	0110	DIR	IMM	DIR	IND	EXT	IMM	DIR	IND	EXT
LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
1000 0	/	SBA	BRA	TSX	/	/	NEG	/	/	/	/	/	SUB	/	/	/	0
0001 1	NOP	CBA	BRN	INS	/	/	/	AIM	/	/	/	/	CMP	/	/	/	1
0010 2	/	/	BHI	PULA	/	/	/	OIM	/	/	/	/	SBC	/	/	/	2
0011 3	/	/	BLS	PULB	/	/	COM	/	/	SUBD	/	/	ADD	/	/	/	3
0100 4	LSRD	/	BCC	DES	/	/	LSR	/	/	/	/	/	AND	/	/	/	4
0101 5	ASLD	/	BCS	TXS	/	/	/	EIM	/	/	/	/	BIT	/	/	/	5
0110 6	TAP	TAB	BNE	PSHA	/	/	ROR	/	/	/	/	/	LDA	/	/	/	6
0111 7	TPA	TBA	BEQ	PSHB	/	/	ASR	/	/	STA	/	/	/	STA	/	/	7
1000 8	INX	XGDX	BVC	PULX	/	/	ASL	/	/	/	/	/	EOR	/	/	/	8
1001 9	DEX	DAA	BVS	RTS	/	/	ROL	/	/	/	/	/	ADC	/	/	/	9
1010 A	CLV	SLP	3PL	ABX	/	/	DEC	/	/	/	/	/	CRA	/	/	/	A
1011 B	SEV	ABA	BMI	RTI	/	/	/	TIM	/	/	/	/	ADD	/	/	/	B
1100 C	CLC	/	BGE	PSHX	/	/	INC	/	/	CPX	/	/	LDD	/	/	/	C
1101 D	SEC	/	BLT	MUL	/	/	TST	/	BSR	JSR	/	/	STD	/	/	/	D
1110 E	CLI	/	BGT	WAI	/	/	/	JMP	/	LDS	/	/	LDX	/	/	/	E
1111 F	SEI	/	BLE	SWI	/	/	CLR	/	/	STS	/	/	STX	/	/	/	F

UNDEFINED OP CODE

. Only AIM, OIM, EIM, and TIM can be used.

LOW POWER CONSUMPTION MODE

The HD6301V has two low power consumption modes: sleep and standby.

- Sleep Mode

When an SLP instruction is executed, the MCU enters sleep mode. In sleep mode, the MPU operation stops but the contents of the registers in the MPU remain unchanged. Since other peripheral functions do not stop, the counter operation, data transmission, and data reception, etc., are not interrupted. In this mode, the power consumption decreases to approx. 1/10 the consumption required for the operation. Interrupts RES and STBY are used to change this mode.

RES resets the MCU and STBY brings it to standby mode. When the MPU receives RES or STBY, sleep mode is released, allowing the MPU to return to operation mode and to vector to the interrupt routine. If the MPU masks this routine, it executes the next instruction after releasing sleep mode. Since no interrupt can be issued to the MPU when the timer disables its interrupt, sleep mode cannot be released.

This sleep mode is especially effective for reducing the average power consumption when the HD6301V is not always driven.

- Standby Mode

When STBY terminal goes "Low", all the HD6301V clocks stop, causing the MPU to be reset and enter standby mode. The use of this mode greatly reduces the HD6301V power consumption.

Since power is continuously supplied to the HD6301V in standby mode, the RAM contents is kept. The reset start function is used to reset standby mode. The following is a typical example of applying this mode.

First, NM1 saves internal MCU information and the SP contents to the RAM, disables the RAME bit of the RAM control register, and sets the STBY bit to place the MPU in standby mode. If the STBY bit is already set at reset a start time, it indicates that power has been continuously supplied to the HD6301V and the RAM contents have correctly been retained. Therefore, the system can be recovered by returning the SP and restoring the internal conditions to those before standby mode.

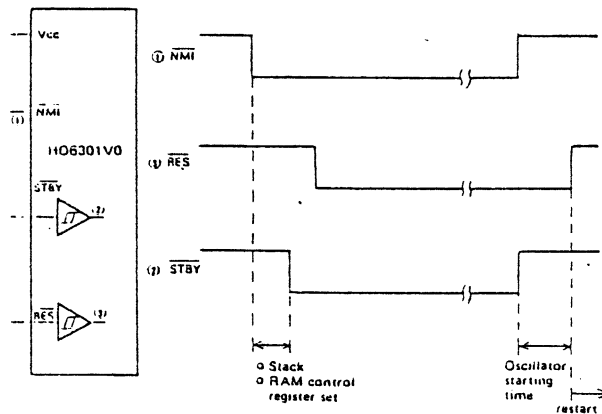


Fig. 24 shows the timing of each line (pin) in standby mode.

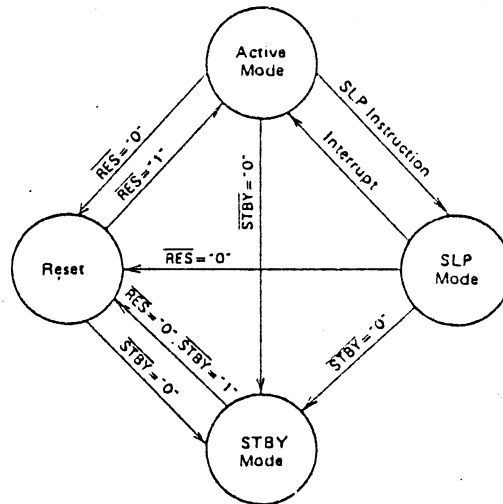


Fig. 25 Transitions between the active mode, sleep mode, standby mode and reset

ERROR PROCESSING

The HD6301V generates a highest-priority internal interrupt to prevent the system overrun that occurs due to a noise or a program error when fetching an undefined instruction or an instruction from the unmounted memory area.

- Op-code Error

When an undefined op-code is fetched, the HD6301V saves the MPU register as in the case of a normal interrupt and vectors to the TRAP (\$FFEE, \$FFEF). This function has the second highest priority next to the reset function.

- Address Error

If an instruction is fetched from other than the built-in ROM, the built-in RAM, and the external memory area, execution branches to the same interrupt operation as for an op-code error. If an instruction is fetched from the external memory area when the external memory is not mounted, this function is not applied.

Table 13 shows the relationship between addresses where an address error occurs and modes.

This function applies only to the instruction fetch but does not apply to the normal data read/write access operations.

Table 13 Error addresses and modes

Mode	0	1	4	5	6	7
Address	\$0000 } \$001F	\$0000 } \$001F	\$0000 } \$001F	\$0000 } \$007F \$0200 } \$EFFF	\$0000 } \$001F	\$0000 } \$007F } \$EFFF

Figs. 26 through 29 show the system configurations of various modes.

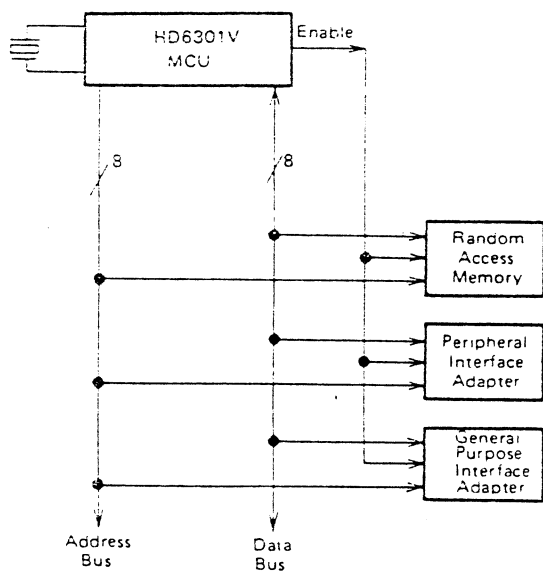


Fig. 27 HD6301V MCU expanded nonmultiplexed mode (mode 5)

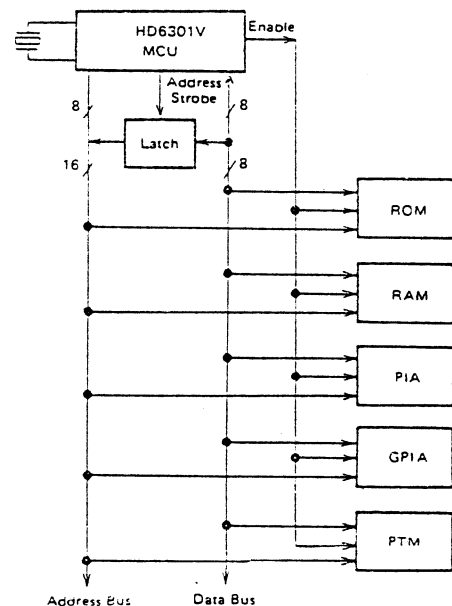


Fig. 28 HD6301V MCU expanded multiplexed mode

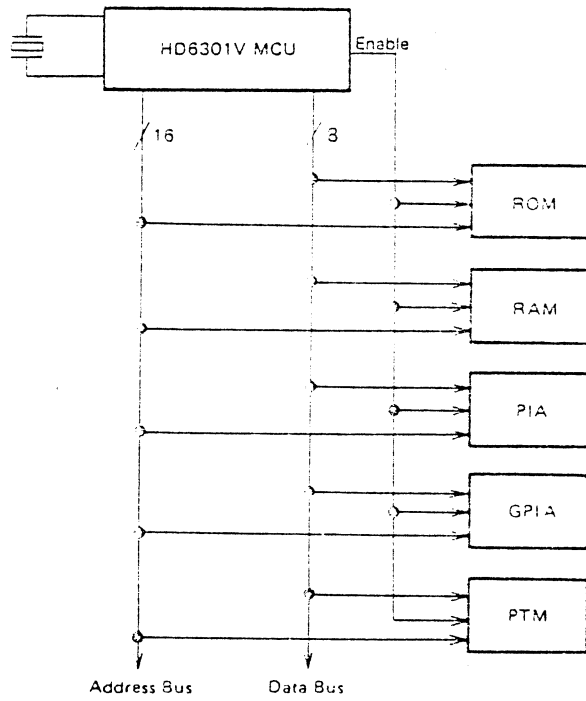


Fig. 29 HD6301V MCU expanded nonmultiplexed mode (mode 1)

4. Mnemonic Codes

Add accumulator B to accumulator A

ABA

Type	Function
Arithmetic operation (two operands)	$ACCA + (AACA) + (ACCB)$ Adds the ACCB contents and the ACCA contents and stores the result in the ACCA. <u>Effect on condition codes</u>
H	$A_3 \ B_3 \cdot B_3 \cdot R_3 \cdot R_3 \cdot A_3$: When bit 3 is carried, this bit is set and otherwise cleared.
I	: Not affected.
N	R_7 : When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.
Z	$\overline{R_7} \cdot \overline{R_6} \cdot \overline{R_5} \cdot \overline{R_4} \cdot \overline{R_3} \cdot \overline{R_2} \cdot \overline{R_1} \cdot \overline{R_0}$: When the result is 0, bit Z is set and otherwise cleared
V	$A_7 \cdot B_7 \cdot \overline{R_7} \odot \overline{A_7} \cdot \overline{B_7} \cdot R_7$: When the result overflows, bit V is set and otherwise cleared.
C	$A_7 \cdot B_7 \odot \overline{R_7} \odot \overline{R_7} \cdot A_7$: When the highest-order bit (MSB) of the result is carried, bit C is set and otherwise cleared.

Add accumulator B to index register

ABX

Type	Function
Arithmetic operation	$1X + (1X) + (ACCB)$ Adds the unsigned contents of the ACCB to the index register contents considering the low-order byte carry of the index register and then stores the result in the index register. <u>Effect on condition codes</u>
H	: Not affected.

Add with Carry

ADC

Type	Function
Arithmetic operation (two operands)	$ACCX + (ACCX) + (M) + (C)$ Adds carry bit C to a combination of the ACCX and memory M and then stores the result in the ACCX. <u>Effect on condition codes</u>
H	$X_3 \cdot M_3 \cdot M_3 \cdot R_3 \cdot R_3 \cdot X_3$: When bit 3 is carried, bit H is set and otherwise cleared.
I	: Not affected.
N	R_7 : When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.
Z	$\overline{R_7} \cdot \overline{R_6} \cdot \overline{R_5} \cdot \overline{R_4} \cdot \overline{R_3} \cdot \overline{R_2} \cdot \overline{R_1} \cdot \overline{R_0}$: When the result is 0, bit Z is set and otherwise cleared.
V	$X_7 \cdot M_7 \cdot \overline{R_7} \odot \overline{X_7} \cdot \overline{M_7} \cdot R_7$: When the result overflows, bit V is set and otherwise cleared.
C	$X_7 \cdot M_7 \odot \overline{R_7} \odot \overline{R_7} \cdot X_7$: When the highest-order bit (MSB) of the result is carried, bit C is set and otherwise cleared.

ADD without carry ADD

Type	Function
Arithmetic operation	ACCX ← (ACCX) + (M) Adds contents of the ACCX to memory M and stores (two operands) the result in the ACCX.
	<u>Effect on condition codes</u>
H	$X_3 \cdot M_3 \oplus M_3 \cdot R_3 \oplus R_3 \cdot X_3$: When bit 3 is carried, bit H is set and otherwise cleared.
I	: Not affected.
N	= R7: When the highest-order bit (MSB) of the result is 1, bit N <u>is set and otherwise cleared.</u>
Z	= R7 · R6 · R5 · R4 · R3 · R2 · R1 · R0: When the result is 0, bit Z is set and otherwise cleared.
V	= $X_7 \cdot M_7 \cdot R_7 \oplus X_7 \cdot M_7 \cdot R_7$: When the result overflows, bit V is set and otherwise cleared.
C	= $X_7 \cdot M_7 \oplus M_7 \cdot R_7 \oplus R_7 \cdot X_7$: When the highest-order bit (MSB) of the result is carried, bit C is set and otherwise cleared.

Double ADD without carry ADDD

Type	Function
Arithmetic operation	ACCAB ← (ACCAB) + (M:M + 1) Adds the contents of the M:M + 1 to ACCAB and stores the result in the ACCAB.
	<u>Effect on condition codes</u>
H	: Not affected.
I	: When the highest-order bit (MSB) of the result is 1, bit N is set <u>and otherwise cleared.</u>
Z	= R15 · R14 · R13 · · R0: When the result is 0, bit Z is set and otherwise cleared.
V	= $AB_{15} \cdot M_{15} \oplus R_{15} \cdot AB_{15} \cdot M_{15} \cdot R_{15}$: When the result overflows, bit V is set and otherwise cleared.
C	= $AB_{15} \cdot M_{15} \oplus M_{15} \cdot R_{15} \oplus R_{15} \cdot AB_{15}$: When the highest-order bit (MSB) of the result is carried, bit C is set and otherwise cleared.

Logical AND AND

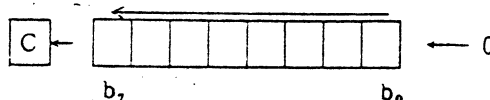
Type	Function
Logical operation	ACCX ← (ACCX) · (M) ANDs the contents of the ACCX with those of memory M and stores the result in the ACCX.
	<u>Effect on condition codes</u>
H	: Not affected.
I	: Not affected.
N	= R7: When the highest-order bit (MSB) of the result is 1, bit N is <u>set and otherwise cleared.</u>
Z	= R7 · R6 · R5 · R4 · R3 · R2 · R1 · R0: When the result is 0, bit Z is set and otherwise cleared.
V	= 0 : Bit V is cleared.
C	: Not affected.

Arithmetic Shift Left

ASL

Type
Shift and
rotation

Function



Shifts the ACCX or memory M to the left by one bit and stores 0 in bit 0 and ACCX or bit 7 of memory M in the carry bit.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z is set and otherwise cleared.

V = N + C: Bit V is set: When bit N is 1 and bit C is 0 after the shift or when bit N is 0 and bit C is 1 after the shift. In all other cases, this bit is cleared.

Note: Bits N and C are those after the operation.

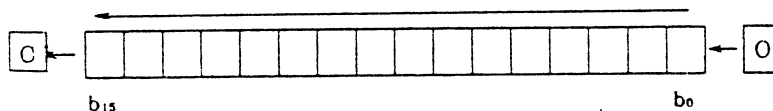
C = M₇: When the highest-order bit (MSB) of the ACCX or memory before shift is 1, bit C is set and otherwise cleared.

Arithmetic Double Shift Left A:B

ASLD

Type
Shift and
rotation

Function



Shifts the ACCAB to the left by one bit and stores 0 in bit 0 and bit 15 of the ACCAB in the carry bit.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₁₅: When the highest-order bit (MSB) of the result is 1, N is set and otherwise cleared.

Z = R₁₅. R₁₄. R₁₃ R₀: When the result is 0, bit Z is set and otherwise cleared.

Z = N ⊕ C: Bit V is set: When bit N is 1 and bit C is 0 after the shift or when bit N is 0 and bit C is 1 after the shift. In all other cases, this bit is cleared.

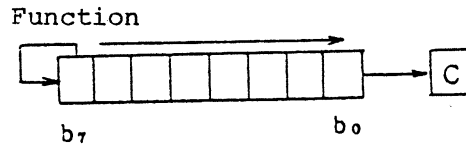
Note: Bits N and C are those after the operation.

C = AB₁₅: When the highest-order bit (MSB) of the ACCAB before shift is 1, bit C is set and otherwise cleared.

Arithmetic Shift Right

ASR

Type
Shift and
rotation



Shifts the contents of the ACCX or memory M to the right by one byte and stores bit 0 in the carry bit. In this case, bit 7 does not change.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R_7 : When the highest-order bit (MBS) of the result is 1, bit N is set and otherwise cleared.

Z = $R_7 \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0$: When the result is 0, bit Z is set and otherwise cleared.

V = N + C: Bit V is set: When N is 1 and C is 0 after the shift or when N is 0 and C is 1 after the shift.

Note: N and C are those after the operation.

C = M_0 : When the lowest-order bit (LSB) before shift is 1, bit C is set and otherwise cleared.

Branch if Carry Clear

BCC

Type
Conditional
branch

Function
PC + (PC) + 0002 + Rel if (C) = 0
Judges bit C and branches when C is 0.

Effect on condition codes

H : Not affected.

Branch if Carry Set

BCS

Type
Conditional
branch

Function
PC + (PC) + 0002 + Rel if (C) = 1
Judges bit C and branches when C is 1.

Effect on condition codes

H : Not affected.

Branch if Equal

BEQ

Type Function
Conditional PC ← (PC) + 0002 + Rel if (Z) = 1
branch Judges bit Z and branches to the specified address
 if Z is 1.
 Effect on condition codes
H : Not affected.

Branch if Greater than or Equal to zero

BGE

Type Function
 PC ← (PC) + 0002 + Rel if (N) + (V) = 0
 In this case, (ACCX) > (M). (Two's complement)
Conditional Branches to the specified address when bits N and V
branch are both 1 or are both 0.
 In other words, a branch occurs if minuend (ACCX)
 represented by two's complement is greater than or
 equal to subtrahend (M) represented by two's
 complement when the BGE instruction is executed
 immediately after execution of the CBA, CMP, SBA,
 and SUB instructions, etc.
 Effect on condition codes
H : Not affected.

Branch if Greater Than zero

BGT

Type Function
 PC ← (PC) + 0002 + Rel if (Z) . [(N) + (V)] = 0
 In this case, (ACCX) > (M). (Two's complement)
Conditional Branches to the specified address when bit Z is 0
branch and bits N and V are both 1 or are both 0.
 In other words, a branch occurs if minuend (ACCX)
 represented by two's complement is greater than
 subtrahend (M) represented by two's complement when
 the BGT instruction is executed immediately after
 execution of the CBA, CMP, SBA, and SUB instructions,
 etc.
 Effect on condition codes
H : Not affected.

Branch if Higher

BHI

Type	Function
	$PC \leftarrow (PC) + 0002 + Rel$ if $(C) \odot (Z) = 0$
	In this case, $(ACCX) > (M)$. (Unsigned binary number)
Conditional branch	Branches to the specified address when bits C and Z are both 0. In other words, a branch occurs if minuend (ACCX) represented by an unsigned binary number is greater than subtrahend (M) represented by an unsigned binary number when the BHI instruction is executed immediately after execution of the CBA, CMP, SBA, and SUB instructions, etc.
	Effect on condition codes

H : Not affected.

Bit Test

BIT

Type	Function
Logical operation	$A (ACCX) \cdot (M)$
	ANDs the contents of the ACCX and those of memory M and modifies the corresponding condition code. In this case, the contents of the ACCX and memory M remain unchanged.
	Effect on condition codes

H : Not affected.

I : Not affected.

N = R7: When the highest-order bit (MSB) of the AND result is 1, bit N is set and otherwise cleared.

Z = R7. R6. R5. R4. R3. R2. R1. R0: If all the bits are 0 after the AND operation, bit Z is set and otherwise cleared.

V = 0: Bit V is cleared.

C : Not affected.

Branch if Less than or Equal to zero

BLE

Type	Function
	$PC \leftarrow (PC) + 0002 + Rel$ if $(Z) \odot [(N) \oplus (V)] = 1$
	In this case, $(ACCX) \leq (M)$ (Two's complement)
Conditional branch	Branches to the specified address when Z is 1, N is 1 and V is 0, or N is 0 and V is 1.
	In other words, a branch occurs if minuend (ACCX) represented by two's complement is less than or equal to subtrahend (M) represented by two's complement when the BLE instruction is executed immediately after execution of the CBA, CMP, SBA, and SUB instructions, etc.
	Effect on condition codes

H : Not affected.

Branch if Plus

BPL

Type	Function
Conditional branch	$PC \leftarrow (PC) + 0002 + Rel$ if $(N) = 0$ Judges bit N and branches to the specified address when N is 0. Effect on condition codes

H : Not affected.

Branch Always

BRA

Type	Function
Unconditional branch and jump	$PC \leftarrow (PC) + 0002 + Rel$ Unconditionally branches to the address obtained by the above expression. Rel indicates the relative address stored in the second byte of the machine code of the branch instruction as two's complement. Effect on condition codes

H : Not affected.

BRanch Never

BRN

Type	Function
Unconditional branch and jump	$PC \leftarrow (PC) + 0002$ The BRN instruction is treated as if NOP were used twice but it is actually a 2-byte, 3-cycle instruction. This instruction is one of the 6801 characteristics and is the reversed version of the BRA instruction. Note: 0 through \$FF (possible branch range) must be specified in the second byte of the instruction code. Effect on condition codes

H : Not affected.

Branch to SubRoutine

BSR

Type	Function	
Subroutine control	PC ← (PC) + 0002	1. 2 is added to the program counter.
	↓ (PCL)	2. The low-order bytes of the program counter are saved to the stack.
	SP ← (SP) - 0001	3. 1 is subtracted from the stack pointer.
	↓ (PCH)	4. The high-order bytes of the program counter are saved to the stack.
	SP ← (SP) - 0001	5. 1 is subtracted from the stack pointer.
	PC ← (PC) + Rel	6. The instruction branches to the address indicated by the program.

Effect on condition codes

H : Not affected.

Branch if oVerflow Clear

BVC

Type	Function	
Conditional branch	PC ← (PC) + 0002 + Rel	if (V) = 0
	Judges bit V and branches to the specified address when bit V is 0.	

Effect on condition codes

H : Not affected.

Branch if oVerflow Set

BVS

Type	Function	
Conditional branch	PC ← (PC) + 0002 + Rel	if (V) = 1
	Judges bit V and branches to the specified address when bit V is 1.	

Effect on condition codes

H : Not affected.

Compare Accumulators

CBA

Type	Function
Comparison and Test	(ACCA) - (ACCB)
	Compares the contents of the ACCA with those of the ACCB and sets an appropriate condition code. This instruction applies to the numeric and logical conditional branch. Both the operands are not affected at all.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R7: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R7. R6. R5. R4. R3. R2. R1. R0: When the result is 0, bit Z is set and otherwise cleared.

V = A7. B7. R7. A7. B7. R7: When an overflow occurs during subtraction, bit V is set and otherwise cleared.

C = A7. B7. B7. R7. R7. A7: When a borrow occurs, bit C is set and otherwise cleared.

CLear Carry

CLC

Type	Function
Bit control	Bit C ← 0 Clears carry bit C Effect on condition codes

C = 0: Bit C is cleared.

CLear Interrupt mask

CLI

Type	Function
Bit control	Bit I ← 0 Clears the interrupt mask bit of a condition code. The microprocessor can receive the interrupt request issued from a peripheral device. Effect on condition codes

H : Not affected.
I = 0 : Bit I is cleared.

CLear

CLR

Type	Function
Arithmetic operation (one operand)	ACCX ← 00 or M ← 00 Clears the contents of the ACCX or memory M. Effect on condition codes

H : Not affected.
I : Not affected.
N = 0: Bit N is cleared.
Z = 1: Bit Z is set.
V = 0: Bit V is cleared.
C = 0: Bit C is cleared.

CLear two's complement oVerflow bit

CLV

Type	Function
Bit control	Clears the overflow bit of a condition code. Effect on condition codes

H : Not affected.
V = 0: Bit V is cleared.
C : Not affected.

CoMPare

CMP

Type	Function
Comparison and test	(ACCX) - (M) Compares the contents of the ACCX with those of memory M and changes the condition code. A conditional branch instruction can be used to reference the contents of this condition code. In this case, both the operands do not change. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = R7:	When the highest-order bit (MSB) of the result is 1, bit N is <u>set and otherwise cleared</u> .
Z = R7. R6. R5. R4. R3. R2. R1. R0:	When the result is 0, bit Z is set and otherwise cleared.
V = X7. M7. R7 @ X7. M7. R7:	When an overflow occurs during subtraction, bit V is set and otherwise cleared.
C = X7. M7 @ M7. R7 @ R7. X7:	When the absolute value of memory is greater than that of the accumulator, bit C is set and otherwise cleared.

COMplement

COM

Type	Function
Logical operation	$ACCX \leftarrow (ACCX) = FF - (ACCX)$ or $M \leftarrow (M) = F - (M)$ Replaces the contents of the ACCX or memory M with one's complement. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = R7:	When the highest-order bit (MSB) of the result is 1, bit N is <u>set and otherwise cleared</u> .
Z = R7. R6. R5. R4. R3. R2. R1. R0:	When the result is 0, bit Z is set and otherwise cleared.
V = 0 :	Bit V is cleared.
C = 1 :	Bit C is set.

ComPare index register

CPX

Type	Function
Index register control	(IX) - (M:M + 1) Compares the contents of the index register with those of the 2-byte memory. Bits N, Z, V, and C are set or cleared according to the compared result. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = RH:	When the highest-order bit of (MSB) of the result is 1, bit N <u>is set and otherwise cleared</u> .
Z = (RH7. RH6. RH5. RH4. RH3. RH2. RH1. RH0). (RL7. RL6. RL5. RL4. RL3. RL2. RL1. RL0):	When the subtraction results of the high- and low-order bytes are 0, bit Z is set and otherwise cleared.

V = $\overline{\text{IXH7}} \cdot \overline{\text{M7}} \cdot \overline{\text{RH7}} \oplus \overline{\text{IXH7}} \cdot \text{M7} \cdot \text{RH7}$: If an overflow occurs when a high-order byte subtraction is performed, bit V is set and otherwise cleared.

C = $\overline{\text{IXH7}} \cdot \text{MH7} \oplus \text{MH7} \cdot \overline{\text{RH7}} \oplus \overline{\text{IXH7}} \cdot \text{RH7}$: When the absolute value of memory is greater than that of the index register, bit C is set and otherwise cleared.

Decimal Adjust ACCA

DAA

Type Function
 Arithmetic operation Adds 00, 06, 60 and 66 to the ACCA (hex number) as shown in the table below when the results obtained by performing a binary coded decimal (BCD) addition with the ABA, ADD and ADC instructions, etc., stored in bits C and H of the ACCA.

Bit C state before DAA execution	4 high-order bits 4 through 7	Initial 4 bits bits 0 through 3	4 low-order bits 0 through 3	Hex. values added to the ACCX by executing DAA	Bit C state after DAA execution
0	0-9	0	0-9	00	0
0	0-8	0	A-F	06	0
0	0-9	1	0-3	06	0
0	A-F	0	0-9	60	1
0	9-F	0	A-F	66	1
0	A-F	0	0-9	66	1
1	0-2	0	0-9	60	1
1	0-2	0	A-F	66	1
1	0-3	1	0-3	66	1

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z is set and otherwise cleared.

C : Bit C is set or cleared according to the same rules of replacing the DAA, ABA, ADD, and ADC instructions by the BCD addition (see the above table).

DECrement

DEC

Type Function
 Arithmetic operation ACCX (ACCX) - 01 or M (M) - 01
 Subtracts 1 from the ACCX or memory M. In this case, bits N, Z, and V are set or cleared according to the result of the subtraction but bit C is not affected by the result at all.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z is set and otherwise cleared.

V = X₇. X₆. X₅. X₄. X₃. X₂. X₁. X₀ = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: If the result overflow, bit V is set and otherwise cleared. If the contents of the ACCX or memory M are 80, an overflow occurs.

C : Not affected.

DEcrement Stack pointer

DES

Type	Function
Stack pointer control	$SP \leftarrow (SP) - 0001$ Subtracts 1 from the stack pointer.

Effect on condition codes

H : Not affected.

DEcrement index register

DEX

Type	Function
Index register control	$IX \leftarrow (IX) - 0001$ Subtracts 1 from the index register. Only bit Z is set or cleared according to the result.

Effect on condition codes

H : Not affected.

I : Not affected.

N : Not affected.

$Z = (\overline{RH7} \cdot \overline{RH6} \cdot \overline{RH5} \cdot \overline{RH4} \cdot RH3 \cdot RH2 \cdot RH1 \cdot RH0) \cdot (RL7 \cdot RL6 \cdot RL5 \cdot$

$RL4 \cdot RL3 \cdot RL2 \cdot RL1 \cdot RL0)$: When the result is 0, bit Z is set and otherwise cleared.

V : Not affected.

C : Not affected.

Exclusive OR

EOR

Type	Function
Logical operation	$ACCX \leftarrow (ACCX) \oplus (M)$ EORs the contents of the ACCX with those of memory M and stores the result in the ACCX.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R₇ · R₆ · R₅ · R₄ · R₃ · R₂ · R₁ · R₀: When the result is 0, bit Z is set and otherwise cleared.

V = 0: Bit V is cleared.

C : Not affected.

INCrement

INC

Type	Function
Arithmetic operation	$ACCX \leftarrow (ACCX) + 01$ or $M \leftarrow (M) + 01$ Adds 1 to the ACCX or memory M. In this case, bits N, Z, and V are set or cleared according to the result of the addition but bit C is not affected at all by the result. Effect on condition codes

H : Not affected.
 I : Not affected.
 N = $\overline{R_7}$: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.
 Z = $\overline{R_7} \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0$: When the result is 0, bit Z is set and otherwise cleared.
 V = $\overline{X_7} \cdot X_6 \cdot X_5 \cdot X_4 \cdot X_3 \cdot X_2 \cdot X_1 \cdot X_0 = \overline{R_7} \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0$:
 When the result overflow, bit V is set and otherwise cleared.
 If the contents of the ACCX or memory M are 7F, an overflow occurs.
 C : Not affected.

INcrement Stack pointer

INS

Type	Function
Stack pointer control	$SP \leftarrow (SP) + 0001$ Adds 1 to the stack pointer (SP). Effect on condition codes

H : Not affected.

INcrement index register

INX

Type	Function
Index register control	$IX \leftarrow (IX) + 0001$ Adds 1 to the index register. Only bit Z is set or cleared according to the result of the addition but no other bits.

Effect on condition codes
 H : Not affected.
 I : Not affected.
 N : Not affected.
 $Z = (\overline{RH_7} \cdot \overline{RH_6} \cdot \overline{RH_5} \cdot \overline{RH_4} \cdot \overline{RH_3} \cdot \overline{RH_2} \cdot \overline{RH_1} \cdot \overline{RH_0}) \cdot (\overline{RL_7} \cdot \overline{RL_6} \cdot \overline{RL_5} \cdot \overline{RL_4} \cdot \overline{RL_3} \cdot \overline{RL_2} \cdot \overline{RL_1} \cdot \overline{RL_0})$: When bit 16 of the result is 0, bit Z is set and otherwise cleared.
 V : Not affected.
 C : Not affected.

JuMP

JMP

Type	Function
Unconditional branch and jump	PC ← numeric address Branches to the instruction with the specified numeric address. The numeric address is specified according to the rules of the extended or index addressing. Effect on condition codes

H : Not affected.

Jump to SubRoutine

JSR

Type	Function
Subroutine control	PC ← (PC) + 0003 (EXTND) or PC ← (PC) + 0002 (INDEX) ↓ (PCL) SF ← (SP) - 0001 ↓ (PCH) SP ← (SP) - 0001 PC ← Numeric address Adds 2 or 3 to the program counter in address mode, saves 2 bytes to the stack, updates the stack pointer, and branches to the specified address. The specified address is obtained according to the rules of the extended or index addressing. Effect on condition codes

H : Not affected.

Load Accumulator

LDA

Type	Function
Load	ACCX ← (M) Loads the contents of memory M to the accumulator. Effect on condition codes

H : Not affected.
I : Not affected.
N = R₇: When the highest-order bit (MBS) of the result is 1, bit N is
set and otherwise cleared.
Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z
is set and otherwise cleared.
V = 0: Bit V is cleared.
C : Not affected.

Double Load accumulator A:B

LDD

Type	Function
Load and storage	$ACCB \leftarrow (M:M + 1)$ Loads 2 bytes of memory M and of M+1 to the ACCAB. Effect on condition codes
H :	Not affected.
I :	Not affected.
N + R ₁₅ :	When the highest-order bit (MSB) of the result is 1, bit N <u>is set</u> and otherwise cleared.
Z = R ₁₅ . R ₁₄ . R ₁₃ R ₀ :	When the result is 0, bit Z is set and otherwise cleared.
V = 0 :	Bit V is cleared.
C :	Not affected.

Load Stack pointer

LDS

Type	Function
Stack pointer control	$SPH \leftarrow (M)$ $SPL \leftarrow (M + 1)$ First loads the contents of memory M to the high-order 8 bits of the SP and then the contents of updated address M+1 (memory M address plus 1) to the low-order 8 bits of the SP. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = RH ₇ :	When the highest-order bit (MSB) of the SP result is 1, <u>bit N is set</u> and otherwise cleared.
Z = (RH ₇ . RH ₆ . RH ₅ . RH ₄ . RH ₃ . RH ₂ . RH ₁ . RH ₀). (RL ₇ . RL ₆ . RL ₅ . RL ₄ . RL ₃ . RL ₂ . RL ₁ . RL ₀) :	When all the bits of the SP result are 0, bit Z is set and otherwise cleared.
V = 0 :	Bit V is cleared.
C :	Not affected.

Load index register

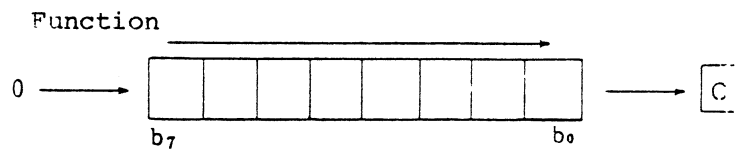
LDX

Type	Function
Index register control	$IXH \leftarrow (M)$ $IXL \leftarrow (M + 1)$ First loads the contents of memory M to the high-order 8 bits of the index register and then the contents of updated address M+1 (memory M address plus 1) to the low-order 8 bits of the index register. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = RH ₇ :	When the highest-order bit (MSB) of the index register is 1, <u>bit N is set</u> and otherwise cleared.
Z = (RH ₇ . RH ₆ . RH ₅ . RH ₄ . RH ₃ . RH ₂ . RH ₁ . RH ₀). (RL ₇ . RL ₆ . RL ₅ . RL ₄ . RL ₃ . RL ₂ . RL ₁ . RL ₀) :	When all the bits of the index register are 0, bit Z is set and otherwise cleared.
V = 0 :	Bit V is cleared.
C :	Not affected.

Logical Shift Right

LSR

Type
Shift and
rotation



Shifts the contents of the ACCX or memory M to the right by one bit, stores 0 in bit 7, loads the lowest-order bit (LSB) of the ACCX or memory M to bit C.

Effect on condition codes

H : Not affected.

I : Not affected.

N = 0: Bit N is cleared. _ _ _

Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z is set and otherwise cleared.

V = N + C: When N is 1 and C is 0 or N is 0 and C is 1, bit V is set and otherwise cleared.

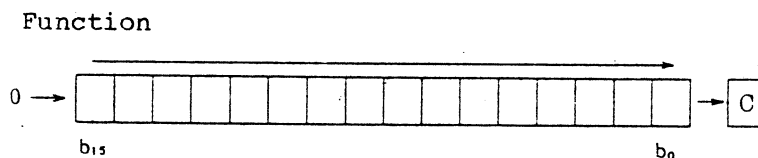
Note: Bits N and C are those after the operation.

C = M₀: When the lowest-order bit (LSB) of the ACCX or memory M before execution of an instruction is 1, bit C is set and otherwise cleared.

Logical Double Shift Right A:B

LSRD

Type
Shift and
rotation



Shifts the contents of the ACCAB to the right by one bit, stores 0 in bit 15, and loads the lowest-order bit (LSB) of the ACCAB to bit C.

Effect on condition codes

H : Not affected.

I : Not affected.

Z = R₁₅. R₁₄. R₁₃..... R₀: When the result is 0, bit Z is set and otherwise cleared.

V = N + C: When bit N is 1 and bit C is 0 or bit N is 0 and bit C is 1, bit V is set and otherwise cleared.

Note: Bits N and C are those after the operation.

C = ABO: When the lowest-order bit (LSB) of the ACCAB or memory M is 1, bit C is set and otherwise cleared.

MULTiply unsigned

MUL

Type
Arithmetic
operation

Function

ACCAB + (ACCA) * (ACCB)

Multiplies the contents of the ACCA by those of the ACCB, stores unsigned bit 16 in the ACCB according to the result, and stores the highest-order byte of the result in the ACCA.

Effect on condition codes

C = R₇: When bit 7 of the result is 1, bit C is set and otherwise cleared.

NEGate

NEG

Type	Function
Arithmetic operation (one operand)	$ACCX \leftarrow (ACCX) = 00 - (ACCX)$ or $M \leftarrow (M) = 00 - (M)$ Performs two's complement for the contents of the ACCX or memory M and stores the result in the ACCX or M. However, if the contents of the ACCX or memory M are $\$80(-128)$, no two's complement is performed. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = R7:	When the highest-order bit of the result is 1, bit N is set and otherwise cleared.
Z = R7. R6. R5. R4. R3. R2. R1. R0:	When the result is 0, bit Z is set and otherwise cleared.
V = R7. R6. R5. R4. R3. R2. R1. R0:	When the result overflows, bit V is set and otherwise cleared.
C = R7. R6. R5. R4. R3. R2. R1. R0:	When a borrow occurs, bit C is set and otherwise cleared. This bit is also set when the contents of the ACCX or memory M are not 0.

No Operation

NOP

Type	Function
Unconditional branch	Updates the program counter but does not affect other registers. Effect on condition codes
H :	Not affected.

inclusive OR

ORA

Type	Function
Logical operation	$ACCX \leftarrow (ACCX) \text{ OR } (M)$ ORs the contents of the ACCX with those of memory M and stores the result in the ACCX. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = R7:	When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.
Z = R7. R6. R5. R4. R3. R2. R1. R0:	When all the bits of the result are 0, bit Z is set and otherwise cleared.
V = 0:	Bit V is cleared.
C :	Not affected.

PuSH data onto stack PSH

Type	Function
Storage	↓ (ACCX) SP ← (SP) - 0001

Stores the contents of the ACCX in the stack indicated by the stack pointer (SP) and subtracts 1 from the SP.
Effect on condition codes

H : Not affected.

PuSH index register onto stack PSHX

Type	Function
Storage	↓ (IXL), SP ← (SP) - 0001 ↓ (IXL), SP ← (SP) - 0001

Stores the contents of the index register in the stack indicated by the SP and subtracts 2 from the SP.
Effect on condition codes

H : Not affected.

PULl data from stack PUL

Type	Function
Load	SP ← (SP) + 0001 ↑ ACCX

Adds 1 to the SP and loads the contents of the stack indicated by the SP to the ACCX.
Effect on condition codes

H : Not affected.

PULl index register from stack PULX

Type	Function
Load	SP ← (SP) + 0001: ↑ IXH SP ← (SP) + 0001: ↑ IXL

Adds 1 to the SP and loads the contents of the stack indicated by the SP to the index register. This means that the SP is totally updated twice.
Effect on condition codes

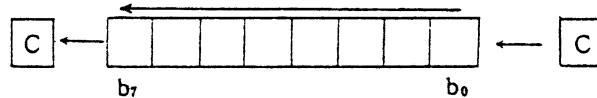
H : Not affected.

ROtate Left

ROL

Type
Shift and
rotation

Function



Shifts the contents of the ACCX or memory M to the left by one byte and transfers bit C to bit 0 (b0) and bit 7 (b7) to bit C.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = $\overline{R_7 \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0}$: When all bits of the results are 0, bit Z is set and otherwise cleared.

V = N ⊕ C: When N is 1 and C is 0 or N is 0 and C is 1 after execution of an instruction, bit V is set and otherwise cleared.

Note: N and C are those after the operation.

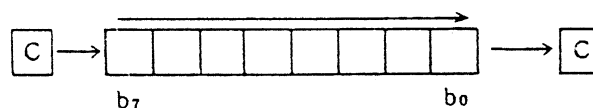
C = M₇: When the lower-order bit (LSB) of the ACCX or memory M is 1 before execution of an instruction, bit C is set and otherwise cleared.

ROtate Right

ROR

Type
Shift and
rotation

Function



Shifts the contents of the ACCX or memory M to the right by one bit and transfers bit C to bit 7 (b7) and bit 0 (b0) to bit C.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = $\overline{R_7 \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0}$: When all bits of the result are 0, bit Z is set and otherwise cleared.

V = N ⊕ C: When N is 1 and C is 0 or N is 0 and C is 1 after execution of an instruction, bit V is set and otherwise cleared.

Note: N and C are those after the operation.

C = M₀: When the lowest-order bit (LSB) of the ACCX or memory M is 1 before execution of an instruction, bit C is set and otherwise cleared.

ReTurn from Interrupt

RTI

Type	Function
Interrupt control	SP ← (SP) + 0001, ↑ CC
	SP ← (SP) + 0001, ↑ ACCB
	SP ← (SP) + 0001, ↑ ACCA
	SP ← (SP) + 0001, ↑ IXH
	SP ← (SP) + 0001, ↑ IXL
	SP ← (SP) + 0001, ↑ PCH
	SP ← (SP) + 0001, ↑ PCL

Stores the contents of the stack indicated by the SP to the CC, ACCB, ACCA, IXH, IXL, PCH, and PCL while adding 1 to the SP one by one. Note that if the interrupt mask bit of the CC saved to the stack is 1, I = 0 is set.

Effect on condition codes

H : The contents saved to the stack return.

ReTurn from Subroutine

RTS

Type	Function
Subroutine control	SP ← (SP) + 0001
	↑ PCH
	SP ← (SP) + 0001

↑ PCL

Adds 1 to the SP, sets the contents of the address indicated by the SP in the high-order 8 bits of the PC, adds 1 to the SP again, and stores the contents of the address indicated by the SP in the low-order 8 bits of the PC.

Effect on condition codes

H : Not affected.

SuBtract Accumulators

SBA

Type	Function
Arithmetic operation	ACCA (ACCA) - (ACCB)

Subtracts the contents of the ACCB from those of the ACCA and stores the result in the ACCA, but the contents of the ACCB do not change.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = R₇. R₆. R₅. R₄. R₃. R₂. R₁. R₀: When the result is 0, bit Z is set and otherwise cleared.

V = A₇. B₇. R₇ ⊙ A₇. B₇. R₇: When the result overflows, bit V is set and otherwise cleared.

C = A₇. B₇ ⊙ B₇ . R₇ ⊙ R₇. A₇: When the absolute value of the ACCB is greater than that of the ACCA, bit C is set and otherwise cleared.

SuBtract with Carry

SBC

Type	Function
Arithmetic operation	ACCX ← (ACCX) - (M) - (C) Subtracts the contents of memories M and C from the ACCX and stores the result in the ACCX.

Effect on condition codes

H : Not affected.

I : Not affected.

N = R7: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.

Z = $\overline{R7} \cdot \overline{R6} \cdot \overline{R5} \cdot \overline{R4} \cdot \overline{R3} \cdot \overline{R2} \cdot \overline{R1} \cdot \overline{R0}$: When the result is 0, bit Z is set and otherwise cleared.

V = $X7 \cdot \overline{M7} \cdot \overline{R7} \oplus \overline{X7} \cdot M7 \cdot R7$: When the result overflows, bit V is set and otherwise cleared.

C = $\overline{X7} \cdot M7 \oplus M7 \cdot R7 \oplus R7 \cdot X7$: When the value obtained by combining the absolute value of memory M and that of memory C is greater than the absolute value of the ACCX, bit C is set and otherwise cleared.

SEt Carry

SEC

Type	Function
Bit control	C bit ← 1 Sets carry bit C of the conditions code register. Effect on condition codes

H : Not affected.

SEt Interrupt mask

SEI

Type	Function
Bit control	I bit ← 1 Sets the interrupt mask bit of the condition code register. When this bit is set, the interrupt from a peripheral device is disabled until it is cleared. Effect on condition codes

H : Not affected.

I = 1: Bit I is set.

SEt two's complement oVerflow bit

SEV

Type	Function
Bit control	V bit ← 1 Sets the overflow bit of the condition code register. Effect on condition codes

H : Not affected.

STore Accumulator

STA

Type	Function
Load and storage	M (ACCX) Stores the contents of the ACCX to memory M but the contents of the ACCX do not change. Effect on condition codes
H :	Not affected.
I :	Not affected.
N = X ₇ :	When the highest-order bit (MSB) of the ACCX is 1, bit N is <u>set and otherwise cleared</u> .
Z = X ₇ . X ₆ . X ₅ . X ₄ . X ₃ . X ₂ . X ₁ . X ₀ :	When the contents of the ACCX are 0, bit Z is set and otherwise cleared.
V = 0:	Bit V is cleared.
C :	Not affected.

Double STore accumulator A:B

STD

Type	Function
Load and storage	M : M + 1 (ACCAB) Stores the contents of the ACCAB to memories M and M+1 but the contents of the ACCAB do not change. Effect on condition codes.
H :	Not affected.
I :	Not affected.
N = AB ₁₅ :	When the highest-order bit (MSB) of the ACCAB is 1, bit N is <u>set and otherwise cleared</u> .
Z = AB ₁₅ . AB ₁₄ . AB ₁₃ AB ₀ :	When the contents of the ACCAB are 0, bit Z is set and otherwise cleared.
V = 0:	Bit V is cleared.
C :	Not affected.

STore Stack pointer

STS

Type	Function
Stack pointer control	M (SPH) M + 1 (SPL) Stores the high-order 8 bits of the SP in memory M and then the low-order 8 bits of the SP in address M+1 (memory M address plus 1). Effect on condition codes
H :	Not affected.
I :	Not affected.
N = SPH ₇ :	When the highest-order bit (MSB) of the SP is 1, bit N is <u>set and otherwise cleared</u> .
Z = (SPH ₇ . SPH ₆ . SPH ₅ . SPH ₄ . SPH ₃ . SPH ₂ . SPH ₁ . SPH ₀ .) (SPL ₇ . SPL ₆ . SPL ₅ . SPL ₄ . SPL ₃ . SPL ₂ . SPL ₁ . SPL ₀):	When the contents of the SP are 0, bit Z is set and otherwise cleared.
V = 0:	Bit V is cleared.
C :	Not affected.

STore index register

STX

Type	Function
Index register	$M + (IXH)$
control	$M + 1 + (IXL)$

Stores the high-order 8 bits of the index register in memory M and then the low-order 8 bits of the index register in address M + 1 (memory M address plus 1).
Effect on condition codes

H : Not affected.

N = IXH₇: When the highest-order bit (MSB) of the index register is 1, bit N is set and otherwise cleared.Z = $(\overline{IXH_7} \cdot \overline{IXH_6} \cdot \overline{IXH_5} \cdot \overline{IXH_4} \cdot \overline{IXH_3} \cdot \overline{IXH_2} \cdot \overline{IXH_1} \cdot \overline{IXH_0}) \cdot (\overline{IXL_7} \cdot \overline{IXL_6} \cdot \overline{IXL_5} \cdot \overline{IXL_4} \cdot \overline{IXL_3} \cdot \overline{IXL_2} \cdot \overline{IXL_1} \cdot \overline{IXL_0})$: When the contents of the index register are 0, bit Z is set and otherwise cleared.

V = 0: Bit V is cleared.

C : Not affected.

SUBtract

SUB

Type	Function
Arithmetic operation	ACCX (ACCX) - (M)

Subtracts the contents of memory M from the ACCX and stores the result in the ACCX.
Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.Z = $\overline{R_7} \cdot \overline{R_6} \cdot \overline{R_5} \cdot \overline{R_4} \cdot \overline{R_3} \cdot \overline{R_2} \cdot \overline{R_1} \cdot \overline{R_0}$: When the result is 0, bit Z is set and otherwise cleared.V = $\overline{R_7} \cdot \overline{M_7} \cdot \overline{R_7} \odot \overline{X_7} \cdot M_7 \cdot R_7$: When the result overflows, bit V is set and otherwise cleared.C = $\overline{X_7} \cdot M_7 \odot M_7 \cdot R_7 \odot R_7 \cdot X_7$: When the absolute value of memory M is greater than that of the ACCX, bit C is set and otherwise cleared.

Double SUBtract without carry

SUBD

Type	Function
Arithmetic operation	ACCAB (ACCAB) - (M:M + 1)

Subtracts 2 bytes of memory M from the ACCAB and stores the result in the ACCAB.
Effect on condition codes

H : Not affected.

I : Not affected.

N = R₁₅: When the highest-order bit (MSB) of the result is 1, bit N is set and otherwise cleared.Z = $\overline{R_{15}} \cdot \overline{R_{14}} \cdot \overline{R_{13}} \cdot \dots \cdot \overline{R_0}$: When the result is 0, bit Z is set and otherwise cleared.V = $\overline{AB_{15}} \cdot \overline{M_{15}} \cdot \overline{R_{15}} \odot \overline{AB_{15}} \cdot M_{15} \cdot R_{15}$: When the result overflows, bit V is set and otherwise cleared.C = $\overline{AB_{15}} \cdot M_{15} \odot M_{15} \cdot R_{15} \odot R_{15} \cdot \overline{AB_{15}}$: When the absolute value of memory M is greater than that of the ACCAB, bit C is set and otherwise cleared.

SoftWare Interrupt

SWI

Type	Function
Interrupt contr	PC ← (PC) + 0001 ↓ (PCL), SP ← (SP) - 0001 ↓ (IXL), SP ← (SP) - 0001 ↓ (IXH), SP ← (SP) - 0001 ↓ (ACCA), SP ← (SP) - 0001 ↓ (ACCB), SP ← (SP) - 0001 ↓ (CC), SP ← (SP) - 0001 I ← 1 PCH ← (highest-order address - 0005) PCL ← (highest-order address - 0004) Adds 1 to the program counter (PC), saves the PCL, PCH, IXL, IXH, ACCA, ACCB, AND CC to the stacks indicated by the SP in turn, subtracts 1 from the saved PCL one by one, saves the set bits 6 and 7 of a condition code, sets the interrupt mask bit, and loads the contents of two highest-order addresses -5 and -4 to the program counter. Effect on condition codes

H : Not affected.

I = 1: Bit I is set.

Transfer from accumulator A to accumulator B

TAB

Type	Function
Transfer	ACCB ← (ACCA) — Transfers the contents of the ACCA to the ACCB but the contents of the ACCA remain unchanged. Effect on condition codes

H : Not affected.

I : Not affected.

N = R₇: When the highest-order bit (MSB) of the ACCA is 1, bit N is set and otherwise cleared.Z = R₇ · R₆ · R₅ · R₄ · R₃ · R₂ · R₁ · R₀: When the contents of the ACCA are 0, bit Z is set and otherwise cleared.

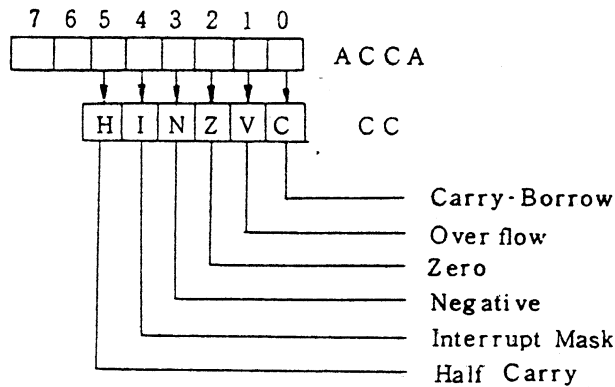
V = 0: Bit V is cleared.

C : Not affected.

Transfer from accumulator A to Processor
condition codes register

TAP

Type Function
Transfer CC ← (ACCA)



Transfers bit 0 through 5 (b_0 through b_5) of the ACCA to the corresponding bits of the condition code register but the contents of the ACCA remain unchanged.

Effect on condition codes

- H : Bit 5 of the ACCA
- I : Bit 4 of the ACCA
- N : Bit 3 of the ACCA
- Z : Bit 2 of the ACCA
- V : Bit 1 of the ACCA
- C : Bit 0 of the ACCA

Transfer from accumulator B to accumulator A

TBA

Type Function
Transfer ACCA ← (ACCB)

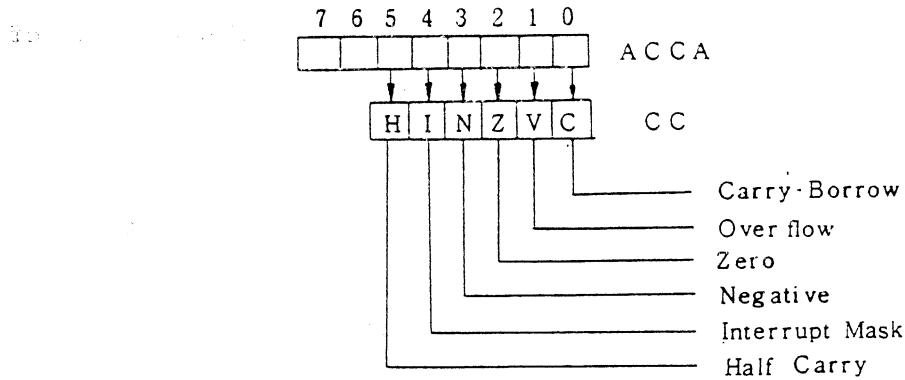
Transfers the contents of the ACCB to ACCA but the contents of the ACCB remain unchanged.

Effect on condition codes

- H : Not affected.
- I : Not affected.
- N = R_7 : When the highest-order bit (MSB) of the ACCA is 1, bit N is set and otherwise cleared.
- Z = $R_7 \cdot R_6 \cdot R_5 \cdot R_4 \cdot R_3 \cdot R_2 \cdot R_1 \cdot R_0$: When the contents of the ACCA are 0, bit Z is set and otherwise cleared.
- V = 0: Bit V is cleared.
- C : Not affected.

Transfer from accumulator A to Processor condition codes register TAP

Type Function
 Transfer CC ← (ACCA)



Transfers bits 0 through 5 of the ACCA to the corresponding bits of the condition code (CC) register but the contents of the ACCA remain unchanged.
 Effect on condition codes

H : Not affected.

TeST

TST

Type Function
 Comparison and (ACCX) - 00
 test (M) - 00

Sets bits N and Z of the condition code according to the contents of the ACCX or memory M.
 Effect on condition codes

H : Not affected.

I : Not affected.

N = M₇: When the highest-order bit (MSB) of the ACCX or memory M is 1, bit N is set and otherwise cleared.

Z = M₇. M₆. M₅. M₄. M₃. M₂. M₁. M₀: When the contents of the ACCX or memory M are 0, bit Z is set and otherwise cleared.

V = 0 : Bit V is cleared.

C = 0 : Bit C is cleared.

Transfer from Stack pointer to index register TSX

Type Function
 Transfer IX (SP) + 0001

Adds 1 to the stack pointer (SP) and sets the result in the index register but the contents of the SP remain unchanged.

Effect on condition codes

H : Not affected.

Transfer from index register to Stack pointer TXS

Type	Function
Transfer	SP ← (IX) + 0001
	Subtracts 1 from the index register and sets the result in the stack pointer (SP) but the contents of the index register remain unchanged.
	Effect on condition codes

Not affected.

WAI for interrupt WAI

Type	Function
Interrupt	PC ← (PC) + 0001
	↓ (PCL), SP ← (SP) - 0001
	↓ (PCH), SP ← (SP) - 0001
	↓ (IXL), SP ← (SP) - 0001
	↓ (IXH), SP ← (SP) - 0001
	↓ (ACCA), SP ← (SP) - 0001
	↓ (ACCB), SP ← (SP) - 0001
	↓ (CC), SP ← (SP) - 0001

This instruction:

- 1) Adds 1 to the program counter (PC).
- 2) Saves the PCL, PCH, IXL, IXH, ACCA, ACCB, and CC indicated by the SP in turn.
- 3) Subtracts 1 from the SP one by one when the PCL is saved.
- 4) Transfers bits 0 through 7 (b₀ through b₇) of the CC. In this case, bits 6 and 7 (b₆ and b₇) must be set.
- 5) Temporarily terminates the execution program until the peripheral device issues an interrupt.
- 6) Sets bit I if bit I is 0 when an interrupt is issued.
- 7) Loads the interrupt vectoring address to the PC.

Effect on condition codes

H : Not affected.

I : Bit I is not affected until an interrupt is issued. In other words, this bit can be set if it is 0 when an interrupt is issued.

N : Not affected.

5. INSTRUCTION CODES

Mode Selection

Mode	P ₂₂ (PC2)	P ₂₁ (PC1)	P ₂₀ (PC0)	ROM	RAM	Interrupt Vectors	Bus Mode	Operating Mode
7	H	H	H	I	I	I	I	Single Chip
6	H	H	L	I	I	I	MUX(5)	Multiplexed/Partial Decode
5	H	L	H	I	I	I	NMUX(5)	Non-Multiplexed/Partial Decode
4	H	L	L	I(2)	I(1)	I	I	Single Chip Test
3	L	H	H	E	E	E	MUX(4)	Multiplexed, No RAM & ROM
2	L	H	L	E	I	E	MUX(4)	Multiplexed/RAM
1	L	L	H	I	I	E	MUX(4)	Multiplexed/RAM & ROM
0	L	L	L	I	I	I(3)	MUX(4)	Multiplexed Test

Legend:

I: Internal
 E: External
 MUX: Multiplexed
 NMUX: Non-multiplexed
 L: Logic 0
 H: Logic 1

Notes:

- 1) The internal RAM is addressed at SXX80 through SXFF.
- 2) The internal ROM cannot be used.
- 3) The reset vector is used as the external vector for 2E clock cycles after RES becomes High level.
- 4) In modes 0, 1, 2, and 3, the addresses related to ports 3 and 4 are used as the external addresses.
- 5) In modes 5 and 6, the addresses related to port 3 are used as the external addresses while the addresses related to port 4 are used as the internal addresses. 1 must be written into the data direction register when an address is output because the unnecessary addresses of port 4 can be used as an input port.
- 6) Only mode 2 can apply to the HD6803.

SCI bit time and transfer rates

SSI:SSO		XTAL	2.4576MHz	4.0MHz	4.9152MHz*
		E	614.4kHz	1.0MHz	1.2288MHz
0	0	E ÷ 16	25µs/38,400Baud	16µs/62,500Baud	13.0µs/76,800Baud
0	1	E ÷ 128	208µs/4,800Baud	128µs/7812.5Baud	104.2µs/9,600Baud
1	0	E ÷ 1024	1.67ms/600Baud	1.024ms/976.6Baud	833.3µs/1,200Baud
1	1	E ÷ 4096	6.67ms/150Baud	4.096ms/244.1Baud	3.33ms/300Baud

*: 49152 MHz can apply only to the 125 MHz version.

SCI formats and clock source control

CCI.CCO	Format	Clock Source	Port2 Bit2	Port2 Bit3	Port2 Bit4
0 0	---	---	---	---	---
0 1	NRZ	Internal	Not Used	**	**
1 0	NRZ	Internal	Output*	**	**
1 1	NRZ	External	Input	**	**

*: A clock is output regardless of the status of bits RE and TE of the TRCS register.

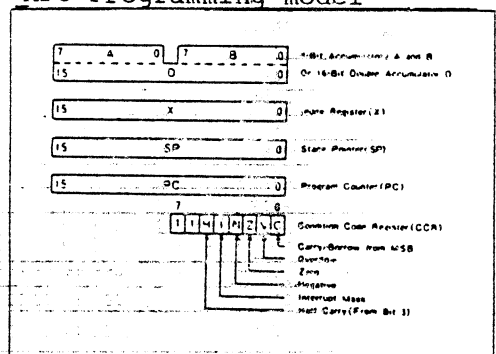
** : When bit RE of the TRCS register is 1, bit 3 is used as a serial input. When bit TE of the TRCS register is 1, bit 4 is used as a serial output.

Jump & Branch Operations	Mnemonic	Addressing Modes										Branch Test	Condition Code Register							
		RELATIVE		DIRECT		INDEX		EXTND		IMPLIED			5	4	3	2	1	0		
		OP	~	=	OP	~	=	OP	~	=	OP		~	=	H	I	N	Z	V	C
Branch Always	BRA	20	3	2										None	•	•	•	•	•	•
Branch Never	BRN	21	3	2										None	•	•	•	•	•	•
Branch If Carry Clear	BCC	24	3	2										C=0	•	•	•	•	•	•
Branch If Carry Set	BCS	25	3	2										C=1	•	•	•	•	•	•
Branch If = Zero	BEQ	27	3	2										Z=1	•	•	•	•	•	•
Branch If ≥ Zero	BGE	2C	3	2										N+V=0	•	•	•	•	•	•
Branch If > Zero	BGT	2E	3	2										Z-(N+V)=0	•	•	•	•	•	•
Branch If Higher	BHI	22	3	2										C+Z=0	•	•	•	•	•	•
Branch If ≤ Zero	BLE	2F	3	2										Z-(N+V)=1	•	•	•	•	•	•
Branch If Lower Of Same	BLS	23	3	?										C+Z=1	•	•	•	•	•	•
Branch If < Zero	BLT	2D	3	2										N+V=1	•	•	•	•	•	•
Branch If Minus	BMI	2B	3	2										N=1	•	•	•	•	•	•
Branch If Not Equal Zero	BNF	26	3	2										Z=0	•	•	•	•	•	•
Branch If Overflow Clear	BVC	28	3	2										V=0	•	•	•	•	•	•
Branch If Overflow Set	BVS	29	3	2										V=1	•	•	•	•	•	•
Branch If Plus	BPL	2A	3	2										N=0	•	•	•	•	•	•
Branch To Subroutine	BSS	8D	6	2											•	•	•	•	•	•
Jump	JMP					6E	3	2	7E	3	3				•	•	•	•	•	•
Jump To Subroutine	JSR				9D	5	2	AD	6	2	BD	6	3		•	•	•	•	•	•
No Operation	NOP												01	2	1					
Return From Interrupt	RTI												3B	10	1					
Return From Subroutine	RTS												39	5	1					
Software Interrupt	SWI												3F	12	1					
Wait for Interrupt	WAI												3E	9	1					

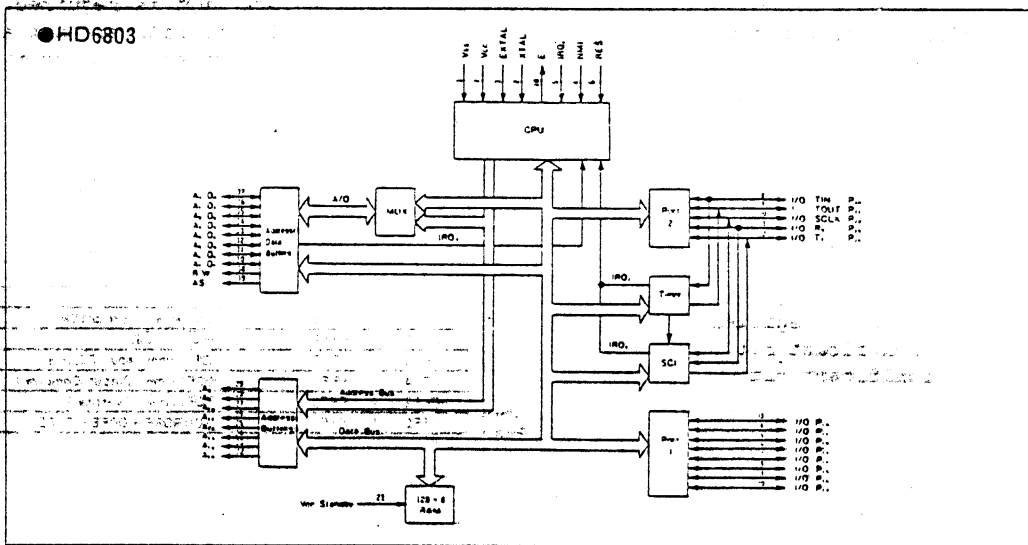
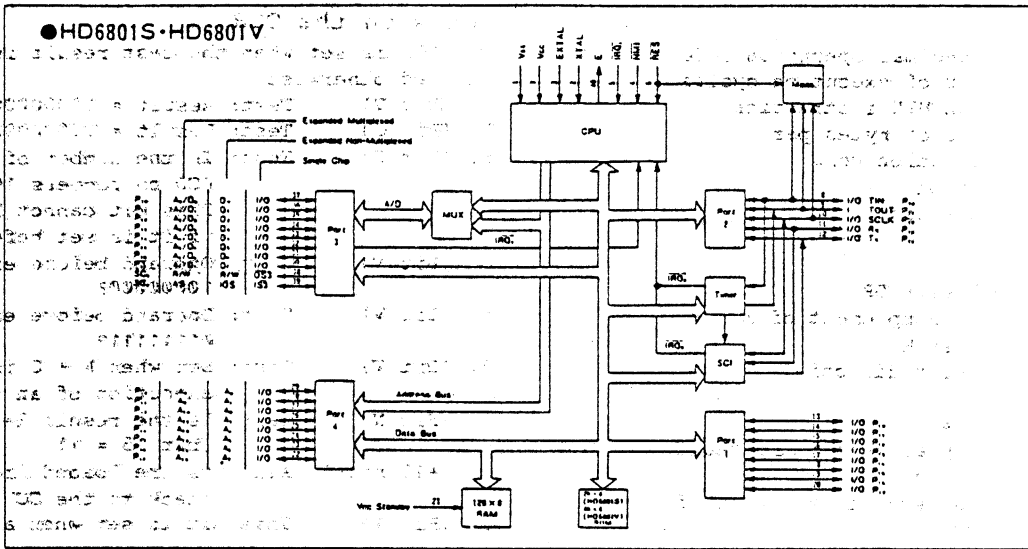
Index Register & Stack Operations	Mnemonic	Addressing Modes										Boolean/ Arithmetic Operation	Condition Code Register							
		IMMED		DIRECT		INDEX		EXTND		IMPLIED			5	4	3	2	1	0		
		OP	~	=	OP	~	=	OP	~	=	OP		~	=	H	I	N	Z	V	C
Compare Index Reg	CPX	8C	4	3	9C	5	2	AC	6	2	BC	6	3		X-M : M-1	•	•	•	•	•
Decrement Index Reg	DEX												09	3	1	X-1→X	•	•	•	•
Decrement Stack Ptr	DES												34	3	1	SP-1→SP	•	•	•	•
Increment Index Reg	INX												08	3	1	X+1→X	•	•	•	•
Increment Stack Ptr	INS												31	3	1	SP+1→SP	•	•	•	•
Load Index Reg	LDX	CE	3	3	DE	4	2	EE	5	2	FE	5	3		M→X _H , (M+1)→X _L	•	•	•	•	
Load Stack Ptr	LDS	8E	3	3	9E	4	2	AE	5	2	BE	5	3		M→SP _H , (M+1)→SP _L	•	•	•	•	
Store Index Reg	STX				DF	4	2	EF	5	2	FF	5	3		X _H →M, X _L →(M+1)	•	•	•	•	
Store Stack Ptr	STS				9F	4	2	AF	5	2	BF	5	3		SP _H →M, SP _L →(M+1)	•	•	•	•	
Index Reg→Stack Ptr	TXS												35	3	1	X-1→SP	•	•	•	•
Stack Ptr→Index Reg	TSX												30	3	1	SP-1→X	•	•	•	•
Add B to Index Reg	ABX												3A	3	1	B+X→X	•	•	•	•
Push Data	PSHX												3C	4	1	X _L →M ₁₀ , SP-1→SP X _H →M ₁₀ , SP-1→SP	•	•	•	•
Pull Data	PULX												38	5	1	SP+1→SP, M ₁₀ →X _H SP+1→SP, M ₁₀ →X _L	•	•	•	•

MPU Programming model

Condition Code Register Operations	Mnemonic	Addressing Modes			Boolean Operation	Condition Code Register														
		IMPLIED	OP	~		=	5	4	3	2	1	0								
Clear Carry	CLC	0C	2	1	0→C	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Clear Interrupt Mask	CLI	0E	2	1	0→I	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Clear Overflow	CLV	0A	2	1	0→V	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Set Carry	SEC	0D	2	1	1→C	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Set Interrupt Mask	SEI	0F	2	1	1→I	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Set Overflow	SEV	0B	2	1	1→V	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
Accumulator A→CCR	TAP	06	2	1	A→CCR	•	•	•	•	•	•	•	•	•	•	•	•	•	•	
CCR→Accumulator A	TPA	07	2	1	CCR→A	•	•	•	•	•	•	•	•	•	•	•	•	•	•	



Block Diagram



Symbols:

- OP : Hexadecimal operation code
- : Number of execution cycles for an MPU instruction
- # : Number of bytes per instruction word
- + : Addition
- : Subtraction
- . : AND
- + : OR
- + : Exclusive OR
- M : One's complement of memory address M
- + : Transfer direction
- 0 : Bit =
- 00 : Byte =
- MSD : Memory address indicated by the stack pointer (SP)
- H : Bit 3 carry to bit 4 (Half Carry)
- I : Interrupt mask
- N : Negative display
- Z : Zero display
- V : Overflow display for two's complement
- C : Bit 7 carry or borrow
- R : Always reset (= 0).
- S : Always set (= 1).
- : Set the bit when true after the test and otherwise cleared.
- : The contents remain unchanged during execution of an instruction.
- CCR : Condition code register
- LS : Least significant bit
- MS : Most significant bit

Notes on the CCR

- The CCR is set when the test result is true and cleared otherwise.
1. (Bit V) Test: Result = 10000000?
 2. (Bit C) Test: Result = 00000000?
 3. (Bit C) Test: Is the number of high-order BCD characters 10?
This bit cannot be cleared if it is set beforehand.
 4. (Bit V) Test: Operand before execution = 10000000?
 5. (Bit V) Test: Operand before execution = 01111111?
 6. (Bit V) Test: Set when N + C is 1 after execution of an instruction.
 7. (Bit N) Test: Is the result less than 0? (bit 15 = 1)
 8. (All bits) All bits are loaded from the stack to the CCR.
 9. (Bit 1) This bit is set when an interrupt occurs.
To reset the set bit, a nonmaskable interrupt is required.
 10. (All bits) All the bits are set according to the contents of accumulator A.
 11. (Bit C) Bit 7 of the ACCB after multiplication = 1?

Memory Map for An Interrupt Vector

Highest Priority	Vector		Interrupt
	MSB	LSB	
	FFFE	FFFF	RES
	FFFC	FFFD	NMI
	FFFA	FFFB	Software Interrupt (SWI)
	FFF8	FFF9	IRQ (or IS3)
	FFF5	FFF7	ICF (Timer Input Capture)
	FFF4	FFF5	OCF (Timer Output Compare)
	FFF2	FFF3	TOF (Timer Overflow)
Lowest Priority	FFF0	FFF1	SCHDRDF + ORFE + TDRE

Op-code map

OP CODE	ACC				IND	EXT	ACCA or SP				ACCB or X						
	A	B					IMM	DIR	IND	EXT	IMM	DIR	IND	EXT			
HI	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111	
LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
0000	0	SBA	BRA	TSX	NEG				SUB				0				
0001	1	NOP	CBA	BRN	INS					CMP				1			
0010	2	BHI		PULA(+1)					SBC				2				
0011	3	BLS		PULB(+1)	COM				*	SUBD(-2)		*	ADD0(+2)		3		
0100	4	LSRO(+1)		BCC	DES	LSR				AND				4			
0101	5	ASLD(-1)		BCS	TXS					BIT				5			
0110	6	TAP	TAB	BNE	PSHA	ROR				LDA				6			
0111	7	TPA	TBA	BEQ	PSHB	ASR				STA		STA		7			
1000	8	INX(-1)		BVC	PULX(-2)	ASL				EOR				8			
1001	9	DEX(+1)		DAA	BVS	RTS(+2)		ROL				ADC				9	
1010	A	ICLV		BPL	ABX	DEC				ORA				A			
1011	B	SEV		ABA	BMI	RTI(+7)						ADD				B	
1100	C	CLC		BGE	PSHX(+1)	INC				*	CPX(+2)		*	LDD(-1)		C	
1101	D	SEC		BLT	MUL(+7)	TST		B	BSR(-4)		JSR(+2)		A	STD(+1)		D	
1110	E	CLI		BGT	WAI(-6)	***		JMP(-3)		*	LDS(-1)		*	LDX(-1)		E	
1111	F	SEI		BLE	SWI(-9)	CLR				*	STS(+1)		*	STX(+1)		F	
BYTE		1/2	1/2	2/3	1/3	1/2	1/2	2/6	3/6	2/2	2/2	3/2	4/3	4/2	2/2	2/3	2/4

	ABA DAA SEC	2	1	Op Code Address	1	Op Code
	ASL DEC SEI		2	Op Code Address + 1	1	Op Code of Next Instruction
	ASR INC SEV					
	CBA LSR TAB					
	CLC NEG TAP					
	CLI NOP TBA					
	CLR ROL TPA					
	CLV ROR TST					
	COM SBA					
	ABX	3	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	ASLD	3	1	Op Code Address	1	Op Code
	LSRD		2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	DBX		1	Op Code Address	1	Op Code
	INS		2	Op Code Address + 1	1	Op Code of Next Instruction
				Previous Register Contents	1	Irrelevant Data
	INX		1	Op Code Address	1	Op Code
	DEX		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	PSHA		1	Op Code Address	1	Op Code
	PSWB		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	0	Accumulator Data
	TSX		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	1	Irrelevant Data
	TXS		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	PULA		1	Op Code Address	1	Op Code
	PULB		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Operand Data from Stack
	PSHX		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	0	Index Register (Low Order Byte)
			4	Stack Pointer + 1	0	Index Register (High Order Byte)
	PULX		5	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Index Register (High Order Byte)
			5	Stack Pointer + 2	1	Index Register (Low Order Byte)
IMPLIED	RTS		5	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Address of Next Instruction (High Order Byte)
			5	Stack Pointer + 2	1	Address of Next Instruction (Low Order Byte)
	WAI		9	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	0	Return Address (Low Order Byte)
			4	Stack Pointer + 1	0	Return Address (High Order Byte)
			5	Stack Pointer + 2	0	Index Register (Low Order Byte)
			6	Stack Pointer + 3	0	Index Register (High Order Byte)
			7	Stack Pointer + 4	0	Contents of Accumulator A
			8	Stack Pointer + 5	0	Contents of Accumulator B
			9	Stack Pointer + 6	0	Contents of Cond. Code Register
	MUL		10	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
			4	Address Bus FFFF	1	Low Byte of Restart Vector
			5	Address Bus FFFF	1	Low Byte of Restart Vector
			6	Address Bus FFFF	1	Low Byte of Restart Vector
			7	Address Bus FFFF	1	Low Byte of Restart Vector
			8	Address Bus FFFF	1	Low Byte of Restart Vector
			9	Address Bus FFFF	1	Low Byte of Restart Vector
			10	Address Bus FFFF	1	Low Byte of Restart Vector
	RTI		10	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Contents of Cond. Code Reg. from Stack
			5	Stack Pointer + 2	1	Contents of Accumulator B from Stack
			6	Stack Pointer + 3	1	Contents of Accumulator A from Stack
			7	Stack Pointer + 4	1	Index Register from Stack (High Order Byte)
			8	Stack Pointer + 5	1	Index Register from Stack (Low Order Byte)
			9	Stack Pointer + 6	1	Next Instruction Address from Stack (High Order Byte)
			10	Stack Pointer + 7	1	Next Instruction Address from Stack (Low Order Byte)
	SWI		12	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	0	Return Address (Low Order Byte)
			4	Stack Pointer + 1	0	Return Address (High Order Byte)
			5	Stack Pointer + 2	0	Index Register (Low Order Byte)
			6	Stack Pointer + 3	0	Index Register (High Order Byte)
			7	Stack Pointer + 4	0	Contents of Accumulator A
			8	Stack Pointer + 5	0	Contents of Accumulator B
			9	Stack Pointer + 6	0	Contents of Cond. Code Register
			10	Stack Pointer + 7	1	Irrelevant Data
			11	Vector Address FFFA (Hex)	1	Address of Subroutine (High Order Byte)
			12	Vector Address FFFB (Hex)	1	Address of Subroutine (Low Order Byte)

Operation of Commands at Each Cycle

Address Mode	Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
IMMEDIATE	ADC EOR ADD LDA AND ORA BIT SBC CMP SUB	2	1 2	Op Code Address Op Code Address + 1	1 1	Op Code Operand Data
	LDS LDX LDD	3	1 2 3	Op Code Address Op Code Address + 1 Op Code Address + 2	1 1 1	Op Code Operand Data (High Order Byte) Operand Data (Low Order Byte)
	CPX SUBD ADD	4	1 2 3 4	Op Code Address Op Code Address + 1 Op Code Address + 2 Address Bus FFFF	1 1 1 1	Op Code Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
	ADC EOR ADD LDA AND ORA BIT SBC CMP SUB	3	1 2 3	Op Code Address Op Code Address + 1 Address of Operand	1 1 1	Op Code Address of Operand Operand Data
	STA	3	1 2 3	Op Code Address Op Code Address + 1 Destination Address	1 1 0	Op Code Destination Address Data from Accumulator
	LDS LDX LDD	4	1 2 3 4	Op Code Address Op Code Address + 1 Address of Operand Operand Address + 1	1 1 1 1	Op Code Address of Operand Operand Data (High Order Byte) Operand Data (Low Order Byte)
	STS STX STD	4	1 2 3 4	Op Code Address Op Code Address + 1 Address of Operand Address of Operand + 1	1 1 0 0	Op Code Address of Operand Register Data (High Order Byte) Register Data (Low Order Byte)
	CPX SUBD ADD	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Operand Address Operand Address + 1 Address Bus FFFF	1 1 1 1 1	Op Code Address of Operand Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
	JSR	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Subroutine Address Stack Pointer Stack Pointer + 1	1 1 1 0 0	Op Code Irrelevant Data First Subroutine Op Code Return Address (Low Order Byte) Return Address (High Order Byte)
	INDEXED	JMP	3	1 2 3	Op Code Address Op Code Address + 1 Address Bus FFFF	1 1 1
ADC EOR ADD LDA AND ORA BIT SBC CMP SUB		4	1 2 3 4	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register Plus Offset	1 1 1 1	Op Code Offset Low Byte of Restart Vector Operand Data
STA		4	1 2 3 4	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register Plus Offset	1 1 1 0	Op Code Offset Low Byte of Restart Vector Operand Data
LDS LDX LDD		5	1 2 3 4 5	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register Plus Offset Index Register Plus Offset + 1	1 1 1 1 1	Op Code Offset Low Byte of Restart Vector Operand Data (High Order Byte) Operand Data (Low Order Byte)
STS STX STD		5	1 2 3 4 5	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register Plus Offset Index Register Plus Offset + 1	1 1 1 0 0	Op Code Offset Low Byte of Restart Vector Operand Data (High Order Byte) Operand Data (Low Order Byte)
ASL LSR ASR NEG CLR ROL COM ROR DEC TST INC		6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register Plus Offset Address Bus FFFF Index Register Plus Offset	1 1 1 1 1 0	Op Code Offset Low Byte of Restart Vector Current Operand Data Low Byte of Restart Vector New Operand Data
CPX SUBD ADD		6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register + Offset Index Register + Offset + 1 Address Bus FFFF	1 1 1 1 1 1	Op Code Offset Low Byte of Restart Vector Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
JSR		6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Address Bus FFFF Index Register - Offset Stack Pointer Stack Pointer - 1	1 1 1 1 0 0	Op Code Offset Low Byte of Restart Vector First Subroutine Op Code Return Address (Low Order Byte) Return Address (High Order Byte)

	ABA DAA SEC ASL DEC SEI ASR INC SEV CBA LSR TAB CLC NEG TAP CLI NOP TBA CLR ROL TPA CLV ROR TST COM SBA	2	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
	ABX	3	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	ASLD	3	1	Op Code Address	1	Op Code
	LSRD		2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	DBS		1	Op Code Address	1	Op Code
	INS		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Previous Register Contents	1	Irrelevant Data
	INX		1	Op Code Address	1	Op Code
	DEX		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	PSHA		1	Op Code Address	1	Op Code
	PSWD		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	0	Accumulator Data
	TSX		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	1	Irrelevant Data
	TXS		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	PULA		1	Op Code Address	1	Op Code
	PULB		2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Operand Data from Stack
	PSHX		1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	0	Index Register (Low Order Byte)
			4	Stack Pointer + 1	0	Index Register (High Order Byte)
	PULX		5	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Index Register (High Order Byte)
			5	Stack Pointer + 2	1	Index Register (Low Order Byte)
IMPLIED	RTS		5	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Address of Next Instruction (High Order Byte)
			5	Stack Pointer + 2	1	Address of Next Instruction (Low Order Byte)
	WAI		9	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Op Code of Next Instruction
			3	Stack Pointer	0	Return Address (Low Order Byte)
			4	Stack Pointer + 1	0	Return Address (High Order Byte)
			5	Stack Pointer + 2	0	Index Register (Low Order Byte)
			6	Stack Pointer + 3	0	Index Register (High Order Byte)
			7	Stack Pointer + 4	0	Contents of Accumulator A
			8	Stack Pointer + 5	0	Contents of Accumulator B
			9	Stack Pointer + 6	0	Contents of Cond. Code Register
	MUL		10	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Address Bus FFFF	1	Low Byte of Restart Vector
			4	Address Bus FFFF	1	Low Byte of Restart Vector
			5	Address Bus FFFF	1	Low Byte of Restart Vector
			6	Address Bus FFFF	1	Low Byte of Restart Vector
			7	Address Bus FFFF	1	Low Byte of Restart Vector
			8	Address Bus FFFF	1	Low Byte of Restart Vector
			9	Address Bus FFFF	1	Low Byte of Restart Vector
			10	Address Bus FFFF	1	Low Byte of Restart Vector
	RTI		10	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	1	Irrelevant Data
			4	Stack Pointer + 1	1	Contents of Cond. Code Reg. from Stack
			5	Stack Pointer + 2	1	Contents of Accumulator B from Stack
			6	Stack Pointer + 3	1	Contents of Accumulator A from Stack
			7	Stack Pointer + 4	1	Index Register from Stack (High Order Byte)
			8	Stack Pointer + 5	1	Index Register from Stack (Low Order Byte)
			9	Stack Pointer + 6	1	Next Instruction Address from Stack (High Order Byte)
			10	Stack Pointer + 7	1	Next Instruction Address from Stack (Low Order Byte)
	SWI		12	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Irrelevant Data
			3	Stack Pointer	0	Return Address (Low Order Byte)
			4	Stack Pointer + 1	0	Return Address (High Order Byte)
			5	Stack Pointer + 2	0	Index Register (Low Order Byte)
			6	Stack Pointer + 3	0	Index Register (High Order Byte)
			7	Stack Pointer + 4	0	Contents of Accumulator A
			8	Stack Pointer + 5	0	Contents of Accumulator B
			9	Stack Pointer + 6	0	Contents of Cond. Code Register
			10	Stack Pointer + 7	1	Irrelevant Data
			11	Vector Address FFFA(Hex)	1	Address of Subroutine (High Order Byte)
			12	Vector Address FFFB(Hex)	1	Address of Subroutine (Low Order Byte)

	JMP	3	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Jump Address (High Order Byte)
			3	Op Code Address + 2	1	Jump Address (Low Order Byte)
	ADC EOR ADD LDA AND ORA	4	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Address of Operand (High Order Byte)
			3	Op Code Address + 2	1	Address of Operand (Low Order Byte)
			4	Address of Operand	1	Operand Data
	BIT SBC CMR SUB	4	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Destination Address (High Order Byte)
			3	Op Code Address + 2	1	Destination Address (Low Order Byte)
			4	Operand Destination Address	0	Data from Accumulator
EXTENDED	STA	4	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Destination Address (High Order Byte)
			3	Op Code Address + 2	1	Destination Address (Low Order Byte)
			4	Operand Destination Address	0	Data from Accumulator
			5	Address of Operand	1	Operand Data (High Order Byte)
	LDS LDX LDD	5	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Address of Operand (High Order Byte)
			3	Op Code Address + 2	1	Address of Operand (Low Order Byte)
			4	Address of Operand	1	Operand Data (High Order Byte)
			5	Address of Operand + 1	1	Operand Data (Low Order Byte)
	STS STX STD	5	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Address of Operand (High Order Byte)
			3	Op Code Address + 2	1	Address of Operand (Low Order Byte)
			4	Address of Operand	0	Operand Data (High Order Byte)
			5	Address of Operand + 1	0	Operand Data (Low Order Byte)
	ASL LSR ASR NEG CLR ROL COM ROR DEC TST INC	6	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Address of Operand (High Order Byte)
			3	Op Code Address + 2	1	Address of Operand (Low Order Byte)
			4	Address of Operand	1	Current Operand Data
			5	Address Bus FFFF	1	Low Byte of Restart Vector
			6	Address of Operand	0	New Operand Data
	CPX SUBD ADDD	6	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Operand Address (High Order Byte)
			3	Op Code Address + 2	1	Operand Address (Low Order Byte)
			4	Operand Address	1	Operand Data (High Order Byte)
			5	Operand Address + 1	1	Operand Data (Low Order Byte)
			6	Address Bus FFFF	1	Low Byte of Restart Vector
	JSR	6	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Address of Subroutine (High Order Byte)
			3	Op Code Address + 2	1	Address of Subroutine (Low Order Byte)
			4	Subroutine Starting Address	1	Op Code of Next Instruction
			5	Stack Pointer	0	Return Address (Low Order Byte)
			6	Stack Pointer - 1	0	Return Address (High Order Byte)

- * : The sixth cycle changes for the TST instruction as follows:
 AB = FFFF, R/W = 1, DB = Low Byte of Restart Vector
- ** : Due to the WAIT instruction, the cycle changes in the wait state as follows:
 AB = Stack Pointer - 7, R/W = 1, DB = Interrupt data

RELATIVE	BCC BHI BNE BCS BLE BPL BEQ BLS BRA BGE BLT BVC BGT BMI BVS BRN	3	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Branch Offset
			3	Address Bus FFFF	1	Low Byte of Restart Vector
	BSR	6	1	Op Code Address	1	Op Code
			2	Op Code Address + 1	1	Branch Offset
			3	Address Bus FFFF	1	Low Byte of Restart Vector
			4	Subroutine Starting Address	1	Op Code of Next Instruction
			5	Stack Pointer	0	Return Address (Low Order Byte)
			6	Stack Pointer - 1	0	Return Address (High Order Byte)

This manual contains parts of the following materials:

- Hitachi Microcomputer System HMCS6800
- HD6801 User Manual published by Hitachi
- HD6301V MCU Temporary Specifications published by Hitachi
(May 1981)
- Instruction Pocket Book published by Hitachi
- HD146818 RTC Temporary Specifications published by Hitachi
- μ PD7227G Specifications published by NEC